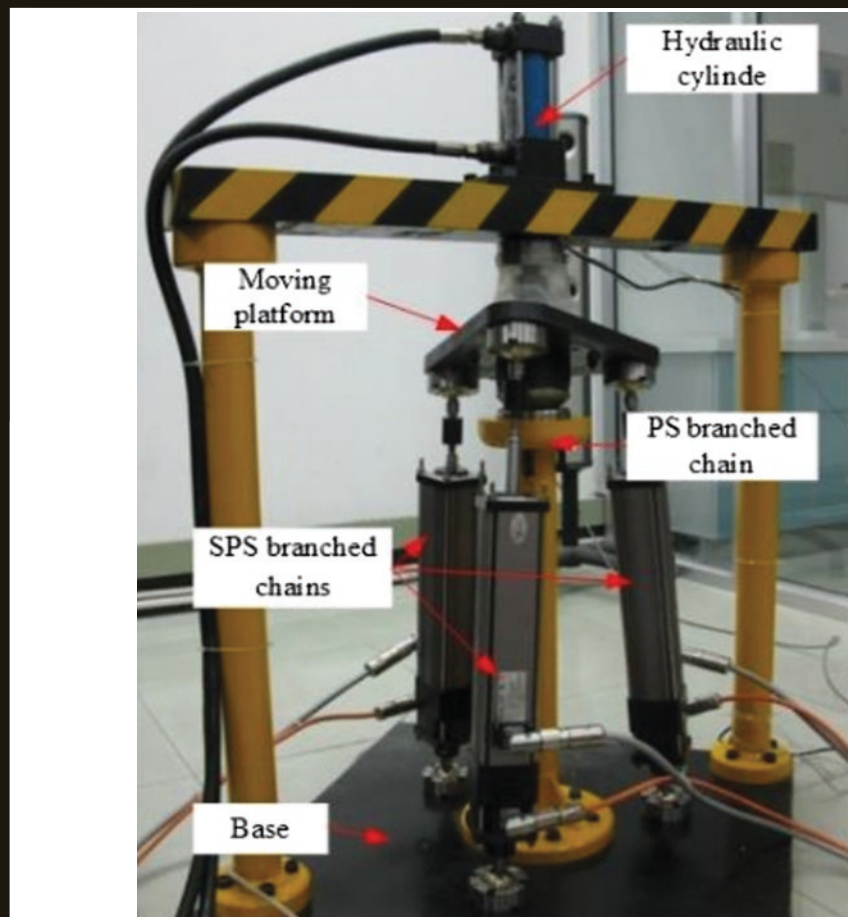


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International Journal of Information, Education and Research
in Robotics and Artificial Intelligence

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Robotica (ISSN 0263-5747) is published as twelve issues per Volume in January, February, March, April, May, June, July, August, September, October, November and December. The electronic-only price for Volume 39, 2021 available to institutional subscribers is £1420 (US \$2507 in USA, Canada and Mexico). EU subscribers (outside the UK) who are not registered for VAT should add VAT at their country's rate. VAT registered subscribers should provide their VAT registration number. Orders, which

must be accompanied by payment, may be sent to a bookseller, subscription agent or direct to the publishers: Cambridge University Press, University Printing House, Shaftesbury Road, Cambridge CB2 8RU, UK. Orders from the USA, Canada and Mexico should be sent to Cambridge University Press, Journals Fulfillment Department, 1 Liberty Plaza, Floor 20, New York, NY 10006, USA. Japanese prices for institutions are available from Kinokuniya Company Ltd, P.O. Box 55, Chitose, Tokyo 156, Japan. Prices include delivery by air.

Periodicals postage paid at New York, NY and additional mailing offices. POSTMASTER: send address changes in USA, Canada and Mexico to *Robotica*, Cambridge University Press, 1 Liberty Plaza, Floor 20, New York, NY 10006, USA.

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Cover Image: Design and Implementation of a Cable Inspection Robot for Cable-Stayed Bridges by Zhipeng Wang, Bin He, Yanmin Zhou, Ke Liu and Chenghong Zhang. Figure 20 'Active vehicle obstacle climbing experiment (1.5 mm height obstacle)'.
