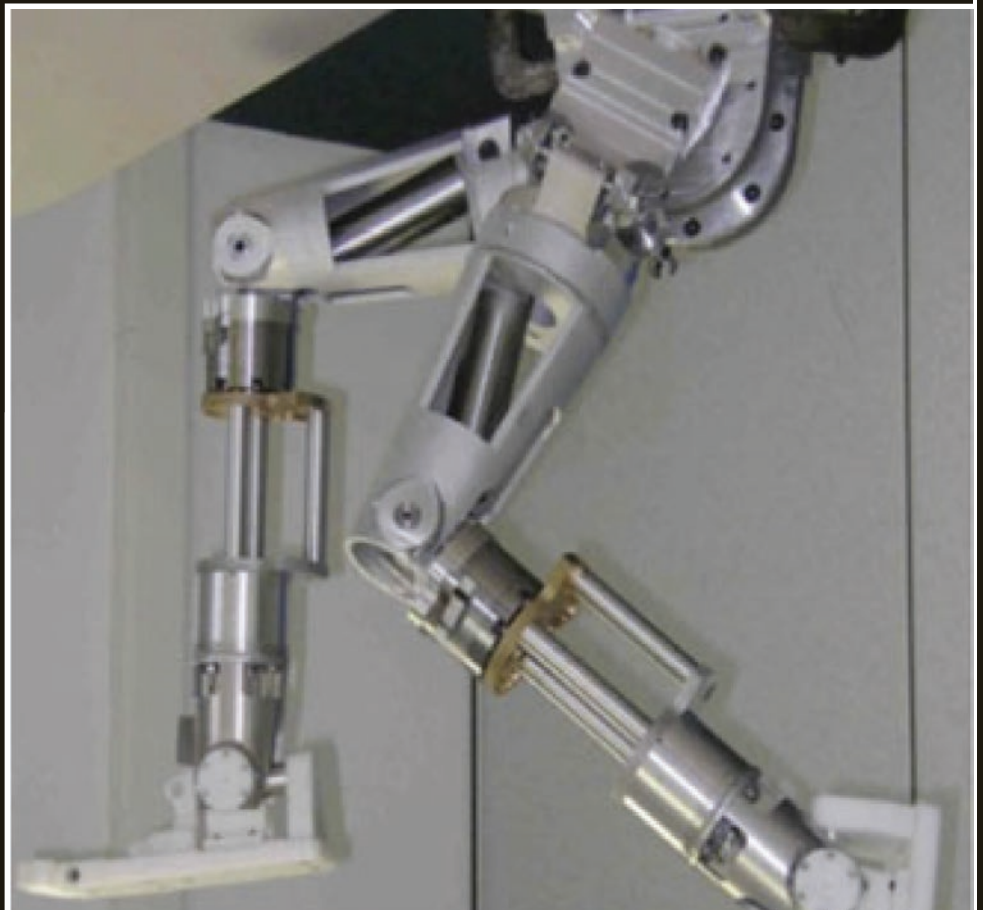


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E-mail: jian.dai@kcl.ac.uk

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Cover Image: Feasible speeds for two optimal periodic walking gaits of a planar biped robot by Mathieu Hobon, Víctor De-León-Gómez, Gabriel Abba, Yannick Aoustin and Christine Chevallereau. **Figure 3.** 'Photography of the locomotor system of Hydroid'.