


TRAJECTORY FITTING ESTIMATION FOR REFLECTED STOCHASTIC LINEAR DIFFERENTIAL EQUATIONS OF A LARGE SIGNAL

XUEKANG ZHANG ,* *Anhui Polytechnic University*
HUI SHENG SHU,** *Donghua University*

Abstract

In this paper we study the drift parameter estimation for reflected stochastic linear differential equations of a large signal. We discuss the consistency and asymptotic distributions of trajectory fitting estimator (TFE).

Keywords: trajectory fitting estimator; reflected stochastic linear differential equation; large signal; consistency; asymptotic distributions

2020 Mathematics Subject Classification: Primary 62F12
Secondary 60J60

1. Introduction

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be equipped with a right continuous and increasing family of σ -algebras $\{\mathcal{F}_t, t \geq 0\}$, and let $\{W_t\}_{t \geq 0}$ be a given standard Brownian motion defined on the probability space $(\Omega, \mathcal{F}, \mathbb{P})$. In this paper we consider a reflected stochastic linear differential equation of a large signal,

$$\begin{cases} dX_t = \frac{\theta}{\varepsilon} X_t dt + dW_t + dL_t, \\ X_t \geq 0, \quad 0 \leq t \leq T, \end{cases} \quad (1)$$

where the initial value $X_0 = x_0 > 0$, $\varepsilon \in (0, 1]$, $\theta \in \mathbb{R}$ is unknown, and $L = \{L_t, t \geq 0\}$ is the minimal increasing non-negative process which makes the reflected stochastic process (1) satisfy $X_t \geq 0$ for all $t \geq 0$. The process L increases only when X hits the boundary zero, so that

$$\int_0^\infty I_{\{X_t > 0\}} dL_t = 0.$$

It can be easily proved (see e.g. [9] and [22]) that the process L has the following explicit expression:

$$L_t = \max \left\{ 0, \sup_{u \in [0, t]} \left(-x_0 - \frac{\theta}{\varepsilon} \int_0^u X_v dv - W_u \right) \right\}. \quad (2)$$

Received 5 May 2022; accepted 17 September 2023.

* Postal address: School of Mathematics-Physics and Finance, and Key Laboratory of Advanced Perception and Intelligent Control of High-end Equipment, Ministry of Education, Anhui Polytechnic University, Wuhu 241000, China. Email address: xkzhang@ahpu.edu.cn

** Postal address: College of Science, Donghua University, Shanghai, 201620, China. Email address: hsshu@dhu.edu.cn

© The Author(s), 2023. Published by Cambridge University Press on behalf of Applied Probability Trust.

Usually in applications to financial engineering, queueing systems, storage models, etc., the reflecting barrier is assumed to be zero. This is principally because of the physical restriction of the state processes. For example, inventory levels, stock prices, and interest rates should take non-negative values. We refer to [2], [3], [8], [9], [14], [17], [18], [19], [20], [21], and [22] for more details on reflected stochastic differential equations (RSDEs) and their wide applications.

But in reality, the drift parameter in RSDEs is seldom known. Parametric inference is one of the effective methods for solving this type of problem. In the case of statistical inference for RSDEs driven by Brownian motion, a popular approach is the maximum likelihood estimation method, based on the Girsanov density (see e.g. [23], [24], and [26]). For example, Bo *et al.* [4] established the maximum likelihood estimator (MLE) for the stationary reflected Ornstein–Uhlenbeck processes (OUPs) and studied the strong consistency and asymptotic normality of the MLE. Jiang and Yang [12] considered asymptotic properties of the MLE of the parameter occurring in ergodic reflected Ornstein–Uhlenbeck processes (ROUPs) with a one-sided barrier. Zang and Zhu [26] investigated the strong consistency and limiting distribution of the MLE in both the stationary and non-stationary cases for reflected OUPs. It is well known that the TFE was introduced by Kutoyants [15] as a numerically attractive alternative to the well-investigated MLE. Recently, Zang and Zhang [25] used the trajectory fitting estimation to investigate the asymptotic behaviour of the estimator for non-stationary reflected OUPs, including strong consistency and asymptotic distribution. Further, they have shown that the TFE for ergodic reflected OUPs is not strongly consistent.

On the other hand, trajectory fitting estimation for stochastic process without reflection have drawn increasing attention (see e.g. [5], [6], [7], [15], and [16]). For instance, Abi-ayad and Mourid [1] discussed the strong consistency and Gaussian limit distribution of the TFE for non-recurrent diffusion processes. Jiang and Xie [11] studied the asymptotic behaviours for the TFE in stationary OUPs with linear drift.

Motivated by the aforementioned works, in this paper we extend the work of Zang and Zhang [25] and study the consistency and asymptotic distributions of the TFE for RSDE (1) based on continuous observation of $X = \{X_t, 0 \leq t \leq T\}$. In order to obtain our estimators, we divide RSDE (1) by $\varepsilon^{1/2}$ and change the variable $t_\varepsilon = t\varepsilon^{-1}$. So $t_\varepsilon \in [0, T_\varepsilon]$ with $T_\varepsilon = T\varepsilon^{-1}$. From the scaling properties of Brownian motion, we find that there exists another standard Brownian motion $\{\tilde{W}_t\}_{t \geq 0}$ on the enlarged probability space such that $\tilde{W}_t \stackrel{d}{=} \varepsilon^{-1/2}W_{\varepsilon t}$. Denote $Y_{t_\varepsilon} = X_{t_\varepsilon\varepsilon}\varepsilon^{-1/2}$. Then, for reflected stochastic process (1), we have

$$\begin{cases} dY_{t_\varepsilon} = \theta Y_{t_\varepsilon} dt_\varepsilon + d\tilde{W}_{t_\varepsilon} + d\tilde{L}_{t_\varepsilon}, \\ Y_{t_\varepsilon} \geq 0, \quad 0 \leq t_\varepsilon \leq T_\varepsilon, \\ Y_0 = x_0\varepsilon^{-1/2}, \end{cases} \tag{3}$$

where the realizations of $\tilde{L}_{t_\varepsilon} = \varepsilon^{-1/2}L_{\varepsilon t_\varepsilon}$. It follows from (2) that

$$\tilde{L}_{t_\varepsilon} = \max \left\{ 0, \sup_{s \in [0, t_\varepsilon]} \left(-x_0\varepsilon^{-1/2} - \theta \int_0^s Y_u du - \tilde{W}_s \right) \right\}. \tag{4}$$

Let

$$A_{t_\varepsilon} = \int_0^{t_\varepsilon} Y_s ds.$$

RSDE (3) can be written as

$$Y_{t_\varepsilon} = Y_0 + \theta A_{t_\varepsilon} + \tilde{W}_{t_\varepsilon} + \tilde{L}_{t_\varepsilon}, \quad 0 \leq t_\varepsilon \leq T_\varepsilon.$$

The TFE of θ should minimize

$$\int_0^{T_\varepsilon} |Y_{t_\varepsilon} - (Y_0 + \theta A_{t_\varepsilon})|^2 dt_\varepsilon.$$

It can easily be seen that the minimum is attained when θ is given by

$$\widehat{\theta}_\varepsilon = \frac{\int_0^{T_\varepsilon} A_{t_\varepsilon} (Y_{t_\varepsilon} - Y_0) dt_\varepsilon}{\int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon}.$$

By simple calculations, we have

$$\widehat{\theta}_\varepsilon - \theta = \frac{\int_0^{T_\varepsilon} A_{t_\varepsilon} \widetilde{W}_{t_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon} + \frac{\int_0^{T_\varepsilon} A_{t_\varepsilon} \widetilde{L}_{t_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon}. \quad (5)$$

2. Consistency of the TFE $\widehat{\theta}_\varepsilon$

In this section we discuss the consistency of the TFE $\widehat{\theta}_\varepsilon$ in both the non-ergodic and ergodic cases, respectively. We shall use the notation ‘ \rightarrow_p ’ to denote ‘convergence in probability’ and the notation ‘ \Rightarrow ’ to denote ‘convergence in distribution’. We write ‘ $\stackrel{d}{=}$ ’ for equality in distribution.

We introduce two important lemmas as follows.

Lemma 2.1. (Dietz and Kutoyants [6].) *If φ_T is a probability measure defined on $[0, \infty)$ such that $\varphi_T([0, T]) = 1$ and $\varphi_T([0, K]) \rightarrow 0$ as $T \rightarrow \infty$ for each $K > 0$, then*

$$\lim_{T \rightarrow \infty} \int_0^T f_t \varphi_T(dt) = f_\infty$$

for every bounded and measure function $f: [0, \infty) \rightarrow \mathbb{R}$ for which the limit $f_\infty := \lim_{t \rightarrow \infty} f_t$ exists.

Lemma 2.2. (Karatzas and Shreve [13].) *Let $z \geq 0$ be a given number and let $y(\cdot) = \{y(t); 0 \leq t < \infty\}$ be a continuous function with $y(0) = 0$. There exists a unique continuous function $k(\cdot) = \{k(t); 0 \leq t < \infty\}$ such that*

- (i) $x(t) := z + y(t) + k(t) \geq 0, 0 \leq t < \infty$,
- (ii) $k(0) = 0, k(\cdot)$ is non-decreasing,
- (iii) $k(\cdot)$ is flat off $\{t \geq 0; x(t) = 0\}$, that is,

$$\int_0^\infty I_{\{x(s) > 0\}} dk(s) = 0.$$

Then the function $k(\cdot)$ is given by

$$k(t) = \max \left[0, \max_{0 \leq s \leq t} \{-(z + y(s))\} \right], \quad 0 \leq t < \infty.$$

Theorem 2.1.

(a) Under $\theta > 0$, we have

$$\lim_{\varepsilon \rightarrow 0} (\widehat{\theta}_\varepsilon - \theta) = 0 \quad \text{a.s.} \quad (6)$$

(b) Under $\theta = 0$, we have

$$\widehat{\theta}_\varepsilon - \theta \rightarrow_p 0 \quad \text{as } \varepsilon \rightarrow 0. \quad (7)$$

(c) Under $\theta < 0$, we have

$$\lim_{\varepsilon \rightarrow 0} \widehat{\theta}_\varepsilon = 0 \quad \text{a.s.}, \quad (8)$$

that is, the TFE $\widehat{\theta}_\varepsilon$ is not strongly consistent.

Proof. (a) (i) If $x_0 > 0$, it is easy to see that

$$e^{-\theta t_\varepsilon} Y_{t_\varepsilon} = x_0 \varepsilon^{-1/2} + \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{W}_s + \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{L}_s. \quad (9)$$

Because the process $\widetilde{L} = \{\widetilde{L}_{t_\varepsilon}\}_{t_\varepsilon \geq 0}$ increases only when $Y = \{Y_{t_\varepsilon}\}_{t_\varepsilon \geq 0}$ hits the boundary zero, $\int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{L}_s$ is a continuous non-decreasing process for which

$$x_0 \varepsilon^{-1/2} + \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{W}_s + \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{L}_s \geq 0,$$

and increases only when

$$x_0 \varepsilon^{-1/2} + \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{W}_s + \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{L}_s = 0.$$

It follows from Lemma 2.2 that

$$\int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{L}_s = \max \left[0, \max_{0 \leq s \leq t_\varepsilon} \left\{ -x_0 \varepsilon^{-1/2} - \int_0^s e^{-\theta u} d\widetilde{W}_u \right\} \right]. \quad (10)$$

For

$$M_t := - \int_0^t e^{-\theta s} d\widetilde{W}_s,$$

by time change for a continuous martingale, there exists another standard Brownian motion $\{\widehat{W}_t\}_{t \geq 0}$ on the enlarged probability space such that $M_t \stackrel{d}{=} \widehat{W}_{\frac{1-e^{-2\theta t}}{2\theta}}$. It follows from (10) that

$$\int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{L}_s = \max \left[0, -x_0 \varepsilon^{-1/2} + \max_{0 \leq s \leq \frac{1-e^{-2\theta t_\varepsilon}}{2\theta}} \widehat{W}_s \right]. \quad (11)$$

Then, under $\theta > 0$ and $x_0 > 0$, by the fact that \widehat{W}_s , $s \in [0, 1/(2\theta)]$ is almost surely finite, we have

$$\lim_{\varepsilon \rightarrow 0} \varepsilon^{1/2} \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{L}_s = 0 \quad \text{a.s.} \quad (12)$$

In view of the definition of the quadratic variation of a continuous local martingale, we find that

$$\lim_{\varepsilon \rightarrow 0} \langle M, M \rangle_{t_\varepsilon} = \frac{1}{2\theta} \quad \text{a.s.}$$

and

$$\check{M}_{t_\varepsilon} := M_{t_\varepsilon}^2 - \langle M, M \rangle_{t_\varepsilon}$$

is a continuous local martingale. Writing this as

$$M_{t_\varepsilon}^2 = \check{M}_{t_\varepsilon} + \langle M, M \rangle_{t_\varepsilon},$$

it follows from the convergence theorem of non-negative semi-martingales that

$$\lim_{\varepsilon \rightarrow 0} M_{t_\varepsilon}^2 < \infty \quad \text{a.s.},$$

and hence

$$\lim_{\varepsilon \rightarrow 0} M_{t_\varepsilon} = - \int_0^\infty e^{-\theta s} d\tilde{W}_s \quad \text{a.s.} \quad (13)$$

Applying (9), (12), and (13), we obtain

$$\lim_{\varepsilon \rightarrow 0} \varepsilon^{1/2} e^{-\theta t_\varepsilon} Y_{t_\varepsilon} = x_0 \quad \text{a.s.} \quad (14)$$

Combining Lemma 2.1 with (14) yields

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \varepsilon^{1/2} e^{-\theta T_\varepsilon} A_{T_\varepsilon} &= \lim_{\varepsilon \rightarrow 0} \int_0^{T_\varepsilon} (\varepsilon^{1/2} e^{-\theta t_\varepsilon} Y_{t_\varepsilon}) \frac{e^{\theta t_\varepsilon}}{\int_0^{T_\varepsilon} e^{\theta t_\varepsilon} dt_\varepsilon} dt_\varepsilon \times e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} e^{\theta t_\varepsilon} dt_\varepsilon \\ &= \frac{x_0}{\theta} \quad \text{a.s.} \end{aligned} \quad (15)$$

By (4) and the self-similarity property for the Brownian motion, we get

$$\tilde{L}_{t_\varepsilon} \leq \max \left\{ 0, \sup_{0 \leq s \leq t_\varepsilon} (-x_0 \varepsilon^{-1/2} - \tilde{W}_s) \right\} \stackrel{d}{=} t_\varepsilon^{1/2} \max \left\{ 0, \max_{0 \leq u \leq 1} (-x_0 t^{-1/2} - \check{W}_u) \right\}, \quad (16)$$

where $\{\check{W}_u, u \geq 0\}$ is a fixed Wiener process on the enlarged probability space. Using (16) and the fact that $\check{W}_u, u \in [0, 1]$ is almost surely finite, we see that

$$\lim_{\varepsilon \rightarrow 0} \frac{\tilde{L}_{t_\varepsilon}}{t_\varepsilon} = 0 \quad \text{a.s.}$$

Obviously,

$$\lim_{\varepsilon \rightarrow 0} \frac{\tilde{L}_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} = 0 \quad \text{a.s.} \quad (17)$$

By the strong law of large numbers, we obtain

$$\lim_{\varepsilon \rightarrow 0} \frac{\widetilde{W}_{t_\varepsilon}}{t_\varepsilon} = 0 \quad \text{a.s.}$$

This implies that

$$\lim_{\varepsilon \rightarrow 0} \frac{\widetilde{W}_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} = 0 \quad \text{a.s.} \tag{18}$$

By (15), (17), (18), and Lemma 2.1, we have

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} (\widehat{\theta}_\varepsilon - \theta) &= \lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \frac{A_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} \frac{\widetilde{W}_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} \frac{\varepsilon^{-1} e^{2\theta t_\varepsilon}}{\int_0^{T_\varepsilon} \varepsilon^{-1} e^{2\theta t_\varepsilon} dt_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} \left(\frac{A_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}}\right)^2 \frac{\varepsilon^{-1} e^{2\theta t_\varepsilon}}{\int_0^{T_\varepsilon} \varepsilon^{-1} e^{2\theta t_\varepsilon} dt_\varepsilon} dt_\varepsilon} \\ &\quad + \lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \frac{A_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} \frac{\widetilde{L}_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} \frac{\varepsilon^{-1} e^{2\theta t_\varepsilon}}{\int_0^{T_\varepsilon} \varepsilon^{-1} e^{2\theta t_\varepsilon} dt_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} \left(\frac{A_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}}\right)^2 \frac{\varepsilon^{-1} e^{2\theta t_\varepsilon}}{\int_0^{T_\varepsilon} \varepsilon^{-1} e^{2\theta t_\varepsilon} dt_\varepsilon} dt_\varepsilon} \\ &= 0 \quad \text{a.s.} \end{aligned} \tag{19}$$

This completes the desired proof.

(ii) If $x_0 = 0$, by Theorem 2.1 of Zang and Zhang [23], it follows that (6) holds. This completes the proof of Theorem 2.1(a).

(b) Under $\theta = 0$, we have $Y_{T_\varepsilon} = x_0 \varepsilon^{-1/2} + \widetilde{W}_{T_\varepsilon} + \widetilde{L}_{T_\varepsilon}$. Then

$$\int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon = T_\varepsilon^4 \int_0^1 \left(\int_0^t \left(\frac{x_0}{\sqrt{T}} + \frac{\widetilde{W}_{sT_\varepsilon}}{\sqrt{T_\varepsilon}} + \frac{\widetilde{L}_{sT_\varepsilon}}{\sqrt{T_\varepsilon}} \right) ds \right)^2 dt$$

and

$$\int_0^{T_\varepsilon} (\widetilde{W}_{t_\varepsilon} + \widetilde{L}_{t_\varepsilon}) A_{t_\varepsilon} dt_\varepsilon = T_\varepsilon^3 \int_0^1 \left(\frac{\widetilde{W}_{sT_\varepsilon}}{\sqrt{T_\varepsilon}} + \frac{\widetilde{L}_{sT_\varepsilon}}{\sqrt{T_\varepsilon}} \right) \int_0^s \left(\frac{x_0}{\sqrt{T}} + \frac{\widetilde{W}_{uT_\varepsilon}}{\sqrt{T_\varepsilon}} + \frac{\widetilde{L}_{uT_\varepsilon}}{\sqrt{T_\varepsilon}} \right) du ds.$$

By the scaling properties of Brownian motion and Lemma 2.2, it follows that

$$\begin{aligned} \{(\widetilde{W}_\nu, \widetilde{L}_\nu); \nu \geq 0\} &\stackrel{d}{=} \left\{ T_\varepsilon^{1/2} \left(\widehat{W}_{\nu/T_\varepsilon}, \max \left\{ 0, \max_{0 \leq s \leq \nu} (-x_0 T^{-1/2} - \widehat{W}_{s/T_\varepsilon}) \right\} \right); \nu \geq 0 \right\} \\ &=: \{T_\varepsilon^{1/2} (\widehat{W}_{\nu/T_\varepsilon}, \widehat{L}_{\nu/T_\varepsilon}); \nu \geq 0\}, \end{aligned}$$

where $\{\widehat{W}_\nu, \nu \geq 0\}$ is another standard Wiener process on the enlarged probability space. By the continuous mapping theorem, we have

$$\begin{aligned} \frac{\int_0^{T_\varepsilon} (\widetilde{W}_{t_\varepsilon} + \widetilde{L}_{t_\varepsilon}) A_{t_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon} &\stackrel{d}{=} \frac{1}{T_\varepsilon} \frac{\int_0^1 (\widehat{W}_s + \widehat{L}_s) \int_0^s (x_0 T^{-1/2} + \widehat{W}_u + \widehat{L}_u) du ds}{\int_0^1 \left(\int_0^t (x_0 T^{-1/2} + \widehat{W}_s + \widehat{L}_s) ds \right)^2 dt} \\ &\rightarrow_p 0 \quad \text{as } \varepsilon \rightarrow 0, \end{aligned} \tag{20}$$

where

$$\widehat{L}_s = \max \left\{ 0, \max_{0 \leq u \leq s} (-x_0 T^{-1/2} - \widehat{W}_u) \right\}.$$

Combining (5) with (20) implies that (7) holds. This completes the desired proof.

(c) We consider the case $\theta < 0$. We first introduce the reflected OUP

$$d\bar{Y}_{t_\varepsilon} = \theta \bar{Y}_{t_\varepsilon} dt_\varepsilon + d\widetilde{W}_{t_\varepsilon} + d\bar{L}_{t_\varepsilon}, \quad \bar{Y}_0 = 0, \quad 0 \leq t_\varepsilon \leq T_\varepsilon. \quad (21)$$

It is easy to see that

$$e^{-\theta t_\varepsilon} \bar{Y}_{t_\varepsilon} = \int_0^{t_\varepsilon} e^{-\theta s} d\widetilde{W}_s + \int_0^{t_\varepsilon} e^{-\theta s} d\bar{L}_s. \quad (22)$$

Similarly to the discussion of (10), we see that

$$\int_0^{t_\varepsilon} e^{-\theta s} d\bar{L}_s = \max \left[0, \max_{0 \leq s \leq t_\varepsilon} \left\{ - \int_0^s e^{-\theta u} d\widetilde{W}_u \right\} \right]. \quad (23)$$

By (9), (10), (22), and (23), we have

$$\begin{aligned} |Y_{T_\varepsilon} - \bar{Y}_{T_\varepsilon}| &= e^{\theta T_\varepsilon} \left| \max \left[0, \max_{0 \leq s \leq T_\varepsilon} \left\{ -x_0 \varepsilon^{-1/2} - \int_0^s e^{-\theta u} d\widetilde{W}_u \right\} \right] \right. \\ &\quad \left. - \max \left[0, \max_{0 \leq s \leq T_\varepsilon} \left\{ - \int_0^s e^{-\theta u} d\widetilde{W}_u \right\} \right] \right| + x_0 \varepsilon^{-1/2} e^{\theta T_\varepsilon} \\ &\leq 2x_0 \varepsilon^{-1/2} e^{\theta T_\varepsilon}. \end{aligned} \quad (24)$$

For the linear system (21), according to the mean ergodic theorem (see Hu *et al.* [10]), we have

$$\lim_{\varepsilon \rightarrow 0} \frac{1}{T_\varepsilon} \int_0^{T_\varepsilon} \bar{Y}_s ds = \frac{1}{\sqrt{-\pi\theta}} \quad \text{a.s.} \quad (25)$$

Combining (24) with (25) yields

$$\lim_{\varepsilon \rightarrow 0} \frac{A_{T_\varepsilon}}{T_\varepsilon} = \lim_{\varepsilon \rightarrow 0} \frac{1}{T_\varepsilon} \int_0^{T_\varepsilon} (Y_s - \bar{Y}_s) ds + \lim_{\varepsilon \rightarrow 0} \frac{1}{T_\varepsilon} \int_0^{T_\varepsilon} \bar{Y}_s ds = \frac{1}{\sqrt{-\pi\theta}} \quad \text{a.s.} \quad (26)$$

It follows from Zang and Zhang [25] that

$$\lim_{\varepsilon \rightarrow 0} \frac{\bar{L}_{T_\varepsilon}}{T_\varepsilon} = \sqrt{\frac{-\theta}{\pi}} \quad \text{a.s.}$$

Note that

$$\begin{aligned} |\widetilde{L}_{T_\varepsilon} - \bar{L}_{T_\varepsilon}| &= \left| \max \left\{ 0, \sup_{s \in [0, T_\varepsilon]} \left(-x_0 \varepsilon^{-1/2} - \theta \int_0^s Y_u du - \widetilde{W}_s \right) \right\} \right. \\ &\quad \left. - \max \left\{ 0, \sup_{s \in [0, T_\varepsilon]} \left(-\theta \int_0^s \bar{Y}_u du - \widetilde{W}_s \right) \right\} \right| \\ &\leq x_0 \varepsilon^{-1/2} + |\theta| \int_0^{T_\varepsilon} 2x_0 \varepsilon^{-1/2} e^{\theta u} du \\ &\leq 3x_0 \varepsilon^{-1/2}. \end{aligned}$$

Then we have

$$\lim_{\varepsilon \rightarrow 0} \frac{\tilde{L}_{T_\varepsilon}}{T_\varepsilon} = \lim_{\varepsilon \rightarrow 0} \frac{\tilde{L}_{T_\varepsilon} - \bar{L}_{T_\varepsilon}}{T_\varepsilon} + \lim_{\varepsilon \rightarrow 0} \frac{\bar{L}_{T_\varepsilon}}{T_\varepsilon} = \sqrt{\frac{-\theta}{\pi}} \quad \text{a.s.} \tag{27}$$

By (26), (27), Lemma 2.1, and the strong law of large numbers, we have

$$\lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \tilde{W}_{t_\varepsilon} A_{t_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon} = \lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \frac{\tilde{W}_{t_\varepsilon} A_{t_\varepsilon}}{t_\varepsilon} \frac{t_\varepsilon^2}{\int_0^{T_\varepsilon} t_\varepsilon^2 dt_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} \left(\frac{A_{t_\varepsilon}}{t_\varepsilon}\right)^2 \frac{t_\varepsilon^2}{\int_0^{T_\varepsilon} t_\varepsilon^2 dt_\varepsilon} dt_\varepsilon} = 0 \quad \text{a.s.} \tag{28}$$

and

$$\lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \tilde{L}_{t_\varepsilon} A_{t_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon} = \lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \frac{\tilde{L}_{t_\varepsilon} A_{t_\varepsilon}}{t_\varepsilon} \frac{t_\varepsilon^2}{\int_0^{T_\varepsilon} t_\varepsilon^2 dt_\varepsilon} dt_\varepsilon}{\int_0^{T_\varepsilon} \left(\frac{A_{t_\varepsilon}}{t_\varepsilon}\right)^2 \frac{t_\varepsilon^2}{\int_0^{T_\varepsilon} t_\varepsilon^2 dt_\varepsilon} dt_\varepsilon} = -\theta \quad \text{a.s.} \tag{29}$$

By (5), (28), and (29), we can conclude that (8) holds. This completes the proof. □

3. Asymptotic distribution of the TFE $\hat{\theta}_\varepsilon$

In this section we investigate the asymptotic distribution of the TFE $\hat{\theta}_\varepsilon$.

Theorem 3.1. *Let $\{\widehat{W}_u, u \geq 0\}$ be another standard Wiener process on the enlarged probability space.*

(a) *Assume $\theta > 0$.*

(i) *If $x_0 > 0$, then*

$$(\hat{\theta}_\varepsilon - \theta) e^{\theta T_\varepsilon} \Rightarrow \frac{2\theta}{x_0} T^{1/2} N \quad \text{as } \varepsilon \rightarrow 0, \tag{30}$$

where N is a random variable with the standard normal distribution.

(ii) *If $x_0 = 0$, then*

$$\frac{e^{\theta T_\varepsilon}}{\sqrt{T_\varepsilon}} (\hat{\theta}_\varepsilon - \theta) \Rightarrow \frac{2\theta N}{|\widehat{W}_{1/(2\theta)} + \widehat{L}_{1/(2\theta)}|} \quad \text{as } \varepsilon \rightarrow 0, \tag{31}$$

where

$$\widehat{L}_{1/(2\theta)} = \max\left[0, \max_{0 \leq u \leq 1/(2\theta)} (-\widehat{W}_u)\right],$$

and N is a standard normal random variable which is independent of $\widehat{W}_{1/(2\theta)}$ and $\widehat{L}_{1/(2\theta)}$.

(b) *If $\theta = 0$, then*

$$\varepsilon^{-1} \hat{\theta}_\varepsilon \Rightarrow \frac{1}{T} \frac{\int_0^1 (\widehat{W}_s + \widehat{L}_s) \int_0^s (x_0 T^{-1/2} + \widehat{W}_u + \widehat{L}_u) du ds}{\int_0^1 \left(\int_0^t (x_0 T^{-1/2} + \widehat{W}_s + \widehat{L}_s) ds\right)^2 dt} \quad \text{as } \varepsilon \rightarrow 0, \tag{32}$$

where

$$\widehat{L}_s = \max\left\{0, \max_{0 \leq u \leq s} (-x_0 T^{-1/2} - \widehat{W}_u)\right\}$$

Proof. (a) (i) If $x_0 > 0$, we have

$$\begin{aligned}
 & e^{\theta T_\varepsilon}(\widehat{\theta}_\varepsilon - \theta) \\
 &= \frac{\varepsilon e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} A_{t_\varepsilon} \widetilde{W}_{t_\varepsilon} dt_\varepsilon + \varepsilon e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} A_{t_\varepsilon} \widetilde{L}_{t_\varepsilon} dt_\varepsilon}{\varepsilon e^{-2\theta T_\varepsilon} \int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon} \\
 &= \frac{T^{1/2}}{\varepsilon e^{-2\theta T_\varepsilon} \int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon} \left(T_\varepsilon^{-1/2} \widetilde{W}_{T_\varepsilon} \varepsilon^{1/2} e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} A_{t_\varepsilon} dt_\varepsilon \right. \\
 &\quad \left. + \varepsilon^{1/2} e^{-\theta T_\varepsilon} T_\varepsilon^{-1/2} \int_0^{T_\varepsilon} A_{t_\varepsilon} (\widetilde{W}_{T_\varepsilon} - \widetilde{W}_{t_\varepsilon}) dt_\varepsilon + \varepsilon^{1/2} e^{-\theta T_\varepsilon} T_\varepsilon^{-1/2} \int_0^{T_\varepsilon} A_{t_\varepsilon} \widetilde{L}_{t_\varepsilon} dt_\varepsilon \right) \\
 &:= I_1(\varepsilon)(I_2(\varepsilon) + I_3(\varepsilon) + I_4(\varepsilon)). \tag{33}
 \end{aligned}$$

We shall study the asymptotic behaviour of $I_i(\varepsilon)$, $i = 1, \dots, 4$. By (15) and Lemma 2.1, we can see that

$$\begin{aligned}
 & \lim_{\varepsilon \rightarrow 0} \varepsilon e^{-2\theta T_\varepsilon} \int_0^{T_\varepsilon} A_{t_\varepsilon}^2 dt_\varepsilon \\
 &= \lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \varepsilon^{-1} e^{2\theta t_\varepsilon} dt_\varepsilon}{\varepsilon^{-1} e^{2\theta T_\varepsilon}} \int_0^{T_\varepsilon} \left(\frac{A_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} \right)^2 \frac{\varepsilon^{-1} e^{2\theta t_\varepsilon}}{\int_0^{T_\varepsilon} \varepsilon^{-1} e^{2\theta t_\varepsilon} dt_\varepsilon} dt_\varepsilon \\
 &= \frac{x_0^2}{2\theta^3} \quad \text{a.s.}
 \end{aligned}$$

It follows that

$$\lim_{\varepsilon \rightarrow 0} I_1(\varepsilon) = \frac{2\theta^3}{x_0^2} T^{1/2} \quad \text{a.s.} \tag{34}$$

Now we consider $I_2(\varepsilon)$. Using (15) and Lemma 2.1 again, we have

$$\begin{aligned}
 & \lim_{\varepsilon \rightarrow 0} \varepsilon^{1/2} e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} A_{t_\varepsilon} dt_\varepsilon \\
 &= \lim_{\varepsilon \rightarrow 0} \frac{\int_0^{T_\varepsilon} \varepsilon^{-1/2} e^{\theta t_\varepsilon} dt_\varepsilon}{\varepsilon^{-1/2} e^{\theta T_\varepsilon}} \int_0^{T_\varepsilon} \left(\frac{A_{t_\varepsilon}}{\varepsilon^{-1/2} e^{\theta t_\varepsilon}} \right) \frac{\varepsilon^{-1/2} e^{\theta t_\varepsilon}}{\int_0^{T_\varepsilon} \varepsilon^{-1/2} e^{\theta t_\varepsilon} dt_\varepsilon} dt_\varepsilon \\
 &= \frac{x_0}{\theta^2} \quad \text{a.s.} \tag{35}
 \end{aligned}$$

For the second factor in $I_2(\varepsilon)$, we find that

$$T_\varepsilon^{-1/2} W_{T_\varepsilon} = T_\varepsilon^{-1/2} (W_{T_\varepsilon} - W_{T_\varepsilon^{1/2}}) + T_\varepsilon^{-1/2} W_{T_\varepsilon^{1/2}}.$$

It is easy to see that the random variable

$$T_\varepsilon^{-1/2} (W_{T_\varepsilon} - W_{T_\varepsilon^{1/2}})$$

has a normal distribution $N(0, 1 - T_\varepsilon^{-1/2})$, which converges weakly to a standard normal random variable N as $\varepsilon \rightarrow 0$. By the strong law of large numbers, we see that

$$\lim_{\varepsilon \rightarrow 0} \frac{W_{T_\varepsilon}^{1/2}}{T_\varepsilon^{1/2}} = 0 \quad \text{a.s.}$$

Hence we have

$$T_\varepsilon^{-1/2} W_{T_\varepsilon} \Rightarrow N \quad \text{as } \varepsilon \rightarrow 0. \tag{36}$$

Combining (35) with (36) gives

$$I_2(\varepsilon) \Rightarrow \frac{x_0}{\theta^2} N \quad \text{as } \varepsilon \rightarrow 0. \tag{37}$$

Next, we show that $I_3(\varepsilon) \rightarrow 0$ in probability as $\varepsilon \rightarrow 0$. Note that

$$\begin{aligned} |I_3(\varepsilon)| &\leq \varepsilon^{1/2} e^{-\theta T_\varepsilon} T_\varepsilon^{-1/2} \int_0^{T_\varepsilon} \left| \int_0^{t_\varepsilon} Y_s \, ds \right| |\tilde{W}_{T_\varepsilon} - \tilde{W}_{t_\varepsilon}| \, dt_\varepsilon \\ &\leq \varepsilon^{1/2} e^{-\theta T_\varepsilon} T_\varepsilon^{-1/2} \int_0^{T_\varepsilon} \left(\int_0^{t_\varepsilon} |\varepsilon^{1/2} e^{-\theta s} Y_s| e^{\theta s} \varepsilon^{-1/2} \, ds \right) |\tilde{W}_{T_\varepsilon} - \tilde{W}_{t_\varepsilon}| \, dt_\varepsilon \\ &\leq \frac{1}{\theta} \sup_{\varepsilon \geq 0} |\varepsilon^{1/2} e^{-\theta T_\varepsilon} Y_{T_\varepsilon}| T_\varepsilon^{-1/2} e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} |W_{T_\varepsilon} - W_{t_\varepsilon}| e^{\theta t_\varepsilon} \, dt_\varepsilon, \end{aligned} \tag{38}$$

which converges to zero in probability as $\varepsilon \rightarrow 0$. In fact, using Markov’s inequality and Fubini’s theorem, we find that for given $\delta > 0$,

$$\begin{aligned} &\mathbb{P}\left(T_\varepsilon^{-1/2} e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} |W_{T_\varepsilon} - W_{t_\varepsilon}| e^{\theta t_\varepsilon} \, dt_\varepsilon > \delta\right) \\ &\leq \delta^{-1} \mathbb{E}\left[T_\varepsilon^{-1/2} e^{-\theta T_\varepsilon} \int_0^{T_\varepsilon} |W_{T_\varepsilon} - W_{t_\varepsilon}| e^{\theta t_\varepsilon} \, dt_\varepsilon\right] \\ &= \delta^{-1} T_\varepsilon^{-1/2} \int_0^{T_\varepsilon} \mathbb{E}|W_{T_\varepsilon} - W_{t_\varepsilon}| e^{-\theta(T_\varepsilon - t_\varepsilon)} \, dt_\varepsilon \\ &= \delta^{-1} T_\varepsilon^{-1/2} \int_0^{T_\varepsilon} v^{1/2} e^{-\theta v} \, dv \\ &\leq \delta^{-1} T_\varepsilon^{-1/2} \theta^{-3/2} \frac{1}{2} \sqrt{\pi}, \end{aligned}$$

which tends to zero as $\varepsilon \rightarrow 0$. Finally, we consider $I_4(\varepsilon)$. Combining the self-similarity property for the Brownian motion with (4) yields

$$\begin{aligned} \frac{\tilde{L}_{t_\varepsilon}}{t_\varepsilon^{1/2}} &= t_\varepsilon^{-1/2} \max\left\{0, \sup_{0 \leq u t_\varepsilon \leq t_\varepsilon} \left(-x_0 \varepsilon^{-1/2} - \theta \int_0^{u t_\varepsilon} Y_r \, dr - \tilde{W}_{u t_\varepsilon}\right)\right\} \\ &\stackrel{d}{=} \max\left\{0, \max_{0 \leq u \leq 1} \left(-x_0 t^{-1/2} - \theta t_\varepsilon^{-1/2} \int_0^{u t_\varepsilon} Y_r \, dr - \tilde{W}_u\right)\right\} \quad \text{a.s.} \end{aligned} \tag{39}$$

Note that for any given $u \in (0, 1]$ we can choose a positive number $\epsilon > 0$ such that $\epsilon < u$. Then we have

$$\begin{aligned} & \lim_{\epsilon \rightarrow 0} \max_{u \in (0, 1]} \left(-x_0 t^{-1/2} - \theta t_\epsilon^{-1/2} \int_0^{ut_\epsilon} Y_r dr - \widehat{W}_u \right) \\ & \leq \lim_{\epsilon \rightarrow 0} \max_{u \in (0, 1]} \left(-\theta t_\epsilon^{-1/2} \int_0^{ut_\epsilon} Y_r dr \right) + \max_{u \in (0, 1]} (-\widehat{W}_u) \\ & \leq -\lim_{\epsilon \rightarrow 0} \theta t_\epsilon^{-1/2} \int_0^{\epsilon t_\epsilon} Y_r dr + \max_{u \in (0, 1]} (-\widehat{W}_u). \end{aligned} \quad (40)$$

By (15), we have

$$\begin{aligned} \lim_{\epsilon \rightarrow 0} \theta t_\epsilon^{-1/2} \int_0^{\epsilon t_\epsilon} Y_s ds &= \theta \lim_{\epsilon \rightarrow 0} \frac{\int_0^{\epsilon t_\epsilon} Y_s ds}{\epsilon^{-1/2} e^{\theta \epsilon t_\epsilon}} \frac{\epsilon^{-1/2} e^{\theta \epsilon t_\epsilon}}{t_\epsilon^{1/2}} \\ &= \theta \lim_{\epsilon \rightarrow 0} \frac{\int_0^{\epsilon t_\epsilon} Y_s ds}{\epsilon^{-1/2} e^{\theta \delta t_\epsilon}} \frac{e^{\theta \epsilon t_\epsilon}}{t^{1/2}} \\ &= \infty \quad \text{a.s.} \end{aligned} \quad (41)$$

By (40), (41), and the fact that \widehat{W}_u , $u \in (0, 1]$ is almost surely finite, we have

$$\lim_{\epsilon \rightarrow 0} \max_{u \in (0, 1]} \left(-x_0 t^{-1/2} - \theta t_\epsilon^{-1/2} \int_0^{ut_\epsilon} Y_r dr - \widehat{W}_u \right) = -\infty \quad \text{a.s.} \quad (42)$$

If $u = 0$, we find that

$$-x_0 t^{-1/2} - \theta t_\epsilon^{-1/2} \int_0^{ut_\epsilon} Y_r dr - \widehat{W}_u = -x_0 t^{-1/2}.$$

Hence we see that

$$\lim_{\epsilon \rightarrow 0} \max_{u \in [0, 1]} \left(-x_0 t^{-1/2} - \theta t_\epsilon^{-1/2} \int_0^{ut_\epsilon} \widetilde{Y}_s ds - \widehat{W}_u \right) = -x_0 t^{-1/2} \quad \text{a.s.} \quad (43)$$

Applying (39) and (43), we obtain

$$\lim_{\epsilon \rightarrow 0} \frac{\widetilde{L}_{t_\epsilon}}{t_\epsilon^{1/2}} = 0 \quad \text{a.s.} \quad (44)$$

By (15) and (44) as well as Lemma 2.1, we have

$$\begin{aligned} \lim_{\epsilon \rightarrow 0} I_4(\epsilon) &= \lim_{\epsilon \rightarrow 0} \int_0^{T_\epsilon} \frac{A_{t_\epsilon}}{\epsilon^{-1/2} e^{\theta t_\epsilon}} \frac{L_{t_\epsilon}}{t_\epsilon^{1/2}} \frac{\epsilon^{-1/2} t_\epsilon^{1/2} e^{\theta t_\epsilon}}{\int_0^{t_\epsilon} \epsilon^{-1/2} t_\epsilon^{1/2} e^{\theta t_\epsilon} dt_\epsilon} dt_\epsilon \frac{\int_0^{T_\epsilon} \epsilon^{-1/2} t_\epsilon^{1/2} e^{\theta t_\epsilon} dt_\epsilon}{\epsilon^{-1/2} T_\epsilon^{1/2} e^{\theta T_\epsilon}} \\ &\leq \lim_{\epsilon \rightarrow 0} \int_0^{T_\epsilon} \frac{A_{t_\epsilon}}{\epsilon^{-1/2} e^{\theta t_\epsilon}} \frac{L_{t_\epsilon}}{t_\epsilon^{1/2}} \frac{\epsilon^{-1/2} t_\epsilon^{1/2} e^{\theta t_\epsilon}}{\int_0^{t_\epsilon} \epsilon^{-1/2} t_\epsilon^{1/2} e^{\theta t_\epsilon} dt_\epsilon} dt_\epsilon \frac{\int_0^{T_\epsilon} e^{\theta t_\epsilon} dt_\epsilon}{e^{\theta T_\epsilon}} \\ &= 0 \quad \text{a.s.} \end{aligned} \quad (45)$$

Therefore, by (33), (34), (37), (38), and (45), we conclude that (30) holds. This completes the desired proof.

(ii) Under $x_0 = 0$, by Theorem 2.2 of Zang and Zhang [23], it follows that (31) holds. This completes the desired proof.

(b) Combining (5) with (20) implies that (32) holds. This completes the proof. \square

4. Discussion

In this section we discuss the properties of the TFE $\widehat{\theta}_\varepsilon$ and MLE

$$\widehat{\theta}_\varepsilon^{\text{MLE}} := \frac{\int_0^{T_\varepsilon} Y_s dY_s}{\int_0^{T_\varepsilon} Y_s^2 ds}$$

separately in terms of the range of θ , i.e. $\theta > 0$, $\theta = 0$, and $\theta < 0$. By comparing the results of Zhang and Shu [27], we obtain the following claims.

(a) Under $\theta > 0$, both estimators are consistent. In addition, the following hold.

(i) If $x_0 > 0$, then

$$\varepsilon^{-1/2} e^{\theta T_\varepsilon} (\widehat{\theta}_\varepsilon^{\text{MLE}} - \theta) \Rightarrow N\left(0, \frac{2\theta}{x_0^2}\right) \quad \text{as } \varepsilon \rightarrow 0, \quad (46)$$

(ii) If $x_0 = 0$, then

$$e^{\theta T_\varepsilon} (\widehat{\theta}_\varepsilon^{\text{MLE}} - \theta) \Rightarrow \frac{\sqrt{2\theta}N}{|\widehat{W}_{1/(2\theta)} + \widehat{L}_{1/(2\theta)}|} \quad \text{as } \varepsilon \rightarrow 0, \quad (47)$$

where

$$\widehat{L}_{1/(2\theta)} = \max\left[0, \max_{0 \leq u \leq 1/(2\theta)} (-\widehat{W}_u)\right],$$

and N is a standard normal random variable which is independent of $\widehat{W}_{1/(2\theta)}$ and $\widehat{L}_{1/(2\theta)}$. For both estimators, the order of the convergence depends heavily on the true value of the parameter. It can also be seen that the MLE $\widehat{\theta}_\varepsilon^{\text{MLE}}$ converges in distribution of higher order than the TFE $\widehat{\theta}_\varepsilon$.

(b) Under $\theta = 0$, it is easy to see that both estimators are consistent. The MLE $\widehat{\theta}_\varepsilon^{\text{MLE}}$ has the limiting distribution

$$\varepsilon^{-1} \widehat{\theta}_\varepsilon^{\text{MLE}} \Rightarrow \frac{1}{T} \frac{\int_0^1 (x_0 T^{-1/2} + \widehat{W}_u + \widehat{L}_u) d\widehat{W}_u}{x_0 T^{-1} + \int_0^1 (\widehat{W}_u + \widehat{L}_u)^2 du + 2x_0 T^{-1/2} \int_0^1 (\widehat{W}_u + \widehat{L}_u) du} \quad \text{as } \varepsilon \rightarrow 0,$$

where

$$\widehat{L}_u = \max\left\{0, \max_{0 \leq r \leq u} (-x_0 T^{-1/2} - \widehat{W}_r)\right\}.$$

Both estimators are neither normal nor a mixture of normals. Further, both estimators have the same order of convergence in this case.

(c) Under $\theta < 0$, the MLE $\widehat{\theta}_\varepsilon^{\text{MLE}}$ of θ is strongly consistent. But the TFE $\widehat{\theta}_\varepsilon$ is not strongly consistent. The MLE $\widehat{\theta}_\varepsilon^{\text{MLE}}$ has the limiting distribution

$$\frac{\widehat{\theta}_\varepsilon^{\text{MLE}} - \theta}{\varepsilon^{1/2}} \Rightarrow N\left(0, -\frac{2\theta}{x_0^2 + T}\right) \quad \text{as } \varepsilon \rightarrow 0.$$

Acknowledgements

The authors thank the anonymous referee for their constructive comments and suggestions, which improved the quality of the paper significantly.

Funding information

This work was supported by the National Natural Science Foundation of China (grants 12101004, 62073071, and 12271003), the Natural Science Research Project of Anhui Educational Committee (grants 2023AH030021 and 2023AH010011), and the Research Start-up Foundation for Introducing Talent of Anhui Polytechnic University (grant 2020YQQ064).

Competing interests

There were no competing interests to declare which arose during the preparation or publication process of this article.

References

- [1] ABI-AYAD, I. AND MOURID, T. (2018). Parametric estimation for non recurrent diffusion processes. *Statist. Prob. Lett.* **141**, 96–102.
- [2] BO, L. J., TANG, D., WANG, Y. J. AND YANG, X. W. (2011). On the conditional default probability in a regulated market: a structural approach. *Quant. Finance* **11**, 1695–1702.
- [3] BO, L. J., WANG Y. J. AND YANG, X. W. (2010). Some integral functionals of reflected SDEs and their applications in finance. *Quant. Finance* **11**, 343–348.
- [4] BO, L. J., WANG, Y. J., YANG, X. W. AND ZHANG, G. N. (2011). Maximum likelihood estimation for reflected Ornstein–Uhlenbeck processes. *J. Statist. Planning Infer.* **141**, 588–596.
- [5] DIETZ, H. M. (2001). Asymptotic behaviour of trajectory fitting estimators for certain non-ergodic SDE. *Statist. Infer. Stoch. Process.* **4**, 249–258.
- [6] DIETZ, H. M. AND KUTOYANTS, Y. A. (1997). A class of minimum-distance estimators for diffusion processes with ergodic properties. *Statist. Decisions* **15**, 211–227.
- [7] DIETZ, H. M. AND KUTOYANTS, Y. A. (2003). Parameter estimation for some non-recurrent solutions of SDE. *Statist. Decisions* **21**, 29–45.
- [8] HAN, Z., HU, Y. Z. AND LEE, C. (2016). Optimal pricing barriers in a regulated market using reflected diffusion processes. *Quant. Finance* **16**, 639–647.
- [9] HARRISON, M. (1986). *Brownian Motion and Stochastic Flow Systems*. John Wiley, New York.
- [10] HU, Y. Z., LEE, C., LEE, M. H. AND SONG, J. (2015). Parameter estimation for reflected Ornstein–Uhlenbeck processes with discrete observations. *Statist. Infer. Stoch. Process.* **18**, 279–291.
- [11] JIANG, H. AND XIE, C. (2016). Asymptotic behaviours for the trajectory fitting estimator in Ornstein–Uhlenbeck process with linear drift. *Stochastics* **88**, 336–352.
- [12] JIANG, H. AND YANG, Q. S. (2022). Moderate deviations for drift parameter estimations in reflected Ornstein–Uhlenbeck process. *J. Theoret. Prob.* **35**, 1262–1283.
- [13] KARATZAS, I. AND SHREVE, S. (1991). *Brownian Motion and Stochastic Calculus*. Springer, New York.
- [14] KRUGMAN, P. R. (1991). Target zones and exchange rate dynamics. *Quart. J. Econom.* **106**, 669–682.
- [15] KUTOYANTS, Y. A. (1991). Minimum distance parameter estimation for diffusion type observations. *C. R. Acad. Sci. Paris* **312**, 637–642.
- [16] KUTOYANTS, Y. A. (2004). *Statistical Inference for Ergodic Diffusion Processes*. Springer, Berlin.
- [17] LINETSKY, V. (2005). On the transition densities for reflected diffusions. *Adv. Appl. Prob.* **37**, 435–460.
- [18] LIONS, P. L. AND SZNITMAN, A. S. (1984). Stochastic differential equations with reflecting boundary condition. *Commun. Pure. Appl. Math.* **37**, 511–537.
- [19] RICCIARDI, L. M. AND SACERDOTE, L. (1987). On the probability densities of an Ornstein–Uhlenbeck process with a reflecting boundary. *J. Appl. Prob.* **24**, 355–369.
- [20] WARD, A. R. AND GLYNN, P. W. (2003). A diffusion approximation for a Markovian queue with reneging. *Queueing Systems* **43**, 103–128.
- [21] WARD, A. R. AND GLYNN, P. W. (2005). A diffusion approximation for a GI/GI/1 queue with balking or reneging. *Queueing Systems* **50**, 371–400.
- [22] WHITT, W. (2002). *Stochastic-Process Limits*. Springer, New York.

- [23] ZANG, Q. P. AND ZHANG, L. X. (2016). Parameter estimation for generalized diffusion processes with reflected boundary. *Sci. China Math.* **59**, 1163–1174.
- [24] ZANG, Q. P. AND ZHANG, L. X. (2016). A general lower bound of parameter estimation for reflected Ornstein–Uhlenbeck processes. *J. Appl. Prob.* **53**, 22–32.
- [25] ZANG, Q. P. AND ZHANG, L. X. (2019). Asymptotic behaviour of the trajectory fitting estimator for reflected Ornstein–Uhlenbeck processes. *J. Theoret. Prob.* **32**, 183–201.
- [26] ZANG, Q. P. AND ZHU, C. L. (2016). Asymptotic behaviour of parametric estimation for nonstationary reflected Ornstein–Uhlenbeck processes. *J. Math. Anal. Appl.* **444**, 839–851.
- [27] ZHANG, X. K. AND SHU, H. S. (2023). Maximum likelihood estimation for the reflected stochastic linear system with a large signal. *Brazilian J. Prob. Statist.* **37**, 351–364.