

Hydrodynamic theory of premixed flames propagating in closed vessels: flame speed and Markstein lengths

John K. Bechtold¹, Gautham Krishnan²,[†] and Moshe Matalon²

¹Department of Mathematical Sciences, New Jersey Institute of Technology, Newark, NJ 07102, USA ²Department of Mechanical Science and Engineering, University of Illinois at Urbana-Champaign, Urbana, IL 61801, USA

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A hydrodynamic theory of premixed flame propagation within closed vessels is developed assuming the flame is much thinner than all other fluid dynamic lengths. In this limit, the flame is confined to a surface separating the unburned mixture from burned combustion products, and propagates at a speed determined from the analysis of its internal structure. Unlike freely propagating flames that propagate under nearly isobaric conditions, combustion in a closed vessel results in continuous increases in pressure, burning rate and flame temperature, and a progressive decrease in flame thickness. The flame speed is shown to depend on the voluminal stretch rate, which measures the deformation of a volume element of the flame zone, and on the rate of pressure rise. Both effects are modulated by pressure-dependent Markstein numbers that depend on heat release and mixture properties while capturing the effects of temperature-dependent transport and stoichiometry. The model applies to flames of arbitrary shape propagating in general flows, laminar or turbulent, within vessels of general configurations. The main limitation of hydrodynamic flame theories is the assumption that variations inside the flame zone due to chemistry or turbulence, which could potentially alter its internal structure, are physically unresolved. Nonetheless, the theory, deduced from physical first principles, identifies the various mechanisms involved in the combustion process as demonstrated in detailed discussions of planar flames propagating in rectangular channels and spherically expanding flames in spherical vessels. It also enables the construction of instructive models to numerically simulate the evolution of multi-dimensional and corrugated flames under confinement.

Key words: combustion, flames

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[†] Email address for correspondence: gautham3@illinois.edu

1. Introduction

Significant advances have been achieved in recent years in understanding the structure and motion of freely propagating premixed flames, including the role of intrinsic flame instabilities and flame-turbulence interactions, using a hydrodynamic theory. Following the multi-scale approach proposed by Clavin & Williams (1982), a general theory of multi-dimensional flames in arbitrary flow fields has been derived systematically from the general governing equations by Matalon & Matkowsky (1982, 1983), and generalized by Matalon, Cui & Bechtold (2003) to account for salient physical properties, including temperature-dependent transport, differential and preferential diffusion (i.e. anon-unity and distinct Lewis numbers for the fuel and oxidizer), and effects due to stoichiometry and reaction orders. The main assumption behind this theory is that the flame is thin relative to all other fluid dynamic length scales and can be treated as a surface of density discontinuity when determining the flow field. The instantaneous shape and location of the flame surface, and expressions relating the pressure and velocities across this surface were obtained by asymptotic matching. Of paramount importance is the flame speed-flame stretch relation that has captivated the interest of experimentalists whose raw data from measurements in laboratory configurations was found to correlate well with this prediction. The hydrodynamic theory has been used in analytical and numerical studies to successfully unravel mechanisms of flame instability, their onset and their nonlinear growth. Moreover, since the complexity of the chemistry is captured elegantly by fewer physicochemical parameters, the restriction on numerical time step and mesh size in turbulent flame calculations is alleviated making it an ideal model for fundamental understanding, which is free of turbulence modelling assumptions, empiricism and/or ad hoc adjustable parameters. The approach was successfully implemented in two and three dimensions for planar and spherically expanding turbulent flames (Creta & Matalon 2011; Fogla, Creta & Matalon 2015; Patyal & Matalon 2018; Mohan & Matalon 2021, 2022; Patyal & Matalon 2022), capturing many important morphological features, such as multiply folded and disjoint surfaces, pinching of surface elements and the creation of pockets of unburned gas, all of which are commonly observed in laboratory flames. Additionally, predictions of flame characteristics, including the turbulent flame speed that is arguably one of the most important properties, were found to compare well with empirical correlations suggested in the literature (Fogla, Creta & Matalon 2017).

The objective of this study is the derivation of a hydrodynamic theory of premixed flames propagating in closed vessels. There are significant differences when the flame propagates in an open or closed space. Consider, for example, a flame initiated from a small ignition source at the centre of a spherical vessel containing a combustible mixture. The outwardly propagating flame appears at first smooth and spherical but, after reaching a critical size, it spontaneously turns into a highly cellular structure. For mixtures deficient in their more mobile component (sub-unity Lewis numbers), such as lean hydrogen-air, the critical flame size at the onset of instability is of the order of the flame thickness and the observed instability is thermo-diffusive in nature. In mixtures for which the Lewis number is greater than one, such as rich hydrogen-air, the critical flame size at the onset of instability is of the order of several flame thicknesses. The average cell size of the developing flame is significantly larger, with the flame surface bearing resemblance to that of a soccer ball. Such mixtures are thermo-diffusively stable, and the observed instability is hydrodynamic in nature. It is the well-known Darrieus-Landau instability (Darrieus 1938; Landau 1944) induced by gas expansion that results from the heat released by the chemical reactions (Istratov & Librovich 1969; Bechtold & Matalon 1987; Addabbo, Bechtold & Matalon 2002). The increase in surface area of the corrugated

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flame, further augmented by the continuous creation of cells as the flame grows bigger, results in enhanced fuel consumption and an increased propagation speed. In open space, this development occurs under nearly isobaric conditions; the mean pressure remains virtually constant and equal to the ambient pressure. In a closed vessel, the mean pressure increases in time, the gas is compressed and its temperature rises, leading to higher flame temperatures and a subsequent increase in propagation speed. The self-acceleration of the flame would be significantly affected by combustion instabilities and, in a turbulent environment, by the highly vortical field within which the flame is propagating. The role of intrinsic combustion instabilities and flame-turbulence interactions when the flame is propagating in a confined environment have not been thoroughly investigated. Fundamental understanding of the flame morphology, the dependence of the burning rate on the state of the gas, the onset of instabilities, self-wrinkling and self-acceleration of the flame surface, and the effects of turbulence all have practical implications on the design of engineering devices. It is also important from a safety perspective, to prevent undesirable phenomena such as knocking or the onset of detonations.

Expanding flames in spherical chambers are frequently used in the laboratory to ascertain the laminar flame speeds and Markstein lengths of various fuel mixtures experimentally, owing to a well-defined stretch rate that diminishes as the flame grows bigger. The continuously changing temperature and pressure of the unburned mixture, the unknown effect of pressure buildup and the onset of flame instabilities poses significant challenges in the accuracy of data reduction and limit the range of mixtures that can be studied. Moreover, the measurements are prone to yielding widely different values of burning velocities (Andrews & Bradley 1972). Some investigators addressed these issues by modifying their experimental device to alleviate the rapid changes in pressure and allowing nearly constant-pressure measurements (Tse, Zhu & Law 2000, 2004). Others have limited measurements to the initial stages of flame propagation by assuming a negligible pressure rise and unconfined conditions (Bradley et al. 1998). The accuracy of the burning velocity values determined by the confined flame method compared with those obtained from unconfined conditions were recently examined, noting that a slight pressure rise contributes to an increase in burned gas density and an inward flow of the expanded burned gas (Chen, Burke & Ju 2009; Omari & Tartakovsky 2016), both of which significantly affect the measured data. Fundamental understanding of the fluid dynamical consequences when the flame propagates in a closed vessel, the dependence of the burning rate on pressure buildup and the onset or delay of instabilities and cellularity will contribute greatly to the experimental effort.

Earlier hydrodynamic studies of confined flames, including the original work of Sivashinsky (1979) and the stability analyses of McGreevy & Matalon (1994*a*,*b*), treated the flame as a structureless surface of discontinuity. The present work is the first asymptotic theory that resolves the structure of the thin but finite flame zone, and captures the effect of pressure rise, flow conditions and mixture properties on the flame speed; it follows a previous exploration by Bechtold & Matalon (2000) that sowed the seeds of this paper. The analysis shows that the flame speed of confined flames is modified not only by flame stretch, representing the distortion of an element of the flame surface, but also by variations of the flame thickness that combine to describe the deformation of a volume element of the flame zone, or the voluminal stretch. This concept, first introduced by Buckmaster (1979) in the context of slowly varying flames, has not been apparent in the hydrodynamic theory of freely propagating flames owing to the assumption of a constant flame thickness. Elements of this idea, referred to as mass-based flame stretch, were exploited by de-Goey and co-workers (van Oijen *et al.* 2016) in their numerical simulations. In addition to

the voluminal stretch, the flame speed is shown to be also modified by the rate of pressure increase. The two ingredients, voluminal stretch and pressure rise, arising from physicochemical influences associated with the internal flame structure, are modulated when cast in dimensional form by two pressure-dependent Markstein lengths of the order of the flame thickness. Since the increase in burning rate as the pressure rises causes the flame to become thinner, their effects diminish during combustion and become negligible in the latter stages of propagation. While this assertion has been phenomenologically recognized, it is the first time that it has been quantified in a detailed analysis.

Flame stretch is an asymptotic concept that is unambiguously defined when the flame is confined to a surface. It measures the distortion of the flame that results from its motion and from the fluid velocity gradient it experiences, and can be expressed in terms of properties of the flame surface, such as curvature and propagation speed, and of the underlying velocity field (Matalon 1983). For freely propagating flames, it may be also expressed as a combination of the curvature of the flame front and the hydrodynamic strain it experiences. This representation is particularly convenient in general computational studies because the strain rate is implemented in most fluid dynamical codes. However, it requires specifying an isosurface within the flame zone that represents the flame front, and accommodating for the velocity divergence that, although it vanishes on either side of the flame, is not zero within the numerically resolved flame zone due to gas expansion (Giannakopoulos et al. 2015). It is shown that under confinement, flame stretch is not a simple combination of the surface curvature and hydrodynamic strain, because the velocity divergence is not zero even outside the flame zone owing to adiabatic compression. Even in the hydrodynamic limit, when the flame is confined to a surface, the contribution of the velocity divergence at the flame front is essential to balance the local strain rate and properly evaluate the stretch rate.

In the freely propagating flame theory, the chemical activity is confined to a thin layer embedded within the flame zone and centred near the location where the temperature reaches its maximum value – the adiabatic flame temperature. For a given mixture, the adiabatic flame temperature is a constant that depends on the total heat release. In a closed vessel the flame temperature exceeds the adiabatic value and varies in time as a consequence of pressure rise. Moreover, the temperature in the burned gas continues to increase due to adiabatic compression. These conditions preclude the use of the standard activation energy asymptotic approximation, which has greatly facilitated analyses of combustion problems by confining the chemical activity to a reaction sheet. The temporal change of flame temperature requires readjusting the reaction zone thickness from one time to the next, while the continual increase in temperature in the burned gas prevents expressing the jump in temperature gradient across the reaction sheet in closed form. Consequently, we employ a delta-function model that has been used in the literature when encountering similar technical difficulties (Matkowsky & Sivashinsky 1978; Buckmaster & Ludford 1983; Margolis & Matkowsky 1983). In this approach, the reaction rate takes the form of a Dirac delta function with a strength expressed as an Arrhenius form of the instantaneous flame temperature. The jump conditions across the reaction sheet are then determined by direct integration of the governing equations. We demonstrate that a formal asymptotic approach can be carried out by adopting the Newtonian approximation (Van Dyke 1954; Cole 1957), whereby the ratio of specific heats is assumed near unity. In this limit the flame temperature is near its adiabatic value, delaying the aforementioned difficulties to higher orders. The restriction placed on the ratio of specific heats leads to a description of flame propagation that is not as rich as the more general case, but provides justification for the delta-function model employed without this limitation.

2. Governing equations

A homogeneous combustible mixture consisting of two reactants, both appearing in small quantities relative to an abundant inert gas, resides in a closed vessel. The mass fraction of the deficient and excess reactants in the mixture are Y_{D_0} and Y_{E_0} , respectively, with the index i = D, E representing the deficient/excess reactant and the subscript 0 identifying conditions of the given initial mixture. In a lean mixture, the fuel is the deficient component, while in a rich mixture the deficient component is the oxidizer. Upon ignition, a flame separating the fresh mixture from the burned products propagates throughout the vessel. The chemical activity is modelled by a single overall step:

$$\nu_D \mathcal{C}_D + \nu_E \mathcal{C}_E \to \text{Products.}$$
 (2.1)

Here C_i represents the chemical symbol and v_i the stoichiometric coefficient of species *i*. The reaction rate is given by

$$\tilde{\omega} = \mathcal{B}\left(\frac{\tilde{\rho}Y_D}{W_D}\right) \left(\frac{\tilde{\rho}Y_E}{W_E}\right) \exp(-E/\mathcal{R}\tilde{T}),$$
(2.2)

where $\tilde{\rho}$ is the density and \tilde{T} the temperature of the mixture, Y_i and W_i are the mass fraction and molecular weight of species *i*, *E* is the overall activation energy, \mathcal{R} is the gas constant and \mathcal{B} a pre-exponential factor. To allow for mixture compositions ranging from lean to rich conditions, we introduce the excess-to-deficient reactant mass ratio

$$\Phi = \frac{Y_{E_0}/\nu_E W_E}{Y_{D_0}/\nu_D W_D} = \frac{Y_{E_0}}{\nu Y_{D_0}},$$
(2.3)

where $v = v_E W_E / v_D W_D$ is the mass-weighted stoichiometric coefficient ratio. As defined, Φ is always larger than one, with $\Phi = 1$ corresponding to a stoichiometric mixture. Hence, Φ is equal to the equivalence ratio for fuel-rich mixtures and to the reciprocal of the equivalence ratio for fuel-lean mixtures.

Deflagrative combustion phenomena are highly subsonic and a low-Mach-number approximation may be employed for their description; the characteristic Mach number Ma is defined as the ratio of the laminar flame speed to the speed of sound in the initial fresh mixture. For $Ma \ll 1$, the pressure in the vessel is rapidly equalized such that spatial variations remain relatively small. The pressure may then be decomposed into the mean pressure $\tilde{P} = \tilde{P}(t)$ and small fluctuations of $O(Ma^2)$ that balance the small changes in momentum. The temporal variations of the mean pressure $\tilde{P}(t)$ are determined by integrating the energy equation throughout the entire domain, after neglecting the small viscous dissipation term. For impermeable walls, and in the absence of heat losses, one finds that

$$\frac{1}{P_0}\frac{\mathrm{d}\tilde{P}}{\mathrm{d}t} = \frac{Q}{c_v T_0}\frac{1}{\tilde{\mathbb{V}}}\int\frac{\tilde{\omega}}{\rho_0}\mathrm{d}V,\qquad(2.4)$$

where t is the time variable, P_0 , ρ_0 , T_0 the pressure, density and temperature of the fresh unburned mixture, Q the total heat release, c_v the specific heat at constant volume (assumed constant) and $\tilde{\mathbb{V}}$ the volume of the vessel. A consequence of this quasi-isobaric approximation is the simplification of the equation of state to

$$\tilde{\rho}\mathcal{R}\tilde{T}/\bar{W} = \tilde{P}(t), \qquad (2.5)$$

where \overline{W} is the mean molecular weight of the mixture (assumed constant).

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The equations governing the combustion process consist of the Navier–Stokes equations supplemented by mass balance equations for the two reactants and an energy equation for the mixture. To express these equations in dimensionless form, the hydrodynamic length scale *l* is used as a unit length, the laminar flame speed S_L as a unit speed and the ratio l/S_L as a unit of time. The hydrodynamic length characterizes the lateral size of the flame or the average wavelength of corrugations evolving on its surface. Diffusion processes introduce an additional length scale $l_d = D_{th}/S_L$, where $D_{th} = \lambda_0/\rho_0 c_p$ is the thermal diffusivity of the initial fresh mixture with λ_0 the thermal conductivity and c_p the specific heat at constant pressure (assumed constant). The ratio of the diffusion-to-hydrodynamic length scales, $\delta \equiv l_d/l$, is a representative measure of the flame thickness. Pressure, density and temperature are scaled with respect to their values in the initial fresh mixture P_0 , ρ_0 , T_0 . The transport coefficients, including the viscosity $\tilde{\mu}$ and thermal conductivity $\tilde{\lambda}$ of the mixture, and the diffusion coefficients $\tilde{\rho}D_i$ where D_i is the molecular diffusivity of species *i* (into the inert gas), depend on temperature. Scaled by their values in the initial fresh mixture, the dimensionless coefficients

$$\tilde{\mu}/\mu_0 = \tilde{\rho}\mathcal{D}_i/(\rho\mathcal{D}_i)_0 = \lambda/\lambda_0 \tag{2.6}$$

are assumed to have the same temperature dependence such that their ratios, consisting of the Prandtl $Pr \equiv \tilde{\mu}c_p/\tilde{\lambda}$ and Lewis $Le_i \equiv \tilde{\lambda}/\tilde{\rho}\mathcal{D}_i c_p$ numbers, remain constant. The common transport coefficient (in dimensionless form) takes the form $\lambda(T) = T^a$, with $1/2 \le a \le 1$. The laminar flame speed for a two-reactant model obeying (2.2) in the large activation energy limit (Bechtold & Matalon 1999), is given by

$$S_L = \sqrt{4\left(\frac{\tilde{\rho}_a}{\rho_0}\right)^2 \frac{\tilde{\lambda}_a}{\lambda_0} \frac{\mathcal{D}_{th}(1+\beta(\Phi-1)/2Le_E)}{\beta^3 v_E^{-1} v_D^{-1} Le_E^{-1} Le_D^{-1}} \frac{\rho_0 Y_{D_0} \mathcal{B}}{v_D W_D} \exp(-E/2\mathcal{R}\tilde{T}_a), \qquad (2.7)$$

where

$$\beta = \frac{E(\tilde{T}_a - T_0)}{\mathcal{R}\tilde{T}_a^2}, \quad \tilde{T}_a = T_0 + \frac{(Q/c_p)Y_{D_0}}{\nu_D W_D}$$
(2.8*a*,*b*)

are, respectively, the Zel'dovich number and adiabatic flame temperature. The subscript a stands for values evaluated at the adiabatic temperature, namely $\tilde{\lambda}_a = \tilde{\lambda}(\tilde{T}_a)$ and $\tilde{\rho}_a/\rho_0 = T_0/\tilde{T}_a$. Below, only when the same symbols are used for both dimensional and dimensionless variables, the dimensional quantities are distinguished by a 'tilde' accent.

In dimensionless form, the governing equations are

$$\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \nabla \cdot \boldsymbol{v} = 0, \qquad (2.9)$$

$$\rho \frac{\mathrm{D}\boldsymbol{v}}{\mathrm{D}t} = -\nabla p + \delta \operatorname{Pr} \nabla \cdot \lambda \boldsymbol{\Sigma}, \qquad (2.10)$$

$$\rho \frac{\mathrm{D}T}{\mathrm{D}t} - \delta \nabla \cdot (\lambda \nabla T) = \frac{\gamma - 1}{\gamma} \frac{\mathrm{d}P}{\mathrm{d}t} + q\omega, \qquad (2.11)$$

$$\rho \frac{\mathrm{D}Y_D}{\mathrm{D}t} - \delta L e_D^{-1} \nabla \cdot (\lambda \nabla Y_D) = -Y_{D_0} \omega, \qquad (2.12)$$

$$\rho \frac{\mathrm{D}Y_E}{\mathrm{D}t} - \delta L e_E^{-1} \nabla \cdot (\lambda \nabla Y_E) = -\nu Y_{D_0} \omega, \qquad (2.13)$$

$$\rho T = P, \tag{2.14}$$

where $D/Dt \equiv \partial/\partial t + v \cdot \nabla$ is the convective derivative, v is the gas velocity, Σ is the viscous stress tensor given by

$$\boldsymbol{\Sigma} = 2\boldsymbol{E} - \frac{2}{3} (\boldsymbol{\nabla} \cdot \boldsymbol{v}) \boldsymbol{I}, \quad \boldsymbol{E} = \frac{1}{2} ((\boldsymbol{\nabla} \boldsymbol{v}) + (\boldsymbol{\nabla} \boldsymbol{v})^{\mathrm{T}}), \quad (2.15a,b)$$

with E and I the strain rate and unit tensors (the superscript T denoting the transpose) and

$$\omega = \mathbb{D}\delta^{-1}\rho^2 Y_D Y_E \exp(\beta_0/T_a - \beta_0/T)$$
(2.16)

the reaction rate. Consistent with the low-Mach-number approximation, the pressure has been expressed as $P(t) + \gamma Ma^2 p(x, t)$, where P is the spatially uniform (or mean) pressure in the vessel and p is the dynamic pressure. In view of (2.4), the overall or mean pressure is obtained from

$$\frac{\mathrm{d}P}{\mathrm{d}t} = \frac{\gamma q}{\mathbb{V}} \int \omega \,\mathrm{d}V,\tag{2.17}$$

where the integration is performed over the entire volume \mathbb{V} expressed in units of the hydrodynamic length *l*. In addition to the Prandtl number Pr and Lewis number Le_D , Le_E , the parameters appearing in these equations are: the ratio of specific heats $\gamma = c_p/c_v$, the heat release parameter $q = (QY_{D_0}/v_DW_D)/c_pT_0$ that represents the ratio of the total heat released per unit mass of the deficient reactant to the enthalpy of the initial mixture, the adiabatic flame temperature $T_a = 1 + q$ and the activation energy parameter $\beta_0 = E/\mathcal{R}T_0$ related to the Zel'dovich number β via $\beta_0 = (T_a^2/q)\beta$. The Damköhler number \mathbb{D} , representing the ratio of the flow to the chemical reaction times, is given by

$$\mathbb{D} = \frac{\mathcal{D}_{th}/S_L^2}{(\tilde{\mathcal{B}}\exp(-E/\tilde{\mathcal{R}}\tilde{T}_a))^{-1}}, \quad \tilde{\mathcal{B}} = \frac{\rho_0}{W_D W_E} \frac{\nu_D W_D}{Y_{D_0}} \mathcal{B}, \quad (2.18a,b)$$

where \hat{B} is the scaled pre-exponential factor (in units of s⁻¹). When substituting for the laminar flame speed (2.7), the Damköhler number simplifies to

$$\mathbb{D} = \frac{1}{4} \left(\frac{\rho_0}{\tilde{\rho}_a}\right)^2 \frac{\lambda_0}{\tilde{\lambda}_a} \frac{Le_E^{-1}Le_D^{-1}\beta^3}{(1+\beta(\Phi-1)/2Le_E)} \frac{\Phi}{Y_{D_0}Y_{E_0}}.$$
(2.19)

For a stoichiometric mixture, $\Phi = 1$, the Damköhler number depends on the Lewis numbers of both reactants, while for a mixture remote from stoichiometry, it depends primarily on the Lewis number of the deficient reactant.

An expression for the end pressure $P = P_e$, defined as the mean pressure in the vessel at time $t = t_e$, namely the time when the flame has consumed all the available reactant, can be obtained by integrating the combined energy and appropriate species equations

$$\frac{\partial}{\partial t} \left(\rho \left(\frac{qY_D}{Y_{D_0}} + T \right) \right) + \nabla \cdot \left(\rho v \left(\frac{qY_D}{Y_{D_0}} + T \right) \right) - \delta \nabla \cdot \left(\lambda \nabla \left(\frac{qY_D}{Y_{D_0}} L e_D^{-1} + T \right) \right)$$
$$= \frac{\gamma - 1}{\gamma} \frac{\mathrm{d}P}{\mathrm{d}t} \tag{2.20}$$

over the entire volume. For impermeable and rigid walls, and in the absence of heat losses, it simplifies to

$$\frac{\mathrm{d}}{\mathrm{d}t} \int \left[\rho \left(\frac{qY_D}{Y_{D_0}} + T \right) \right] \mathrm{d}V = \frac{\gamma - 1}{\gamma} \frac{\mathrm{d}P}{\mathrm{d}t} \int \mathrm{d}V, \qquad (2.21)$$

which can be integrated in time from t = 0 to $t = t_e$, to give $P_e = 1 + \gamma q$. If combustion was to occur uniformly throughout the vessel as in a stirred reactor, such that $\rho = 1$, the

final temperature would be the constant-volume adiabatic temperature $1 + \gamma q$. However, owing to the fluid dynamics associated with the flame propagation, neither the density nor the temperature remain spatially uniform. It should be noted that in determining P_e we have assumed that a flame already exists at t = 0. In other words, the theory does not describe the short ignition event that is expected to have a minor effect on the end pressure level.

The governing equations (2.9)–(2.17) will be analysed using a multi-scale approach that exploits the disparity in length scales associated with the fluid dynamics, diffusion and chemical reactions. The flame zone consisting of the region where diffusion and chemical reactions occur may be treated as an internal layer of $O(\delta)$, with $\delta \ll 1$, that separates the unburned gas from the burned products. Consequently, the governing equations in the hydrodynamic regions on either side of the flame zone are greatly simplified, but they remain dependent on the instantaneous shape and location of the flame surface, or equivalently, on the flame propagation speed. The latter, which is the focus of the subsequent analysis, depends on the diffusion and chemical processes occurring inside the flame zone, on the pressure buildup and on the interaction of the flame with the local flow conditions.

In the following sections we start by examining the simplifications that result in the hydrodynamic zones. We then analyse the physicochemical processes occurring in the thin but finite flame zone and derive explicit expressions for the flame speed and overall pressure rise. Following a general discussion of the results, applicable to general time-dependent multi-dimensional flames in vessels of arbitrary geometry, we provide a complete description of planar and spherical flames. We conclude with general comments about and future applications of the derived hydrodynamic theory.

3. The hydrodynamic zones

In the limit $\delta \to 0$, the flame zone shrinks to a surface described by $\psi(x, t) = 0$ and referred to as the flame front. It separates the unburned gas in the region $\psi(x, t) < 0$ from the burned products in the region $\psi(x, t) > 0$, and is characterized by the geometric factors

$$\boldsymbol{n} = \frac{\nabla \psi}{|\nabla \psi|}, \quad V_f = -\frac{1}{|\nabla \psi|} \frac{\partial \psi}{\partial t}, \quad (3.1a,b)$$

defined to represent the unit normal pointing towards the burned gas region and the propagation speed (in the laboratory frame) of the flame surface back along its normal. The determination of the instantaneous shape and location of the flame front and/or the propagation speed depend on the diffusion and reaction processes occurring inside the flame zone, as discussed in the next section.

To leading order in δ , diffusion and chemical reactions are negligible on either side of the flame front, i.e. $\psi(x, t) \leq 0$, and the governing equations reduce to

$$\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \nabla \cdot \boldsymbol{v} = 0, \qquad (3.2)$$

$$\rho \frac{\mathrm{D}\boldsymbol{v}}{\mathrm{D}t} = -\boldsymbol{\nabla}p,\tag{3.3}$$

$$\rho \frac{\mathrm{D}Y_D}{\mathrm{D}t} = 0, \quad \rho \frac{\mathrm{D}Y_E}{\mathrm{D}t} = 0, \tag{3.4a,b}$$

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$$\rho \frac{\mathrm{D}T}{\mathrm{D}t} = \frac{\gamma - 1}{\gamma} \frac{\mathrm{d}P}{\mathrm{d}t},\tag{3.5}$$

$$\rho T = P. \tag{3.6}$$

The combination of the continuity (3.2) and energy (3.5) equations implies that the volume dilatation rate is

$$\nabla \cdot \boldsymbol{v} = -\frac{1}{\gamma P} \frac{\mathrm{d}P}{\mathrm{d}t}; \qquad (3.7)$$

namely, fluid elements on either side of the flame are progressively compressed. Integrating (2.9)–(2.13) across the flame zone and taking the limit $\delta \rightarrow 0$ yield the Rankine–Hugoniot (RH) jump conditions

$$\llbracket \rho(\boldsymbol{v} \cdot \boldsymbol{n} - V_f) \rrbracket = 0, \tag{3.8}$$

$$\llbracket \boldsymbol{n} \times (\boldsymbol{v} \times \boldsymbol{n}) \rrbracket = 0 \quad \llbracket \boldsymbol{p} + \rho (\boldsymbol{v} \cdot \boldsymbol{n} - V_f) (\boldsymbol{v} \cdot \boldsymbol{n}) \rrbracket = 0, \tag{3.9}$$

$$[[Y_E - \nu Y_D]] = 0 \quad [[T + qY_D/Y_{D_0}]] = 0, \tag{3.10}$$

where the bracket [[]] denotes the jump across the flame front, i.e. $[[\Theta]] = \Theta|_{\psi=0^+} - \Theta|_{\psi=0^-}$. Comments regarding the $O(\delta)$ corrections will be discussed below, following the flame zone analysis.

Given that the fresh mixture in the vessel is initially homogeneous, and assuming that the deficient reactant is completely consumed in the flame zone, (3.4a,b) yield

$$Y_D = \begin{cases} Y_{D_0}, & Y_E = \begin{cases} v Y_{D_0} \Phi, & \psi(\mathbf{x}, t) < 0, \\ v Y_{D_0}(\Phi - 1), & \psi(\mathbf{x}, t) > 0. \end{cases}$$
(3.11)

The energy equation (3.5), when combined with the equation of state (3.6), shows that the function

$$\mathcal{E} = \frac{T}{P^{(\gamma-1)/\gamma}} = \frac{P^{1/\gamma}}{\rho},\tag{3.12}$$

referred to as the entropy function (the entropy of the gas is proportional to $\ln \mathcal{E}$), satisfies

$$\frac{\mathrm{D}\mathcal{E}}{\mathrm{D}t} = 0, \quad \text{subject to } [\![\mathcal{E}]\!] = \frac{q}{P^{(\gamma-1)/\gamma}}. \tag{3.13}$$

Since the state of the fresh gas is initially uniform and the entropy ahead of the flame is conserved along particle paths, $\mathcal{E} = 1$ in the unburned gas region. In the burned gas region $\mathcal{E} = \mathcal{E}(\mathbf{x}, t)$ is determined by solving (3.13). As a consequence,

$$\rho = \begin{cases} P^{1/\gamma}, & T = \begin{cases} P^{(\gamma-1)/\gamma}, & \psi(\mathbf{x},t) < 0, \\ P^{1/\gamma}/\mathcal{E}(\mathbf{x},t), & P^{(\gamma-1)/\gamma}\mathcal{E}(\mathbf{x},t), & \psi(\mathbf{x},t) > 0. \end{cases}$$
(3.14)

The temperature and density of the unburned gas remain spatially uniform, but their values increase in time because of gas compression, a conclusion that remains true to all orders in δ . By contrast, the temporally varying temperature and density at the moving front,

$$T_b = T_a + P^{(\gamma - 1)/\gamma} - 1, \quad \rho_b = P/T_b,$$
 (3.15*a*,*b*)

are advected with the flow downstream such that the burned gas is no longer spatially uniform. Here and below, subscripts b and u will be used to denote conditions on the burned/unburned side of the flame front; i.e. at $\psi = 0^{\pm}$, respectively. The flame temperature T_f , defined as the temperature at $\psi = 0^{\pm}$, is given to leading order by T_b and is seen to exceed the adiabatic flame temperature T_a as a result of adiabatic compression. On the other hand, the extent of gas expansion across the flame,

$$T_b/T_u = \rho_u/\rho_b = 1 + qP^{-(\gamma - 1)/\gamma} = \mathcal{E}_b,$$
 (3.16)

diminishes as the pressure rises.

To complete the formulation, an equation describing the evolution of the flame surface $\psi(x, t) = 0$ or, equivalently, the propagation speed V_f , must be derived. It is customary to use instead of the propagation speed, the flame speed, which is defined as the propagation speed relative to the flow of fresh mixture, namely

$$S_f \equiv \boldsymbol{v}^* \cdot \boldsymbol{n} - V_f, \qquad (3.17)$$

where the * denotes conditions at $\psi = 0^-$. The local mass burning rate

$$m^* \equiv \rho_u(\boldsymbol{v}^* \cdot \boldsymbol{n} - V_f) = \rho_u S_f \tag{3.18}$$

refers to the normal mass flux at the cold edge of the flame zone as viewed from an observer moving with the flame front. The flame speed, burning rate and mean pressure rise depend on the physicochemical processes occurring inside the flame zone, as discussed next.

4. The flame zone

It is convenient in the following analysis to introduce a curvilinear coordinate system attached to the flame front, as shown in figure 1. The flame front is parametrized by the surface coordinates (ξ_1, ξ_2) aligned with the principal directions of curvature at each point of the surface, and e_1, e_2 denote unit vectors tangential to the parametric curves $\xi_2 = \text{const.}$ and $\xi_1 = \text{const.}$, respectively. The three vectors e_1, e_2, n , with $n = e_1 \times e_2$, form an orthogonal triad of unit vectors and (ξ_1, ξ_2, n) may be taken as the coordinates of an arbitrary point P in space at time t. The vector position r of the point P with respect to the fixed rectangular coordinate system may be expressed in terms of the distance n from the flame front and the position vector r_f of the projection of P on the surface, namely

$$\mathbf{r}(x_1, x_2, x_3, t) = \mathbf{r}_f(\xi_1, \xi_2, t) + n\mathbf{n}(\xi_1, \xi_2, t),$$
(4.1)

which serves as the transformation from the rectangular to the moving intrinsic surface coordinate system. The unit vectors e_1 and e_2 are given by

$$\boldsymbol{e}_1 = \frac{1}{a_1} \frac{\partial \boldsymbol{r}_f}{\partial \xi_1}, \quad \boldsymbol{e}_2 = \frac{1}{a_2} \frac{\partial \boldsymbol{r}_f}{\partial \xi_2}, \tag{4.2a,b}$$

where $a_i = |\partial \mathbf{r}_f / \partial \xi_i|$. The gas velocity may be decomposed as $\mathbf{v} = \mathbf{v}_\perp + v_n \mathbf{n}$, where v_n is the velocity component oriented normal to the flame surface and $\mathbf{v}_\perp = v_1 \mathbf{e}_1 + v_2 \mathbf{e}_2$. Consequently, $m \equiv \rho(v_n - V_f)$ is the normal mass flux. Computation of the vector differential operators involve the scale factors

$$l_1 = a_1(1 - n\kappa_1), \quad l_2 = a_2(1 - n\kappa_2), \quad l_3 = 1,$$
 (4.3*a*-*c*)

where κ_1 and κ_2 are the principal curvatures in the ξ_1 and ξ_2 directions, respectively. The sum $\kappa = \kappa_1 + \kappa_2$ is referred below as the curvature of the flame surface. The gradient





Figure 1. The intrinsic curvilinear coordinates (ξ_1, ξ_2, n) to the flame surface. The blue and magenta vectors correspond to the normal component of the gas velocity $v_n n$ and normal propagation velocity $-V_f n$, respectively.

operator then takes the form

$$\nabla = \mathbf{n}\frac{\partial}{\partial n} + \nabla_s, \quad \nabla_s = \mathbf{e}_1 \frac{1}{l_1} \frac{\partial}{\partial \xi_1} + \mathbf{e}_2 \frac{1}{l_2} \frac{\partial}{\partial \xi_2}, \quad (4.4a,b)$$

where ∇_s is its surface component. The divergence of a vector **b**, with components (b_1, b_2, b_3) in the directions e_1, e_2 and **n** respectively, is given by

$$\nabla \cdot \boldsymbol{b} = \frac{1}{l_1 l_2} \left\{ \frac{\partial (l_2 b_1)}{\partial \xi_1} + \frac{\partial (l_1 b_2)}{\partial \xi_2} + \frac{\partial (l_1 l_2 b_3)}{\partial n} \right\},\tag{4.5}$$

and the Laplacian of a scalar φ is

$$\nabla^2 \varphi = \frac{1}{l_1 l_2} \left\{ \frac{\partial}{\partial \xi_1} \left(\frac{l_2}{l_1} \frac{\partial \varphi}{\partial \xi_1} \right) + \frac{\partial}{\partial \xi_2} \left(\frac{l_1}{l_2} \frac{\partial \varphi}{\partial \xi_2} \right) + \frac{\partial}{\partial n} \left(l_1 l_2 \frac{\partial \varphi}{\partial n} \right) \right\}.$$
 (4.6)

Transforming the governing equations also requires expressing time derivatives in the moving frame, using

$$\frac{\partial}{\partial t} \mapsto \frac{\partial}{\partial t} + \dot{\boldsymbol{\xi}} \cdot \boldsymbol{\nabla}_s - V_f \frac{\partial}{\partial n}, \qquad (4.7)$$

with $\dot{\xi} = l_1 \dot{\xi}_1 e_1 + l_2 \dot{\xi}_2 e_2$, where the 'dot' corresponds to differentiation with respect to time, and $V_f = -\partial n/\partial t$. We will avoid writing the general equations in the moving curvilinear system and express only the relevant terms at each stage of the analysis. Further details can be found in Matalon *et al.* (2003, appendix B).

To examine the internal structure of the flame zone, centred near the surface along which n = 0, we introduce the stretched conductivity-weighted coordinate

$$\eta = \int_0^{n/\delta} \frac{1}{\lambda} \mathrm{d}n' \tag{4.8}$$

with $\delta \ll 1$, and seek solutions that match those in the hydrodynamic zones as $\eta \to \pm \infty$. Although it is straightforward to simplify the governing equations in the flame zone using this transformation, they remain intractable analytically due to the highly nonlinear reaction rate term. A common simplification that has paved the way to most of the theoretical advances in combustion is the activation energy asymptotic approximation. The activation energy of chemical reactions occurring in combustion systems is typically large compared with the thermal energy of the fresh mixture, such that $\beta_0 \gg 1$ or, equivalently, the Zel'dovich number $\beta = q\beta_0/T_a^2 \gg 1$ (in the following analysis it is more convenient to use β_0). As a result, the chemical activity is confined to a thin layer embedded within the flame zone and centred about the location where the temperature is near its maximum value – the flame temperature T_f . In the limit $\beta_0 \to \infty$, the reaction rate ω takes the form of a Dirac delta function of strength ~ exp $(-\beta_0/T_f)$; i.e. an Arrhenius form of temperature T_f . This approximation has been implemented in one of two ways: as a formal asymptotic approach, in which the solution is expressed in terms of gauge functions that depend on β_0 , or as a model – the delta-function model with β_0 treated as a finite parameter (Matkowsky & Sivashinsky 1978; Buckmaster & Ludford 1983; Margolis & Matkowsky 1983). The latter, which captures the essence of activation energy asymptotics, was used primarily when encountering technical difficulties that prevented the use of a formal approach.

A systematic asymptotic approach was used to describe the dynamics of freely propagating flames (Matalon & Matkowsky 1982; Matalon *et al.* 2003). In this case, the flame temperature is constant and equal to T_a and the reaction zone spans the region where $T - T_a = O(1/\beta_0)$ such that $\omega = O(1)$. The reaction rate (2.16) is exponentially small, and hence, negligible in the preheat zone where $T < T_a$, and vanishes identically in the post-reaction zone where the deficient reactant or both reactants for a stoichiometric mixture are completely consumed. The solution in the reaction zone that constitutes a balance between the diffusion and chemical reaction rates provides, through asymptotic matching, jump conditions across the reaction sheet that can be used to facilitate the determination of the solution in the flame zone. The analysis also requires adopting a near-equidiffusion formulation (Buckmaster & Ludford 1982), whereby $Le_i^{-1} = 1 - le_i/\beta_0$, and a near-stoichiometric mixture limit (Bechtold & Matalon 1999) where $Y_{E_0} - \nu Y_{D_0} = O(1/\beta_0)$, such that $\Phi = 1 + \varphi/\beta_0$ with $\varphi = O(1)$ representing the deviation from stoichiometry.

When propagating in a closed vessel, the flame temperature T_f varies in time and exceeds the adiabatic flame temperature T_a . The reaction rate may then be expressed in the form

$$\omega = \mathbb{D}\delta^{-1}\rho^2 Y_D Y_E \exp(\beta_0/T_a - \beta_0/T_f) \exp(\beta_0/T_f - \beta_0/T), \qquad (4.9)$$

ensuring that the chemical reaction remains confined to a thin layer where $T - T_f = O(1/\beta_0)$. Retaining a reaction-diffusion balance inside the thin reaction layer, however, requires rescaling the equations from one time to the next by readjusting the reaction zone thickness with an exponentially small scale that balances the factor $\exp(\beta_0/T_a - \beta_0/T_f)$. This constitutes a technical difficulty that prevents the use of a formal asymptotic approach. A resolution can be obtained if one adopts a Newtonian approximation (Van Dyke 1954; Cole 1957), whereby $(\gamma - 1)/\gamma$ is treated as a small parameter. In this limit, $T_f \sim T_a$ and the factor $\exp(\beta_0/T_a - \beta_0/T_f)$ remains, to leading order, an O(1) quantity. This approach is implemented in § 7. Although the Newtonian approximation accounts for gas compression, the increase in density translates entirely into a pressure rise, with the temperature minimally affected. To allow for gas compression to modify both the temperature and pressure, as anticipated physically, and circumvent the aforementioned difficulty, we use instead the delta-function approach.

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Flames in closed vessels

The reaction rate in the governing equations is now replaced by the Dirac delta function of strength $\sim \exp(-\beta_0/T_f)$, and β_0 is subsequently treated as a finite parameter. The chemical reaction is now confined to a surface located, without loss of generality, at $\eta = 0$. For consistency with earlier studies, we retain the near-equidiffusion and near-stoichiometric assumptions and use the same scaling for the temperature–mass fraction coupling functions, namely

$$T + qY_D/Y_{D_0} = H + \beta_0^{-1}h_D + \cdots,$$

$$T + qY_E/\nu Y_{D_0} = H + \beta_0^{-1}(h_E + q\varphi) + \cdots,$$
(4.10)

where the enthalpy functions satisfy

$$\rho \frac{\mathrm{D}H}{\mathrm{D}t} - \delta \nabla \cdot (\lambda \nabla H) = \frac{\gamma - 1}{\gamma} \frac{\mathrm{d}P}{\mathrm{d}t},$$

$$\rho \frac{\mathrm{D}h_i}{\mathrm{D}t} - \delta \nabla \cdot (\lambda \nabla h_i) = -\delta le_i \nabla \cdot (\lambda \nabla (H - T)).$$
(4.11)

The enthalpy perturbations h_D and h_E may then be used as the dependent variables replacing the mass fractions. Since the deficient reactant is depleted by the chemical reaction,

$$Y_D = 0, \quad T = H + \frac{1}{\beta_0} h_D, \quad Y_E = \frac{\nu Y_{D_0}}{q\beta_0} (h_E + q\varphi - h_D)$$
 (4.12*a*-*c*)

in the burned gas region ($\eta \ge 0$). At the reaction sheet ($\eta = 0$),

$$T_f = H|_{\eta=0} + \frac{1}{\beta_0} h_D^*, \quad Y_E|_{\eta=0} = \frac{\nu Y_{D_0}}{q\beta_0} (h_E^* + q\varphi - h_D^*), \tag{4.13a,b}$$

representing, respectively, the flame temperature and the mass of unconsumed reactant leaking through the reaction sheet. A direct integration of the governing equations across $\eta = 0$ yields the following jump relations:

$$[\rho] = [T] = [H] = [h_i] = [v] = 0,$$

$$[p] = \frac{4}{3} \Pr\left[\lambda \frac{\partial v_n}{\partial \eta}\right], \quad \left[\frac{\partial v_{\perp}}{\partial \eta}\right] = 0,$$

$$\left[\frac{\partial H}{\partial \eta}\right] = 0, \quad \left[\frac{\partial h_i}{\partial \eta}\right] = -le_i \left[\frac{\partial T}{\partial \eta}\right],$$
(4.14)

$$\left[\frac{\partial T}{\partial \eta}\right] = -qP\left(\frac{T_f}{T_a}\right)^2 \sqrt{\frac{\lambda_b}{\lambda_a}} \sqrt{\frac{1 + (h_E^* - h_D^* + q\varphi)/2T_f^2}{1 + q\varphi/2T_a^2}} \exp\left(\frac{\beta_0}{2T_a} - \frac{\beta_0}{2T_f}\right).$$
(4.15)

Here $\lambda_b = \lambda(T_b)$ and the bracket [] denotes the jump, i.e. $[\Theta] = \Theta|_{\eta=0^+} - \Theta|_{\eta=0^-}$. To avoid confusion, we note the distinction between the single brackets [] used here to represent the jump across the reaction zone from the double brackets [[]] used earlier that represent the jump across the entire flame zone. The relations (4.14)–(4.15) constitute an obvious generalization of those derived systematically in the Newtonian limit (§ 7), and reduce to the corresponding relations for freely propagation flames (Matalon *et al.* 2003) when P = 1. Although the jump in temperature gradient includes the factor $\exp(\beta_0/2T_a - \beta_0/2T_f)$, which is exponentially large when β_0 is formally treated as a

large parameter, this factor is quite moderate, approximately 1–2 for practical values of the physical parameters.

To describe the combustion field in the flame zone $(-\infty < \eta < \infty)$, all variables are expanded in power series of δ , namely

$$m = m^{(0)}(\eta, \xi_{1}, \xi_{2}, t) + \delta m^{(1)}(\eta, \xi_{1}, \xi_{2}, t) + \cdots,$$

$$T = T^{(0)}(\eta, \xi_{1}, \xi_{2}, t) + \delta T^{(1)}(\eta, \xi_{1}, \xi_{2}, t) + \cdots,$$

$$H = H^{(0)}(\eta, \xi_{1}, \xi_{2}, t) + \delta H^{(1)}(\eta, \xi_{1}, \xi_{2}, t) + \cdots,$$

$$h_{i} = h_{i}^{(0)}(\eta, \xi_{1}, \xi_{2}, t) + \delta h_{i}^{(1)}(\eta, \xi_{1}, \xi_{2}, t) + \cdots,$$

$$v_{n} = v_{n}^{(0)}(\eta, \xi_{1}, \xi_{2}, t) + \delta v_{n}^{(1)}(\eta, \xi_{1}, \xi_{2}, t) + \cdots,$$

$$p = p^{(0)}(\eta, \xi_{1}, \xi_{2}, t) + \delta p^{(1)}(\eta, \xi_{1}, \xi_{2}, t) + \cdots.$$
(4.16)

The mean pressure P(t) has not been explicitly expanded, but it too will be determined to $O(\delta)$ when evaluating the integral in (2.17). The equations that need to be solved at each order are obtained by applying the transformation $(n, \xi_1, \xi_2, t) \mapsto (\eta, \xi_1, \xi_2, t)$ to the governing equations, noting that

$$\lambda \frac{\partial}{\partial n} = \frac{1}{\delta} \frac{\partial}{\partial \eta}, \quad \frac{\partial}{\partial t} = \frac{\partial}{\partial t} + \frac{\partial \eta}{\partial t} \frac{\partial}{\partial \eta}, \quad \nabla_s = \nabla_s + \nabla_s \eta \frac{\partial}{\partial \eta}. \tag{4.17a-c}$$

They must be solved for $\eta \leq 0$ subject to the jump conditions (4.14) across $\eta = 0$. The matching conditions for the state variables are readily available from (3.11) and (3.14), namely

$$Y_D \sim \begin{cases} Y_{D_0}, & Y_E \sim \begin{cases} Y_{E_0} & \text{as } \eta \to -\infty, \\ \nu Y_{D_0} \varphi / \beta_0 & \text{as } \eta \to +\infty, \end{cases} \\ \rho \sim \begin{cases} P^{1/\gamma}, & T \sim \begin{cases} P^{(\gamma-1)/\gamma} & \text{as } \eta \to -\infty, \\ T_b & \text{as } \eta \to +\infty, \end{cases} \end{cases}$$
(4.18)

where $T_b = T_b^{(0)}(t) + \delta T_b^{(1)}(t) + \cdots$, with $T_b^{(0)} = P^{(\gamma-1)/\gamma} + q$. Consequently, $H \sim T_b$ as $\eta \to \pm \infty$, but the enthalpy perturbations that satisfy $h_D = h_E \sim 0$ as $\eta \to -\infty$ remain to be determined on the burned side as $\eta \to +\infty$.

To leading order,

$$\frac{\partial m^{(0)}}{\partial \eta} = 0,$$

$$m^{(0)} \frac{\partial T^{(0)}}{\partial \eta} - \frac{\partial^2 T^{(0)}}{\partial \eta^2} = 0,$$

$$m^{(0)} \frac{\partial H^{(0)}}{\partial \eta} - \frac{\partial^2 H^{(0)}}{\partial \eta^2} = 0,$$

$$m^{(0)} \frac{\partial h_i^{(0)}}{\partial \eta} - \frac{\partial^2 h_i^{(0)}}{\partial \eta^2} = -le_i \left(\frac{\partial^2 H^{(0)}}{\partial \eta^2} - \frac{\partial^2 T^{(0)}}{\partial \eta^2}\right),$$

$$m^{(0)} \frac{\partial v_n^{(0)}}{\partial \eta} - \frac{4}{3} \operatorname{Pr} \frac{\partial^2 v_n^{(0)}}{\partial \eta^2} = -\frac{\partial p^{(0)}}{\partial \eta},$$

$$m^{(0)} \frac{\partial \mathbf{v}_{\perp}^{(0)}}{\partial \eta} - \operatorname{Pr} \frac{\partial^2 \mathbf{v}_{\perp}^{(0)}}{\partial \eta^2} = 0.$$
(4.19)

Conservation of mass implies that $m^{(0)} = M$ independent of η . The solution of the state variables that satisfies the jump relations at $\eta = 0$ and the matching conditions as $\eta \to \pm \infty$ is

$$T^{(0)} = \begin{cases} P^{(\gamma-1)/\gamma} + q e^{M\eta} \\ P^{(\gamma-1)/\gamma} + q \end{cases}, \quad h_i^{(0)} = le_i \begin{cases} -q\eta M e^{M\eta} \\ 0 \end{cases}, \quad \rho^{(0)} = \frac{P}{T^{(0)}} \end{cases}, \quad (4.20a-c)$$

with $H^{(0)} = T_b^{(0)}$ independent of η . The top and bottom expressions correspond to $\eta < 0$ and $\eta > 0$, respectively, a notation that is also kept below. The solution of the velocity and pressure that satisfies the jump relations at $\eta = 0$ is given by

$$v_{n}^{(0)} = v_{n}^{(0)}|_{\eta = -\infty} + \frac{1}{P} \begin{cases} qM e^{M\eta} , \quad \boldsymbol{v}_{\perp}^{(0)} = \boldsymbol{v}_{\perp}^{(0)}|_{\eta = -\infty}, \\ p^{(0)} = p^{(0)}|_{\eta = -\infty} + \frac{1}{P} \begin{cases} \left(\frac{4}{3} \operatorname{Pr} - 1\right) qM^{2} e^{M\eta}, \\ -qM^{2}, \end{cases}$$

$$(4.21)$$

where it can be verified that the behaviour as $\eta \to \pm \infty$ confirms the RH relations across the flame. Finally, the jump relation for the temperature gradient yields an expression for the burning rate, given by

$$M = P\left(\frac{T_f}{T_a}\right)^2 \sqrt{\frac{\lambda_b}{\lambda_a}} \sqrt{\frac{1 + q\varphi/2T_f^2}{1 + q\varphi/2T_a^2}} \exp\left(\frac{\beta_0}{2T_a} - \frac{\beta_0}{2T_f}\right),\tag{4.22}$$

where here, $T_f = T_b^{(0)}$. Below, we will use T_f and $T_b^{(0)}$ interchangeably when only the leading order of flame temperature is needed in a given expression. Equation (4.22) shows that, to leading order, the burning rate depends only on time and simplifies to M = 1 for a freely propagating flame, as it should.

We now proceed to the next order in the perturbation scheme. Before writing the simplified equations to $O(\delta)$ we note that since $\lambda = \lambda(T)$ and $T \sim T^{(0)}(\eta, t)$, the

transformation (4.17a-c) implies that

$$\frac{\partial}{\partial t} = \frac{\partial}{\partial t} + \frac{\partial\eta}{\partial t} \frac{\partial}{\partial \eta} + O(\delta), \quad \nabla_s = \nabla_s + O(\delta),$$

$$\lambda \frac{\partial\eta}{\partial t} = \int_{\eta}^{0} \lambda_T \frac{\partial T}{\partial t} d\eta' = \begin{cases} \dot{T}_f \int_{\eta}^{0} \lambda_T d\eta' - \frac{\dot{M}}{M} \left(\lambda \eta + \int_{\eta}^{0} \lambda d\eta' \right), \\ -\lambda_T \dot{T}_f \eta, \end{cases}$$
(4.23)

where $\lambda_T = d\lambda/dT$ and the 'dot', here and thereafter, signifies differentiation with respect to *t*.

The continuity equation takes the form

$$\frac{1}{\lambda}\frac{\partial m^{(1)}}{\partial \eta} = -\frac{\partial \rho^{(0)}}{\partial t} - \frac{\partial \eta}{\partial t}\frac{\partial \rho^{(0)}}{\partial \eta} + M\kappa - \rho^{(0)}\mathbb{K}, \qquad (4.24)$$

where κ is the local curvature of the flame surface taken to be positive when the surface is concave towards the burned gas, as per the convention adopted earlier, and

$$\mathbb{K} = -V_{f}\kappa + \underbrace{\frac{1}{a_{1}a_{2}}\left(\frac{\partial(a_{2}v_{1})}{\partial\xi_{1}} + \frac{\partial(a_{1}v_{2})}{\partial\xi_{2}}\right)}_{\nabla_{s}\cdot v_{\perp}}$$
(4.25)

is the (dimensionless) stretch rate experienced by the flame (Matalon *et al.* 2003, appendix A), both being independent of η . Its influence on the flame propagation will be discussed in § 5. The solution of (4.24), which satisfies continuity at $\eta = 0$, takes the form

$$m^{(1)} = A + \begin{cases} g(\eta), \\ \lambda_b \left(M\kappa - \frac{P}{T_f} \mathbb{K} - \frac{\dot{P}}{T_f} + \frac{\gamma - 1}{\gamma} \frac{T_u \dot{P}}{T_f^2} \right) \eta, \end{cases}$$
(4.26)

where $A = A(\xi_1, \xi_2, t)$ remains to be determined, and

$$g(\eta) = \left(M\kappa - \frac{\dot{M}P}{M\vartheta(\eta)}\right)\mathcal{J}_1(\eta) + \left(\frac{\dot{M}P}{M} - P\mathbb{K} - \dot{P}\right)\mathcal{J}_2(\eta) + \frac{\gamma - 1}{\gamma}\dot{P}T_u\left(\frac{\mathcal{J}_3(\eta)}{\vartheta} - \mathcal{J}_4(\eta)\right).$$
(4.27)

Here

$$\mathcal{J}_{1}(\eta) = \int_{0}^{\eta} \lambda(\eta') \, \mathrm{d}\eta', \quad \mathcal{J}_{2}(\eta) = \int_{0}^{\eta} \frac{\lambda(\eta')}{\vartheta(\eta')} \mathrm{d}\eta',$$

$$\mathcal{J}_{3}(\eta) = \int_{0}^{\eta} \frac{\mathrm{d}}{\mathrm{d}\vartheta} (\lambda(\eta')) \, \mathrm{d}\eta', \quad \mathcal{J}_{4}(\eta) = \int_{0}^{\eta} \frac{\mathrm{d}}{\mathrm{d}\vartheta} \left(\frac{\lambda(\eta')}{\vartheta(\eta')}\right) \mathrm{d}\eta',$$
(4.28)

where ϑ is the leading-order temperature in the preheat zone, namely $\vartheta(\eta) = T_u + q e^{M\eta}$, and $T_u = P^{(\gamma-1)/\gamma}$ is the temperature on the unburned side of the flame zone. For simplicity of notation, we have displayed explicitly only the dependence on η , which is needed for integration, although g is a function of ξ_1, ξ_2, η and t and the integrals \mathcal{J}_i depend on both η and t. The same notation is adopted below. The remaining equations describing the combustion field are

$$M\frac{\partial T^{(1)}}{\partial \eta} - \frac{\partial^2 T^{(1)}}{\partial \eta^2} = -(m^{(1)} + \lambda\kappa)\frac{\partial T^{(0)}}{\partial \eta} - \lambda\rho^{(0)}\left(\frac{\partial T^{(0)}}{\partial t} + \frac{\partial \eta}{\partial t}\frac{\partial T^{(0)}}{\partial \eta}\right) + \lambda\frac{\gamma - 1}{\gamma}\dot{P},$$
(4.29)

$$M\frac{\partial H^{(1)}}{\partial \eta} - \frac{\partial^2 H^{(1)}}{\partial \eta^2} = -\lambda \rho^{(0)} \frac{\partial H^{(0)}}{\partial t} + \lambda \frac{\gamma - 1}{\gamma} \dot{P}$$
(4.30)

and

$$M\frac{\partial h_i^{(1)}}{\partial \eta} - \frac{\partial^2 h_i^{(1)}}{\partial \eta^2} = -(m^{(1)} + \lambda\kappa)\frac{\partial h_i^{(0)}}{\partial \eta} - \lambda\rho^{(0)}\left(\frac{\partial h_i^{(0)}}{\partial t} + \frac{\partial \eta}{\partial t}\frac{\partial h_i^{(0)}}{\partial \eta}\right) + le_i\left(\frac{\partial^2 T^{(1)}}{\partial \eta^2} - \frac{\partial^2 H^{(1)}}{\partial \eta^2} - \lambda\kappa\frac{\partial T^{(0)}}{\partial \eta}\right),$$
(4.31)

for $h_D^{(1)}$ and $h_E^{(1)}$. They must satisfy the $O(\delta)$ contributions of the jump relations (4.14) across $\eta = 0$, namely

$$[T^{(1)}] = [H^{(1)}] = [h_i^{(1)}] = 0,$$

$$\left[\frac{\partial H^{(1)}}{\partial \eta}\right] = 0, \quad \left[\frac{\partial h_i^{(1)}}{\partial \eta}\right] = -le_i \left[\frac{\partial T^{(1)}}{\partial \eta}\right],$$

$$\left[\frac{\partial T^{(1)}}{\partial \eta}\right] = -\frac{qM}{2T_f^2} \left(h_D^{*\,(1)} + \frac{h_E^{*\,(1)} - h_D^{*\,(1)}}{2 + q\varphi/T_f^2}\right) - q\frac{\partial M}{\partial T_f}T_b^{(1)},$$
(4.32)

and the matching conditions $H^{(1)} = T^{(1)} = h_i^{(1)} \sim 0$ as $\eta \to -\infty$, where

$$\frac{\partial M}{\partial T_f} = M \left\{ \frac{2}{T_f} + \frac{1}{2\lambda_b} \lambda_T \Big|_{T_f} - \frac{q\varphi/2T_f^3}{1 + q\varphi/2T_f^2} + \frac{\beta_0}{2T_f^2} \right\}.$$
(4.33)

We note that the equations for $h_D^{(1)}$ and $h_E^{(1)}$ combine naturally into a single equation when introducing

$$\mathcal{H} = h_D + \frac{h_E - h_D}{2 + q\varphi/T_f^2}, \quad le_{eff} = le_D + \frac{le_E - le_D}{2 + q\varphi/T_f^2}$$
 (4.34*a*,*b*)

as the effective enthalpy and (reduced) Lewis number of the mixture. Then

$$\mathcal{H}^{(0)} = le_{eff} \begin{cases} -qM\eta \,\mathrm{e}^{M\eta}, \\ 0, \end{cases}$$
(4.35)

$$M\frac{\partial\mathcal{H}^{(1)}}{\partial\eta} - \frac{\partial^{2}\mathcal{H}^{(1)}}{\partial\eta^{2}} = -(m^{(1)} + \lambda\kappa)\frac{\partial\mathcal{H}^{(0)}}{\partial\eta} - \lambda\rho^{(0)}\left(\frac{\partial\mathcal{H}^{(0)}}{\partial t} + \frac{\partial\eta}{\partial t}\frac{\partial\mathcal{H}^{(0)}}{\partial\eta}\right) + le_{eff}\left(\frac{\partial^{2}T^{(1)}}{\partial\eta^{2}} - \frac{\partial^{2}H^{(1)}}{\partial\eta^{2}} - \lambda\kappa\frac{\partial T^{(0)}}{\partial\eta}\right),$$
(4.36)

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and the jump relations across $\eta = 0$ simplify to

$$[T^{(1)}] = [\mathcal{H}^{(1)}] = 0, \quad \left[\frac{\partial T^{(1)}}{\partial \eta}\right] = -\frac{qM}{2T_f^2}\mathcal{H}^{*(1)} - q\frac{\partial M}{\partial T_f}T_b^{(1)}, \\ \left[\frac{\partial \mathcal{H}^{(1)}}{\partial \eta}\right] = -le_{eff}\left[\frac{\partial T^{(1)}}{\partial \eta}\right].$$

$$(4.37)$$

We are left to address (4.29)–(4.36) for $T^{(1)}$, $H^{(1)}$ and $\mathcal{H}^{(1)}$, respectively, subject to the jump relations (4.37).

The solution in the burned gas region ($\eta > 0$) is

$$T^{(1)} = T_b^{(1)} + q\lambda_b \frac{\gamma - 1}{\gamma} \frac{P}{MT_f} \eta, H^{(1)} = T^{(1)}, \quad \mathcal{H}^{(1)} = B,$$
(4.38)

where $T_b^{(1)}$ and *B* remain to be determined. In the preheat zone ($\eta < 0$) the temperature equation (4.29) takes the form

$$M\frac{\partial T^{(1)}}{\partial \eta} - \frac{\partial^2 T^{(1)}}{\partial \eta^2} = -AqM e^{M\eta} - qs(\eta)M e^{M\eta},$$

$$s(\eta) = g(\eta) + \kappa\lambda(\eta) - \frac{\gamma - 1}{\gamma}\frac{\dot{P}}{M}\frac{\lambda(\eta)}{\vartheta(\eta)} + \frac{\dot{M}}{M}\frac{P}{\vartheta(\eta)}\mathcal{J}_1(\eta) - \frac{\gamma - 1}{\gamma}\frac{T_u\dot{P}}{\vartheta(\eta)}\mathcal{J}_3(\eta),$$
(4.39)

and the general solution that satisfies continuity at $\eta = 0$ is

$$T^{(1)} = T_b^{(1)} + D(e^{M\eta} - 1) + Aq\eta \, e^{M\eta} + q \int_{\eta}^{0} s(\eta')(e^{M\eta'} - e^{M\eta}) \, \mathrm{d}\eta'.$$
(4.40)

Similarly, the solution of (4.30) that is continuous and smooth at $\eta = 0$ is

$$H^{(1)} = T_b^{(1)} + \frac{\gamma - 1}{\gamma} \frac{q\lambda_b \dot{P}}{M^2 T_f} \left\{ (e^{M\eta} - 1) + \frac{MT_f}{\lambda_b} \int_{\eta}^{0} \frac{\lambda(\eta')}{\vartheta(\eta')} (e^{M\eta} - e^{M\eta'}) \, \mathrm{d}\eta' \right\}.$$
 (4.41)

Matching as $\eta \to -\infty$ yields

$$T_{b}^{(1)} = \frac{\gamma - 1}{\gamma} \frac{q\lambda_{b}\dot{P}}{M^{2}T_{f}} \left(1 + \frac{MT_{f}}{\lambda_{b}} \int_{-\infty}^{0} \frac{\lambda(\eta')}{\vartheta(\eta')} e^{M\eta'} d\eta' \right),$$

$$D = T_{b}^{(1)} + q \int_{-\infty}^{0} s(\eta') e^{M\eta'} d\eta'.$$
(4.42)

Although an explicit solution can also be written for $\mathcal{H}^{(1)}$, it suffices for our purpose to integrate (4.36) from $\eta = -\infty$ to $\eta = 0^-$ and use the matching condition $\mathcal{H}^{(1)} \sim 0$ as **998** A59-18

 $\eta \rightarrow -\infty$ and the jump conditions (4.37). One finds that

$$MB = qle_{eff} \left\{ \int_{-\infty}^{0} \left(s(\eta') + \frac{\gamma - 1}{\gamma} \frac{\dot{P}}{M} \frac{\lambda(\eta')}{\vartheta(\eta')} \right) (1 + M\eta') M e^{M\eta'} d\eta' \right\} - M\kappa \int_{-\infty}^{0} \lambda(\eta') e^{M\eta'} d\eta' \right\},$$

$$\frac{qM}{2T_{f}^{2}} B = -\frac{\gamma - 1}{\gamma} \frac{q\lambda_{b}}{MT_{f}} \dot{P} + MD + qA - q \frac{\partial M}{\partial T_{f}} T_{b}^{(1)}.$$

$$(4.43)$$

This results in the determination of all the unknown functions

$$T_{b}^{(1)} = \frac{\gamma - 1}{\gamma} \frac{\dot{P}}{M^{2}} \left\{ J_{1} + \frac{q\lambda_{b}}{T_{f}} \right\},$$

$$B = -le_{eff} \frac{P}{M^{2}} \left\{ J_{2} \left(\mathbb{K} + \frac{\dot{P}}{P} - \frac{\dot{M}}{M} \right) - \dot{T}_{u} J_{3} \right\},$$

$$D = T_{b}^{(1)} + \frac{P}{M^{2}} \left\{ J_{1} \left(\mathbb{K} + \frac{\dot{P}}{P} - \frac{\dot{M}}{M} \right) - \left(\frac{\lambda_{u}}{T_{u}} - \frac{\lambda_{b}}{T_{f}} \right) \dot{T}_{u} \right\},$$

$$A = \frac{\partial M}{\partial T_{f}} T_{b}^{(1)} - \left(\frac{P}{M} \mathbb{K} + \frac{d}{dt} \left(\frac{P}{M} \right) \right) \left(\frac{J_{1}}{q} - \frac{le_{eff}}{2T_{f}^{2}} J_{3} \right) - \frac{\dot{T}_{u} P}{qM} \left(\frac{\lambda_{b}}{T_{f}} - \frac{\lambda_{u}}{T_{u}} - \frac{qle_{eff}}{2T_{f}^{2}} J_{3} \right) \right\}$$

$$(4.44)$$

expressed in terms of the (convergent) definite integrals

$$J_{1} = \int_{T_{u}}^{T_{f}} \frac{\lambda(x)}{x} dx, \quad J_{2} = \int_{T_{u}}^{T_{f}} \frac{\lambda(x)}{x} \ln\left(\frac{q}{x - T_{u}}\right) dx,$$

$$J_{3} = -\int_{T_{u}}^{T_{f}} \frac{d}{dx} \left(\frac{\lambda(x)}{x}\right) \ln\left(\frac{q}{x - T_{u}}\right) = -\frac{\dot{J}_{2}}{\dot{T}_{u}}.$$

$$(4.45)$$

Note that $J_1, J_2 > 0$ and $J_3 > 0$ for $\lambda(T) = T^a$ for a < 1. For $\lambda(T) = T$, they can be evaluated such that $J_1 = J_2 = q$ and $J_3 = 0$. At the initial time, the limits of integration are from 1 to T_a and the corresponding integrals will be denoted with the accent 'hat', i.e. \hat{J}_1 and \hat{J}_2 . They are identical to the integrals appearing in a similar context in the freely propagating flame theory.

We have now obtained solutions correct to $O(\delta)$ for the state variables ρ , T, the enthalpy functions H, \mathcal{H} , or equivalently the mass fractions Y_D, Y_E , and mass flux m inside the flame zone. The latter, which determines the burning rate, is the primary focus of this study. Although one can also solve the fluid mechanics equations to the same order, the algebra is rather lengthy and beyond the scope of this paper.

5. Flame speed and pressure rise

We proceed in deriving explicit expressions for the burning rate and/or flame speed, the flame temperature and the overall pressure rise in the vessel.

5.1. The flame speed

The burning rate m^* , as defined in (3.18), is obtained by matching the hydrodynamic solution $m_{hyd} = m_{hyd}^{(0)} + \delta m_{hyd}^{(1)}$ at $n = 0^-$ with the corresponding solution in the flame zone, namely $m \sim m^{(0)} + \delta m^{(1)}$ as $\eta \to -\infty$. Evidently, to leading order,

$$m_{hyd} \sim m_{hyd}^{(0)}|_{n=0^-} = \lim_{\eta \to -\infty} m^{(0)} = M.$$
 (5.1)

To proceed to the next order, we note that as $\eta \to -\infty$,

$$\mathcal{J}_{2} \sim \frac{J_{1}}{MT_{u}} + \frac{\mathcal{J}_{1}(\eta)}{T_{u}},$$

$$T_{u}\left(\frac{\mathcal{J}_{3}}{\vartheta(\eta)} - \mathcal{J}_{4}\right) \sim -\frac{\dot{J}_{1}}{M\dot{T}_{u}} + \frac{J_{1}}{MT_{u}} + \frac{\mathcal{J}_{1}(\eta)}{T_{u}},$$
(5.2)

such that

$$m \sim M + \delta \left\{ A - \frac{P}{MT_u} \left(\left(\mathbb{K} + \frac{1}{\gamma} \frac{\dot{P}}{P} - \frac{\dot{M}}{M} \right) J_1 + \dot{J}_1 \right) + \left(M\kappa - \frac{P\mathbb{K}}{T_u} - \frac{\dot{P}}{\gamma T_u} \right) \mathcal{J}_1(\eta) \right\}.$$
(5.3)

The hydrodynamic solution to $O(\delta)$ at $n = 0^-$ takes the form

$$m_{hyd} \sim M + \delta \left\{ m_{hyd}^{(1)}|_{n=0^-} + \left. \frac{\partial m_{hyd}^{(0)}}{\partial n} \right|_{n=0^-} \mathcal{J}_1(\eta) \right\},$$
 (5.4)

where, here and below, it is understood that M must be expanded to $O(\delta)$, namely replaced by $M + \delta(\partial M/\partial T_f)T_b^{(1)}$ with the $O(\delta)$ retained when necessary. Matching then yields an expression for m^* which, after dividing by ρ_u , gives the expression

$$S_f = \frac{M}{\rho_u} - \frac{\delta}{M} \left\{ \mathcal{M}_1 \left(\mathbb{K} - \frac{\dot{M}}{M} \right) + \mathcal{M}_2 \frac{\dot{P}}{P} \right\} + o(\delta).$$
(5.5)

The flame speed S_f is modulated by two time-dependent coefficients

$$\mathcal{M}_{1} = \frac{T_{f}}{q}J_{1} + \left(\frac{T_{a}}{T_{f}}\right)^{2}\frac{\beta(Le_{eff}-1)}{2q}T_{u}J_{2},$$

$$\mathcal{M}_{2} = \mathcal{M}_{1} - \frac{\gamma-1}{\gamma}\left\{J_{1} + \left(\frac{\lambda_{u}}{T_{u}} - \frac{\lambda_{b}}{T_{f}}\right)\frac{T_{u}T_{f}}{q} + \left(\frac{T_{a}}{T_{f}}\right)^{2}\frac{\beta(Le_{eff}-1)}{2q}T_{u}^{2}J_{3}\right\},$$
(5.6)

which results from (5.3) after expressing the scaled parameters le_{eff} and φ in terms of the effective Lewis number Le_{eff} and the excess-to-deficient reactant mass ratio Φ while using the Zel'dovich number β in lieu of β_0 . Matching the gradients does not reveal new information because the gradient of the mass flux to leading order can also be deduced from the continuity equation (3.2) when evaluated at $n = 0^-$. The $O(\delta)$ correction to the flame speed consists of two terms; the first will be recognized below as the voluminal stretch and the second is the proportionate time rate of change of the pressure; the coefficients \mathcal{M}_1 and \mathcal{M}_2 , which can arguably be referred to as Markstein numbers, will be further discussed below.

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The flame speed, as defined in (3.17), is based on the prevalent convention that it is measured relative to the velocity of the fresh unburned gas. It is often convenient to relate the propagation speed to the gas velocity of the burned gas and define the flame speed as $S_f^b \equiv m^b/\rho_b$, where the superscript ^b here and below signifies that the quantity is measured relative to the burned gas. This requires evaluating the mass flux m^b at the burned edge of the flame, i.e. at $n = 0^+$, which is directly obtained by matching with the solution (4.26) as $\eta \to +\infty$. The flame speed is then given by

$$\frac{\rho_b}{\rho_u} S_f^b = \frac{M}{\rho_u} - \frac{\delta}{M} \left\{ \mathcal{M}_1^b \left(\mathbb{K} - \frac{\dot{M}}{M} \right) + \mathcal{M}_2^b \frac{\dot{P}}{P} \right\} + o(\delta), \tag{5.7}$$

with time-dependent coefficients

$$\mathcal{M}_{1}^{b} = \frac{T_{u}}{q}J_{1} + \left(\frac{T_{a}}{T_{f}}\right)^{2}\frac{\beta(Le_{eff}-1)}{2q}T_{u}J_{2},$$

$$\mathcal{M}_{2}^{b} = \mathcal{M}_{1}^{b} - \frac{\gamma-1}{\gamma}T_{u}^{2}\left\{\frac{1}{q}\left(\frac{\lambda_{u}}{T_{u}} - \frac{\lambda_{b}}{T_{f}}\right) + \left(\frac{T_{a}}{T_{f}}\right)^{2}\frac{\beta(Le_{eff}-1)}{2q}J_{3}\right\},$$
(5.8)

which may be referred to as the burned Markstein numbers. Here too, matching the gradients does not reveal new information; the gradient of the mass flux to leading order can be also deduced from the continuity equation (3.2) when evaluated at $n = 0^+$.

From the above relations, it can be verified that there is an $O(\delta)$ jump in the normal mass flux across the entire flame given by

$$\llbracket m \rrbracket = \frac{\delta}{M} \left\{ \rho_u J_1 \left(\mathbb{K} - \frac{\dot{M}}{M} \right) + \frac{\mathrm{d}}{\mathrm{d}t} (\rho_u J_1) \right\}.$$
(5.9)

Although the mass flux is conserved across an infinitesimally thin flame, when accounting for the finite (albeit small) thickness of the flame zone, the normal mass flux leaving the flame differs from that into the flame due to transverse transport and/or mass accumulation. One also notes that the jump in the gas velocity across the flame given by

$$\llbracket \boldsymbol{v} \cdot \boldsymbol{n} \rrbracket = \frac{T_f - T_u}{P} m^* + \frac{T_f}{P} \llbracket m \rrbracket = \frac{qM}{P} + O(\delta)$$
(5.10)

always increases in time, a direct result of the rise in flame temperature.

Although the density and temperature of the unburned gas ρ_u and T_u remain spatially uniform to all orders in δ , the state of the burned gas is modified to $O(\delta)$ by corrections arising from variations in the flame temperature. In particular, the temperature is determined by solving

$$\rho \frac{\mathrm{D}T}{\mathrm{D}t} - \frac{\gamma - 1}{\gamma} \frac{\mathrm{d}P}{\mathrm{d}t} = \delta \nabla \cdot (\lambda \nabla T), \qquad (5.11)$$

subject to

$$T_{f} = T_{u} + q - \frac{\delta P}{M^{2}} \left\{ \frac{\gamma - 1}{\gamma} \left(J_{1} + \frac{q\lambda_{b}}{T_{u} + q} \right) \frac{\dot{P}}{P} \right\} - (Le_{D} - 1) \frac{\delta}{M} \left\{ \left(\frac{PJ_{2}}{M} \right) \mathbb{K} + \frac{d}{dt} \left(\frac{PJ_{2}}{M} \right) \right\}$$
(5.12)

at $n = 0^+$, with appropriate boundary conditions to $O(\delta)$ at the vessel's walls. The expression for T_f results from matching with the solution in the flame zone as $\eta \to +\infty$.

Although the flame temperature T_f varies primarily in time as a result of the pressure rise, there are small changes in temperature associated with flame stretch that depend on the Lewis number of the deficient reactant, i.e. the fuel in a lean mixture and the oxidizer in a rich mixture. The dependence on flame stretch was corroborated with direct numerical simulations for freely expanding spherical flames (Giannakopoulos *et al.* 2015) where it was shown that, depending on the equivalence ratio that determines whether Le_D is above/below one, the flame temperature is lower/higher than its adiabatic value and increases/decreases towards T_a when $\mathbb{K} \to 0$.

The equations describing the flow field and state variables in the hydrodynamic zones were presented in § 3 to leading order. To extend the results to $O(\delta)$, (2.9)–(2.13) must be considered with the reaction term set to zero and diffusion added as correction terms. For the determination of the flow field, the $O(\delta)$ corrections to the RH conditions (3.9) must be derived, as carried out in Matalon & Matkowsky (1982) for freely propagating flames. Not being the focus of this work, the derivation will not be pursued here. For configurations that depend on a single spatial coordinate, such as planar or spherical flames, the velocity field is directly determined from the continuity equation (3.7) which, when extended to $O(\delta)$ takes the form

$$\nabla \cdot \boldsymbol{v} + \frac{1}{\gamma P} \frac{\mathrm{d}P}{\mathrm{d}t} = \delta \frac{1}{P} \nabla \cdot (\lambda \nabla T), \qquad (5.13)$$

and needs to be solved subject to the jump condition (5.9) across the flame surface. The momentum equation is used *a posteriori* to evaluate the dynamic pressure.

As a final remark, we note that the expressions for the flame speed and Markstein lengths (relative to burned or unburned gas), and the flame temperature simplify to the corresponding expressions for freely propagating flames. With $P = T_u = 1$, the flame temperature, to leading order, is the adiabatic flame temperature $T_a = 1 + q$ and the density is a piecewise constant function with $\rho_u = 1$ and $\rho_b = 1/T_a$. Then, the flame speed depends on a single Markstein number \mathcal{M}_1 that takes the form

$$\mathcal{M}_1 = \frac{\sigma}{\sigma - 1} \int_1^\sigma \frac{\lambda(x)}{x} dx + \frac{\beta(Le_{eff} - 1)}{2(\sigma - 1)} \int_1^\sigma \frac{\lambda(x)}{x} \ln\left(\frac{\sigma - 1}{x - 1}\right) dx, \tag{5.14}$$

where $\sigma = \rho_u / \rho_b$ is the unburned-to-burned density ratio. The stretch-corrected flame speed and temperature reduce to

$$S_{f} = 1 - \delta \mathcal{M}_{1}\mathbb{K},$$

$$T_{f} = T_{a} - \delta \left\{ (Le_{D} - 1) \int_{1}^{\sigma} \frac{\lambda(x)}{x} \ln\left(\frac{\sigma - 1}{x - 1}\right) \mathrm{d}x \right\} \mathbb{K},$$
(5.15)

as in Matalon et al. (2003).

5.2. Pressure rise

The pressure rise in the vessel is determined from (2.17) where the integral on the right-hand side is to be carried out over the entire volume. In the hydrodynamic limit it simplifies to

$$\frac{\mathrm{d}P}{\mathrm{d}t} = \frac{\gamma q}{\mathbb{V}} \int \omega \,\mathrm{d}n \,\mathrm{d}\mathcal{A} = \frac{\gamma q}{\mathbb{V}} \int_{\mathcal{A}_f} \int_{-\infty}^{\infty} \omega \delta \lambda \mathrm{d}\eta \,\mathrm{d}\mathcal{A},\tag{5.16}$$

where the integration is carried out across the flame zone and over the entire flame surface A_f . Since the chemical reaction rate ω is replaced by a Dirac delta function, the latter

simplifies to

$$\frac{\mathrm{d}P}{\mathrm{d}t} = -\frac{\gamma}{\mathbb{V}} \int_{\mathcal{A}_f} \left[\frac{\partial T}{\partial \eta}\right] \mathrm{d}\mathcal{A}.$$
(5.17)

The integrand consists of the jump in temperature gradient across the reaction sheet, namely the fraction of the total heat generated by the chemical reaction and conducted in different proportions to the burned and unburned gas. Under adiabatic conditions, more heat is transported to the fresh mixture justifying the assertion that the pressure always rises. The jump in temperature gradient across $\eta = 0$ is obtained directly from the solution constructed in the previous section, such that

$$\frac{\mathrm{d}P}{\mathrm{d}t} = \frac{\gamma q \mathbb{A}_f}{\mathbb{V}} \left\{ M - \delta \left(\frac{T_a}{T_f} \right)^2 \frac{\beta (Le_{eff} - 1)}{2q} \left(\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{PJ_2}{M} \right) + \frac{PJ_2}{M} \frac{1}{\mathbb{A}_f} \int_{\mathcal{A}_f} \mathbb{K} \,\mathrm{d}\mathcal{A} \right) \right\}, \quad (5.18)$$

where \mathbb{A}_f is the flame surface area. For consistency, $O(\delta^2)$ terms in the curly bracketed expression must be discarded. It may be verified when using (4.22) that the factor multiplying the last term in this equation decreases in time implying that the influence of flame stretch diminishes as the pressure rises. Equation (5.18) can be also expressed as

$$\frac{\mathrm{d}P}{\mathrm{d}t} = \frac{\gamma}{\mathbb{V}} \int_{\mathcal{A}_f} (qm^* + T_f[[m]]) \,\mathrm{d}\mathcal{A} + \delta \left(\frac{\mathbb{A}_f}{\mathbb{V}}\right)^2 \gamma(\gamma - 1) q J_1, \tag{5.19}$$

a form found useful in the next section.

5.3. Flame stretch

Flame stretch, first introduced by Karlovitz *et al.* (1953), is a measure of the deformation of the flame surface resulting from its motion and from the underlying flow field. It is defined as the proportionate rate of change of the area of an infinitesimal surface element A of the flame front, namely $\mathbb{K} \equiv A^{-1} dA/dt$. The stretch rate appeared naturally in the mass conservation equation (4.24) when expressed in terms of intrinsic surface coordinates, and may be expressed in the coordinate-free form as

$$\mathbb{K} = -V_f \kappa - \underbrace{\boldsymbol{n} \cdot \boldsymbol{\nabla} \times (\boldsymbol{v} \times \boldsymbol{n})}_{-\boldsymbol{\nabla}_s \cdot \boldsymbol{v}_\perp}, \tag{5.20}$$

obtained from the basic definition (Matalon 1983). The first term corresponds to the surface dilatation resulting from the motion of the flame front, and the second term is the surface extension/compression resulting from the underlying velocity gradient on the surface of the flame front. The curvature can be evaluated from $\kappa = -\nabla \cdot \mathbf{n}$, evaluated at the flame front. Since \mathbf{v}_{\perp} is continuous across the flame (to leading order), the stretch rate is uniquely defined on the flame surface and can be evaluated from (5.20) on either side of the interface.

It is often stated that flame stretch is a combination of curvature and strain, a statement that requires careful consideration. When expanding the right-hand side of (5.20), one finds that

$$\mathbb{K} = (\boldsymbol{v} \cdot \boldsymbol{n} - V_f)\boldsymbol{\kappa} + K_S + \boldsymbol{\nabla} \cdot \boldsymbol{v}, \qquad (5.21)$$

where $K_S = -n \cdot E \cdot n$ is the local strain rate. It must be noted that the first two terms on the right-hand side admit different values when evaluated on the unburned and burned sides of the flame front. Thus, using (5.21) to determine the stretch rate requires specifying



Figure 2. The dependence of (a) the flame thickness l_f and (b) the flame temperature T_f scaled by the adiabatic flame temperature T_a on pressure P(t) representing time, for various values of the heat release parameter q; the curves end at $P = P_e$ marked on the axis.

on which side of the flame front this expression is to be evaluated. For a freely propagating flame in the hydrodynamic limit, $\nabla \cdot v = 0$ on either side of the flame and the stretch rate is indeed a combination of curvature and strain, but each of these components have different expressions when evaluated on the unburned and burned sides. On the unburned side of the flame, $v \cdot n - V_f \sim 1$ and $\mathbb{K} = \kappa + K_S^u$; on the burned side of the flame $v \cdot n - V_f \sim \sigma$, where σ is the unburned-to-burned density ratio and $\mathbb{K} = \sigma \kappa + K_S^b$. Both yield the same value for the stretch rate because $[[K_S]] = -(\sigma - 1)\kappa$, a relation derived in Matalon *et al.* (2003). For a flame propagating in a closed vessel, the stretch rate is not just a combination of curvature and strain because the volume dilatation rate $\nabla \cdot v \neq 0$ due to gas compression, but may be expressed in the form

$$\mathbb{K} = \frac{M}{\rho}\kappa + K_S - \frac{1}{\gamma P}\frac{\mathrm{d}P}{\mathrm{d}t}, \quad \text{at } \psi = 0^{\pm}.$$
(5.22)

A planar flame, for example, is not stretched, but in a closed vessel it experiences normal strain that balances the volume dilatation rate, thus ensuring that $\mathbb{K} = 0$. Similarly, a spherical flame experiences normal straining and a non-zero dilatation rate such that (5.22) simplifies to $\mathbb{K} = -V_f \kappa$ as it should. These examples will be further discussed in § 6.

Although the flame zone expressed in units of the diffusion length l_d is of infinite extent, the distance required for the temperature to rise from the cold value T_u to the flame temperature T_f occurs over a relatively small multiple of this length. The flame thickness may therefore be defined as the distance from the reaction zone to the point where the temperature falls within 1% of T_u . For a freely propagating flame (M = 1), this distance is constant; typically $l_f \approx 7l_d$ with an accuracy of 10^{-4} . Under confinement, however, $l_f \sim 1/M$ and, since M increases in time due to the pressure rise, the flame becomes consistently thinner when propagating towards the end of the vessel, as shown in figure 2(a). The graph exhibits the dependence of l_f on time, represented by P(t), for various values of q, with $\varphi = 0$, $\lambda = T^{0.7}$ and $\beta = 10$. Changes in equivalence ratio and/or the dependence $\lambda(T)$ show no significant quantitative difference in the behaviour of l_f .

Due to the significant decrease in the flame thickness with time, the correction to the flame speed resulting from the physicochemical processes occurring inside the flame zone

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has been expressed in (5.5) as a multiple of δ/M , which being proportional to l_f/l , is a more accurate measure of its thickness. The proportionate time rate of change of the flame thickness $l_f^{-1} dl_f/dt = -\dot{M}/M$ combines with the proportionate time rate of change of the area of a flame surface element to define a voluminal stretch rate

$$\frac{1}{V}\frac{\mathrm{d}V}{\mathrm{d}t} = \frac{1}{A}\frac{\mathrm{d}A}{\mathrm{d}t} + \frac{1}{l_f}\frac{\mathrm{d}l_f}{\mathrm{d}t} = \mathbb{K} - \frac{M}{M},\tag{5.23}$$

where $V = l_f A$ is an infinitesimal volume element of the flame zone. Accordingly, the flame speed (5.5) was found to depend on the voluminal stretch rate that measures the local deformation of a volume element of the flame zone. The voluminal stretch concept was first introduced by Buckmaster (1979) in the context of slowly varying flames, as noted in the introduction.

5.4. The effective Lewis number

Although distinct Lewis numbers were assumed for the two reactants, the burning rate was found to depend on a stoichiometry-weighted combination of the two, or an effective Lewis number of the form

$$Le_{eff} = \frac{Le_E + Le_D(1 + \Delta)}{2 + \Delta},$$

$$\Delta = \left(\frac{T_a}{T_f}\right)^2 \beta(\Phi - 1), \quad \Phi \sim \begin{cases} 1/\phi & \text{lean mixtures,} \\ \phi & \text{rich mixtures,} \end{cases}$$
(5.24)

where ϕ is the equivalence ratio and Δ measures the deviation from stoichiometry. It is an average of the Lewis numbers of fuel and oxidizer, with a heavier weight on the deficient component in the mixture. The effective Lewis number is the mean value of Le_D and Le_E for a stoichiometric mixture ($\Delta = 0$) and tends towards Le_D for conditions sufficiently far from stoichiometry ($\Delta \gg 1$). It also varies in time due to the dependence of T_f/T_a on pressure shown in figure 2(b). The figure displays the dependence of the (leading-order) flame temperature scaled by the adiabatic temperature T_a on pressure, which varies in time from P = 1 initially to the end pressure $P_e = 1 + \gamma q$; the latter is shown on the axis for each value of q. Given that T_f/T_a does not increase considerably, and the uncertainty in accurately specifying the individual Lewis numbers, a time-averaged value can serve as the representative Le_{eff} .

Figure 3 shows the dependence of Le_{eff} , averaged over the total propagation time, on the equivalence ratio ϕ of the mixture, for several fuels burning in air. They are plotted for the representative value q = 6, which characterizes mixtures of various heat releases Q and mass fractions Y_{D_0} . The determination of the effective Le_{eff} requires specifying the limiting Lewis numbers; the fuel Lewis number Le_F for lean mixtures and the oxygen Lewis number Le_O for rich mixtures. These values are defined as the ratio of the thermal diffusivity of the mixture to the binary diffusivity of the fuel/oxygen into N₂, as per the dilute-mixture assumption used when adopting Fick's law in the governing equations; they were estimated near the lean/rich flammability limits and are marked by a dashed line in the figure. The formula (5.24) then provides the distribution of Le_{eff} as a function of the equivalence ratio ϕ , approaching the respective limiting Lewis numbers for lean and rich mixtures. A monotonically decreasing curve results for heavy hydrocarbon fuels with $Le_F > 1$, and a monotonically increasing curve results for light fuels with $Le_F < 1$, such as hydrogen and methane. The transitional curves display a weak dependence on the Zel'dovich number, which has been specified in this figure as $\beta = 10$.



Figure 3. The dependence of the effective Lewis number Le_{eff} , averaged over the total propagation time, on the mixture equivalence ratio for several fuels burning in air. The dashed lines mark the limiting Lewis numbers; the fuel Lewis number Le_F for lean mixtures and the oxygen Lewis number Le_O for rich mixtures.

5.5. The Markstein numbers

When viewed on the hydrodynamic scale, the flame is effectively an interface embedded in the flow field; the preheat zone of the flame collapses to $\psi = 0^{-}$ and the post-reaction zone of the flame to $\psi = 0^+$. The propagation speed can be expressed relative to either the unburned or burned gas. When expressed relative to the unburned gas, the flame speed S_f exhibits a linear dependence on the voluminal stretch rate, modulated by a parameter \mathcal{M}_1 , and on the rate of pressure rise, modulated by a parameter \mathcal{M}_2 . Similarly, when expressed relative to the burned gas, the flame speed S_f^b exhibits a linear dependence on the voluminal stretch rate, modulated by a parameter \mathcal{M}_1^b , and on the rate of pressure rise, modulated by a parameter \mathcal{M}_2^b . We note that unlike S_f , which mimics the diffusion and reaction processes occurring in the entire flame zone and is not evaluated at any specific isotherm, S_f^b is effectively evaluated at the flame temperature $T = T_f$. This has practical implications when seeking comparison with experimental and/or numerical simulations aimed at quantifying the dependence of the flame speed on stretch and pressure rise. Measurements and simulations that resolve the flame structure require selecting an isotherm to represent the flame surface, and the burned Markstein numbers in that regard are the most relevant ones. Indeed, it has been established that the most appropriate isotherm for the evaluation of the flame speed, which is well conditioned and displays the best agreement with the theory, must be sufficiently close to the burned side of the flame (Giannakopoulos et al. 2015). The flame speed S_f and Markstein numbers \mathcal{M}_1 and \mathcal{M}_2 , on the other hand, are the appropriate expressions to use for the evolving flame front when determining the flow field in the hydrodynamic regions.

Although the Markstein numbers (5.6) and (5.8) are pressure dependent, for a given mixture they are mostly affected by the effective Lewis number Le_{eff} . Given that their dependence on time for a wide range of Le_{eff} is quite moderate, they can be represented by an average value. In figure 4 we show the variation of the Markstein numbers (unburned and burned, averaged over the total propagation time) of selected fuels burning in air



Figure 4. The dependence of the Markstein numbers (averaged over the total propagation time) on the mixture equivalence ratio ϕ for several fuels burning in air.

across the entire range of the stoichiometric spectrum, which evidently mirror the variation of Le_{eff} on the equivalence ratio. We note that the second member on the right-hand side of (5.8) is identically zero for $\lambda(T) = T$ and negligibly small otherwise, implying that $\mathcal{M}_2^b \approx \mathcal{M}_1^b = \mathcal{M}^b$. For the unburned coefficients, $\mathcal{M}_2 < \mathcal{M}_1$, but the difference is typically small and does not exceed 20 %.

There are circumstances where despite the moderate variation of the Markstein numbers with time they may change sign during the propagation. This becomes particularly relevant when attempting to extract the burned Markstein number from experimental measurements. Since the integrals J_1 and J_2 are both positive, \mathcal{M}^b is strictly positive for $Le_{eff}^{cr} > Le_{eff}^{cr}$ and negative otherwise, where

$$Le_{eff}^{cr} \sim 1 - \frac{2}{\beta} \left(\frac{T_f}{T_a}\right)^2 \frac{J_1}{J_2}.$$
(5.25)

In most cases, \mathcal{M}^b is either positive or negative, but in a limited range of sub-unity Lewis number, estimated as $0.75 \leq Le_{eff} \leq 0.82$, it may change sign during the propagation. The implication being that in such cases, the location where flame speed measurements are taken to estimate the Markstein numbers becomes important. Two examples illustrating this effect are shown in figure 5, where the dependence of \mathcal{M}^b on time is shown for several values of the equivalence ratio. For a sufficiently lean hydrogen–air mixture, such as $\phi \leq 0.775$, the Markstein number is strictly negative and becomes strictly positive for



Figure 5. Two cases illustrating circumstances where the 'burned' Markstein number \mathcal{M}^b may change sign during the propagation. Results are shown for the (a) H₂-air mixture and (b) C₈H₁₈-air-CO₂ mixture.



Figure 6. Flame configurations: (*a*) planar flame propagating from left to right and (*b*) outwardly propagating spherical flame; the blue arrows show the flow direction.

 $\phi \ge 0.845$; it changes sign during the propagation when $\phi \approx 0.8$. The opposite trend is observed for a rich octane–air mixture when diluted with CO₂ to increase the effective Lewis number; the Markstein number is strictly positive for $\phi \le 1.98$, negative for $\phi \ge 2.92$ and changes sign during the propagation when $\phi \approx 2.4$.

6. Planar and spherical flames

The asymptotic theory derived in the previous sections is used next to examine flame propagation in two canonical configurations: a planar flame propagating in a rectangular channel of length L and a centrally ignited outwardly propagating flame in a spherical vessel of radius L (see figure 6). The results are illustrated below for vessels of length/radius L = 100, measured in units of the hydrodynamic length scale l. For typical $\delta = l_d/l \sim 0.02 - 0.002$, it corresponds to approximately 1000–10 000 flame thicknesses. Different mixtures will be represented by varying the heat release parameter q and effective Lewis number Le_{eff} , assuming stoichiometric conditions $\varphi = 0$, a power law $\lambda = T^a$ with a = 0.7 and ratio of specific heats $\gamma = 1.4$.

6.1. Planar flame

We consider first the propagation of a planar flame travelling from left to right in a rectangular channel, as shown in figure 6(a). If the channel's width (in the y and z directions) is chosen as the hydrodynamic length scale *l*, the flame surface area $\mathbb{A}_f = 1$ and the ratio $\mathbb{A}_f/\mathbb{V} = 1/L$. The flame front is described by $\psi(x, t) \equiv x_f(t) - x = 0$, such that $0 < x < x_f$ corresponds to the burned gas and $x_f < x < L$ to the unburned gas region. The propagation speed is then given by $V_f = -\dot{x}_f$.

To leading order, the gas velocity determined from (5.13) and satisfying u(0, t) = u(L, t) = 0 is given by

$$u(x,t) = \begin{cases} \frac{\dot{P}}{\gamma P}(L-x), & x_f < x < L, \\ -\frac{\dot{P}}{\gamma P}x, & 0 < x < x_f, \end{cases}$$
(6.1)

with the pressure obtained by solving $\dot{P} = \gamma q M/L$ subject to P(0) = 1, and M given by (4.22). The RH relation $[\rho(\dot{x}_f - u)] = 0$ then yields an expression for the flame position,

$$x_f(t) = \left(1 - \frac{P_e - P}{P_e - 1}P^{-1/\gamma}\right)L,$$
(6.2)

where $P_e = 1 + \gamma q$ is the end pressure. In a sufficiently long channel $(L \gg 1)$, the pressure increases linearly in time, namely $P \sim 1 + \gamma q t/L$, and the velocity simplifies to

$$u(x,t) \sim \begin{cases} q - q(x + \gamma qt)/L + O(1/L), & x_f < x < L, \\ -qx/L, & 0 < x < x_f, \end{cases}$$
(6.3)

where the additional O(1/L) contribution in the unburned gas comes from the expansion of M. When $L \to \infty$, the solution tends to that of a planar flame propagating from the closed end of a semi-infinite channel towards an open end at a speed $\dot{x}_f \sim 1 + q$. Determining the state of the burned gas requires first solving the advection equation

$$\frac{\partial \mathcal{E}}{\partial t} + \frac{P}{\gamma P} x \frac{\partial \mathcal{E}}{\partial x} = 0 \tag{6.4}$$

for the entropy function, subject to $\mathcal{E} = \mathcal{E}_b$ at $x = x_f$. The general solution is $\mathcal{E} = f(xP^{1/\gamma})$, where the function $f(\zeta)$ is determined from the relation

$$f(\zeta) = 1 + \frac{q}{P(\gamma - 1)/\gamma} \quad \text{for } \zeta = \left(P^{1/\gamma} - \frac{P_e - P}{P_e - 1}\right)L.$$
 (6.5)

Evidently, f(0) = 1 + q and $f(\zeta) \sim 1$ as $\zeta \to \infty$, but the values of interest are limited to ζ corresponding to $1 \le P < P_e$, with the end point determined by the parameters γ and q.

Next we examine the influences arising from the finite thickness of the flame. Evidently, the planar flame surface is not stretched; although it experiences normal strain, the strain rate $K_S = -\partial u/\partial x$ balances the dilatation rate resulting from gas compression such that $\mathbb{K} = K_S + \nabla \cdot \mathbf{v} = 0$. The flame thickness however decreases as the pressure rises and the influence of the internal structure on the flame speed, given by (5.5), diminishes in time. Equation (5.18) for the pressure simplifies to

$$\frac{\mathrm{d}P}{\mathrm{d}t} = \frac{\gamma q}{L} \left\{ M - \delta \left(\frac{T_a}{T_f} \right)^2 \frac{\beta (Le_{eff} - 1)}{2q} \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{PJ_2}{M} \right) \right\},\tag{6.6}$$

with the only changes at $O(\delta)$ resulting from non-unity Lewis number effects. Their contributions however are generally small and amount to less than 5 % for typical values



Figure 7. (a) The pressure P and (b) the mass burning rate m^* as a function of time, for a planar flame propagating in a closed channel, for various values of the heat release parameter q.

of δ and a wide range of Le_{eff}. The RH condition (5.9) combined with (5.19) yields

$$x_{f} = \left(1 - \frac{P_{e} - P}{P_{e} - 1}P^{-1/\gamma}\right)L + \frac{\delta}{q}\left(\frac{T_{f}J_{1}}{M} - \frac{T_{a}\widehat{J_{1}}}{P^{1/\gamma}}\right),$$
(6.7)

relating flame location to pressure. Although the gas velocity is affected to $O(\delta)$ by the corresponding variations in pressure, the velocity in the burned gas includes an additional correction resulting from the right-hand side of (5.13), such that

$$u = -\frac{\dot{P}}{\gamma P} x + \delta \lambda f'(x P^{1/\gamma}) \Big|_{x=0}^{x}, \quad 0 < x < x_{f},$$
(6.8)

where the prime in f' denotes differentiation with respect to the function's argument and λ at the wall is evaluated at $T(0) = P^{(\gamma-1)/\gamma}T_a$. Overall, the contributions arising from the internal flame structure on the propagation of a planar flame are small.

The results are illustrated in figures 7 and 8 for a representative value $\delta = 0.05$, starting with the solution of an unconfined planar flame at x = 0. Although the computations account for the $O(\delta)$ corrections, the solutions appear indistinguishable from their leading-order counterparts.

Figure 7 shows the dependence of the pressure P and burning rate m^* on time, for several values of the heat release parameter q. The pressure and burning rate, which at first grow linearly, increase rapidly after the flame has travelled beyond the middle of the vessel. Although the transition appears to occur earlier for larger values of q, the duration of flame propagation is also shortened. Note that the overall pressure increases by nearly ten fold, approaching $P_e = 1 + \gamma q$ when the flame reaches the end of the channel.

Density and temperature profiles at equal time intervals are shown in figure 8. The gas on both sides of the flame is compressed continuously as the pressure rises. In the unburned gas region the density and temperature remain spatially uniform but vary in time. The larger pressure translates primarily in increasing the density of the fresh mixture, which reaches a value of approximately five times its initial value, near the end of propagation. The temporally increasing temperature and density of the moving flame front are advected with the flow upstream such that their values in the burned gas region are no longer spatially uniform. A temperature gradient is established in the burned



Figure 8. (a) Density and (b) temperature profiles of a planar flame in a closed channel at equal time intervals, for a representative value q = 6.

gas region and is responsible for the re-illumination observed in photographic records of flames propagating in closed spherical bombs at the centre of the vessel, a phenomenon known as the Flamm-Mache effect (Flamm & Mache 1917; Lewis & von Elbe 1987). The finite temperature gradient observed at x = 0 can be smoothed out in a thin thermal boundary layer to ensure the adiabaticity condition at the wall.

Velocity profiles are plotted in figure 9(a) for the representative value q = 6. Initially the burned gas trapped between the flame and the left wall is at rest, the flame advances at a speed $\dot{x}_f \sim 1 + q$ and the fresh mixture is forced to the right at a constant velocity $u^* \sim q$. As the flame propagates forward, the fresh mixture is being forced against a denser gas causing it to slow down, gradually coming to rest at the end of the channel. The jump in velocity across the flame increases due to the higher flame temperature and the burned gas is swiftly advected away from the flame at an increasing speed. The flame propagation speed $\dot{x}_f = S_f + u^*$ results from a balance between the increasing flame speed and the gradual reduction in gas velocity ahead of the flame front. The flame speed S_f and propagation speed \dot{x}_f are shown in figure 9(b) for increasing values of q, starting respectively from 1 and 1 + q at time t = 0 to a common value when the flame reaches the end of the vessel and $u^* = 0$. Being an intrinsic property of the combustion process, the flame speed (dashed curves) increases continuously in time and is higher for larger values of heat release. The propagation speed (solid curves) on the other hand depends on the flow conditions, such that the flame accelerates throughout the vessel for low values of q and decelerates for large values of q. Indeed, the velocity profiles shown in figure 9(a)at equal time intervals demonstrate that the flame for q = 6 decelerates throughout the channel.

6.2. Spherical flame

We consider now the propagation of a centrally ignited flame in a closed spherical vessel of radius *L*, as shown in figure 6(*b*). The flame front is described by $\psi(r, t) = R(t) - r = 0$, such that 0 < r < R corresponds to the burned gas and R < r < L to the unburned gas region. The propagation speed is then given by $V_f = -\dot{R}$. The ratio of the flame surface area to the volume of the vessel, $\mathbb{A}_f/\mathbb{V} = 3R^2/L^3$, increases in time as the flame propagates outward.



Figure 9. Planar flames propagating in a closed channel: (a) velocity profiles at equal time intervals, for a representative value q = 6, and (b) flame speed S_f (dashed curves) and propagation speed \dot{x}_f (solid curves) as a function of time for various values of q.

To leading order, the gas velocity determined from (5.13) and satisfying u(0, t) = u(L, t) = 0 is given by

$$v(r,t) = \begin{cases} \frac{\dot{P}}{3\gamma P} \left(\frac{L^3}{r^2} - r\right), & R < r < L, \\ -\frac{\dot{P}}{3\gamma P}r, & 0 < r < R, \end{cases}$$
(6.9)

with the pressure obtained by solving $\dot{P} = 3\gamma qMR^2/L^3$ subject to P(0) = 1, and M given by (4.22). The RH relation $[[\rho(\dot{R} - v)]] = 0$ then yields the following expression for the flame position:

$$R(t) = \left(1 - \frac{P_e - P}{P_e - 1}P^{-1/\gamma}\right)^{1/3}L.$$
(6.10)

Determining the state of the burned gas requires solving the advection equation

$$\frac{\partial \mathcal{E}}{\partial t} - \frac{P}{3\gamma P} r \frac{\partial \mathcal{E}}{\partial r} = 0$$
(6.11)

for the entropy function, subject to $\mathcal{E} = \mathcal{E}_b$ at r = R. The general solution is $\mathcal{E} = f(rP^{1/3\gamma})$ where the function $f(\zeta)$ is obtained from the relation

$$f(\zeta) = 1 + \frac{q}{P^{(\gamma-1)/\gamma}} \quad \text{for } \zeta = \left(P^{1/\gamma} - \frac{P_e - P}{P_e - 1}\right)^{1/3} L.$$
(6.12)

Similar to the equivalent function for the planar solution, f(0) = 1 + q and $f(\zeta) \sim 1$ as $\zeta \to \infty$; its relevance is limited to values of ζ corresponding to $1 \le P \le P_e$.

Next, we examine the influences that result from the finite thickness of the flame. Unlike the planar flame, the surface of the spherical flame is stretched at a rate $\mathbb{K} = 2\dot{R}/R$ apparent from the fundamental expression (5.20). We recall that for a flame under confinement, the stretch rate is not a simple combination of curvature and strain, and is obtained only when combined with the volume dilatation rate. Moreover, the flame experiences normal strain

at different rates on the unburned and burned sides of the flame surface, given by

$$K_{S}^{u} = \frac{qM}{P} \left(\frac{2}{R} + \frac{R^{2}}{L^{3}}\right), \quad K_{S}^{b} = \frac{qM}{P} \frac{R^{2}}{L^{3}},$$
 (6.13*a*,*b*)

respectively. When substituted in (5.22) with the curvature term $(M/\rho)\kappa$ evaluated appropriately, one finds that

$$\mathbb{K} = \left(\frac{M}{P^{1/\gamma}} + \frac{qM}{P}\right)\frac{2}{R} - \frac{qM}{P}\frac{2R^2}{L^3} = \frac{2R}{R},\tag{6.14}$$

as expected. The flame speed is given by (5.5), with the corrections resulting from flame stretch most significant when the flame is relatively small. Equation (5.18) for the pressure simplifies to

$$\frac{\mathrm{d}P}{\mathrm{d}t} = \frac{3\gamma qR^2}{L^3} \left\{ M - \delta \left(\frac{T_a}{T_f}\right)^2 \frac{\beta (Le_{eff} - 1)}{2qR^2} \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{PJ_2}{M}R^2\right) \right\}$$
(6.15)

with the only changes at $O(\delta)$ resulting from non-unity Lewis number effects. As for the planar flame, their contribution is generally small for a wide range of Le_{eff} . The RH condition (5.9) combined with (5.19) yields the equation

$$R^{3} = \left(1 - \frac{P_{e} - P}{P_{e} - 1}P^{-1/\gamma}\right)L^{3} - \delta\left(\frac{3R^{2}}{q}\frac{T_{f}J_{1}}{M}\right)$$
(6.16)

relating the flame location to the pressure. The gas velocity is affected to $O(\delta)$ by the pressure variations, with an additional correction in the burned gas region resulting from the right-hand side of (5.13). One finds that

$$v(r,t) = -\frac{\dot{P}}{3\gamma P}r + \delta \left. \frac{\lambda}{P^{2/3\gamma}} f'(rP^{1/3\gamma}) \right|_{r=0}^{r}, \quad 0 < r < R,$$
(6.17)

where $\lambda = \lambda(T)$ is evaluated at the origin where $T(0) = P^{(\gamma-1)/\gamma}T_a$.

The results presented below correspond to a spherical flame evolving from a small unconfined flame kernel and, unless otherwise specified, $\delta = 0.05$. Although the computations account for the $O(\delta)$ corrections, their contributions are generally small except for the flame speed and propagation speed; the solutions of the state variables remain indistinguishable from their leading-order counterparts.

The dependence of the pressure level P on time is shown in figure 10(*a*) for several values of the heat release parameter q. The initial linear rise in P appears much slower than for a planar flame, but the sharp increase occurring after the flame has travelled beyond the middle of the vessel is more rapid, being proportional to the flame surface area R^2 . When increasing q, the transition appears to occur at an earlier time, but the duration of flame propagation is also shorter. Unlike the planar flame, the effect of flame stretch on the flame speed and, consequently, on the mass burning rate m^* is evident in figure 10(*b*). In the absence of stretch, with $P \sim 1$ during the early stages of propagation the flame speed would remain close to the laminar flame speed with $m^* \sim 1$. The incipient spherical flame, however, is highly stretched such that S_f , and consequently m^* , are significantly lower for practically all values of the unburned Markstein number \mathcal{M}_1 . This behaviour changes at later times due to the diminished effect of stretch on one hand and the pressure rise on the other.



Figure 10. The pressure *P* and burning rate m^* as a function of time, for a spherically expanding flame in a closed vessel at various values of the heat release parameter *q* and $Le_{eff} = 1$.



Figure 11. Density and temperature profiles of a spherical flame in a closed vessel at equal time intervals, for a representative value q = 6.

Profiles of density and temperature are shown in figure 11 at equal time intervals for the representative value of q = 6. The results are similar to those observed for planar flames. The gas on both sides of the flame is compressed continuously as the pressure rises. In the unburned gas the density and temperature remain spatially uniform, but vary in time. The pressure rise translates primarily in increasing the gas density with the temperature increasing only slightly. In the burned gas the density and temperature are no longer spatially uniform; the temporally varying temperature and density of the moving flame front are advected with the flow in the burned gas region. The temperature increases significantly reaching its maximum value at the centre of the vessel, as observed by Flamm & Mache (1917).

Velocity profiles at equal time intervals are shown in figure 12 for q = 6, $Le_{eff} = 1$ and two values of δ . The sharp discontinuity represents the flame location. Initially the burned gas is at rest and the propagating flame drives the fresh mixture ahead into motion. As the flame grows outwards, the velocity across the flame increases because of the higher flame temperature and the burned gas is swiftly advected away from the flame at an increasing speed. The fresh mixture that moves against a denser gas slows down, coming to rest at



Figure 12. Velocity profiles of a spherical flame propagating in a closed vessel at equal time intervals. The dashed lines correspond to the leading-order solution, absent of stretch effects, and the solid lines to the solution with $O(\delta)$ contributions included; for q = 6 and $Le_{eff} = 1$. Results are shown for (a) $\delta = 0.05$ and (b) $\delta = 0.001$.

the end of the vessel. Two profiles are shown at each time; the dashed curves correspond to the leading-order solution, absent of flame stretch effects, and the solid curves to the complete solution. For $\delta = 0.05$, the expanding stretched flame is seen to propagate slower, lagging behind the solution predicted in the absence of stretch. When stretch effects are underplayed, as for $\delta = 0.001$, the solutions with and without the $O(\delta)$ corrections appear closer.

We now consider the effects of flame stretch on the propagation speed and its dependence on the properties of the combustible mixture. It is instructive to examine first the simplifications that result when the flame propagates in a sufficiently large vessel $(L \gg 1)$. In this limit, the equation for the pressure takes the form

$$\frac{\mathrm{d}P}{\mathrm{d}t} \sim \frac{3\gamma q}{L^3} \left(1 - \delta \frac{\beta (Le_{eff} - 1)}{2} \hat{J}_2 \mathbb{K} \right) R^2, \tag{6.18}$$

with the velocity field given by

$$v(r,t) \sim q\left(1 - \delta \frac{\beta(Le_{eff} - 1)}{2} \hat{J}_2 \mathbb{K}\right) \begin{cases} \frac{R^2}{r^2} - \frac{R^2}{L^3} r, & R < r < L, \\ -\frac{R^2}{L^3} r, & 0 < r < R. \end{cases}$$
(6.19)

When $L \to \infty$, we recover the solution of a centrally ignited freely propagating spherical flame; the pocket of burned gas encompassed by the flame remains at rest, the unburned gas forced forward decays according to the inverse of the square of radial distance, and the flame propagation speed is given by

$$\dot{R} \sim (1+q) \left(1 - \delta \mathcal{M}_1^b \frac{2(1+q)}{R} \right).$$
 (6.20)

The propagation speed highlights the combined effects of stretch and differential diffusion, as shown in figure 13(*a*). In mixtures with $Le_{eff} > Le_{eff}^{cr}$, for which $\mathcal{M}_1^b > 0$, the spherical flame expands slower as compared with the unstretched flame (dashed line) and accelerates toward the asymptotic value $\dot{R} = 1 + q$, associated with the (burned) laminar flame speed. In mixtures with $Le_{eff} < Le_{eff}^{cr}$ the flame expands at a relatively faster rate that is gradually



Figure 13. Propagation speed of spherical flames for various Le_{eff} ; plots correspond to q = 6 and $\delta = 0.001$; the dashed line indicates the solution (leading-order) in the absence of stretch effects. (a) Freely propagating flame. (b) Propagation in a closed vessel.

reduced due to stretching and decelerates towards the asymptotic value R = 1 + q. This stretch-dominated behaviour was observed experimentally in various mixtures (Strehlow 1984; Kwon, Tseng & Faeth 1992; Beeckmann et al. 2017) by varying the equivalence ratio, and confirmed theoretically by Frankel & Sivashinsky (1983), Bechtold & Matalon (1987) and Addabbo *et al.* (2002). It persists when the propagation occurs in a closed vessel as illustrated in figure 13(b) for $\delta = 0.001$, but is limited to the early time before the flame encounters a significantly denser gas and slows down until reaching the end of the vessel. The intersection of the curves for various *Le_{eff}* with the dashed line corresponding to the leading-order solution occurs when the flame zone contributions vanish, namely at radii within $O(\delta)$ of each other. For $\delta = 0.05$, stretch effects extend to larger radii as shown in figure 14. For $Le_{eff} > Le_{eff}^{cr}$, the flame accelerates, reaches a peak at nearly the midway point to the vessel wall before slowing down, while for smaller values of Leeff, the flame undergoes monotonic deceleration throughout the bulk of the propagation. Finally, we note that the small increase in speed observed when $R \approx 100$ is due to the limitation of the model that does not account for the interaction of the flame zone with the vessel's walls.

Since the problem under consideration is inherently unsteady, it is appropriate to comment on the initial state of the mixture and its effect on the flame propagation. As noted earlier, the present theory does not describe the ignition event and assumes that a flame already exists at t = 0. However, when igniting the mixture, a small pocket of burned gas of radius R_0 and temperature T_a is first formed and then propagates outward. Accounting for this condition when integrating (2.21) leads to

$$P_e = 1 + \gamma q - \gamma q (R_0/L)^3, \tag{6.21}$$

which modifies the dependence of the flame size on pressure (6.16) to read

$$R^{3} = \left(1 - \frac{P_{e} - P}{\gamma q} P^{-1/\gamma}\right) L^{3} - \delta \left(\frac{3R^{2}}{q} \frac{T_{f}J_{1}}{M} - \frac{3R_{0}^{2}}{q} T_{a}\hat{J}_{1}P^{-1/\gamma}\right).$$
 (6.22)

Since the initial kernel of radius R_0 is of the order of the flame thickness δ , the correction term is extremely small and can be neglected.

Constant volume combustion chambers are commonly used in the laboratory to determine the laminar flame speed of different mixtures. In one approach, measurements

Flames in closed vessels



Figure 14. Propagation speed of spherical flames for various Le_{eff} ; plots correspond to q = 6 and $\delta = 0.05$; the dashed line indicates the solution (leading-order) in the absence of stretch effects.

of centrally ignited expanding flames are taken up to a limited distance and the laminar flame speed is determined by extrapolating the data to the zero-stretch limit; namely from the asymptotic value $\dot{R} = 1 + q$ shown in figure 13(a). Data are collected during the early stages of propagation when pressure rise is minimal so that the burned gas enclosed by the flame remains essentially at rest and, thus, $\dot{R} = S_f^b$. The laminar flame speed is then given by $S_f = (\rho_b/\rho_u)S_f^b$ with ρ_b and ρ_u taken as constants. However, unless the experimental set-up ensures that the ambient pressure remains constant, the results may be tainted by small pressure changes, effects due to compression and by the inward flow of burned gas that becomes substantial when the flame grows bigger as shown in figure 12. The present theory provides a means for estimating these effects in sufficiently large chambers. The dependence of the flame radius on the pressure level given by (6.10), and the gas velocity in the burned gas given by (6.9), may be used to more accurately determine the distance where measurements can be taken without being significantly affected by fluid motion and compressibility effects. Figure 13(b) illustrates a scenario where the laminar flame speed can be reasonably estimated from measurements taken up to $R \approx 30$, in contrast to the conditions presented in figure 14.

Another approach to determine the laminar flame speed involves the use of smaller spherical vessels with thick walls that can accommodate higher pressures. Transducers measure the pressure history as the flame propagates outward, and flame location, propagation speed and flow velocities are then determined from theoretically derived relationships, which are essentially the leading-order expressions presented here. Our theory provides corrections to these quantities that account for effects resulting from the internal flame structure, as given by (6.16) and (6.17). When included in data extrapolation these contributions may lead to better accuracy.

The same reasoning to the aforementioned comments applies to the determination of the Markstein length that, as the present theory demonstrates, is affected by the rise in pressure and flame temperature. Additionally, the experimental pursuit may be hampered by onset of the hydrodynamic instability that may be enhanced by the attenuated influence of diffusion on the thinner flames that result under confinement.

7. The Newtonian limit

A formal asymptotic approach of the flame zone analysis can be carried out when adopting the Newtonian limit $(\gamma - 1)/\gamma \ll 1$, in lieu of the delta-function model used above. It requires adopting the distinguished limit

$$(\gamma - 1)/\gamma = \epsilon \hat{\gamma},\tag{7.1}$$

with $\epsilon = \beta_0^{-1} \ll 1$. Here we use ϵ as the perturbation parameter to avoid confusion with β_0 treated earlier in the delta-function model as a finite parameter.

We start by examining the implication of the Newtonian limit on the solution in the hydrodynamic zones. The entropy in the homogeneous fresh mixture remains constant, $\mathcal{E} = 1$, while in the burned gas it is given by $\mathcal{E} = T_a + \epsilon \hat{\gamma} \mathcal{E}_1 + \cdots$, with \mathcal{E}_1 determined by solving

$$\frac{\mathrm{D}\mathcal{E}_1}{\mathrm{D}t} = 0 \quad \text{subject to } \mathcal{E}_1|_{\psi=0^+} = -q\ln P.$$
(7.2)

The density and temperature are then given by

$$\rho \sim \begin{cases}
P - \epsilon \hat{\gamma} P \ln P, & \psi(\mathbf{x}, t) < 0, \\
\frac{P}{T_a} - \epsilon \hat{\gamma} \left(\frac{P}{T_a} \ln P + \frac{P}{T_a^2} \mathcal{E}_1(\mathbf{x}, t) \right), & \psi(\mathbf{x}, t) > 0, \\
T \sim \begin{cases}
1 + \epsilon \hat{\gamma} \ln P, & \psi(\mathbf{x}, t) < 0, \\
T_a + \epsilon \hat{\gamma} (T_a \ln P + \mathcal{E}_1(\mathbf{x}, t)), & \psi(\mathbf{x}, t) > 0,
\end{cases}$$
(7.3)

with the flame temperature given by $T_f \sim T_a + \epsilon \hat{\gamma} \ln P$. Gas compression leads to a pressure rise that minimally affects the temperature but, as shown below, alters the burning rate in a more meaningful way.

The solution in the flame zone requires, as before, introducing the stretching transformation (4.8), expanding all variables in powers of δ and seeking solutions that match those in the hydrodynamic zones as $\eta \to \mp \infty$. Instead of replacing the reaction rate by a Dirac delta function, the thin reaction zone centred near $\eta = 0$ is now resolved on the $\hat{\eta} = \eta/\epsilon$ scale, with $\epsilon \ll \delta$. The equations in the flame zone that do not contain explicitly the reaction rate term, can be directly integrated with respect to $\hat{\eta}$ to provide, through matching, the jump conditions (4.14) across $\eta = 0$. The exception is the energy equation that determines the jump in the temperature gradient. To this end, we retain the near-equidiffusion and near-stoichiometric assumptions and expand the temperature and mass fractions about their values at $\eta = 0$, such that

$$T = T_{a} + \epsilon(\hat{\gamma} \ln P + \theta(\hat{\eta}, \xi_{1}, \xi_{2}, t)) + \cdots,$$

$$T + qY_{D}/Y_{D_{0}} = T_{a} + \epsilon(\hat{\gamma} \ln P + \hat{h}_{D}(\hat{\eta}, \xi_{1}, \xi_{2}, t)) + \cdots,$$

$$T + qY_{E}/\nu Y_{D_{0}} = T_{a} + \epsilon(\hat{\gamma} \ln P + q\varphi + \hat{h}_{E}(\hat{\eta}, \xi_{1}, \xi_{2}, t)) + \cdots.$$
(7.4)

where use has been made of $Y_{E_0} = \nu Y_{D_0}(1 + \epsilon \varphi)$. Being conserved scalars, the enthalpies satisfy $\partial^2 \hat{h}_i / \partial \hat{\eta}^2 = 0$, and the bounded solutions remain independent of $\hat{\eta}$ such that

$$\hat{h}_D = h_D(0, \xi_1, \xi_2, t) \equiv h_D^*, \quad \hat{h}_E = h_E(0, \xi_1, \xi_2, t) \equiv h_E^*.$$
 (7.5*a*,*b*)

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As a consequence, the energy equation simplifies to

$$-\frac{\partial^2 \theta}{\partial \hat{\eta}^2} = \Lambda(h_D^* - \theta)(h_E^* + q\varphi - \theta) \exp(\theta/T_a^2),$$

$$\Lambda = \frac{q^2 P^{2+\hat{\gamma}/T_a^2}}{4T_a^6(1 + q\varphi/2T_a^2)} = O(1),$$
(7.6)

consisting of a balance between the diffusion and chemical reaction rates. The associated matching conditions are

$$\frac{\partial \theta}{\partial \hat{\eta}} \sim \frac{\partial T}{\partial \eta} \bigg|_{\eta=0^{-}} \quad \text{as } \hat{\eta} \to -\infty, \quad \frac{\partial \theta}{\partial \hat{\eta}} \sim 0, \quad \theta \sim h_D^* \quad \text{as } \hat{\eta} \to +\infty, \tag{7.7}$$

where the latter results from the fact that $T(\eta, \xi_1, \xi_2, t)$ for $\eta > 0$ is, to leading order, independent of η , and h_D^* is effectively the perturbation of the flame temperature in the post-reaction region. A first integral of (7.6) can be obtained after multiplying both sides of the equation by $\partial \theta / \partial \hat{\eta}$. Using the matching conditions (7.7) one finds that

$$\left. \left(\frac{\partial T}{\partial \eta} \right)^2 \right|_{\eta=0^-} = 2\Lambda \int_{-\infty}^{h_D^*} (h_D^* - \theta) (h_E^* + q\varphi - \theta) \exp(\theta/T_a^2) \,\mathrm{d}\theta$$
$$= 2\Lambda T_a^4 (h_E^* - h_D^* + q\varphi + 2T_a^2) \exp(h_D^*/T_a^2), \tag{7.8}$$

which can be expressed as a jump relation for the temperature gradient across the action zone ($\eta = 0$), namely

$$\left[\frac{\partial T}{\partial \eta}\right] = -qP^{1+\hat{\gamma}/2T_a^2} \sqrt{\frac{1+(h_E^*-h_D^*+q\varphi)/2T_a^2}{1+q\varphi/2T_a^2}} \exp(h_D^*/2T_a^2).$$
(7.9)

The jump in the temperature gradient (4.15) adopted in the delta-function model is a straightforward generalization of this relation.

The solution in the flame zone can be easily deduced from the results derived in § 4 by taking the limit $(\gamma - 1)/\gamma \ll 1$ and will not be repeated here. The resulting leading-order expressions for pressure and burning rate are

$$\frac{\mathrm{d}P}{\mathrm{d}t} \sim \frac{q\mathbb{A}_f}{\mathbb{V}} P^{\alpha}, \quad M \sim P^{\alpha}, \tag{7.10a,b}$$

with $\alpha = 1 + \hat{\gamma}/2T_a^2$. A closed form solution can then be obtained for the planar flame, for which $\mathbb{A}_f/\mathbb{V} = 1/L$. One finds that

$$P = \left(\frac{L}{L - q(\alpha - 1)t}\right)^{1/(\alpha - 1)}, \quad M = \left(\frac{L}{L - q(\alpha - 1)t}\right)^{\alpha/(\alpha - 1)}, \quad (7.11a,b)$$

consistent with the results shown in figure 7. The flame location and propagation speed are given by

$$x_f = \frac{1+q}{q} \frac{P-1}{P} L, \quad \dot{x}_f = (1+q)P^{\alpha-2}.$$
 (7.12*a*,*b*)

Similar to the observations in figure 9(*b*), when propagating forward, the flame accelerates for $\alpha > 2$ (small values of *q*) and decelerates for $\alpha < 2$ (large values of *q*); steady

propagation results when $\alpha = 2$. For the spherical flame, $\mathbb{A}_f/\mathbb{V} = 3R^2/L^3$ and when integrated numerically, (7.10*a*,*b*) yield results that are consistent with those in the previous section. Here too, steady propagation results when $\alpha = 2$, with $\dot{R} = 1 + q$ and $P = (1 - qT_a^2t^3/L^3)^{-1}$.

8. Conclusions

A general theory of premixed flames propagating in closed vessels is developed using a multi-scale approach that exploits the disparity in length scales associated with the fluid dynamics, diffusion and chemical reactions. The formulation reduces the problem to the analysis of a free boundary fluid dynamical problem, where the free boundary is the flame surface that separates burned gases from the unburned combustible mixture. By resolving the internal structure of the flame zone, explicit expressions for the flame speed and temperature, and their dependence on the flow and mixture conditions are derived. The flame speed is shown to be modified by the voluminal stretch rate, which quantifies the deformation of a volume element of the flame zone that results from the motion of the flame and the underlying flow field, and by the rate of pressure rise. Both effects are modulated by Markstein numbers of the order of the flame thickness that depend on the heat release, mixture composition and diffusion properties of the reactants, while capturing the effects of temperature-dependent transport and stoichiometry. The flame temperature rises above the adiabatic flame temperature as a result of the pressure buildup, with a weak dependence on the Lewis number of the deficient reactant. Integration across the entire volume of the vessel yields an equation for the pressure buildup and its dependence on the burning rate and mixture properties. The determination of the flow field and the evolution of the flame surface are strongly coupled. The fluid velocity is affected by the progressive increase in density and temperature resulting from the combined effects of heat release, adiabatic compression and pressure buildup, while the instantaneous shape and location of the flame surface relies on the local flow conditions through the stretch rate, and on the pressure and mixture compositions through the Markstein numbers.

The present hydrodynamic theory differs significantly from that of freely propagating flames. Unlike the latter where the flame propagates under nearly isobaric conditions and its structure remains quasi-steady, combustion in a closed vessel is accompanied by an increase in pressure that leads to a decrease in flame thickness and a diminishing effect of its influence on the propagation. The temperature along the flame surface exceeds the adiabatic flame temperature, and keeps increasing in the burned gas region due to adiabatic compression. The flame speed depends not only on the conventional stretch rate, which measures the distortion of the flame surface, but also on the rate of decrease of the flame thickness, as well as on the rate of pressure buildup. The flow field ahead and behind the confined flame is strongly affected by gas compression. Although thermo-diffusive effects are captured by Markstein numbers, similar to the freely propagating flame theory, these are now pressure dependent and in some circumstances may change sign during the course of propagation.

To illustrate the richness of the current theory, we employ it to study the propagation of a planar flame in a rectangular channel and a centrally ignited expanding flame in a spherical vessel, demonstrating the role of compression and heat release on the burning rate and flame speed, and the effect of confinement on the flow field induced by the flame motion. During the early stages of propagation, the pressure rise is moderate and the flame propagates in a quasi-steady manner. When the flame reaches a distance of roughly one third of the vessel's size, the sharp increase in pressure results in an appreciable

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increase in burning rate. Influences resulting from the internal flame structure are primarily manifested through flame stretch and have therefore a minimal effect on the unstretched planar flame. Spherical flames on the other hand are found to accelerate or decelerate for different Lewis numbers during the initial stage of propagation when stretch effects are substantial, before they inevitably decelerate due to gas compression. The fundamental insights will serve to guide the experimental effort, since measurements of flame speed and Markstein length are often carried out in constant volume chambers.

The hydrodynamic model is amenable to further the study of flames of arbitrary shape within closed vessels of general configuration. The detailed analysis presented in this study identifies the causes and effects of various mechanisms involved in the combustion process and permits the construction of instructive models to numerically simulate the evolution of multi-dimensional and corrugated flames in closed vessels. The main limitation is the assumption that variations inside the flame zone due to enhanced chemistry or turbulence, which could potentially alter its internal structure, are not physically resolved. Though the model represents general chemical reactions via a single overall step, it is valid where chemical kinetic parameters such as the activation energy remain fairly constant with pressure rise. It is also limited to cases where the overall kinetics are not substantially affected by drastic increases in pressure and temperature (Westbrook *et al.* 2009), mixing with burned products (Dagan *et al.* 2019) or a high degree of turbulence (Aspden, Day & Bell 2015). Future studies will leverage the model to analyse the stability properties of confined flames and their propagation in turbulent media of moderate intensity, neither of which are currently well understood.

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Author ORCIDs.

Gautham Krishnan https://orcid.org/0000-0002-5044-9688;

Moshe Matalon https://orcid.org/0000-0003-3022-9343.

Author contributions. All authors contributed equally to theoretical derivations, reaching conclusions and in writing the paper.

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