TOTAL MEAN CURVATURE SURFACES IN THE PRODUCT SPACE $\mathbb{S}^n \times \mathbb{R} \text{ AND APPLICATIONS}$

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Abstract The total mean curvature functional for submanifolds into the Riemannian product space $\mathbb{S}^n \times \mathbb{R}$ is considered and its first variational formula is presented. Later on, two second-order differential operators are defined and a nice integral inequality relating both of them is proved. Finally, we prove our main result: an integral inequality for closed stationary \mathcal{H} -surfaces in $\mathbb{S}^n \times \mathbb{R}$, characterizing the cases where the equality is attained.

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1. Introduction

Along the last decades, integral inequalities have become an interesting tool for the study of rigidity results for closed submanifolds immersed in Riemannian spaces. In this setting, we point out that the first contribution in this thematic was given in the 60s by Simons [14] who computed the Laplacian of the squared norm of the second fundamental form σ of a minimal submanifold in the sphere. As a consequence, he showed that if Σ^m is a closed minimal submanifold in \mathbb{S}^n , the following integral inequality holds:

$$\int_{\Sigma} |\sigma|^2 \left(|\sigma|^2 - c(n,m) \right) d\Sigma \ge 0 \quad \text{with} \quad c(n,m) = \frac{m(n-m)}{2(n-m)-1}, \tag{1.1}$$

where $d\Sigma$ is the volume element on Σ^m . Simons noticed that the inequality (1.1) provides a natural gap concerning the size of the squared norm of the second fundamental form. Indeed, if the second fundamental form satisfies $0 \leq |\sigma|^2 \leq c(n,m)$, then either $|\sigma|^2 = 0$ and Σ^m is totally geodesic, so a sphere \mathbb{S}^m , or $|\sigma|^2 = c(n,m)$. This last equality was

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studied by Chern, do Carmo and Kobayashi [5], who concluded that in this case, Σ^m is necessarily a Cliffod torus or a Veronese surface in \mathbb{S}^4 . It is worth pointing out that the case of co-dimension 1 was also studied simultaneous and independently by Lawson [10]. Nowadays, the inequality (1.1) is known as the Simons integral inequality.

On the other hand, an interesting line of research is to study which submanifolds are critical points of certain geometric functionals. In this scenario, let us highlight three classical different functionals. First, Chen considered in [4] the following functional for closed surfaces Σ^2 in \mathbb{R}^3 :

$$\widetilde{\mathcal{W}}(\Sigma) = \frac{1}{2} \int_{\Sigma} |\phi|^2 \,\mathrm{d}\Sigma = \int_{\Sigma} (H^2 - K) \,\mathrm{d}\Sigma, \tag{1.2}$$

where $\phi = A - HI$ is the umbilicity tensor of Σ , A denotes the shape operator of Σ and H and K stand for the mean and Gaussian curvature of Σ , respectively. Closely related to Equation (1.2), we can consider the well-known Willmore energy or Willmore functional given by

$$\mathcal{W}(\Sigma) = \int_{\Sigma} H^2 \,\mathrm{d}\Sigma. \tag{1.3}$$

In fact, because of the classical Gauss–Bonnet theorem, both functionals $\widetilde{\mathcal{W}}$ and \mathcal{W} have the same critical points in the set of closed surfaces in \mathbb{R}^3 . Associated to Equation (1.3), there is the famous Willmore conjecture, proposed in 1965 by Willmore [16] and solved in 2014 by Marques and Neves [12], which guarantees that the value of $\mathcal{W}(\Sigma)$ is at least $2\pi^2$ when Σ^2 is an immersed torus into \mathbb{R}^3 .

Finally, another interesting functional, the *total mean curvature* functional, was introduced by Chen [3] for any closed submanifold Σ^m in the Euclidean space \mathbb{R}^n :

$$\mathcal{H}(\Sigma) = \int_{\Sigma} H^m \,\mathrm{d}\Sigma. \tag{1.4}$$

Chen proved that \mathcal{H} is bounded from below by the volume of the unit *m*-sphere, being the equality attained precisely when the submanifold is the unit *m*-sphere. The total mean curvature functional has also been considered for submanifolds in other ambient spaces. In the case of closed submanifolds in the sphere \mathbb{S}^n , \mathcal{H} is bounded from below by zero and the equality is attached at all closed minimal submanifolds of \mathbb{S}^n . Considering the variational problem associated to such functional, it is said that a submanifold Σ^m is an \mathcal{H} -submanifold if it is a stationary point for the functional \mathcal{H} . In this context, Guo and Yin [9] established an integral inequality relating the total umbilicity tensor and the Euler characteristic $\chi(\Sigma)$ of a closed \mathcal{H} -surface Σ^2 immersed in \mathbb{S}^n :

$$\int_{\Sigma} \left\{ |\phi|^2 \left(1 - \left(2 - \frac{1}{n-2} \right) |\phi|^2 \right) + 2 \right\} d\Sigma \le 4\pi\chi(\Sigma)$$
(1.5)

being the equality achieved if and only if Σ^2 is either a totally geodesic 2-sphere, a Clifford torus in \mathbb{S}^3 or a Veronese surface in \mathbb{S}^4 .

Considering more general ambient spaces, recently the first and third authors computed in [1] the Euler–Lagrange equation of a suitable Willmore functional for closed

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immersed surfaces in an homogeneous space $\mathbb{E}^3(\kappa, \tau)$. As an application, they developed a Simons-type integral inequality for such surfaces, characterizing the surfaces for which the equality holds as Clifford or Hopf tori of the ambient space. Furthermore, recently, the last two authors obtained an integral inequality for closed immersed submanifolds Σ^m into the product space $\mathbb{S}^n \times \mathbb{R}$ having parallel normalized mean curvature vector field [7]. They also showed that, in this case, the equality is attained if and only if Σ^m is isometric to either a totally umbilical sphere or to a certain family of Clifford tori in a totally geodesic sphere \mathbb{S}^{m+1} of \mathbb{S}^n .

In the spirit of the previous results, we will obtain the Euler-Lagrange equation of the total mean curvature functional for closed immersed surfaces into the product space $\mathbb{S}^n \times \mathbb{R}$, Proposition 2. As a consequence, we will get a Simons-type integral inequality and we will characterize when the equality is attained. Specifically, if ϕ and ϕ_h stand for the umbilicity tensor of Σ^m , and the umbilicity tensor related to the mean curvature vector field h, respectively, and T denotes the tangential part of the vector field ∂_t in $\mathbb{S}^n \times \mathbb{R}$, the main aim of the paper is to prove the following result:

Theorem 1. Let Σ^2 be a closed immersed \mathcal{H} -surface into the product space $\mathbb{S}^n \times \mathbb{R}$. Then,

$$\int_{\Sigma} \left\{ |\phi|^2 \left(1 - 5|T|^2 - \frac{3}{2}|\phi|^2 \right) - 2(|\phi_h| + 1)|T|^2 + 2 \right\} \, \mathrm{d}\Sigma \le 4\pi\chi(\Sigma). \tag{1.6}$$

In particular, the equality holds if and only if Σ^2 is isometric to either

(i) a slice $\mathbb{S}^2 \times \{t_0\}$, or

- (ii) a totally geodesic 2-sphere or a Clifford torus in $\mathbb{S}^3 \times \{t_0\}$, or
- (iii) a Veronese surface in $\mathbb{S}^4 \times \{t_0\}$,

for some $t_0 \in \mathbb{R}$.

On the one hand, let us remark that, since given $m, n \in \mathbb{N}$, m < n, the unit sphere \mathbb{S}^m is a totally geodesic submanifold of the unit sphere \mathbb{S}^n , the above surfaces for which the equality in Equation (1.6) is attained are in fact surfaces of the product $\mathbb{S}^n \times \mathbb{R}$ in general dimension. On the other hand, let us also observe that Equation (1.6) do not depend on the co-dimension. Besides that, in the case where Σ^2 is contained in a slice of $\mathbb{S}^n \times \mathbb{R}$, T = 0. Thus, Equation (1.6) reduces to

$$\int_{\Sigma} \left\{ |\phi|^2 \left(1 - \frac{3}{2} |\phi|^2 \right) + 2 \right\} \, \mathrm{d}\Sigma \le 4\pi \chi(\Sigma), \tag{1.7}$$

which in the case n = 4 coincides with Guo and Yin's inequality [Equation (1.5)], and it improves it when n > 4.

2. Preliminaries

In this section, we will present some basic facts about the product manifold $\mathbb{S}^n \times \mathbb{R}$, as well as a suitable Simons-type formula for submanifolds immersed in such product.

As usual, let \mathbb{R}^{n+2} be the (n+2)-dimensional Euclidean space. Then, the product space $\mathbb{S}^n \times \mathbb{R}$ is defined as the following subset of \mathbb{R}^{n+2} :

$$\mathbb{S}^n \times \mathbb{R} = \{ (x_1, \dots, x_{n+2}) \in \mathbb{R}^{n+2}; \ x_1^2 + \dots + x_{n+1}^2 = 1 \}$$
(2.1)

equipped with the induced metric from the Euclidean space, \langle, \rangle , that is, $\mathbb{S}^n \times \mathbb{R}$ is the usual product of the unit sphere $\mathbb{S}^n(1)$ and the real line. Associated to it,

$$\partial_t := (\partial/\partial_t)\big|_{(p,t)}, \qquad (p,t) \in \mathbb{S}^n \times \mathbb{R},$$
(2.2)

is a parallel and unitary vector field, that is,

$$\overline{\nabla}\partial_t = 0 \quad \text{and} \quad \langle \partial_t, \partial_t \rangle = 1,$$
(2.3)

where $\overline{\nabla}$ is the Levi-Civita connection of $\mathbb{S}^n \times \mathbb{R}$.

Concerning the curvature tensor of $\mathbb{S}^n \times \mathbb{R}$, it is well known that it satisfies (see [6])

$$R(X,Y)Z = \langle X, Z \rangle Y - \langle Y, Z \rangle X + \langle Z, \partial_t \rangle (\langle Y, \partial_t \rangle X - \langle X, \partial_t \rangle Y) + (\langle Y, Z \rangle \langle X, \partial_t \rangle - \langle X, Z \rangle \langle Y, \partial_t \rangle) \partial_t,$$
(2.4)

where $X, Y, Z \in \mathfrak{X}(\mathbb{S}^n \times \mathbb{R})$ and \overline{R} is defined by (see [13])

$$\overline{R}(X,Y)Z = \overline{\nabla}_{[X,Y]}Z - [\overline{\nabla}_X,\overline{\nabla}_Y]Z.$$
(2.5)

Let us consider Σ^m an *m*-dimensional submanifold of $\mathbb{S}^n \times \mathbb{R}$ and let us also denote by \langle , \rangle the induced metric on Σ^m . In this setting, we will denote by ∇ the Levi-Civita connection of Σ^m and ∇^{\perp} will stand for the normal connection of Σ^m in $\mathbb{S}^n \times \mathbb{R}$. We will denote by σ the second fundamental form of Σ^m in $\mathbb{S}^n \times \mathbb{R}$ and by A_{ξ} the Weingarten operator associated to a fixed normal vector field $\xi \in \mathfrak{X}(\Sigma)^{\perp}$. We note that for each $\xi \in \mathfrak{X}(\Sigma)^{\perp}$, A_{ξ} is a symmetric endomorphism of the tangent space $T_p\Sigma$ at $p \in \Sigma^m$. Moreover, A_{ξ} and σ are related by

$$\langle \sigma(X,Y),\xi\rangle = \langle A_{\xi}(X),Y\rangle \tag{2.6}$$

for all $X, Y \in \mathfrak{X}(\Sigma)$ and $\xi \in \mathfrak{X}(\Sigma)^{\perp}$. We also recall that the Gauss and Weingarten formulas of Σ^m in $\mathbb{S}^n \times \mathbb{R}$ are given by

$$\overline{\nabla}_X Y = \nabla_X Y + \sigma(X, Y) \quad \text{and} \quad \overline{\nabla}_X \xi = -A_{\xi}(X) + \nabla_X^{\perp} \xi, \tag{2.7}$$

for all $X, Y \in \mathfrak{X}(\Sigma)$ and $\xi \in \mathfrak{X}(\Sigma)^{\perp}$.

Since $\partial_t \in \mathfrak{X}(\mathbb{S}^n \times \mathbb{R})$, it can be decomposed along Σ^m as

$$\partial_t = T + N, \tag{2.8}$$

where $T := \partial_t^{\top}$ and $N := \partial_t^{\perp}$ denote, respectively, the tangent and normal part of the vector field ∂_t on the tangent and normal bundle of the submanifold Σ^m in $\mathbb{S}^n \times \mathbb{R}$.

Moreover, from Equations (2.3) and (2.8), we get the relation

$$1 = \langle \partial_t, \partial_t \rangle = |T|^2 + |N|^2, \tag{2.9}$$

 $|\cdot|$ being the norm related to the metric \langle, \rangle . It is clear that if T vanishes identically along Σ , then ∂_t is normal to Σ^m and hence Σ^m lies in a slice $\mathbb{S}^n \times \{t_0\}, t_0 \in \mathbb{R}$. Besides that, a direct computation from Equations (2.3) and (2.7) gives

 $\nabla_X T = A_N(X)$ and $\nabla_X^{\perp} N = -\sigma(T, X)$, for all $X \in \mathfrak{X}(\Sigma)$. (2.10)

A well-known fact is that the curvature tensor R of Σ^m can be described in terms of its second fundamental form σ and the curvature tensor \overline{R} of the ambient space $\mathbb{S}^n \times \mathbb{R}$ by the so-called *Gauss equation*, which is given by

$$\langle R(X,Y)Z,W \rangle = \langle \overline{R}(X,Y)Z,W \rangle + \langle \sigma(X,Z),\sigma(Y,W) \rangle - \langle \sigma(Y,Z),\sigma(X,W) \rangle$$

$$= \langle X,Z \rangle \langle Y,W \rangle - \langle Y,Z \rangle \langle X,W \rangle + \langle Z,T \rangle (\langle Y,T \rangle \langle X,W \rangle - \langle X,T \rangle \langle Y,W \rangle)$$

$$+ (\langle Y,Z \rangle \langle X,T \rangle - \langle X,Z \rangle \langle Y,T \rangle) \langle T,W \rangle$$

$$+ \langle \sigma(X,Z),\sigma(Y,W) \rangle - \langle \sigma(Y,Z),\sigma(X,W) \rangle$$

$$(2.11)$$

for all $X, Y, Z, W \in \mathfrak{X}(\Sigma)$, and the *Codazzi equation*

$$(\nabla_Y^{\perp}\sigma)(X,Z) - (\nabla_X^{\perp}\sigma)(Y,Z) = (\overline{R}(X,Y)Z)^{\perp} = (\langle Y,Z \rangle \langle X,T \rangle - \langle X,Z \rangle \langle Y,T \rangle) N \quad (2.12)$$

for all $X, Y, Z \in \mathfrak{X}(\Sigma)$, where $\nabla^{\perp} \sigma$ satisfies

$$(\nabla_X^{\perp}\sigma)(Y,Z) = \nabla_X^{\perp}\sigma(Y,Z) - \sigma(\nabla_X Y,Z) - \sigma(Y,\nabla_X Z).$$
(2.13)

Let us denote by h the mean curvature vector field of Σ^m in $\mathbb{S}^n \times \mathbb{R}$, defined by

$$h = \frac{1}{m} \operatorname{tr}(\sigma) \tag{2.14}$$

and by *H* its norm, that is, $H^2 = \langle h, h \rangle$. It is immediate to check that if $\{e_{m+1}, \ldots, e_{n+1}\}$ is an orthonormal frame of $\mathfrak{X}(\Sigma)^{\perp}$, we can write Equation (2.14) in the following way:

$$h = \sum_{\alpha} H^{\alpha} e_{\alpha} \quad \text{where } H^{\alpha} := \frac{1}{m} \operatorname{tr}(A_{\alpha}) = \langle h, e_{\alpha} \rangle, \tag{2.15}$$

and $A_{\alpha} := A_{e_{\alpha}}$. In particular, $mH^2 = \operatorname{tr}(A_h)$.

Next, for any normal vector field ξ , let us define the tensor ϕ_{ξ} as the traceless part of A_{ξ} , i.e. $\phi_{\xi} := A_{\xi} - \frac{1}{m} \operatorname{tr}(A_{\xi})I$. We shall also consider ϕ the traceless part of σ , given by

$$\phi(X,Y) := \sigma(X,Y) - \langle X,Y \rangle h. \tag{2.16}$$

The tensors ϕ and ϕ_{ξ} are also known as the umbilicity tensor and the umbilicity tensor related to ξ of Σ^m , respectively. It is easy to check that

$$|\phi|^2 = |\sigma|^2 - mH^2$$
 and $|\phi_{\xi}|^2 = |A_{\xi}|^2 - m\langle\xi, h\rangle^2$. (2.17)

Observe that $|\phi|^2 = 0$ if and only if Σ^m is a totally umbilical submanifold of $\mathbb{S}^n \times \mathbb{R}$.

We end this section by recalling the following two results, which we shall use later in this paper. The first one is a Simons-type formula proved in [7, 8]. It should be noticed that, for the sake of simplicity, in Proposition 1 and, in general, along this manuscript, we will naturally identify, at convenience, the Weingarten operator with its associated symmetric matrix.

Proposition 1. Let Σ^m be a submanifold in the product space $\mathbb{S}^n \times \mathbb{R}$. Then

$$\frac{1}{2}\Delta|\sigma|^{2} = |\nabla^{\perp}\sigma|^{2} + m\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}) + m|\phi_{N}|^{2} - 2m\sum_{\alpha} |\phi_{\alpha}(T)|^{2} + (m - |T|^{2})|\phi|^{2} - m\langle\phi_{h}(T), T\rangle + \sum_{\alpha,\beta} \operatorname{tr}(A_{\beta})\operatorname{tr}(A_{\alpha}^{2}A_{\beta}) - \sum_{\alpha,\beta} \left(N(A_{\alpha}A_{\beta} - A_{\beta}A_{\alpha}) + [\operatorname{tr}(A_{\alpha}A_{\beta})]^{2}\right),$$
(2.18)

where $\phi_{\alpha} := \phi_{e_{\alpha}}, m+1 \leq \alpha, \beta \leq n+1 \text{ and } N(B) := \operatorname{tr}(BB^{t})$ for all matrix B.

The second one is an algebraic lemma which was proved in [11].

Lemma 1. Let B_1, \ldots, B_p , where $p \ge 2$, be symmetric $m \times m$ matrices. Then

$$\sum_{\alpha,\beta=1}^{p} \left(N(B_{\alpha}B_{\beta} - B_{\beta}B_{\alpha}) + [\operatorname{tr}(B_{\alpha}B_{\beta})]^{2} \right) \le \frac{3}{2} \left(\sum_{\alpha=1}^{p} N(B_{\alpha}) \right)^{2}.$$
 (2.19)

3. The first variation of the total mean curvature

The goal of this section is to study the stationary points of the functional \mathcal{H} , defined in (1.4), for closed surfaces in $\mathbb{S}^n \times \mathbb{R}$. To that end, we will recall the rough Laplacian $\Delta^{\perp} : \mathfrak{X}(\Sigma)^{\perp} \to \mathfrak{X}(\Sigma)^{\perp}$, which is defined by setting

$$\Delta^{\perp}\xi := \operatorname{tr}(\nabla^2 \xi) = \sum_i \nabla^{\perp}_{e_i} \nabla^{\perp}_{e_i} \xi, \qquad (3.1)$$

where $\{e_1, \ldots, e_m\}$ is any orthonormal frame of $\mathfrak{X}(\Sigma)$.

Now, let us compute the first variational formula of \mathcal{H} .

Proposition 2. Let $x : \Sigma^m \to \mathbb{S}^n \times \mathbb{R}$ be an isometrically immersed closed submanifold. Then x is a stationary point of \mathcal{H} , or an \mathcal{H} -submanifold, if and only if

$$H^{m-2}\left(\Delta^{\perp}h + \left(m - |T|^2 - mH^2\right)h - m\langle N, h\rangle N + \sum_{\alpha,\beta} H^{\alpha} \operatorname{tr}(A_{\alpha}A_{\beta})e_{\beta}\right) = 0, \quad (3.2)$$

for m > 2, and

$$\Delta^{\perp}h + \left(2 - |T|^2 - 2H^2\right)h - 2\langle N, h\rangle N + \sum_{\alpha,\beta} H^{\alpha} \operatorname{tr}(A_{\alpha}A_{\beta})e_{\beta} = 0, \qquad (3.3)$$

in the case m = 2, where $m + 1 \le \alpha, \beta \le n + 1$.

Proof. Let us consider a variation of x, that is, a smooth map $X : \Sigma^m \times (-\varepsilon, \varepsilon) \to \mathbb{S}^n \times \mathbb{R}$ satisfying that for each $s \in (-\varepsilon, \varepsilon)$, the map $X_s : \Sigma^m \to \mathbb{S}^n \times \mathbb{R}$, given by $X_s(p) = X(p, s)$, is an immersion and $X_0 = x$. Then, we can compute the first variation of \mathcal{H} along X, that is,

$$\left. \frac{\mathrm{d}}{\mathrm{d}s} \mathcal{H}(X_s) \right|_{s=0} = \int_{\Sigma} \left. \frac{\mathrm{d}}{\mathrm{d}s} \left(H_s^m \,\mathrm{d}\Sigma_s \right) \right|_{s=0},\tag{3.4}$$

where, for each $s \in (-\varepsilon, \varepsilon)$, $H_s = \sqrt{\langle h_s, h_s \rangle}$ stands for the norm of the mean curvature vector of Σ^m in $\mathbb{S}^n \times \mathbb{R}$ with respect to the metric induced by X_s and $d\Sigma_s$ denotes its volume element.

On the one hand, let us compute $\left. \frac{\mathrm{d}}{\mathrm{d}s} H_s^m \right|_{s=0}$. For the sake of simplicity, let us denote $v = \mathrm{d}/\mathrm{d}s$. We claim that

$$\frac{m}{2}v(H_s^2)\bigg|_{s=0} = \langle mh - |T|^2h - m\langle N, h\rangle N + \sum_{\alpha,\beta} H^{\alpha}\operatorname{tr}(A_{\alpha}A_{\beta})e_{\beta}, v^{\perp}\rangle + \frac{m}{2}v^{\top}(H^2) + \langle h, \Delta^{\perp}v^{\perp}\rangle.$$
(3.5)

Let us assume now that m > 2. Then,

$$v(H_s^m) = v((H_s^2)^{\frac{m}{2}}) = \frac{m}{2} H_s^{m-2} v(H_s^2)$$
(3.6)

and, consequently,

$$\left. v(H_s^m) \right|_{s=0} = H^{m-2} \langle mh - |T|^2 h - m \langle N, h \rangle N + \sum_{\alpha, \beta} H^{\alpha} \operatorname{tr}(A_{\alpha} A_{\beta}) e_{\beta}, v^{\perp} \rangle$$

$$+ H^{m-2} \left(\frac{m}{2} v^{\top} (H^2) + \langle h, \Delta^{\perp} v^{\perp} \rangle \right).$$

$$(3.7)$$

Total mean curvature surfaces in the product space $\mathbb{S}^n \times \mathbb{R}$ and applications 353 Furthermore, by using [15, Lemma 5.4] (see also [2, Lemma 4.2]), we have

$$v(\mathrm{d}\Sigma_s)\Big|_{s=0} = \left(-m\langle h, v^{\perp}\rangle + \operatorname{div}(v^{\top})\right) \,\mathrm{d}\Sigma.$$
(3.8)

Therefore, along Σ^m , m > 2, it holds

$$\begin{aligned} v(H_s^m \,\mathrm{d}\Sigma_s) \Big|_{s=0} &= v(H_s^m) \Big|_{s=0} \mathrm{d}\Sigma + H^m v(\mathrm{d}\Sigma_s) \Big|_{s=0} \\ &= \left\{ H^{m-2} \left(\langle mh - |T|^2 h - m \langle N, h \rangle N - mH^2 h, v^\perp \rangle \right) \right\} \,\mathrm{d}\Sigma \\ &+ \left\{ H^{m-2} \left(\sum_{\alpha,\beta} H^\alpha \mathrm{tr}(A_\alpha A_\beta) \langle e_\beta, v^\perp \rangle + \langle h, \Delta^\perp v^\perp \rangle \right. \\ &+ \operatorname{div}(H^m v^\top) \right) \right\} \,\mathrm{d}\Sigma, \end{aligned}$$
(3.9)

where Equations (3.7) and (3.8) have been used and the fact that

$$\operatorname{div}(H^{m}v^{\top}) = \frac{m}{2}H^{m-2}v^{\top}(H^{2}) + H^{m}\operatorname{div}(v^{\top}).$$
(3.10)

Consequently,

$$\frac{\mathrm{d}}{\mathrm{d}s} \int_{\Sigma} H_s^m \,\mathrm{d}\Sigma_s \bigg|_{s=0} = \int_{\Sigma} H^{m-2} \langle \Delta^{\perp} v^{\perp}, h \rangle \,\mathrm{d}\Sigma + \int_{\Sigma} H^{m-2} \sum_{\alpha,\beta} H^{\alpha} \operatorname{tr}(A_{\alpha} A_{\beta}) \langle e_{\beta}, v^{\perp} \rangle \,\mathrm{d}\Sigma - \int_{\Sigma} H^{m-2} \left(\langle |T|^2 h - mh + m \langle N, h \rangle N + mH^2 h, v^{\perp} \rangle \right) \,\mathrm{d}\Sigma.$$
(3.11)

Hence, x is a stationary point of \mathcal{H} if and only if

$$H^{m-2}\left(\Delta^{\perp}h - |T|^{2}h + mh - m\langle N, h\rangle N - mH^{2}h + \sum_{\alpha,\beta} H^{\alpha}\mathrm{tr}(A_{\alpha}A_{\beta})e_{\beta}\right) = 0. \quad (3.12)$$

The case m=2 follows with an analogous argument using Equation (3.5) instead of Equation (3.7).

It remains to prove the claim. By (2.14),

$$mv(H_s^2) = \sum_i \langle (\overline{\nabla}_v A_{hs}) e_i, e_i \rangle = \sum_i \langle \overline{\nabla}_v A_{hs}(e_i), e_i \rangle - \sum_i \langle A_{hs}(\overline{\nabla}_v e_i)^\top, e_i \rangle, \quad (3.13)$$

for any $\{e_1, \ldots, e_m\}$ orthonormal frame of $\mathfrak{X}(\Sigma)$. In particular, given $p \in \Sigma$, we can choose locally a totally geodesic frame, that is, $(\nabla_{e_i} e_j)(p) = 0$ for all $1 \leq i, j \leq m$.

Although in the following we will work at p, by simplicity, we will omit the point. Let us denote

$$I = \sum_{i} \langle \overline{\nabla}_{v} A_{h_{s}}(e_{i}), e_{i} \rangle \quad \text{and} \quad II = \sum_{i} \langle A_{h_{s}}(\overline{\nabla}_{v} e_{i})^{\top}, e_{i} \rangle$$
(3.14)

and let us compute both terms separately. From Equation (2.7) and the fact that $[v, e_i] = \overline{\nabla}_v e_i - \overline{\nabla}_{e_i} v = 0$, we have

$$\begin{split} I &= -\sum_{i} \langle \overline{\nabla}_{v} \overline{\nabla}_{e_{i}} h_{s}, e_{i} \rangle + \sum_{i} \langle \overline{\nabla}_{v} \nabla_{e_{i}}^{\perp} h_{s}, e_{i} \rangle \\ &= \sum_{i} \langle \overline{R}(v, e_{i}) h_{s}, e_{i} \rangle - \sum_{i} \langle \overline{\nabla}_{e_{i}} \overline{\nabla}_{v} h_{s}, e_{i} \rangle - \sum_{i} \langle \nabla_{v} h_{s}, \overline{\nabla}_{e_{i}} e_{i} \rangle \\ &= \sum_{i} \langle \overline{R}(v, e_{i}) h_{s}, e_{i} \rangle - \sum_{i} e_{i} \langle \overline{\nabla}_{v} h_{s}, e_{i} \rangle + \sum_{i} \langle \overline{\nabla}_{v} h_{s}, \overline{\nabla}_{e_{i}} e_{i} \rangle - \sum_{i} \langle \nabla_{e_{i}}^{\perp} h_{s}, \overline{\nabla}_{e_{i}} v \rangle \\ &= \sum_{i} \langle \overline{R}(v, e_{i}) h_{s}, e_{i} \rangle + \sum_{i} e_{i} \langle h_{s}, \overline{\nabla}_{v} e_{i} \rangle + \sum_{i} \langle \overline{\nabla}_{v} h_{s}, \sigma(e_{i}, e_{i}) \rangle - \sum_{i} \langle \nabla_{e_{i}}^{\perp} h_{s}, \sigma(e_{i}, v^{\top}) \rangle \\ &- \sum_{i} \langle \nabla_{e_{i}}^{\perp} h_{s}, \nabla_{e_{i}}^{\perp} v^{\perp} \rangle \\ &= \sum_{i} \langle \overline{R}(v, e_{i}) h_{s}, e_{i} \rangle + \sum_{i} e_{i} \langle h_{s}, \sigma(e_{i}, v^{\top}) \rangle + \sum_{i} e_{i} \langle h_{s}, \nabla_{e_{i}}^{\perp} v^{\perp} \rangle \\ &- \sum_{i} \langle \nabla_{e_{i}}^{\perp} h_{s}, \sigma(v^{\top}, e_{i}) \rangle - \sum_{i} \langle \nabla_{e_{i}}^{\perp} h_{s}, \nabla_{e_{i}}^{\perp} v^{\perp} \rangle \\ &= \sum_{i} \langle \overline{R}(v, e_{i}) h_{s}, e_{i} \rangle + \sum_{i} \langle h_{s}, \nabla_{e_{i}}^{\perp} \sigma(v^{\top}, e_{i}) \rangle + \langle h_{s}, \Delta^{\perp} v^{\perp} \rangle + \frac{m}{2} v(H_{s}^{2}), \end{split}$$
(3.15)

where we have also used Equations (2.14) and (3.1).

From the Codazzi equation (2.12) it holds that

$$\nabla_{e_i}^{\perp} \sigma(v^{\top}, e_i) = (\nabla_{e_i}^{\perp} \sigma)(v^{\top}, e_i) + \sigma(e_i, \nabla_{e_i} v^{\top})$$
$$= (\overline{R}(v^{\top}, e_i)e_i)^{\perp} + (\nabla_{v^{\top}}^{\perp} \sigma)(e_i, e_i) + \sigma(e_i, \nabla_{e_i} v^{\top}).$$
(3.16)

Inserting Equation (3.16) in Equation (3.15),

$$I = \sum_{i} \langle \overline{R}(v^{\perp}, e_{i})h_{s}, e_{i} \rangle + \sum_{i} \langle h_{s}, \nabla_{v^{\top}}^{\perp} \sigma(e_{i}, e_{i}) + \sigma(e_{i}, \nabla_{e_{i}}v^{\top}) \rangle + \langle h_{s}, \Delta^{\perp}v^{\perp} \rangle + \frac{m}{2}v(H_{s}^{2})$$
$$= \sum_{i} \langle \overline{R}(v^{\perp}, e_{i})h_{s}, e_{i} \rangle + \frac{m}{2}v^{\top}(H_{s}^{2}) + \sum_{i} \langle A_{hs}(e_{i}), \nabla_{e_{i}}v^{\top} \rangle + \langle h_{s}, \Delta^{\perp}v^{\perp} \rangle + \frac{m}{2}v(H_{s}^{2}).$$
(3.17)

For the second expression of (3.14), it is not difficult to check that

$$II = \sum_{i} \langle A_{hs} (\overline{\nabla}_{v} e_{i})^{\top}, e_{i} \rangle$$

$$=\sum_{i} \langle A_{hs}(\overline{\nabla}_{e_{i}}v^{\top} + \overline{\nabla}_{e_{i}}v^{\perp}), e_{i} \rangle = \sum_{i} \langle A_{hs}(\nabla_{e_{i}}v^{\top}), e_{i} \rangle - \operatorname{tr}(A_{hs}A_{v^{\perp}}).$$
(3.18)

Therefore,

$$\frac{m}{2}v(H_s^2) = \sum_i \langle \overline{R}(v^{\perp}, e_i)h_s, e_i \rangle + \frac{m}{2}v^{\top}(H_s^2) + \langle h_s, \Delta^{\perp}v^{\perp} \rangle + \operatorname{tr}(A_{hs}A_{v^{\perp}}); \quad (3.19)$$

thus,

$$\frac{m}{2}v(H_s^2)|_{s=0} = \sum_i \langle \overline{R}(v^\perp, e_i)h, e_i \rangle + \frac{m}{2}v^\top (H^2) + \langle h, \Delta^\perp v^\perp \rangle + \operatorname{tr}(A_h A_{v^\perp}).$$
(3.20)

On the other hand, writing $v^{\perp} = \sum_{\beta} \langle v^{\perp}, e_{\beta} \rangle e_{\beta}$ and $h = \sum_{\alpha} H^{\alpha} e_{\alpha}$, from Equation (2.14), we get

$$A_{h} = \sum_{\alpha} H^{\alpha} A_{\alpha} \quad \text{and} \quad A_{v^{\perp}} = \sum_{\beta} \langle v^{\perp}, e_{\beta} \rangle A_{\beta}.$$
(3.21)

Hence,

$$\operatorname{tr}(A_h A_{v\perp}) = \sum_{\alpha,\beta} H^{\alpha} \operatorname{tr}(A_{\alpha} A_{\beta}) \langle v^{\perp}, e_{\beta} \rangle.$$
(3.22)

Besides this, from Equation (2.4),

$$\sum_{i=1}^{m} \langle \overline{R}(v^{\perp}, e_i)h, e_i \rangle = \langle mh - |T|^2 h - m \langle N, h \rangle N, v^{\perp} \rangle.$$
(3.23)

So, the claim is proved by replacing Equations (3.22) and (3.23) into Equation (3.20). \Box

It is not difficult to see that minimal submanifolds are stationary points of the total mean curvature functional \mathcal{H} . In fact, Equation (3.2) is trivial for minimal submanifolds and Equation (3.3) is also satisfied since H = 0 implies that the mean curvature vector field h vanishes identically at Σ^m . Let us prove that minimal submanifolds are the only stationary points in the class of totally umbilical submanifolds contained in a slice of $\mathbb{S}^n \times \mathbb{R}$. To that end, we need to present first the following auxiliary result.

Lemma 2. If Σ^m is a totally umbilical submanifold contained in a slice of $\mathbb{S}^n \times \mathbb{R}$, then the mean curvature vector field is parallel in the normal bundle.

Proof. From umbilicity, Equation (2.16) gives

$$\sigma(X,Y) = \langle X,Y \rangle h, \qquad X,Y \in \mathfrak{X}(\Sigma). \tag{3.24}$$

Hence, a direct computation from the Codazzi equation (2.12) yields

$$(\langle Y, Z \rangle \langle X, T \rangle - \langle X, Z \rangle \langle Y, T \rangle) N = \langle X, Z \rangle \nabla_Y^{\perp} h - \langle Y, Z \rangle \nabla_X^{\perp} h, \qquad (3.25)$$

for all $X, Y, Z \in \mathfrak{X}(\Sigma)$. Since Σ^m is contained in a slice, T = 0, so from Equation (3.25)

$$\langle Y, Z \rangle \nabla_X^{\perp} h = \langle X, Z \rangle \nabla_Y^{\perp} h$$
 (3.26)

for all $X, Y, Z \in \mathfrak{X}(\Sigma)$. Therefore, choosing Y = Z orthogonal to X, we conclude that h is parallel in the normal bundle.

As a consequence of the previous result, we get the following corollary.

Corollary 1. Let Σ^m be a totally umbilical submanifold contained in a slice of $\mathbb{S}^n \times \mathbb{R}$. Then, Σ^m is an \mathcal{H} -submanifold of $\mathbb{S}^n \times \mathbb{R}$ if and only if it is totally geodesic.

Proof. Let Σ^m be a submanifold of $\mathbb{S}^n \times \mathbb{R}$ under the assumptions of the corollary. From Lemma 2 it follows that $\nabla^{\perp} h = 0$. Furthermore, since Σ^m is contained in a slice, T = 0. Thus, using Equation (2.10) and the assumption of umbilicity, we have

$$0 = \langle A_N(X), Y \rangle = \langle \sigma(X, Y), N \rangle = \langle X, Y \rangle \langle h, N \rangle$$
(3.27)

for all $X, Y \in \mathfrak{X}(\Sigma)$, so $\langle h, N \rangle = 0$. Besides that, the umbilicity of Σ^m also implies that, for every $m + 1 \leq \alpha \leq n + 1$, it holds that $A_{\alpha}(X) = \langle h, e_{\alpha} \rangle X$.

Hence, the first variational formula for \mathcal{H} in Proposition 2 becomes

$$0 = H^{m-2} \left(mh - mH^2h + m\sum_{\alpha} \langle h, e_{\alpha} \rangle^2 h \right) = mH^{m-2}h$$
(3.28)

if m > 2 and simply h = 0 in the case m = 2. In any case, it is immediate to check that Σ^m is a \mathcal{H} -submanifold if and only if it is minimal. Thus, from umbilicity, if and only if it is totally geodesic.

4. Two key lemmas

Associated to the second fundamental form of Σ^m , let us consider the following operator $P: \mathfrak{X}(\Sigma) \times \mathfrak{X}(\Sigma) \to \mathfrak{X}(\Sigma)^{\perp}$ by setting

$$P(X,Y) = m\langle X,Y\rangle h - \sigma(X,Y).$$
(4.1)

We observe that P is symmetric and tr(P) = m(m-1)h. Concerning P, let us consider the following second-order differential operator:

$$\Box^*: \mathfrak{X}(\Sigma)^{\perp} \to \mathcal{C}^{\infty}(\Sigma) \tag{4.2}$$

given by

$$\Box^*(\xi) = \langle P, \nabla^2 \xi \rangle, \tag{4.3}$$

where \langle , \rangle denotes the Hilbert–Schmidt inner product. We observe that for each $\alpha \in \{m+1, n+1\}$, by Equation (4.1), it holds that

$$\langle P(X,Y), e_{\alpha} \rangle = m \langle X, Y \rangle \langle h, e_{\alpha} \rangle - \langle \sigma(X,Y), e_{\alpha} \rangle$$

= $m \langle X, Y \rangle H^{\alpha} - \langle A_{\alpha}(X), Y \rangle,$ (4.4)

which motivates the definition of the operator $P_{\alpha} : \mathfrak{X}(\Sigma) \to \mathfrak{X}(\Sigma)$ given by $P_{\alpha} = mH^{\alpha}I - A_{\alpha}$. It is immediate to see that P_{α} is symmetric, $\operatorname{tr}(P_{\alpha}) = m(m-1)H^{\alpha}$ and

$$\sum_{\alpha} \operatorname{tr}(P_{\alpha})e_{\alpha} = m(m-1)\sum_{\alpha} H^{\alpha}e_{\alpha} = m(m-1)h = \operatorname{tr}(P).$$
(4.5)

We can also define another second differential operator

$$\Box: \mathcal{C}^{\infty}(\Sigma) \to \mathfrak{X}(\Sigma)^{\perp}$$
(4.6)

such that

$$\Box(f) = \sum_{\alpha} \operatorname{tr}(P_{\alpha} \circ \operatorname{Hess} f) e_{\alpha}.$$
(4.7)

The following result gives a relation between both operators \Box^* and \Box .

Lemma 3. Let Σ^m be a closed submanifold in the product space $\mathbb{S}^n \times \mathbb{R}$. Then

$$\int_{\Sigma} f \,\Box^*(\xi) \,\mathrm{d}\Sigma = \int_{\Sigma} \langle \Box(f), \xi \rangle \,\mathrm{d}\Sigma + (m-1) \int_{\Sigma} \left(f \langle \nabla_T^{\perp} \xi, N \rangle - \langle N, \xi \rangle \langle \nabla f, T \rangle \right) \,\mathrm{d}\Sigma \quad (4.8)$$

for all $f \in \mathcal{C}^2(\Sigma)$ and $\xi \in T\Sigma^{\perp}$.

Proof. Let $p \in \Sigma^m$ and $\{e_1, \ldots, e_m\}$ be an orthonormal frame of $\mathfrak{X}(\Sigma)$ on a neighbourhood $U \subset \Sigma^m$ of p, geodesic at p, that is, $(\nabla_{e_i} e_j)(p) = 0$ for all $1 \leq i, j \leq m$. By using the Hilbert–Schmidt inner product, we have

$$f \Box^{*}(\xi) = f \langle P, \nabla^{2} \xi \rangle = f \sum_{i,j} \langle P(e_{i}, e_{j}), \nabla^{2} \xi(e_{i}, e_{j}) \rangle$$

$$= \sum_{i,j} e_{j} \left(f \langle P(e_{i}, e_{j}), \nabla^{\perp}_{e_{i}} \xi \rangle \right) - \sum_{i,j} e_{i} \left(e_{j}(f) \langle P(e_{i}, e_{j}), \xi \rangle \right)$$

$$- f \sum_{i,j} \langle \nabla^{\perp}_{e_{j}} P(e_{i}, e_{j}), \nabla^{\perp}_{e_{i}} \xi \rangle + \sum_{i,j} e_{i}(e_{j}(f)) \langle P(e_{i}, e_{j}), \xi \rangle$$

$$+ \sum_{i,j} e_{j}(f) \langle \nabla^{\perp}_{e_{i}} P(e_{i}, e_{j}), \xi \rangle.$$

$$(4.9)$$

On the other hand, by a direct computation

$$\sum_{i,j} e_i(e_j(f)) \langle P(e_i, e_j), \xi \rangle = m \sum_{i,j} e_i(e_j(f)) \delta_{ij} \langle h, \xi \rangle - \sum_{i,j} e_i(e_j(f)) \langle \sigma(e_i, e_j), \xi \rangle$$
$$= m \Delta f \langle h, \xi \rangle - \sum_{\alpha, i, j} e_i(e_j(f)) \langle A_\alpha(e_i), e_j \rangle \langle e_\alpha, \xi \rangle$$
$$= \sum_{\alpha} (m H^\alpha \Delta f - \operatorname{tr}(A_\alpha \circ \operatorname{Hess} f)) \langle e_\alpha, \xi \rangle$$
$$= \sum_{\alpha} \operatorname{tr}(P_\alpha \circ \operatorname{Hess} f) \langle e_\alpha, \xi \rangle = \langle \Box(f), \xi \rangle, \qquad (4.10)$$

where $\delta_{ij} = \langle e_i, e_j \rangle$. Inserting Equation (4.10) in Equation (4.9), we get

$$f\Box^{*}(\xi) = \langle \Box(f), \xi \rangle - f \sum_{i,j} \langle \nabla_{e_{j}}^{\perp} P(e_{i}, e_{j}), \nabla_{e_{i}}^{\perp} \xi \rangle + \sum_{i,j} e_{j}(f) \langle \nabla_{e_{i}}^{\perp} P(e_{i}, e_{j}), \xi \rangle$$
$$+ \sum_{i,j} e_{j} \left(f \langle P(e_{i}, e_{j}), \nabla_{e_{i}}^{\perp} \xi \rangle \right) - \sum_{i,j} e_{i} \left(e_{j}(f) \langle P(e_{i}, e_{j}), \xi \rangle \right).$$
(4.11)

We observe that the last expressions in Equation (4.11) can be seen as divergences, that is,

$$\sum_{i,j} \operatorname{div} \left(e_j(f) \langle P(e_i, e_j), \xi \rangle e_i \right) = \sum_{i,j} e_j(f) \langle P(e_i, e_j), \xi \rangle \operatorname{div}(e_i) + \sum_{i,j} e_i \left(e_j(f) \langle P(e_i, e_j), \xi \rangle \right)$$

$$(4.12)$$

and

$$\sum_{i,j} \operatorname{div} \left(f \langle P(e_i, e_j), \nabla_{e_i}^{\perp} \xi \rangle e_j \right) = f \sum_{i,j} \langle P(e_i, e_j), \nabla_{e_i}^{\perp} \xi \rangle \operatorname{div}(e_j) + \sum_{i,j} e_j \left(f \langle P(e_i, e_j), \nabla_{e_i}^{\perp} \xi \rangle \right).$$
(4.13)

Since at $p \in \Sigma^m$ it holds $\operatorname{div}(e_i)(p) = 0$ for any $1 \leq i \leq m$, we obtain

$$\sum_{i,j} \operatorname{div} \left(f \langle P(e_i, e_j), \nabla_{e_i}^{\perp} \xi \rangle e_j - e_j(f) \langle P(e_i, e_j), \xi \rangle e_i \right)$$
$$= \sum_{i,j} e_j \left(f \langle P(e_i, e_j), \nabla_{e_i}^{\perp} \xi \rangle \right) - \sum_{i,j} e_i \left(e_j(f) \langle P(e_i, e_j), \xi \rangle \right).$$
(4.14)

Now, by using the Codazzi equation (2.12),

$$\langle \nabla_{e_j}^{\perp} P(e_i, e_j), \nabla_{e_i}^{\perp} \xi \rangle = m \delta_{ij} \langle \nabla_{e_j}^{\perp} h, \nabla_{e_i}^{\perp} \xi \rangle - \langle \nabla_{e_i}^{\perp} \sigma(e_j, e_j), \nabla_{e_i}^{\perp} \xi \rangle + \langle \overline{R}(e_i, e_j) \nabla_{e_i}^{\perp} \xi, e_j \rangle$$

$$= m \delta_{ij} \langle \nabla_{e_j}^{\perp} h, \nabla_{e_i}^{\perp} \xi \rangle - \langle \nabla_{e_i}^{\perp} \sigma(e_j, e_j), \nabla_{e_i}^{\perp} \xi \rangle$$

$$+ \langle \nabla_{e_i}^{\perp} \xi, N \rangle \left(\langle e_j, T \rangle \delta_{ij} - \langle e_i, T \rangle \right),$$

$$(4.15)$$

and hence

$$f\sum_{i,j} \langle \nabla_{e_j}^{\perp} P(e_i, e_j), \nabla_{e_i}^{\perp} \xi \rangle = -(m-1)f \langle \nabla_T^{\perp} \xi, N \rangle.$$
(4.16)

In a similar way,

$$\sum_{i,j} e_j(f) \langle \nabla_{e_i}^{\perp} P(e_i, e_j), \xi \rangle = -(m-1) \langle N, \xi \rangle \langle \nabla f, T \rangle.$$
(4.17)

Replacing Equations (4.14), (4.16) and (4.17) all in Equation (4.11),

$$f\Box^{*}(\xi) = \langle \Box(f), \xi \rangle + \sum_{i,j} \operatorname{div} \left(f \langle P(e_{i}, e_{j}), \nabla_{e_{i}}^{\perp} \xi \rangle e_{j} - e_{j}(f) \langle P(e_{i}, e_{j}), \xi \rangle e_{i} \right)$$

$$+ (m-1) \left(f \langle \nabla_{T}^{\perp} \xi, N \rangle - \langle N, \xi \rangle \langle \nabla f, T \rangle \right).$$

$$(4.18)$$

It is worth pointing that the expression in the divergence term is independent of the chosen frame. Finally, by using the divergence theorem, we obtain the desired result. \Box

In particular, taking $f \equiv 1$ in Lemma 3, we get the following:

Corollary 2. Let Σ^m be a closed submanifold in the product space $\mathbb{S}^n \times \mathbb{R}$. Then, for all $\xi \in \mathfrak{X}(\Sigma)^{\perp}$,

$$\int_{\Sigma} \Box^*(\xi) \,\mathrm{d}\Sigma = (m-1) \int_{\Sigma} \langle \nabla_T^{\perp} \xi, N \rangle \,\mathrm{d}\Sigma.$$
(4.19)

The next result gives a Hiusken-type inequality for submanifolds in $\mathbb{S}^n \times \mathbb{R}$.

Lemma 4. If Σ^m is a submanifold in the product space $\mathbb{S}^n \times \mathbb{R}$, then

$$|\nabla^{\perp}\sigma|^2 \ge \frac{m}{m+2} \left(3m|\nabla^{\perp}h|^2 + 4(m-1)\langle\nabla^{\perp}_Th,N\rangle \right).$$
(4.20)

Proof. Let $F : \mathfrak{X}(\Sigma)^3 \to \mathfrak{X}(\Sigma)^{\perp}$ be the tensor defined by

$$F(X,Y,Z) = \nabla_{Z}^{\perp}\sigma(X,Y) + a\left(\langle Y,Z\rangle\nabla_{X}^{\perp}h + \langle X,Z\rangle\nabla_{Y}^{\perp}h + \langle X,Y\rangle\nabla_{Z}^{\perp}h\right)$$
(4.21)

for a given $a \in \mathbb{R}$. Let us compute its norm. A direct computation gives

$$\langle F(X,Y,Z), F(X,Y,Z) \rangle = \langle \nabla_Z^{\perp} \sigma(X,Y), \nabla_Z^{\perp} \sigma(X,Y) \rangle + 2aQ_1(X,Y,Z) + a^2Q_2(X,Y,Z),$$
(4.22)

where

$$Q_1(X,Y,Z) = \langle Y,Z \rangle \langle \nabla_X^{\perp}h, \nabla_Z^{\perp}\sigma(X,Y) \rangle + \langle X,Z \rangle \langle \nabla_Y^{\perp}h, \nabla_Z^{\perp}\sigma(X,Y) \rangle + \langle X,Y \rangle \langle \nabla_Z^{\perp}h, \nabla_Z^{\perp}\sigma(X,Y) \rangle,$$
(4.23)

and

$$Q_{2}(X,Y,Z) = \left(\langle Y,Z \rangle^{2} \langle \nabla_{X}^{\perp}h, \nabla_{X}^{\perp}h \rangle + \langle X,Z \rangle^{2} \langle \nabla_{Y}^{\perp}h, \nabla_{Y}^{\perp}h \rangle + \langle X,Y \rangle^{2} \langle \nabla_{Z}^{\perp}h, \nabla_{Z}^{\perp}h \rangle \right) + 2 \langle Y,Z \rangle \langle X,Z \rangle \langle \nabla_{X}^{\perp}h, \nabla_{Y}^{\perp}h \rangle + 2 \langle Y,Z \rangle \langle X,Y \rangle \langle \nabla_{X}^{\perp}h, \nabla_{Z}^{\perp}h \rangle + 2 \langle X,Z \rangle \langle X,Y \rangle \langle \nabla_{Y}^{\perp}h, \nabla_{Z}^{\perp}h \rangle.$$

$$(4.24)$$

Given $p \in \Sigma^m$ and $\{e_1, \ldots, e_m\}$ an orthonormal frame of $\mathfrak{X}(\Sigma)$ on a neighbourhood $U \subset \Sigma^m$ of p, which is geodesic at p, it is not difficult to check that

$$\sum_{i,j,k} \langle \nabla_{e_k}^{\perp} \sigma(e_i, e_j), \nabla_{e_k}^{\perp} \sigma(e_i, e_j) \rangle = |\nabla^{\perp} \sigma|^2 \quad \text{and} \quad \sum_{i,j,k} Q_2(e_i, e_j, e_k) = 3(m+2) |\nabla^{\perp} h|^2.$$

$$(4.25)$$

Besides that, from the Codazzi equation (2.12), we have

$$\sum_{i,j,k} Q_1(e_i, e_j, e_k) = \sum_{i,j,k} \left(\delta_{jk} \langle \nabla_{e_i}^{\perp} h, \nabla_{e_k}^{\perp} \sigma(e_i, e_j) \rangle + \delta_{ik} \langle \nabla_{e_j}^{\perp} h, \nabla_{e_k}^{\perp} \sigma(e_i, e_j) \rangle + \delta_{ij} \langle \nabla_{e_k}^{\perp} h, \nabla_{e_k}^{\perp} \sigma(e_i, e_j) \rangle \right)$$

$$= 3m |\nabla^{\perp} h|^2 + 2(m-1) \sum_i \langle e_i, T \rangle \langle \nabla_{e_i}^{\perp} h, N \rangle$$

$$= 3m |\nabla^{\perp} h|^2 + 2(m-1) \langle \nabla_T^{\perp} h, N \rangle.$$
(4.26)

Hence,

$$|F|^{2} = |\nabla^{\perp}\sigma|^{2} + 2a\left(3m|\nabla^{\perp}h|^{2} + 2(m-1)\langle\nabla^{\perp}h,N\rangle\right) + 3a^{2}(m+2)|\nabla^{\perp}h|^{2}.$$
 (4.27)

Taking a = -m/(m+2), we obtain Equation (4.20).

5. Proof of Theorem 1

From now on, we will deal with \mathcal{H} -surfaces immersed in the product space $\mathbb{S}^n \times \mathbb{R}$. Before proving our main result, Theorem 1, we need the following auxiliary proposition.

Proposition 3. Let Σ^2 be an \mathcal{H} -surface in the product space $\mathbb{S}^n \times \mathbb{R}$. Then, we have

$$\int_{\Sigma} \left(|\nabla^{\perp} \sigma|^2 + 2\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}) \right) \, \mathrm{d}\Sigma \ge \int_{\Sigma} \left(2\langle N, h \rangle^2 - (2 - |T|^2 + |\phi|^2) H^2 \right) \, \mathrm{d}\Sigma.$$
(5.1)

Proof. First, taking into account the definition of P, a direct computation gives us

$$\begin{split} \langle P, \nabla^2 \xi \rangle &= \sum_{i,j} \langle P(e_i, e_j), \nabla^2 \xi(e_i, e_j) \rangle \\ &= 2 \sum_{i,j} \delta_{ij} \langle h, \nabla^2 \xi(e_i, e_j) \rangle - \sum_{i,j} \langle \sigma(e_i, e_j), \nabla^2 \xi(e_i, e_j) \rangle \end{split}$$

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$$= 2\langle h, \Delta^{\perp}\xi \rangle - \sum_{i,j} \langle \sigma(e_i, e_j), \nabla^2\xi(e_i, e_j) \rangle,$$
(5.2)

for any orthonormal frame $\{e_1, e_2\}$ of $\mathfrak{X}(\Sigma)$. Furthermore, with a similar reasoning as the one in Equation (4.10), we get

$$\sum_{i,j} \langle \sigma(e_i, e_j), \nabla^2 \xi(e_i, e_j) \rangle = \sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} \xi^{\alpha}),$$
(5.3)

where $\xi^{\alpha} := \langle \xi, e_{\alpha} \rangle$. Therefore,

$$\Box^*(\xi) = 2\langle h, \Delta^{\perp}\xi \rangle - \sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess}\xi^{\alpha}).$$
(5.4)

Making $\xi = 2h$ in Equation (5.4), we write

$$\Box^*(2h) = 4\langle \Delta^{\perp}h, h \rangle - 2\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess}H^{\alpha}).$$
(5.5)

On the other hand, by using the following identity

$$\frac{1}{2}\Delta H^2 = \langle \Delta^{\perp} h, h \rangle + |\nabla^{\perp} h|^2, \qquad (5.6)$$

Equation (5.5) reads

$$\Box^*(2h) = \langle \Delta^{\perp}h, h \rangle + \frac{3}{2}\Delta H^2 - 3|\nabla^{\perp}h|^2 - 2\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}).$$
(5.7)

By using Lemma 4 in the case m = 2,

$$-3|\nabla^{\perp}h|^2 \ge -|\nabla^{\perp}\sigma|^2 + 2\langle\nabla_T^{\perp}h,N\rangle.$$
(5.8)

Hence,

$$\Box^*(2h) \ge \langle \Delta^{\perp}h, h \rangle + \frac{3}{2} \Delta H^2 - |\nabla^{\perp}\sigma|^2 + 2\langle \nabla_T^{\perp}h, N \rangle - 2\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}).$$
(5.9)

Let us consider now $\{e_3, \ldots, e_{n+1}\}$ a normal orthonormal frame in $\mathfrak{X}(\Sigma)^{\perp}$. Then, by writing $h = \sum_{\alpha} H^{\alpha} e_{\alpha}$ and taking into account the definition of ϕ_{α} , we easily get

$$\sum_{\alpha,\beta} H^{\alpha} \operatorname{tr}(A_{\alpha}A_{\beta}) \langle e_{\beta}, h \rangle = \sum_{\alpha,\beta,\gamma} H^{\alpha} H^{\gamma} \operatorname{tr}(A_{\alpha}A_{\beta}) \langle e_{\beta}, e_{\gamma} \rangle$$
$$= \sum_{\alpha,\beta} H^{\alpha} H^{\beta} \operatorname{tr}(\phi_{\alpha}\phi_{\beta}) + 2 \sum_{\alpha,\beta} (H^{\alpha})^{2} (H^{\beta})^{2}$$

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$$=\sum_{\alpha,\beta}H^{\alpha}H^{\beta}\mathrm{tr}(\phi_{\alpha}\phi_{\beta})+2H^{4}.$$
(5.10)

So, by Proposition 2,

$$\langle \Delta^{\perp} h, h \rangle + \left(2 - |T|^2 \right) H^2 - 2 \langle N, h \rangle^2 + \sum_{\alpha, \beta} H^{\alpha} H^{\beta} \operatorname{tr}(\phi_{\alpha} \phi_{\beta}) = 0.$$
 (5.11)

Now let us consider $\sigma_{\alpha\beta} = \operatorname{tr}(\phi_{\alpha}\phi_{\beta})$ for all $3 \leq \alpha, \beta \leq n+1$. Observe that the $(n-1) \times (n-1)$ -matrix $(\sigma_{\alpha\beta})$ is symmetric, and it can be assumed to be diagonal for a suitable choice of the normal orthonormal frame $\{e_3, \ldots, e_{n+1}\}$. Hence,

$$\sum_{\alpha,\beta} H^{\alpha} H^{\beta} \operatorname{tr}(\phi_{\alpha} \phi_{\beta}) = \sum_{\alpha} (H^{\alpha})^{2} \operatorname{tr}(\phi_{\alpha}^{2}) \leq \sum_{\alpha} (H^{\alpha})^{2} \sum_{\beta} \operatorname{tr}(\phi_{\beta}^{2}) = H^{2} |\phi|^{2}.$$
(5.12)

Replacing Equations (5.11) and (5.12) in Equation (5.9),

$$\Box^*(2h) - 2\langle \nabla_T^{\perp}h, N \rangle \ge -(2 - |T|^2 + |\phi|^2)H^2 + 2\langle N, h \rangle^2 + \frac{3}{2}\Delta H^2 - |\nabla^{\perp}\sigma|^2 - 2\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}).$$
(5.13)

Finally, Proposition 3 is proved taking into account Corollary 2 and the divergence theorem. $\hfill \Box$

Now, we are in the position to present the proof of Theorem 1.

Proof. To begin with, taking into account the definition of ϕ_{α} , it is immediate to check that for all $3 \leq \alpha, \beta \leq n+1$, it holds that

$$A_{\alpha}A_{\beta} - A_{\beta}A_{\alpha} = \phi_{\alpha}\phi_{\beta} - \phi_{\beta}\phi_{\alpha}.$$
(5.14)

Furthermore, since for any $3 \leq \alpha \leq n+1$, ϕ_{α} is a 2×2 symmetric matrix with $\operatorname{tr}(\phi_{\alpha}) = 0$, we easily get $\phi_{\alpha}^2 = \lambda I$ for a certain $\lambda \in \mathbb{R}$ and, consequently,

$$\operatorname{tr}(\phi_{\alpha}^2 \phi_{\beta}) = 0 \tag{5.15}$$

for all $3 \leq \alpha, \beta \leq n+1$.

Besides that, with a straightforward computation and considering Equation (5.15), we can get the following algebraic identities:

$$\sum_{\alpha,\beta} \operatorname{tr}(A_{\beta}) \operatorname{tr}(A_{\alpha}^2 A_{\beta}) = 2H^2 |\phi|^2 + 4H^4 + 4\sum_{\alpha,\beta} H^{\alpha} H^{\beta} \operatorname{tr}(\phi_{\alpha} \phi_{\beta})$$
(5.16)

and

$$\sum_{\alpha,\beta} [\operatorname{tr}(A_{\alpha}A_{\beta})]^{2} = \sum_{\alpha,\beta} [\operatorname{tr}(\phi_{\alpha}\phi_{\beta})]^{2} + 4H^{4} + 4\sum_{\alpha,\beta} H^{\alpha}H^{\beta}\operatorname{tr}(\phi_{\alpha}\phi_{\beta}).$$
(5.17)

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Total mean curvature surfaces in the product space $\mathbb{S}^n \times \mathbb{R}$ and applications 363 Hence, from all the above identities,

$$-\sum_{\alpha,\beta} \left(N(A_{\alpha}A_{\beta} - A_{\beta}A_{\alpha}) + [\operatorname{tr}(A_{\alpha}A_{\beta})]^{2} - \operatorname{tr}(A_{\beta})\operatorname{tr}(A_{\alpha}^{2}A_{\beta}) \right)$$
$$= -\sum_{\alpha,\beta} \left(N(\phi_{\alpha}\phi_{\beta} - \phi_{\beta}\phi_{\alpha}) + [\operatorname{tr}(\phi_{\alpha}\phi_{\beta})]^{2} \right) + 2H^{2}|\phi|^{2}.$$
(5.18)

So, Proposition 1 can be written as follows:

$$\frac{1}{2}\Delta|\sigma|^{2} = |\nabla^{\perp}\sigma|^{2} + 2\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}) + 2|\phi_{N}|^{2} - 4\sum_{\alpha} |\phi_{\alpha}(T)|^{2} + (2 - |T|^{2} + 2H^{2}) |\phi|^{2} - 2\langle\phi_{h}(T), T\rangle - \sum_{\alpha,\beta} \left(N(\phi_{\alpha}\phi_{\beta} - \phi_{\beta}\phi_{\alpha}) + [\operatorname{tr}(\phi_{\alpha}\phi_{\beta})]^{2}\right).$$
(5.19)

Observe now that by using Lemma 1,

$$-\sum_{\alpha,\beta} \left(N(\phi_{\alpha}\phi_{\beta} - \phi_{\beta}\phi_{\alpha}) + [\operatorname{tr}(\phi_{\alpha}\phi_{\beta})]^{2} \right) \ge -\frac{3}{2} |\phi|^{4}.$$
(5.20)

Moreover, the Cauchy-Schwarz's inequality implies

$$-4\sum_{\alpha} |\phi_{\alpha}(T)|^{2} \ge -4|\phi|^{2}|T|^{2} \quad \text{and} \quad -2\langle\phi_{h}(T),T\rangle \ge -2|\phi_{h}||T|^{2}.$$
(5.21)

Inserting Equations (5.20) and (5.21) in Equation (5.19), we get

$$\frac{1}{2}\Delta|\sigma|^{2} \ge |\nabla^{\perp}\sigma|^{2} + 2\sum_{\alpha} \operatorname{tr}(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}) + 2|\phi_{N}|^{2} - 2|\phi_{h}||T|^{2} + \left(2 - 5|T|^{2} + 2H^{2} - \frac{3}{2}|\phi|^{2}\right)|\phi|^{2}.$$
(5.22)

Taking integrals and using the divergence theorem, it follows from Proposition 3 that

$$0 \ge \int_{\Sigma} \left\{ 2(|\phi_N|^2 + \langle N, h \rangle^2) + (|T|^2 + |\phi|^2) H^2 \right\} d\Sigma + \int_{\Sigma} \left\{ \left(2 - 5|T|^2 - \frac{3}{2} |\phi|^2 \right) |\phi|^2 - 2H^2 - 2|\phi_h| |T|^2 \right\} d\Sigma.$$
(5.23)

Hence,

$$\int_{\Sigma} \left\{ \left(2 - 5|T|^2 - \frac{3}{2} |\phi|^2 \right) |\phi|^2 - 2H^2 - 2|\phi_h| |T|^2 \right\} \, \mathrm{d}\Sigma \le 0.$$
(5.24)

On the other hand, by the Gauss equation (2.11), it holds that

$$2H^2 = 2K + |\phi|^2 - 2(1 - |T|^2).$$
(5.25)

Then, the Gauss–Bonnet theorem implies

$$\int_{\Sigma} \left\{ \left(1 - 5|T|^2 - \frac{3}{2} |\phi|^2 \right) |\phi|^2 - 2(|\phi_h| + 1)|T|^2 + 2 \right\} \, \mathrm{d}\Sigma \le 4\pi\chi(\Sigma). \tag{5.26}$$

Finally, let us study when the equality holds in Equation (5.26). In such case, all the inequalities obtained along the proof should become equalities. In particular, the equality in Equations (5.23) and (5.24) holds. Thus, $|\phi_N| = \langle N, h \rangle = 0$ and either $|T| = |\phi| = 0$ or H = 0. In the first case, Σ^2 is a \mathcal{H} -surface satisfying the assumptions of Corollary 1, so it is totally geodesic. Therefore, either it is isometric to a slice $\mathbb{S}^2 \times \{t_0\}$ in the case n = 2 or to a totally geodesic sphere \mathbb{S}^2 in a certain $\mathbb{S}^3 \times \{t_0\}$.

Let us focus on the second case. On the one hand, since $|\phi_N| = \langle N, h \rangle = 0$, Equation (2.17) implies that $A_N = 0$. Consequently, from Equation (2.10), we have that |T| is constant on Σ^2 , and so it is |N|. On the other hand, since H = 0 and the equality also holds in Lemma 4, Σ^2 is necessarily a parallel surface of $\mathbb{S}^2 \times \mathbb{R}$. Then, the Codazzi equation (2.12) reads

$$0 = \langle \overline{R}(X,Y)Z,N \rangle = |N|^2 \left(\langle X,T \rangle \langle Y,Z \rangle - \langle Y,T \rangle \langle X,Z \rangle \right)$$
(5.27)

for all $X, Y, Z \in \mathfrak{X}(\Sigma)$. Therefore, we easily get that either N = 0 or T = 0. In the case where N = 0, we must have that Σ^2 is a vertical cylinder $\pi^{-1}(\gamma)$, γ being a circle in \mathbb{S}^2 and $\pi : \mathbb{S}^2 \times \mathbb{R} \to \mathbb{S}^2$ the natural projection map. This case cannot occur since it contradicts the compactness assumption of Σ^2 . Hence, T = 0, so Σ^2 is a minimal surface in a slice of $\mathbb{S}^n \times \mathbb{R}$. For the case where Σ^2 can be isometrically immersed in a certain $\mathbb{S}^3 \times \{t_0\}$, a classical result of isoparametric surfaces in Riemannian space forms [10] guarantees that Σ^2 is isometric to a Clifford torus $\mathbb{S}^1(1/\sqrt{2}) \times \mathbb{S}^1(1/\sqrt{2})$ in $\mathbb{S}^3 \times \{t_0\}$, for some $t_0 \in \mathbb{R}$. In other case, observe that, again from Equation (2.17), $|\phi|^2 = |\sigma|^2$, so the equality in Equation (5.24) becomes

$$\int_{\Sigma} |\sigma|^2 \left(\frac{3}{2}|\sigma|^2 - 2\right) d\Sigma = 0.$$
(5.28)

Therefore, from [11, Theorem 1], Σ^2 is isometric to a Veronese surface in $\mathbb{S}^4 \times \{t_0\}$, for some $t_0 \in \mathbb{R}$.

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