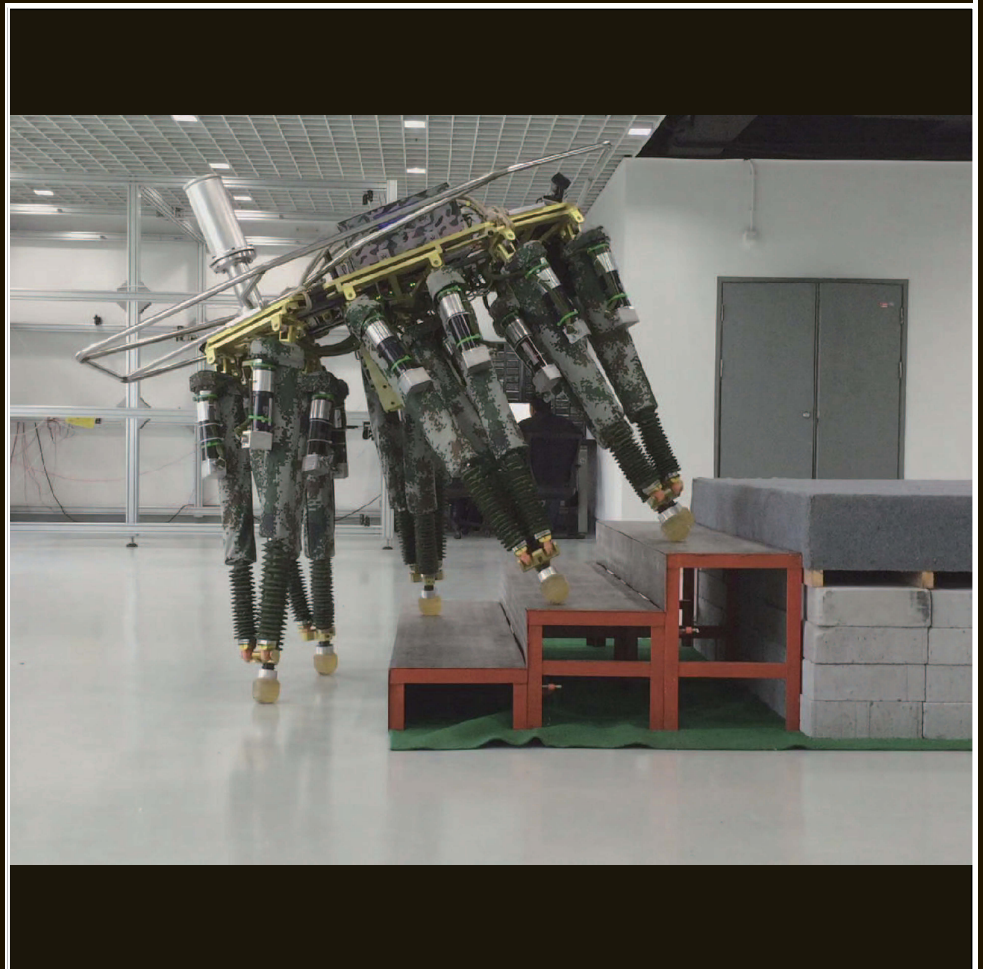


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# ROBOTICA



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Cover image: Figure 11 from **Efficient motion generation for a six-legged robot walking on irregular terrain via integrated foothold selection and optimization-based whole-body planning**, by Yuan Tian and Feng Gao.