

NOTE ON GENERALIZED WITT ALGEBRAS

RIMHAK REE

Introduction. Throughout this note K will denote a field of characteristic $p > 0$. Let I be the set $\{1, 2, \dots, m\}$, and \mathcal{G} a finite additive group of functions on I with values in K . We assume that \mathcal{G} is total in the sense that, for any $\lambda_1, \dots, \lambda_m$ in K , $\sum_{i=1}^m \lambda_i \sigma(i) = 0$ for all σ in G implies all $\lambda_i = 0$. It is clear that \mathcal{G} is an elementary p -group. Let p^n be the order of \mathcal{G} . A generalized Witt algebra \mathfrak{L} is defined as an algebra over K with basis elements $\{e(\sigma, i) \mid \sigma \in \mathcal{G}, i \in I\}$ and the multiplication table

$$(0.0.1) \quad e(\sigma, i)e(\tau, j) = \tau(i)e(\sigma + \tau, j) - \sigma(j)e(\sigma + \tau, i).$$

\mathfrak{L} is a simple Lie algebra except when $p = 2, m = 1$.

In the first section of this note we shall prove that the outer derivation algebra of a generalized Witt algebra is abelian, assuming that K is infinite. We shall see that actually a result of Jacobson (3) is generalized.

It was shown in (5) that any generalized Witt algebra \mathfrak{L} can be reformulated as follows: Let \mathfrak{A} be a commutative associative algebra over K with a unity element, and D_1, \dots, D_m be derivations of \mathfrak{A} such that:

- (1) $[D_i, D_j] = D_i D_j - D_j D_i = 0$ for all i and j ;
- (2) If $f \in \mathfrak{A}$ and $\lambda_1, \dots, \lambda_k$ in K are such that $D_i f = \lambda_i f$ for all i then $f = 0$ or f is a unit in \mathfrak{A} ;
- (3) $\sum_{i=1}^m f_i D_i = 0$, where $f_i \in \mathfrak{A}$, implies $f_i = 0$ for all i .

Now any generalized Witt algebra can be regarded as the subalgebra $\mathfrak{L}(\mathfrak{A}; D_1, \dots, D_m)$ of the derivation algebra of \mathfrak{A} consisting of all derivations of the form $f_1 D_1 + \dots + f_m D_m$. In the second section of this note we shall consider $\mathfrak{L}(\mathfrak{A}; D_1, \dots, D_m)$ under the conditions (1) and (2) above only, and extend some results proved in (5).

1. The derivation algebra of a generalized Witt algebra. We prove the following

THEOREM 1.1. *Let \mathfrak{L} be a generalized Witt algebra over an infinite field K of characteristic $p > 2$. Let $\{e(\sigma, i) \mid \sigma \in G, i \in I\}$ be a basis of \mathfrak{L} . Then any derivation of \mathfrak{L} is the sum of an inner derivation and a derivation δ_1 given by*

$$(1.1.1) \quad \delta_1(e(\sigma, i)) = \phi(\sigma)e(\sigma, i)$$

where ϕ is a linear map of \mathcal{G} into K .

Received May 12, 1958. This research was supported by the United States Air Force through the Air Research and Development Command under Contract No. AF 49(638)-152.

Proof. First of all we show that we may assume (1.1.2): for any $i, 1 \leq i \leq m$, $\sigma(i) = 0$ implies $\sigma = 0$. Suppose (1.1.2) is not satisfied. Since K is infinite and \mathfrak{G} total, we may proceed as in the proof of Lemma 9.1 of (5, p. 533) to obtain an $m \times m$ non-singular matrix (β_{ij}) such that if we define $\sigma[i]$ by

$$\sigma[i] = \sum_{j=1}^m \beta_{ij} \sigma(j), \quad (i = 1, \dots, m),$$

then, for any $i, \sigma[i] = 0$ implies $\sigma = 0$. Define a new basis $\{e[\sigma, i] \mid \sigma \in \mathfrak{G}, i \in I\}$ of \mathfrak{L} by

$$e[\sigma, i] = \sum_{j=1}^m \beta_{ij} e(\sigma, i).$$

Then by (0.0.1) we have

$$\begin{aligned} e[\sigma, i] e[\tau, j] &= \sum_{s,t} \beta_{is} \beta_{jt} e(\sigma, s) e(\tau, t) \\ &= \sum_{s,t} \beta_{is} \beta_{jt} (\tau(s) e(\sigma + \tau, t) - \sigma(t) e(\sigma + \tau, s)) \\ &= \tau[s] e[\sigma + \tau, t] - \sigma[t] e[\sigma + \tau, s]. \end{aligned}$$

Thus $\{e[\sigma, i]\}$ satisfies the same multiplication table as $\{e(\sigma, i)\}$ with $\sigma(i)$ replaced by $\sigma[i]$. But here $\sigma[i] = 0$ implies $\sigma = 0$. Suppose that the given derivation is the sum of an inner derivation and a derivation δ_1 given by $\delta_1(e[\sigma, i]) = \phi(\sigma) e[\sigma, i]$, where ϕ is an additive map of \mathfrak{G} into K . Then clearly we have $\delta_1(e(\sigma, i)) = \phi(\sigma) e(\sigma, i)$ also. This shows that we can assume (1.1.2) from the beginning.

Now let δ be the given derivation, and let

$$\delta(e(\sigma, i)) = \sum_{\tau, j} \gamma(\sigma, i; \tau, j) e(\sigma + \tau, j)$$

with coefficients $\gamma(\sigma, i; \tau, j)$ in K . Then from

$$\delta(e(0, 1)) e(\sigma, i) + e(0, 1) \delta(e(\sigma, i)) = \sigma(1) \delta(e(\sigma, i))$$

we obtain

$$(1.1.3) \quad \gamma(\sigma, i; \tau, j) = \gamma(0, 1; \tau, j) \tau(i) \tau(1)^{-1}$$

for $i \neq j$ and $\tau \neq 0$, and

$$(1.1.4) \quad \sum_j \gamma(0, 1; \tau, j) \sigma(j) + \gamma(\sigma, i; \tau, i) \tau(1) = \gamma(0, 1; \tau, i) \tau(i).$$

By (1.1.3) and (1.1.4) we see easily that

$$\begin{aligned} \delta(e(\sigma, i)) &= \sum_j \gamma(\sigma, i; 0, j) e(\sigma, j) \\ &\quad + e(\sigma, i) \sum_{\tau \neq 0} \sum_j \gamma(0, 1; \tau, j) \tau(1)^{-1} e(\tau, j). \end{aligned}$$

Hence δ is the sum of an inner derivation and a derivation δ_1 of the form

$$(1.1.5) \quad \delta_1(e(\sigma, i)) = \sum_j \gamma(\sigma, i, j) e(\sigma, j)$$

with coefficients $\gamma(\sigma, i, j)$ in K .

We shall show that $\gamma(\sigma, i, j) = 0$ if $i \neq j$, that $\gamma(\sigma, 1, 1) = \dots = \gamma(\sigma, m, m)$, and that $\gamma(\sigma, 1, 1)$ is additive with respect to σ . If $m = 1$, then the additivity of $\gamma(\sigma, 1, 1)$ follows immediately from

$$\delta_1(e(\sigma, 1))e(\tau, 1) + e(\sigma, 1)\delta_1(e(\tau, 1)) = \delta_1(e(\sigma, 1)e(\tau, 1)).$$

Hence we shall assume that $m > 1$. Then from

$$\delta_1(e(\sigma, 1))e(\tau, j) + e(\sigma, i)\delta_1(e(\tau, j)) = \delta_1(e(\sigma, i)e(\tau, j))$$

we have, for $i \neq j$,

$$(1.1.6) \quad \gamma(\sigma, i, j)\sigma(i) - \gamma(\tau, i, j)\tau(i) = \gamma(\sigma + \tau, i, j)(\sigma(i) - \tau(i));$$

$$(1.1.7) \quad \sum_k \gamma(\sigma, i, k)\tau(k) = \gamma(\sigma, i, j)\sigma(j) - \gamma(\tau, j, j)\tau(i) \\ + \gamma(\sigma + \tau, j, j)\tau(i) - \gamma(\sigma + \tau, i, j)\sigma(j).$$

Setting $\sigma = 0$ in (1.1.7) and using the fact that G is total, we have

$$(1.1.8) \quad \gamma(0, i, k) = 0$$

for all i and k . Set $\tau = -\sigma$, in (1.1.6) and use (1.1.8). Then we have, for any σ and $i \neq j$,

$$(1.1.9) \quad \gamma(\sigma, i, j) + \gamma(-\sigma, i, j) = 0.$$

Replace τ in (1.1.6) by $-\tau$, and use (1.1.9). Then we have

$$\gamma(\sigma, i, j)\sigma(i) - \gamma(\tau, i, j)\tau(i) = \gamma(\sigma - \tau, i, j)(\sigma(i) + \tau(i)).$$

Combining this with (1.1.6) yields

$$(1.1.10) \quad \gamma(\sigma - \tau, i, j)(\sigma(i) + \tau(i)) = \gamma(\sigma + \tau, i, j)(\sigma(i) - \tau(i)).$$

Since \mathfrak{G} is an elementary p -group and $p \neq 2$, $\sigma - \tau$ and $\sigma + \tau$ may be regarded as two arbitrary elements in \mathfrak{G} . Hence by (1.1.10) it follows that, for $i \neq j$,

$$(1.1.11) \quad \gamma(\sigma, i, j) = \alpha_{ij}\sigma(i),$$

where α_{ij} are in K and independent of σ . Substituting this in (1.1.7) we obtain

$$(1.1.12) \quad \gamma(\sigma, i, i)\tau(i) + \sum_{k \neq i} \alpha_{ik}\sigma(i)\tau(k) \\ = \gamma(\sigma + \tau, j, j)\tau(i) - \gamma(\tau, j, j)\tau(i) - \alpha_{ij}\tau(i)\sigma(j),$$

which shows that $(\gamma(\sigma + \tau, j, j) - \gamma(\tau, j, j))\tau(i)$ is additive with respect to τ . Hence

$$(1.1.13) \quad \gamma(\sigma + \tau, j, j) - \gamma(\tau, j, j) = \gamma(\sigma - \tau, j, j) - \gamma(-\tau, j, j)$$

for all σ and τ . Let $\sigma = \tau$ in the above and use (1.1.8). Then

$$(1.1.14) \quad \gamma(2\tau, j, j) - \gamma(\tau, j, j) = -\gamma(-\tau, j, j).$$

By (1.1.13) and (1.1.4) we have

$$\gamma(\sigma + \tau, j, j) = \gamma(\sigma - \tau, j, j) + \gamma(2\tau, j, j)$$

which shows that $\gamma(\sigma, j, j)$ is additive with regard to σ , since, as before, $\sigma + \tau$ and $\sigma - \tau$ can be regarded as two arbitrary elements in \mathfrak{G} . Now from (1.1.12) we obtain

$$\gamma(\sigma, i, i)\tau(i) + \sum_{k \neq i} \alpha_{ik}\sigma(i)\tau(k) = \gamma(\sigma, j, j)\tau(i) - \alpha_{ij}\tau(i)\sigma(j)$$

for all σ and τ . Using the fact that G is total, we see from the above that $\alpha_{ik} = 0$ for $k \neq i$ and that $\gamma(\sigma, i, i) = \gamma(\sigma, j, j)$ for any i and j . Set $\gamma(\sigma, i, i) = \phi(\sigma)$. Then ϕ is additive, and we have (1.1.1) as desired. Thus Theorem 1.1 is proved.

When is the derivation δ defined by $\delta(e(\sigma, i)) = \phi(\sigma)e(\sigma, i)$, where ϕ is an additive function on G , inner? Let

$$\delta(e(\sigma, i)) = e(\sigma, i) \sum_{\tau, j} \alpha_{\tau, j} e(\tau, j)$$

with $\alpha_{\tau, j} \in K$. Then

$$0 = e(0, i) = \sum_{\tau, j} \alpha_{\tau, j} \tau(i) e(\tau, j).$$

Hence $\tau(i) = 0, \tau = 0$, whenever $\alpha_{\tau, j} \neq 0$. From this it follows that δ is inner if, and only if, $\phi(\sigma) = \sum_j \alpha_j \sigma(j)$ with $\alpha_j \in K$. Such additive functions ϕ form clearly an m -dimensional vector space over K . On the other hand, if \mathfrak{G} is an elementary group of order p^n , then all the additive functions on \mathfrak{G} with values in K form an n -dimensional vector space over K . Hence we have

COROLLARY 1.2. *Let \mathfrak{X} be a generalized Witt algebra with basis $\{e(\sigma, i) | \sigma \in \mathfrak{G}, i \in I\}$, where \mathfrak{G} is an elementary p -group of order p^n , and $I = \{1, 2, \dots, m\}$. Let \mathfrak{D} and \mathfrak{S} be the derivation algebra and the algebra of inner derivations of \mathfrak{X} , respectively. Then $\mathfrak{D}/\mathfrak{S}$ is an abelian algebra of dimension $n - m$, provided that the characteristic of K is greater than 2.*

From the above corollary it follows immediately that the number m is uniquely determined by \mathfrak{X} . This is, however, proved in (5, p. 546). Also, if $m = n$, then every derivation of \mathfrak{X} is inner. This is a result of Jacobson (3).

2. Generalized orthogonal systems. Let \mathfrak{A} be a finite-dimensional commutative associative algebra over the algebraically closed ground field K . We assume that \mathfrak{A} has a unity element.

An ordered set (D_1, \dots, D_m) of derivations of \mathfrak{A} will be called a *generalized orthogonal (g.o.) system* if the following conditions (2.1.1.)-(2.1.2) are satisfied:

$$(2.1.1.) \quad [D_i, D_j] = D_i D_j - D_j D_i = 0 \text{ for all } i \text{ and } j;$$

(2.1.2) *If $f \in \mathfrak{A}$ and $\lambda_1, \dots, \lambda_m \in K$ are such that $D_i f = \lambda_i f$ for all i , then $f = 0$ or f is a unit of \mathfrak{A} .*

A g.o. system (D_1, \dots, D_m) will be called an *o. system* if it satisfies the following condition:

$$(2.1.3.) \quad \sum_{i=1}^m f_i D_i = 0, \text{ where } f_i \in \mathfrak{A}, \text{ implies } f_i = 0 \text{ for all } i.$$

LEMMA 2.1. *The conditions (2.1.1.)–(2.1.2) imply the following:*

$$(2.1.4) \quad D_i f = 0 \text{ for all } i = 1, \dots, m \text{ implies } f \in K.$$

Proof. The set \mathfrak{B} of all $f \in \mathfrak{A}$ such that $D_i f = 0$ for all i is clearly a sub-algebra of \mathfrak{A} , and, moreover, if $0 \neq f \in \mathfrak{B}$ then by (2.1.2) f^{-1} exists and belongs to \mathfrak{B} , since $D_i f^{-1} = -f^{-2} D_i f = 0$. Therefore, \mathfrak{B} is a finite extension field of K . Since K is algebraically closed, we have $\mathfrak{B} = K$.

THEOREM 2.2. *For any g.o. system (D_1, \dots, D_m) there exists a non-void subset $S = \{i_1, \dots, i_r\}$ of indices $1, \dots, m$ such that (2.2.1)–(2.2.2), below, hold:*

$$(2.2.1) \quad (D_{i_1}, \dots, D_{i_r}) \text{ is an } o. \text{ system};$$

$$(2.2.2) \quad \text{There exists } \alpha_{i_s} \in K \text{ such that}$$

$$D_i = \sum_{s \in S} \alpha_{i_s} D_s, \quad (i = 1, \dots, m).$$

Proof. Let S be a minimal subset of the indices $1, \dots, m$ with respect to the property: there exist $a_{i_s} \in \mathfrak{A}$ such that

$$(2.2.3) \quad D_i = \sum_{s \in S} a_{i_s} D_s \quad (i = 1, \dots, m).$$

We may assume without loss of generality that $S = \{1, \dots, r\}$. Let V be the set of all r -tuples (f_1, \dots, f_r) of elements $f_s \in \mathfrak{A}$ such that $\sum_{s \in S} f_s D_s = 0$. Define addition in V componentwise, scalar multiplication by $\alpha(f_1, \dots, f_r) = (\alpha f_1, \dots, \alpha f_r)$, $\alpha \in K$. Then V is a finite-dimensional vector space over K . We shall prove (2.1.3) for (D_1, \dots, D_r) by showing that $V = 0$. Suppose $V \neq 0$. Since $\sum_{s \in S} f_s D_s = 0$ implies $\sum_{s \in S} (D_i f_s) D_s = 0$, the mapping $(f_1, \dots, f_r) \rightarrow (D_i f_1, \dots, D_i f_r)$ is a linear transformation of V . Since $D_i(D_j f) = D_j(D_i f)$ for all $f \in \mathfrak{A}$, i , and j , and since K is algebraically closed, there exists a non-zero $(f_1, \dots, f_r) \in V$ and $\lambda_1, \dots, \lambda_m \in K$ such that

$$(D_i f_1, \dots, D_i f_r) = \lambda_i (f_1, \dots, f_r)$$

for $i = 1, \dots, m$. Then $D_i f_s = \lambda_i f_s$ for all i and s . Then from (2.1.2) it follows that f_s is either 0 or a unit in \mathfrak{A} . Since not all f_s are zero, we may assume $f_1 \neq 0$; f_1 is a unit. Then $D_1 = -f_1^{-1} f_2 D_2 - \dots - f_1^{-1} f_r D_r$. Then every D_i can be written as a linear combination of D_2, \dots, D_r with coefficients in \mathfrak{A} . This contradicts the minimality of S . Thus $V = 0$, and hence (2.1.3) is proved for (D_1, \dots, D_r) .

Now, from (2.1.1) and (2.2.3) it follows that $\sum_{s \in S} (D_k a_{i_s}) D_s = 0$ for all $i, k = 1, \dots, m$. Therefore by (2.2.1), we have $D_k a_{i_s} = 0$ and hence, by Lemma 2.1, $a_{i_s} = \alpha_{i_s} \in K$ for all i and s . This proves (2.2.2).

In order to show that (D_1, \dots, D_r) is an o . system, it remains to be shown that $D_s f = \lambda_s f$, $\lambda_s \in K$, for $s = 1, \dots, r$ implies that $f = 0$ or f is a unit. This, however, follows easily from (2.2.2) and (2.1.2). Thus the proof of Theorem 2.2 is complete.

COROLLARY 2.3. *A g.o. system (D_1, \dots, D_m) is an o . system if, and only if, D_1, \dots, D_m are linearly independent over K .*

COROLLARY 2.4. *If there exists a g.o. system of derivations of \mathfrak{A} , then \mathfrak{A} is isomorphic to the group algebra over K of an abelian p -group of type (p, p, \dots, p) .*

Proof. By Theorem 2.2, there exists an o . system of derivations of \mathfrak{A} . Then Corollary 2.3 follows from Lemma 2.1 above and Theorem 6.10 of (5).

COROLLARY 2.5. *The conditions (2.1.1)–(2.1.2) imply the following: If $f, a_1, \dots, a_m \in \mathfrak{A}$ are such that $D_i f = a_i f$ for all i , then $f = 0$ or f is a unit in \mathfrak{A} .*

Proof. Corollary 2.5 follows immediately from Theorem 2.2 above, and Lemma 6.3 of (5).

The following theorem, which also follows immediately from Theorem 2.2, above, and Theorem 6.10 of (5), is a partial generalization of Theorem 6.10 of (5).

THEOREM 2.6. *If (D_1, \dots, D_m) is a g.o. system, then the subalgebra of the derivation algebra of \mathfrak{A} , consisting of all derivations of the form $\sum f_i D_i$, where $f_i \in \mathfrak{A}$, is isomorphic to a generalized Witt algebra.*

Now let (D_0, \dots, D_m) be a set of derivations of \mathfrak{A} , satisfying (2.1.1), and let $a_0, \dots, a_m \in \mathfrak{A}$ be such that $D_i a_j = D_j a_i$ for all i and j . Then the set $\mathfrak{L} = \mathfrak{L}(D_0, \dots, D_m; a_0, \dots, a_m)$ of all derivations of the form $\sum f_i D_i$, where $f_i \in \mathfrak{A}$ satisfy $\sum_i (D_i f_i - a_i f_i) = 0$, forms a subalgebra of the derivation algebra of \mathfrak{A} . A special case of such algebras was considered for the first time by Frank (2), and another by Albert and Frank (1). The general case where (D_0, \dots, D_m) is an o . system was considered by Jennings and Ree (4). Here we consider the case where (D_0, \dots, D_m) is an arbitrary g.o. system.

THEOREM 2.7. *If (D_0, \dots, D_m) is a g.o. system, then the algebra $L(D_0, \dots, D_m; a_0, \dots, a_m)$ is isomorphic either to a generalized Witt algebra or to an algebra of the form $L(D_0', \dots, D_r'; a_0', \dots, a_r')$, where (D_0', \dots, D_r') is an o . system.*

Proof. If $m = 0$, then (D_0, \dots, D_m) is an o . system, and so our theorem is clear. We shall proceed by induction on m . Assume that Theorem 2.7 is true for $m - 1$. If (D_0, \dots, D_m) is an o . system then our theorem is clear. If (D_0, \dots, D_m) is not an o . system, then, by Theorem 2.2, we may assume without loss of generality that $D_m = \alpha_0 D_0 + \dots + \alpha_{m-1} D_{m-1}$ with $\alpha_i \in K$. We have

$$D_k \left(a_m - \sum_{i=0}^{m-1} \alpha_i a_i \right) = D_m a_k - \sum_{i=0}^{m-1} \alpha_i D_i a_k = 0$$

for $k = 0, 1, \dots, m$. Hence

$$a_m - \sum_{i=0}^{m-1} \alpha_i a_i = \alpha$$

belongs to K by Lemma 2.1.

If $\alpha = 0$ then $\mathfrak{L} = \mathfrak{L}(D_0, \dots, D_m; a_0, \dots, a_m)$ and $\mathfrak{L}_1 = \mathfrak{L}(D_0, \dots, D_{m-1}; a_0, \dots, a_{m-1})$ coincide. This is seen as follows: Let $\sum_0^m f_i D_i \in L$. Then by definition, $\sum_0^m (D_i f_i - a_i f_i) = 0$, and hence

$$\sum_{i=0}^{m-1} (D_i (f_i + \alpha_i f_m) - a_i (f_i + \alpha_i f_m)) = 0.$$

On the other hand,

$$\sum_{i=0}^m f_i D_i = \sum_{i=0}^{m-1} (f_i + \alpha_i f_m) D_i.$$

Therefore, $\sum_0^m f_i D_i \in \mathfrak{L}_1$ and hence $\mathfrak{L} \leq \mathfrak{L}_1$ is proved. Since $\mathfrak{L}_1 \leq \mathfrak{L}$ is clear, we have $\mathfrak{L} = \mathfrak{L}_1$.

If $\alpha \neq 0$ then $\mathfrak{L} = \mathfrak{L}(D_0, \dots, D_m; a_0, \dots, a_m)$ coincides with the set \mathfrak{L}_2 of all derivations of the form $\sum_0^{m-1} g_i D_i$, where g_i runs over \mathfrak{A} . This is seen as follows: Clearly we have $L \leq L_2$. Now, for an arbitrary element $\sum_0^{m-1} g_i D_i$ in \mathfrak{L}_2 , define f_0, f_1, \dots, f_m by the formulae:

$$f_m = \alpha^{-1} \sum_{i=0}^{m-1} (D_i g_i - a_i g_i);$$

$$f_i = g_i - \alpha_i f_m, \quad (0 \leq i < m).$$

Then it is easily seen that $\sum_0^{m-1} g_i D_i = \sum_0^m f_i D_i$, and that

$$\sum_{i=0}^m (D_i f_i - a_i f_i) = 0.$$

Therefore $\sum_0^{m-1} g_i D_i \in \mathfrak{L}$, and hence $\mathfrak{L}_2 \leq \mathfrak{L}$ is proved. Thus we have $\mathfrak{L} = \mathfrak{L}_2$. Since \mathfrak{L}_2 is a generalized Witt algebra, this completes the proof of Theorem 2.7.

Consider now a set of derivations (D_1, \dots, D_m) of \mathfrak{A} satisfying only the condition (2.1.1) and denote by \mathfrak{L} the subalgebra of the derivation algebra of \mathfrak{A} consisting of all derivations of the form $f_i D_i$, where $f_i \in \mathfrak{A}$. Let \mathfrak{N} be the radical of \mathfrak{A} , and let \mathfrak{D} be the set of all $f \in \mathfrak{N}$ such that $D_k(D_j(\dots(D_i f)\dots)) \in \mathfrak{N}$ for any i, j, \dots, k (the number of indices i, j, \dots, k is arbitrary). It is easily seen that \mathfrak{D} is an ideal of \mathfrak{A} and that $f \in \mathfrak{D}$ implies $D_i f \in \mathfrak{D}$ for all i . Therefore every D_i induces a derivation \bar{D}_i of the algebra $\bar{\mathfrak{A}} = \mathfrak{A}/\mathfrak{D}$. Since $[\bar{D}_i, \bar{D}_j] = 0$ follows from $[D_i, D_j] = 0$, we can consider the subalgebra $\bar{\mathfrak{L}}$ of the derivation algebra of $\bar{\mathfrak{A}}$ consisting of all derivations of the form $\sum \bar{f}_i \bar{D}_i$, where $\bar{f}_i \in \bar{\mathfrak{A}}$. Denote by \bar{f} the image of $f \in \mathfrak{A}$ under the natural homomorphism: $\mathfrak{A} \rightarrow \bar{\mathfrak{A}}$. Since $\sum f_i D_i = 0$ implies $\sum \bar{f}_i \bar{D}_i = 0$, a mapping ϕ is uniquely

defined by $\phi(\sum f_i D_i) = \sum \bar{f}_i \bar{D}_i$. It is easily seen that ϕ is a homomorphism of \mathfrak{L} onto $\bar{\mathfrak{L}}$. The kernel \mathfrak{I} of ϕ consists of elements $\sum f_i D_i$ such that $\sum \bar{f}_i \bar{D}_i = 0$. Note that $\sum \bar{f}_i \bar{D}_i = 0$ if and only if $\sum f_i (D_i g) \in \mathfrak{D}$ for all $g \in \mathfrak{A}$. From this it follows immediately that the ideal $[\mathfrak{I}, \mathfrak{I}]$ of \mathfrak{L} is contained in the algebra \mathfrak{L}_1 consisting of all derivations of the form $\sum f_i D_i$, where $f_i \in \mathfrak{D}$. For a positive integer k , denote by \mathfrak{L}_k the algebra of all derivations of the form $\sum f_i D_i$, where $f_i \in \mathfrak{D}^k$. It is easily seen that $[\mathfrak{L}_k, \mathfrak{L}_1] \subseteq \mathfrak{L}_{k+1}$ for any k . Since $\mathfrak{D} \subseteq \mathfrak{N}$, it follows that \mathfrak{D} is nilpotent, say, $\mathfrak{D}^t = 0$. Then $\mathfrak{L}_t = 0$, and hence \mathfrak{L}_1 is nilpotent, and \mathfrak{I} is solvable.

Consider now the algebra $\bar{\mathfrak{L}}$, assuming that every non-unit element in \mathfrak{A} is contained in the radical \mathfrak{N} . We shall prove that $(\bar{D}_1, \dots, \bar{D}_m)$ is a g.o. system of $\bar{\mathfrak{L}}$. Suppose that $\bar{D}_i \bar{f} = \lambda_i \bar{f}$ for all i , and that \bar{f} is a non-unit in $\bar{\mathfrak{L}}$. Then $D_i f = \lambda_i f + g_i$, where $g_i \in \mathfrak{D}$. Since \bar{f} is not a unit f is also not a unit, and hence by our assumption $f \in \mathfrak{N}$. Then from $D_i f - \lambda_i f \in \mathfrak{D}$ it follows easily that $f \in \mathfrak{D}$. Therefore $\bar{f} = 0$, and hence $(\bar{D}_1, \dots, \bar{D}_m)$ is proved to be a g.o. system. Then, by Theorem 1.6, $\bar{\mathfrak{L}}$ is isomorphic to a generalized Witt algebra.

An associative algebra \mathfrak{A} is called *completely primary* if the set of non-unit elements coincide with the radical of \mathfrak{A} . Summarizing the above, we have

THEOREM 2.8. *Suppose that the commutative associative algebra \mathfrak{A} is completely primary. Then for any set of derivatives (D_1, \dots, D_m) of \mathfrak{A} , which satisfies the condition (2.1.1.), the algebra \mathfrak{L} consisting of all derivations of the form $\sum f_i D_i$, where $f_i \in \mathfrak{A}$, has a solvable ideal \mathfrak{I} such that $\mathfrak{L}/\mathfrak{I}$ is isomorphic to a generalized Witt algebra.*

Similarly we may obtain the following

THEOREM 2.9. *Suppose that the commutative associative algebra \mathfrak{A} is completely primary. Then for any set of derivatives (D_1, \dots, D_m) of \mathfrak{A} , which satisfies the condition (2.1.1.), an algebra \mathfrak{L} of the form $\mathfrak{L}(D_0, \dots, D_m; a_0, \dots, a_m)$ has a solvable ideal \mathfrak{I} such that $\mathfrak{L}/\mathfrak{I}$ is isomorphic either to a generalized Witt algebra or to an algebra of the form $\mathfrak{L}(E_0, \dots, E_r; b_0, \dots, b_r)$, where (E_0, \dots, E_r) is an o. system of derivations of the group algebra over K of an abelian group of type (p, \dots, p) .*

REFERENCES

1. A. A. Albert and M. S. Frank, *Simple Lie algebras of characteristic p* , Rendiconti del Sem. Mat., Univ. e Politech di Torino, 14 (1955), 117-39.
2. M. S. Frank, *A new class of simple Lie algebras*, Proc. Nat. Acad. Sci., 40 (1954), 713-18.
3. N. Jacobson, *Abstract derivation and Lie algebras*, Trans. Amer. Math. Soc., 42 (1937), 206-24.
4. S. A. Jennings and Rimhak Ree, *On a class of Lie algebras of characteristic p* , Trans. Amer. Math. Soc., 84 (1957), 192-207.
5. Rimhak Ree, *On generalized Witt algebras*, Trans. Amer. Math. Soc., 83 (1956), 510-46.

The University of British Columbia