The geometric index and attractors of homeomorphisms of \mathbb{R}^3

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(Received 14 April 2021 and accepted in revised form 17 August 2021)

Abstract. In this paper we focus on compacta $K \subseteq \mathbb{R}^3$ which possess a neighbourhood basis that consists of nested solid tori T_i . We call these sets toroidal. Making use of the classical notion of the geometric index of a curve inside a torus, we introduce the self-geometric index of a toroidal set K, which roughly captures how each torus T_{i+1} winds inside the previous T_i as $i \to +\infty$. We then use this index to obtain some results about the realizability of toroidal sets as attractors for homeomorphisms of \mathbb{R}^3 .

Key words: toroidal set, geometric index, attractor 2020 Mathematics Subject Classification: 57K99, 37B35, 37E99 (Primary); 55N99 (Secondary)

1. Introduction

This paper lies at the intersection of geometric topology and topological dynamics. We focus on the class of toroidal sets, which are those compact subsets $K \subseteq \mathbb{R}^3$ that have a neighbourhood basis of solid tori. They are a natural generalization of the well-known cellular sets of geometric topology, which are those that have a neighbourhood basis of cells. Toroidal sets encompass objects such as *n*-adic solenoids, generalized solenoids (where the winding number *n* of each torus inside the previous need not be constant), knotted solenoids (where the construction begins with a knotted torus), classical knots, and some wild knots such as those constructed by taking an infinite connected sum of tame knots.

We are interested in the problem of characterizing what toroidal sets $K \subseteq \mathbb{R}^3$ can be realized as an attractor for a flow or a homeomorphism of \mathbb{R}^3 or, since this problem is

much too difficult, at least of showing that certain toroidal sets cannot be so realized. By an attractor we mean a compact invariant set $K \subseteq \mathbb{R}^3$ which is stable in the sense of Lyapunov and attracts all points in some neighbourhood U of K. The latter condition means that the forward orbit of any point in U eventually enters any prescribed neighbourhood of K, and the stability condition then implies that this property actually holds for any compact subset of U, rather than just points. Precise definitions and a detailed discussion are given at the beginning of §7.

The motivation for this 'realization problem' is the well-known fact that attractors can have a very complicated structure. Heuristically, obtaining topological obstructions which prevent a compactum from being an attractor provides 'upper bounds' on the complexity of attractors. Realizability problems of this sort have been studied in many different contexts and accordingly with different techniques: attractors for topological flows [3, 11, 15, 28, 31], for analytic flows [18, 19], critical sets rather than attractors [12, 24, 33], attractors for homeomorphisms [14, 20, 25, 29, 30], or iterated function systems instead of single homeomorphisms [6, 8].

Perhaps we should mention that we always consider K as a given subset of \mathbb{R}^3 and not in the abstract; that is, we do not consider whether there is an embedding of K in some suitable Euclidean space where it can be realized as an attractor. These two problems are very different in nature, since in the first the way K sits in \mathbb{R}^3 is crucial whereas in the second only the topological properties of K may play a role. Thus, for example, Williams, in his work on expanding attractors, obtains a very general realizability result for solenoids [34, Theorem B, p. 171] which would appear to be in conflict with our Corollary 7.3; however, Williams's results are concerned with the realizability problem in the abstract.

A toroidal set *K* can be expressed as an intersection of nested solid tori. Since these tori can be knotted and wind inside each other, it seems reasonable to think that *K* itself may have some sort of knottedness and some amount of winding 'in itself'. As it turns out, both phenomena have implications for the realization problem and so we need to develop tools to formalize and analyse them. The first one was already addressed in an earlier paper [2] by defining the *genus* g(K) of a toroidal set *K* as a generalization of the classical genus of a knot. Namely, g(K) is the smallest $g = 0, 1, \ldots, +\infty$ such that *K* has arbitrarily close neighbourhoods which are solid tori whose core curves, thought of as classical knots, have genus bounded above by *g*. A toroidal set which can be realized as an attractor must have a finite genus, and so this provides a first obstruction for the realization problem.

In this paper we introduce the *self-geometric index* $\mathcal{N}(K)$ of a toroidal set K to describe the winding of K in itself mentioned above. Since measuring winding algebraically would essentially reproduce the Čech cohomology of the toroidal set we turn to another measure of winding which was first introduced by Schubert [32, §9] under the name 'order'. Consider a simple closed curve γ contained in the interior of a solid torus T. The geometric index of γ with respect to T is defined as the minimum number of points of intersection of γ with any meridional disk D of T. Now, if T_2 is a solid torus contained in the interior of another solid torus T_1 , the geometric index of T_2 with respect to T_1 is defined as the geometric index of any core curve of T_2 with respect to T_1 . We denote this index by $N(T_2, T_1)$ following the notation used in [1]. Now let the toroidal set K be written as the intersection of a nested sequence $\{T_j\}$ of solid tori. One may attempt to define the self-geometric index of K as some sort of limit of the sequence $N(T_{j+1}, T_j)$. This runs into difficulties since the limit depends on the sequence $\{T_j\}$, and so a subtler approach is needed. The self-geometric index of a toroidal set K will turn out to be a subgroup $\mathcal{N}(K)$ of the (additive) group of the real numbers. In certain cases $\mathcal{N}(K)$ behaves essentially as an integer number n, and we will then say that $\mathcal{N}(K)$ is 'number-like' and write $\mathcal{N}(K) \sim n$. For example, $\mathcal{N}(K) \sim n$ for an n-adic solenoid, and $\mathcal{N}(K) \sim 1$ precisely when $\mathcal{N}(K) = \mathbb{Z}$. All this is made precise in §4 after some preparatory work in §3.

With these definitions we can now state our main results about the realization problem for toroidal sets. We start with the case of flows.

THEOREM A. A toroidal set $K \subseteq \mathbb{R}^3$ can be realized as an attractor for a flow if and only if its genus is finite and $\mathcal{N}(K) \sim 1$.

The realization problem for homeomorphisms is much more complicated than that for flows, and in fact to our knowledge it has only been completely solved when K is either a cellular subset of \mathbb{R}^n or a compact subset of a 2-manifold. The case of toroidal sets is no exception, and in this paper we obtain the following partial result.

THEOREM B. Let K be a toroidal set that is an attractor for a homeomorphism f of \mathbb{R}^3 . Then $\mathcal{N}(K)$ is number-like. Moreover, $\mathcal{N}(K) \sim 1$ if and only if K can be realized as an attractor for a flow.

The main application of this theorem is in showing that certain toroidal sets cannot be realized as attractors for homeomorphisms. By combining some technical results in §5 with Theorem B we obtain the following result (p. 7) which guarantees the existence of many toroidal sets which are unknotted, have a prescribed cohomology, and cannot be realized as attractors.

THEOREM C. Let H be a feasible group. There exists an uncountable family $\{K_{\alpha}\}$ of toroidal sets such that:

- (i) none of the K_{α} can be realized as an attractor for a homeomorphism of \mathbb{R}^3 ;
- (ii) the K_{α} are pairwise different (that is, not ambient homeomorphic);
- (iii) each K_{α} is unknotted;
- (iv) each K_{α} has H as its first Čech cohomology group.

The feasibility condition on H is explained in §5 and is unrelated to dynamics: it just ensures that H can be realized as the cohomology of some toroidal set.

As another illustration of Theorem B we consider the case of generalized knotted solenoids. Such a solenoid K is the intersection of a nested sequence of solid tori $\{T_j\}$ such that each T_{j+1} winds monotonically (that is, without turning back) n_j times inside the previous T_j and the thickness of the T_j tends to 0 as j increases. To avoid degenerate cases we require $n_j > 1$ for each j, and if all the $n_j = n$ then we say that K is an n-adic solenoid. Notice that by choosing T_1 to be knotted one obtains a knotted solenoid. Then one can prove the following (Corollary 7.3).

COROLLARY. If a generalized solenoid $K \subseteq \mathbb{R}^3$ can be realized as an attractor for a homeomorphism of \mathbb{R}^3 , then it must be an unknotted n-adic solenoid for some n.

The assumption that *K* be realized as an attractor for a homeomorphism defined on the whole of \mathbb{R}^3 is crucial in our results. If homeomorphisms defined only on subsets of \mathbb{R}^3 are allowed, counterexamples to Theorem B can be found (see, for instance, the first stage of the construction of the example in [13, §5]). If phase spaces other than \mathbb{R}^3 are allowed, then the corollary above is false since knotted *n*-adic solenoids can indeed be realized as attractors (see, for instance, [17]). Similarly, if the condition $n_j > 1$ is omitted then the corollary is again false: any polyhedral or smooth knot then qualifies as a generalized knotted solenoid and can be easily realized as an attractor, even for a flow.

The paper is organized as follows. In §2 we recall some definitions and provide some bibliographic references. Section 3 discusses some simple algebra needed for the definition of the self-geometric index in §4. The contents of §§5 and 6 are of a more technical nature and are required in the proof of the main results stated above. These are proved in §7. Finally, §8 contains some concluding remarks and questions.

2. Background definitions

A *toroidal* set is a compact set $K \subseteq \mathbb{R}^3$ that is not cellular and has a neighbourhood basis comprised of solid tori. In this paper we will always assume that sets other than toroidal sets are polyhedral (toroidal sets, in general, can have a very complicated structure). For maps we adopt the opposite convention: they will never be assumed to be piecewise linear unless explicitly stated otherwise. A taming result of Moise ensures that a toroidal set has a neighbourhood basis of polyhedral solid tori (see [2, p. 5]). We say that two solid tori T_1 and T_2 are *nested* if T_2 is contained in the interior of T_1 . Here the word 'interior' may be taken in the topological sense or in the manifold sense: both agree by the invariance of domain theorem. A *standard basis* for a toroidal set K is a sequence of (polyhedral) nested solid tori { T_i } whose intersection is K.

A framing of a solid torus $T \subseteq \mathbb{R}^3$ is a particular piecewise linear homeomorphism $f: \mathbb{D}^2 \times \mathbb{S}^1 \longrightarrow T$, where \mathbb{D}^2 is a closed 2-disk. A *core* curve of T is a curve γ of the form $f(0 \times \mathbb{S}^1)$ for some framing f. Notice that γ lies in the interior of T and T is a regular neighbourhood of γ (recall our convention about the polyhedral nature of sets unless otherwise explicitly stated). Core curves are not unique, but any two core curves are related by an isotopy of T that is the identity on ∂T . A meridian of T is a curve of the form $f(\partial \mathbb{D}^2 \times *)$ for some framing of T (here * denotes any point in \mathbb{S}^1). Alternatively, meridians can be characterized as those simple closed curves in ∂T which bound a disk in T but not in ∂T . A *meridional disk* of T is a disk $D \subseteq T$ that is properly embedded (that is, $D \cap \partial T = \partial D$) and whose boundary ∂D is a meridian of T.

Consider a pair of nested solid tori $T_2 \subseteq T_1$. The *geometric index of* T_2 *in* T_1 is the minimum number of points of intersection of a core curve γ of T_2 with any meridional disk D of T_1 . The minimum is taken over all meridional disks that intersect γ transversely, so that $D \cap \gamma$ consists of finitely many points. Since any two core curves of T_2 are related by an isotopy of T_2 that is the identity on ∂T_2 and can therefore be extended to an isotopy of T_1 , it follows that this definition is independent of the particular core curve γ .

The geometric index is multiplicative: if $T_3 \subseteq T_2 \subseteq T_1$ are three nested solid tori, then $N(T_3, T_1) = N(T_3, T_2) \cdot N(T_2, T_1)$ (see [32, Satz 3, p. 175]). We will make extensive use of this property.

Suppose $T_2 \subseteq T_1$ and $T'_2 \subseteq T'_1$ are two pairs of nested solid tori. It is clear from the definition of the geometric index that if there exists a piecewise linear homeomorphism between the pairs (T_1, T_2) and (T'_1, T'_2) then the geometric indices $N(T_2, T_1)$ and $N(T'_2, T'_1)$ are equal. We will need a slightly stronger statement, however, which is given in Lemma 2.1 below. We have opted for a quick, if not particularly neat, proof.

LEMMA 2.1. Suppose that $f : (T_1, T_2) \longrightarrow (T'_1, T'_2)$ is a homeomorphism between two pairs of nested polyhedral tori. Assume that f is piecewise linear on T_1 – int T_2 . Then the geometric indices of the two pairs are equal.

Proof. By an approximation theorem of Bing (see, for instance, [4, Theorem 4, p. 149]) there exists a piecewise linear homeomorphism $f': T_1 \longrightarrow T'_1$ which coincides with f on $T_1 - \text{int } T_2$. In particular, it sends T_2 onto T'_2 and therefore provides a piecewise linear homeomorphism from (T_1, T_2) onto (T'_1, T'_2) . The result follows.

A natural way of constructing toroidal sets is, of course, by taking a nested sequence of tori $\{T_j\}$ and letting $K := \bigcap_{j\geq 0} T_j$. Although such a *K* certainly has a neighbourhood basis of solid tori, to guarantee that *K* is a toroidal set we must also make sure that it is not cellular. The following proposition provides an easy criterion to check this in terms of the geometric index.

PROPOSITION 2.2. Let K be defined as the intersection of a nested sequence of solid tori $\{T_i\}$. Then K is cellular if and only if $N(T_{i+1}, T_i) = 0$ for infinitely many j.

For the proof we make use of the following fact: if $T_2 \subseteq T_1$ is a nested pair of solid tori, then $N(T_2, T_1) = 0$ if and only if T_2 is contained in a 3-cell *B* inside *T*. This should be intuitively clear, and a very sketchy argument will be given in the proof of the proposition. A formal proof can be found in [32, Satz 1, p. 171].

Proof of Proposition 2.2. Assume first that *K* is cellular. Choose any T_{j_0} . Since *K* is cellular, it has a neighbourhood *B* which is a 3-cell contained in int T_{j_0} . In turn, take j_1 such that $T_{j_1} \subseteq$ int *B*. Shrink the cell *B* by an ambient isotopy of T_{j_0} (relative to ∂T_{j_0}) until it becomes extremely small. It is then clear that there is a meridional disk *D* of T_{j_0} that is disjoint from the shrunken cell. Carrying *D* along with the reverse isotopy, one obtains a meridional disk of T_{j_0} that is disjoint from the original cell *B*, and consequently also from T_{j_1} . Thus the geometric index of T_{j_1} in T_{j_0} is 0. The multiplicativity of the index then implies that $N(T_{j+1}, T_j) = 0$ for some $j_0 \le j < j_1$.

Conversely, assume that $N(T_{j+1}, T_j) = 0$ for infinitely many *j*. Choose any T_{j_0} and pick $j \ge j_0$ such that $N(T_{j+1}, T_j) = 0$. Then $N(T_{j+1}, T_{j_0}) = 0$ too by the multiplicative property of the geometric index. This means that there exists a meridional disk *D* of T_{j_0} such that T_{j+1} is disjoint from *D*. Thickening *D* to a regular neighbourhood (relative to ∂T_{j_0}) small enough that it is still disjoint from T_{j+1} and then removing its interior from

 T_{j_0} produces a polyhedral 3-cell *B* contained in T_{j_0} . Thus *K* has a neighbourhood basis of 3-cells and is therefore cellular.

Warning. Whenever we construct a toroidal set as an intersection of a sequence of nested tori we will never check explicitly that it is not cellular, since this will always be a direct consequence of the above proposition.

Consider once more a nested pair of solid tori $T_2 \subseteq T_1$. The inclusion induces a map $H^1(T_1; \mathbb{Z}) \longrightarrow H^1(T_2; \mathbb{Z})$ which, after identifying each of the cohomology groups with \mathbb{Z} with an appropriate orientation, simply becomes multiplication by a non-negative integer $w \ge 0$. This is usually called the *winding number* of T_2 inside T_1 . It is not difficult to see that, if D is any meridional disk of T_1 and γ is a core curve of T_2 transverse to D, then w is the (absolute value of the) number of intersections of γ with D counted with sign according to the sense in which γ crosses D. In particular, choosing D to minimize the number of points of intersection with γ , one has that $w \le N(T_2, T_1)$ and also that w and $N(T_2, T_1)$ have the same parity.

The (Čech) cohomology of toroidal sets will play a role in this paper, so we now devote a few lines to its description. Let $\{T_j\}$ be a standard basis for a toroidal set K. By the continuity property of Čech cohomology, $\check{H}^q(K; \mathbb{Z})$ is the direct limit of the direct sequence $\check{H}^q(T_j; \mathbb{Z}) \longrightarrow \check{H}^q(T_{j+1}; \mathbb{Z})$, where the arrows are induced by the inclusions $T_{j+1} \subseteq T_j$. In degrees $q \ge 2$ clearly $\check{H}^q(K; \mathbb{Z}) = 0$. In degree q = 1, and according to the discussion in the previous paragraph, each of these arrows can be identified with $\mathbb{Z} \xrightarrow{\cdot w_j} \mathbb{Z}$, where w_j is the winding number of T_{j+1} inside T_j . It is very easy to check (or see a proof in [2, Proposition 1.6]) that there are three mutually exclusive possibilities for $\check{H}^1(K; \mathbb{Z})$.

- (i) If infinitely many of the w_j vanish, then $\check{H}^1(K; \mathbb{Z}) = 0$. We then say that K is *trivial*.
- (ii) If $w_j = 1$ from some *j* onwards, then $\check{H}^1(K; \mathbb{Z}) = \mathbb{Z}$.
- (iii) Otherwise $\check{H}^1(K; \mathbb{Z})$ is not finitely generated.

3. Some algebraic preliminaries

We shall begin with some very simple algebra. Given a sequence of non-negative integers $\{m_j\}_{j\geq 1}$, consider the direct sequence

$$\mathbb{Z} \xrightarrow{\cdot m_1} \mathbb{Z} \xrightarrow{\cdot m_2} \mathbb{Z} \longrightarrow \cdots, \tag{1}$$

where each arrow is multiplication by m_j . Denote by G the direct limit of this sequence. The following mutually exclusive alternatives hold.

- (i) G = 0 if and only if $m_i = 0$ for infinitely many *j*.
- (ii) $G = \mathbb{Z}$ if and only if $m_i = 1$ from some *j* onwards.
- (iii) Otherwise G is not finitely generated.

Let p be a prime number. If every element in G is divisible by p we then say that p divides G, or that p is a prime factor of G, and write p|G. The following proposition provides an alternative characterization of this notion. The proof is extremely simple but we include it for completeness.

PROPOSITION 3.1. With the above notation, p|G if and only if p divides infinitely many of the m_j .

Proof. It will be convenient to attach a subscript (j) to each copy of \mathbb{Z} in (1) to distinguish them. We choose the notation so that the arrows read $\mathbb{Z}_{(j)} \xrightarrow{m_j} \mathbb{Z}_{(j+1)}$. Any element $z \in G$ is represented by some $z_{(j_0)} \in \mathbb{Z}_{(j_0)}$. Of course, z is also represented by any of its successive images $z_{(j)} \in \mathbb{Z}_{(j)}$ along the sequence. The relation between $z_{(j_0)}$ and $z_{(j)}$ is just

$$z_{(j)} = z_{(j_0)} \cdot m_{j_0} \cdot m_{j_0+1} \cdot \dots \cdot m_{j-1}.$$
 (2)

Suppose first that *p* divides infinitely many of the m_j . Let *z* be represented by $z_{(j_0)} \in \mathbb{Z}_{(j_0)}$. Our assumption implies that there exists $j \ge j_0$ such that $p|m_j$. From (2) we see that $p|z_{(j+1)}$, and then $z'_{(j+1)} := z_{(j+1)}/p \in \mathbb{Z}_{(j+1)}$ represents an element $z' \in G$ such that pz' = z.

Conversely, assume every element in *G* is divisible by *p*. Fix j_0 and consider the element $z \in G$ represented by $z_{(j_0)} = 1 \in \mathbb{Z}_{(j_0)}$. By assumption there exists $z' \in G$ such that pz' = z. Then for big enough *j* we must have $pz'_{(j)} = z_{(j)}$, so in particular $p|z_{(j)}$. But then from (2) we see that *p* divides some m_k with $j_0 \le k < j$. Since j_0 was arbitrary, it follows that *p* divides infinitely many of the m_j .

Using the proposition, one can easily see that G may not have any prime factors at all or, at the other extreme, it may have infinitely many of them. In fact, it is easy to produce groups G having any prescribed set P of prime numbers as prime divisors.

Example 3.2. Given any set P of prime numbers, there exists a group G whose prime divisors are precisely the elements of P. For instance:

- (i) when $P = \emptyset$ choose m_i to be the *j*th prime number;
- (ii) when *P* is finite choose all the m_j to be equal to *m*, the product of all the elements in *P*;
- (iii) when P is infinite, let $\{p_k\}$ be an enumeration of its elements and choose $m_j := p_1 \cdot \cdots \cdot p_j$.

If all the m_j are equal to some number $m \ge 1$ for big enough j we will say that G is *number-like* \dagger . It is well known that G can then be identified with the *m*-adic rationals; that is, the subgroup of \mathbb{Q} that consists of numbers of the form z/m^k with $z \in \mathbb{Z}$ and k a non-negative integer. This subgroup is usually denoted by $\mathbb{Z}[1/m]$. We will now show that the prime divisors of a number-like G determine it completely.

PROPOSITION 3.3. Let G be number-like. Then it has finitely many prime divisors p_1, \ldots, p_r and $G = \mathbb{Z}[1/(p_1 \cdot \cdots \cdot p_r)]$.

Proof. Since G is number-like, it is the direct limit of (1) with $m_j = m \ge 1$ for large enough j. Then by Proposition 3.1 the prime divisors of G are exactly the prime divisors

 $[\]dagger$ This terminology is slightly abusive, because as introduced it describes not an intrinsic property of *G* but rather of the particular description of *G* afforded by the direct sequence (1) of *G*.

of *m* (in the sense of ordinary arithmetic). In particular, *G* has finitely many prime divisors (and it has none exactly when m = 1, or equivalently when $G = \mathbb{Z}$). Write $m = p_1^{n_1} \cdots p_r^{n_r}$ for appropriate exponents $n_i \ge 1$. Also, set $m_0 := p_1 \cdots p_r$ for brevity. Notice that $m_0 | m$.

Now we prove that $G = \mathbb{Z}[1/m_0]$. Since G can be identified with the subgroup of *m*-adic rationals, we only need to show that the *m*-adic rationals are the same as the m_0 -adic rationals. First, every m_0 -adic rational can be written as an *m*-adic rational as follows:

$$\frac{z}{m_0^k} = \frac{z}{m^k} \cdot \frac{m^k}{m_0^k} = \frac{z \cdot (m/m_0)^k}{m^k} \in \mathbb{Z}[1/m]$$

because $m_0|m$. To prove that every *m*-adic rational is an m_0 -adic rational we first perform the following computation. Letting $n = \max n_i$, we can write *m* as follows:

$$m = p_1^{n_1} \cdot \dots \cdot p_r^{n_r} = \frac{(p_1 \cdot \dots \cdot p_r)^n}{p_1^{n-n_1} \cdot \dots \cdot p_r^{n-n_r}} = \frac{m_0^n}{m'_1}$$

where $m' = p_1^{n-n_1} \cdot \cdots \cdot p_r^{n-n_r} \in \mathbb{Z}$ because of the definition of *n*. Then any *m*-adic rational can be expressed as

$$\frac{z}{m^k} = \frac{z}{(m_0^n/m')^k} = \frac{z \cdot m'^k}{m_0^{nk}} \in \mathbb{Z}[1/m_0].$$

We thus see that when *G* is number-like it conveys exactly the same information as the number $p_1 \cdot \cdots \cdot p_r$. Hopefully this justifies our terminology. We shall sometimes write $G \sim p_1 \cdot \cdots \cdot p_r$. As mentioned in the proof of the proposition, a somewhat degenerate case is $G = \mathbb{Z}$, which is indeed number-like but has no prime factors. We shall then write $G \sim 1$. Notice that \mathbb{Z} is the only number-like *G* that does not have any prime factors.

We conclude this section with a very simple observation. There are two manipulations that can be performed on (1) which clearly do not alter its limit G. The first is just removing a finite number of terms from the beginning of the sequence. The second involves organizing the arrows in (1) into groups of k_1, k_2, \ldots consecutive arrows and replacing each group with a single arrow which is the composition of all the arrows in the group, obtaining the direct sequence

These two operations allow the sequence (1) to be put in a somewhat canonical form that is sometimes convenient.

LEMMA 3.4. Given any group G represented as the direct limit of (1) we may assume that the $\{m_i\}$ are in one of the mutually exclusive forms.

- (i) All the $m_i = 0$, in which case G = 0.
- (ii) All the $m_i = 1$, in which case $G = \mathbb{Z}$.
- (iii) All the $m_i \ge 2$, in which case G is not finitely generated.

Proof. (i) If infinitely many of the m_j are zero, then by grouping the arrows in such a way that each group contains at least one zero arrow we may assume that $m_j = 0$ for all *j*. Clearly then G = 0.

(ii) If (i) does not hold, then only finitely many of the m_j are zero. We may discard them and assume directly that $m_j \ge 1$ for every *j*. If only finitely many of the m_j satisfy $m_j \ge 2$ then we may also discard them and obtain $m_j = 1$ for every *j*. Clearly then $G = \mathbb{Z}$.

(iii) If (i) and (ii) do not hold, then infinitely many of the m_j satisfy $m_j \ge 2$ (and $m_j \ge 1$ for every *j*). Then by grouping the arrows in (1) in such a way that each group contains at least one element equal to or greater than 2 we may assume that $m_j \ge 2$ for every *j*. It is then very easy to see that *G* is not finitely generated (the argument is essentially the same as in [2, Proposition 1.6]).

4. The self-index of a toroidal set

Let *K* be a toroidal set and let $\{T_j\}$ be a standard basis for *K*. Denote by N_j the geometric index of T_{j+1} inside T_j and consider the direct sequence

$$\mathcal{N}\{T_j\}: \mathbb{Z} \xrightarrow{\cdot N_1} \mathbb{Z} \longrightarrow \cdots \longrightarrow \mathbb{Z} \xrightarrow{\cdot N_j} \mathbb{Z} \longrightarrow \cdots$$

PROPOSITION 4.1. The direct limit of $\mathcal{N}\{T_j\}$ is independent of the basis $\{T_j\}$ chosen to compute it.

Proof. First let us show that replacing $\{T_j\}$ with a subsequence $\{T_{j_k}\}$ leaves the direct limit of $\mathcal{N}\{T_i\}$ unchanged. The multiplicativity of the geometric index ensures that

$$N(T_{j_2}, T_{j_1}) = N(T_{j_2}, T_{j_2-1}) \cdot \cdots \cdot N(T_{j_1+1}, T_{j_1}) = N_{j_2-1} \cdot \cdots \cdot N_{j_1}$$

and similarly for the following j_k . Thus the sequence $\mathcal{N}\{T_{j_k}\}$ associated to $\{T_{j_k}\}$ is precisely

$$\mathcal{N}\{T_{j_k}\}: \mathbb{Z} \xrightarrow{\cdot N_{j_1} \cdot \cdots \cdot N_{j_2-1}} \mathbb{Z} \xrightarrow{\cdot N_{j_2} \cdot \cdots \cdot N_{j_3-1}} \mathbb{Z} \xrightarrow{\cdot \cdots \cdot N_{j_3-1}} \mathbb{Z}$$

This can be obtained from the original $\mathcal{N}\{T_j\}$ by removing the first $j_1 - 1$ terms and then grouping the remaining arrows into the blocks $N_{j_k} \cdot \cdots \cdot N_{j_{k+1}-1}$. These two manipulations do not alter the direct limit of the original sequence, and so $\mathcal{N}\{T_j\}$ and $\mathcal{N}\{T_{j_k}\}$ have the same direct limit, as claimed above.

Now let $\{T'_j\}$ be another standard basis for K. We want to show that the direct limits of $\mathcal{N}\{T_j\}$ and $\mathcal{N}\{T'_j\}$ coincide. After passing to suitable subsequences of $\{T_j\}$ and $\{T'_j\}$ we may assume that $T_j \supseteq T'_j \supseteq T_{j+1}$ for every j. By the previous paragraph there is no loss of generality in doing this. As before, we use the notation $N_j = N(T_{j+1}, T_j)$ and $N'_j = N(T'_{j+1}, T'_j)$. Also, set

$$M_j = N(T'_j, T_j)$$
 and $M'_j = N(T_{j+1}, T'_j)$.

The multiplicative property of the geometric index ensures that $N_j = M_j M'_j$ and $N'_j = M'_j M_{j+1}$. Consider the direct sequence

$$\mathbb{Z} \xrightarrow{\cdot M_1} \mathbb{Z} \xrightarrow{\cdot M_1'} \mathbb{Z} \xrightarrow{} \cdots \longrightarrow \mathbb{Z} \xrightarrow{\cdot M_j} \mathbb{Z} \xrightarrow{\cdot M_j'} \mathbb{Z} \xrightarrow{} \cdots$$

Grouping the arrows in pairs yields the sequence

 $\mathbb{Z} \xrightarrow{\cdot N_1} \mathbb{Z} \longrightarrow \cdots \longrightarrow \mathbb{Z} \xrightarrow{\cdot N_j} \mathbb{Z} \longrightarrow \cdots$

which is precisely $\mathcal{N}\{T_j\}$, whereas discarding the first arrow and grouping the remaining ones in pairs yields the sequence

$$\mathbb{Z} \xrightarrow{\cdot N'_1} \mathbb{Z} \longrightarrow \cdots \longrightarrow \mathbb{Z} \xrightarrow{\cdot N'_j} \mathbb{Z} \longrightarrow \cdots$$

which is precisely $\mathcal{N}\{T'_j\}$. It follows that the direct limit of all three sequences is the same, and so in particular $\mathcal{N}\{T_i\}$ and $\mathcal{N}\{T'_i\}$ have the same direct limit, as was to be shown. \Box

The proposition justifies the correctness of the following definition.

Definition 4.2. Given a toroidal set *K*, its *self-geometric index* (or *self-index* for brevity) is the direct limit of the direct sequence $\mathcal{N}\{T_j\}$ for any standard basis $\{T_j\}$ of *K*. We denote the self-index by $\mathcal{N}(K)$.

Since a toroidal set is not cellular by definition, it follows from Proposition 2.2 that $N_j \ge 1$ for sufficiently large *j*. Thus $\mathcal{N}(K) \ne 0$ and $\mathcal{N}(K)$ is either \mathbb{Z} or not finitely generated. The case $\mathcal{N}(K) = \mathbb{Z}$, or $\mathcal{N}(K) \sim 1$ in our notational convention, is interesting enough to single out.

PROPOSITION 4.3. Let $K \subseteq \mathbb{R}^3$ be a toroidal set. The following three statements are equivalent.

(i) $\mathcal{N}(K) \sim 1$.

(ii) $N(T_{j+1}, T_j) = 1$ for large enough j for some standard basis $\{T_j\}$ for K.

(iii) $N(T_{j+1}, T_j) = 1$ for large enough j for any standard basis $\{T_j\}$ for K.

Moreover, if any of these conditions holds then $\check{H}^1(K; \mathbb{Z}) = \mathbb{Z}$.

Proof. Notice that $\mathcal{N}(K) = \mathbb{Z}$ occurs precisely when $N_j = N(T_{j+1}, T_j) = 1$ for large j, so this condition must be independent of the basis $\{T_j\}$ since the same is true of $\mathcal{N}(K)$ by Proposition 4.1. This establishes the equivalence of (i), (ii) and (iii). Denote by w_j the winding number of T_{j+1} inside T_j . Recall that w_j and N_j have the same parity and also $w_j \leq N_j$. These two conditions (together with $N_j = 1$) force $w_j = 1$, and so $\check{H}^1(K; \mathbb{Z}) = \mathbb{Z}$.

Mimicking the definitions of the previous section, we say that a prime *p* divides $\mathcal{N}(K)$ if every element in $\mathcal{N}(K)$ is divisible by *p* or, more operationally and as a consequence of Proposition 3.1, if $p|N(T_{i+1}, T_i)$ for infinitely many *j*.

Example 4.4. Recall from the Introduction that a (possibly knotted) generalized solenoid is a toroidal set *K* defined as the intersection of nested solid tori $\{T_j\}$ such that each T_{j+1} winds monotonically n_j times inside the previous T_j and the thickness of the T_j tends to 0 as *j* increases. We require $n_j > 1$ for each *j*. The monotonicity condition implies that $N(T_{j+1}, T_j) = n_j$ for every *j*, and so $\mathcal{N}(K) \neq 1$ and $p|\mathcal{N}(K)$ if and only if *p* is a prime factor of infinitely many of the n_j . Depending on our choice of the n_j we may find several scenarios.

- (i) If *K* is an *n*-adic solenoid $(n_j = n \text{ for every } j)$ then $\mathcal{N}(K)$ is number-like and the prime divisors of $\mathcal{N}(K)$ are precisely the prime divisors of *n* (in the ordinary sense of elementary arithmetic).
- (ii) One may pick the n_j in such a way that each prime *p* appears as a factor of infinitely many of them (for instance, by taking $n_j = j!$). Then every prime divides $\mathcal{N}(K)$.
- (iii) At the other extreme, one may choose the n_j in such a way that no prime p is a factor of infinitely many of them, for instance by letting all the n_j be pairwise prime to each other. Then $\mathcal{N}(K)$ has no prime divisors.

We conclude this section with a very simple remark concerning generalized solenoids. The monotonicity condition on the tori $\{T_j\}$ implies that the geometric index and the winding number of each pair of consecutive tori both coincide. In particular, the direct sequences that arise when computing the self-index of a generalized solenoid and its Čech cohomology in degree 1 are the same and so their direct limits coincide; that is, $\mathcal{N} = \check{H}^1$. Moreover, since generalized solenoids are topologically characterized by their Čech cohomology (see, for instance, the argument in [22, p. 198]), we have the following remark.

Remark 4.5. Let *K* and *K'* be two generalized solenoids. Then *K* is homeomorphic to *K'* if and only if their self-indices $\mathcal{N}(K)$ and $\mathcal{N}(K')$ are isomorphic (as groups).

5. Elementary properties of the self-index

In this section we discuss some elementary properties of the self-index. We begin by considering the status of the prime p = 2 as a factor of $\mathcal{N}(K)$, which turns out to be somewhat special.

PROPOSITION 5.1. The prime p = 2 is a factor of $\mathcal{N}(K)$ if and only if every element in $\check{H}^1(K; \mathbb{Z})$ is divisible by 2. In particular, having p = 2 as a prime factor of $\mathcal{N}(K)$ is a topological property of toroidal sets.

Proof. Let $\{T_j\}$ be a standard basis for K and denote by w_j and N_j the winding number and the geometric index of each T_{j+1} inside T_j , respectively. By the continuity property of Čech cohomology $\check{H}^1(K; \mathbb{Z})$ is the direct limit of the direct sequence

$$\mathbb{Z} \xrightarrow{\cdot w_1} \mathbb{Z} \xrightarrow{\cdot w_2} \cdots \longrightarrow \mathbb{Z} \xrightarrow{\cdot w_j} \mathbb{Z} \longrightarrow \cdots$$

whereas $\mathcal{N}(K)$ is by definition the direct limit of

 $\mathbb{Z} \xrightarrow{\cdot N_1} \mathbb{Z} \xrightarrow{\cdot N_2} \cdots \longrightarrow \mathbb{Z} \xrightarrow{\cdot N_j} \mathbb{Z} \longrightarrow \cdots.$

Since the geometric index and the winding number both have the same parity, p = 2 divides infinitely many of the w_j if and only if it divides infinitely many of the N_j . The result follows from the characterization of Proposition 3.1.

The next property we consider is the invariance of the self-index under (local) ambient homeomorphisms. It seems reasonable to expect it to hold, but there is a slight technical subtlety: since Definition 4.2 involves neighbourhood bases that consist of polyhedral tori (for the geometric index to be defined), it is clear that the self-index is invariant under piecewise linear homeomorphisms, but not necessarily under arbitrary ones. To prove this in general we will need to make use of the deep result that any homeomorphism of a 3-manifold can be approximated arbitrarily closely by a piecewise linear one.

PROPOSITION 5.2. Let K and K' be toroidal sets in \mathbb{R}^3 . Suppose that $f: O \longrightarrow f(O)$ is a homeomorphism defined on an open neighbourhood O of K and f(K) = K'. Then $\mathcal{N}(K)$ and $\mathcal{N}(K')$ are equal.

Proof. By the invariance of domain theorem f is an open map and O' := f(O) is a neighbourhood of K'. Consider the open 3-manifolds O - K and O' - K'. These are homeomorphic via f. Let $\phi : O - K \longrightarrow (0, +\infty)$ be defined by $\phi(p) := d(p, K)$, where d denotes the usual distance. Clearly ϕ is bounded away from 0 on every compact subset of O - K, and then [23, Theorem 1, p. 253] guarantees that there exists a piecewise linear homeomorphism $g : O - K \longrightarrow O' - K'$ such that $d(f(p), g(p)) < \phi(p)$ for every $p \in O - K$. Extend g to all of O by defining g(p) := f(p) for $p \in K$. It is straightforward to check that this extension provides a continuous bijection from O to O', which is therefore a homeomorphism by the invariance of domain theorem.

Now let $\{T_j\}$ be a standard basis for K with all T_j contained in O. Define $T'_j := g(T_j)$. These clearly form a standard basis for K' because g is a homeomorphism. Moreover, by construction g provides homeomorphisms of pairs $g : (T_j, T_{j+1}) \longrightarrow (T'_j, T'_{j+1})$ which are piecewise linear on T_j – int T_{j+1} . Thus by Lemma 2.1 the geometric indices $N(T_{j+1}, T_j)$ and $N(T'_{j+1}, T'_j)$ are equal. The equality $\mathcal{N}(K) = \mathcal{N}(K')$ then follows from Proposition 4.1.

We conclude this section by investigating the relation between the cohomology of a toroidal set and its self-index. Essentially we shall see that, besides the relation between these two magnitudes afforded by Propositions 4.3 and 5.1, they are independent variables. This we do by showing how to construct toroidal sets *K* that have a prescribed cohomology group *H* (in degree 1) and whose self-index is some prescribed group *N*. Of course *H* and *N* cannot be entirely arbitrary since they must be the direct limit of a direct sequence of the form (1). Let us say that a group is *feasible* if it has this form. Also, the fact that toroidal sets cannot be cellular requires that $N \neq 0$ by Proposition 2.2. Finally, and as a consequence of Propositions 4.3 and 5.1, if the variables *H* and *N* are to be realized as the cohomology and self-index of a toroidal set they must satisfy the following two compatibility conditions.

- (C1) 2|H if and only if 2|N.
- (C2) If $N \sim 1$ then $H \sim 1$.

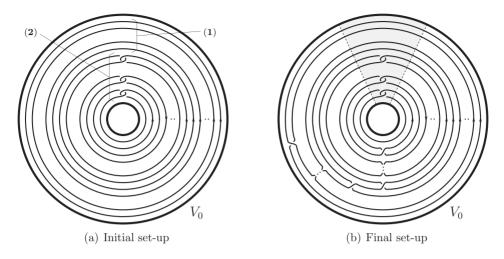


FIGURE 1. The construction for Lemma 5.4.

THEOREM 5.3. Let H and N be feasible groups. Suppose that $N \neq 0$, and H and N satisfy the above compatibility conditions. Then there exists a toroidal set K such that $\check{H}^1(K;\mathbb{Z}) = H$ and $\mathcal{N}(K) = N$. Moreover, K is unknotted.

We recall that a toroidal set is *unknotted* if it has a neighbourhood basis of unknotted solid tori. A consequence of Theorem 5.3 and Example 3.2 is that if *P* is any set of prime numbers that satisfies the consistency condition $2 \in P \Leftrightarrow 2|\check{H}^1(K;\mathbb{Z})$, there exists a toroidal set *K* such that the prime divisors of $\mathcal{N}(K)$ are precisely the elements of *P*.

To prove the theorem we need an auxiliary lemma which provides the key to the construction.

LEMMA 5.4. Let w and k be a pair of non-negative integers. Denote by $V_0 \subseteq \mathbb{R}^3$ the standard unknotted solid torus. Then there exists an unknotted solid torus $V_1 \subseteq$ int V_0 such that the winding number of V_1 inside V_0 is w and the geometric index $N(V_1, V_0) = w + 2k$.

Proof. To prove the lemma it suffices to find an unknotted simple closed curve γ in int V_0 such that its winding number and geometric index in V_0 are w and w + 2k respectively, since then any regular neighbourhood V_1 of γ contained in int V_0 will fulfil our requirements.

Figure 1(a) shows a view of V_0 from the top and, contained in its interior, two groups of oriented simple closed curves. The outermost group, labeled (1), consists of w curves $\gamma_1, \ldots, \gamma_w$ that wind monotonically once around V_0 . The innermost group (2) consists of k curves $\gamma_{w+1}, \ldots, \gamma_{w+k}$ which we call Whitehead curves because they are patterned after one of the components of the Whitehead link. All the curves in the first group have the same orientation. The Whitehead curves have alternating orientations, chosen in such a way that the outermost strand of the outermost Whitehead curve runs parallel to the innermost curve of group (1).

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Let γ be the result of taking the (oriented) connected sum of all the γ_j arranged as shown in Figure 1(b). The choice of orientations ensures that in performing the connected sum of each curve with the adjacent one we include a twist rather than having a turning point where γ would double back over.

Since each γ_j is the unknot, the same is true of γ . It is also clear from the construction that each γ_j with $j \le w$ has winding number 1 in V_0 while each γ_j with j > w has winding number 0, so that γ has winding number w in V_0 . It only remains to check that the geometric index of γ in V_0 is precisely 2k + w. To see this we apply a technique of Andrist *et al.* [1]. The dotted radial lines in Figure 1(b) represent two meridional disks which decompose the solid torus V_0 into two sectors C_1 and C_2 , where C_1 is shaded light grey. Sectors of this form are called chambers in [1]. For $1 \le j \le w$ the intersection $\gamma_j \cap C_1$ just consists of an arc that runs from one of the meridional disks to the other without turning back over. Arcs of this form are called spanning arcs. For $w + 1 \le j \le w + k$ the intersection $\gamma_j \cap C_1$ consists of a pair of linked arcs; these are called Whitehead clasps (see [1, Figure 5(b), p. 9]). The intersection of every γ_j with the chamber C_2 just consists of one or two spanning arcs. In this situation [1, Corollary 4.6, p. 237] ensures that the geometric index $N(\gamma, V_0) = w + 2k$.

Proof of Theorem 5.3. Since *H* and *N* are feasible, both can be written as direct limits of the form

$$H = \varinjlim \{ \mathbb{Z} \xrightarrow{w_j} \mathbb{Z} \} \text{ and } N = \varinjlim \{ \mathbb{Z} \xrightarrow{n_j} \mathbb{Z} \}$$

where the $\{w_j\}$ and $\{n_j\}$ are as described in Lemma 3.4. Of the cases considered there we must have $n_j \ge 1$ for all *j* because $N \ne 0$ by assumption.

CLAIM. We can assume that all the w_j and n_j have the same parity.

To check this suppose first that 2|H. By Proposition 3.1 we see that w_j must be even for infinitely many *j*, and by grouping the w_j into blocks each of which contains at least an even arrow we may assume that all the w_j are even. By the consistency condition of the theorem 2|N too, and by the same argument we may take n_j to be even for all *j*. A similar reasoning applies when $2 \ / H$ (this time discarding a finite number of the w_j and n_j instead of grouping arrows as before), and in that case we may take all the w_j and n_j to be odd. Summing up, we can assume without loss of generality that all the w_j and n_j have the same parity.

CLAIM. We can assume that $w_j \leq n_j$ for every j.

In the case $N \sim 1$ the compatibility condition (C2) requires $H \sim 1$ and so $w_j = n_j = 1$ for large enough *j*. Let us assume then that $N \not\sim 1$. Then according to Lemma 3.4 we must have $n_j \geq 2$ for every *j*. Now consider w_1 . Since $n_j \geq 2$ for every *j*, by taking a product $n_1 \cdots n_{k_1}$ for sufficiently large k_1 we can achieve $w_1 \leq n_1 \cdots n_{k_1}$. Similarly, taking $k_2 > k_1$ big enough we can achieve $w_2 \leq n_{k_1+1} \cdots n_{k_2}$, and so on. That is, by grouping the arrows in the defining sequence for *N* we can certainly assume that $w_j \leq n_j$ for every *j*. Notice that this does not change the parity of the n_j .

Our choice of the w_j and n_j ensures that the equation $2k_j + w_j = n_j$ has an integer solution $k_j \ge 1$ for each j. Then by Lemma 5.4 we may construct a nested sequence of

unknotted solid tori $\{T_j\}$ such that the winding number and the geometric index of T_{j+1} inside T_j are precisely w_j and n_j , respectively. Let $K := \bigcap_{j\geq 0} T_j$. Proposition 2.2 shows that K is not cellular; hence, it is a toroidal set. It is clear that K is unknotted and has $\check{H}^1(K; \mathbb{Z}) = H$ and $\mathcal{N}(K) = N$ as required.

6. Weak tameness of toroidal sets

In this section we characterize weakly tame toroidal sets. A compact set $K \subseteq \mathbb{R}^3$ is called *weakly tame* if there exists a compact polyhedron $P \subseteq \mathbb{R}^3$ such that $\mathbb{R}^3 - K$ and $\mathbb{R}^3 - P$ are homeomorphic. For example, cellular sets are weakly tame because they are point-like: their complement is homeomorphic to the complement of a point. Every tame set (that is, a set that can be carried onto a polyhedron by an ambient homeomorphism) is also weakly tame, but the converse is not generally true. For example, there is an arc in \mathbb{R}^3 (see [23, pp. 137–138]) which is not tame but is weakly tame because its complement is homeomorphic to the complement of a point.

To formulate our results we need to recall a definition (see [2]) which generalizes the classical notion of the genus of a knot to toroidal sets. First define the genus g(T) of a solid torus T as the genus of a core curve of T (this definition is correct because core curves are unique up to isotopy). Then for a toroidal set $K \subseteq \mathbb{R}^3$ define its genus g(K) as the minimum $g = 0, 1, \ldots, +\infty$ such that K has arbitrarily small neighbourhoods that are solid tori of genus less than or equal to g. Notice that if K has finite genus then it has a standard basis $\{T_j\}$ such that $g(T_j) = g(K)$ for every j. By contrast, if K has infinite genus then $\lim_{j\to +\infty} g(T_j) = +\infty$ for any such basis. Also, a toroidal set K has genus 0 if and only if it has a neighbourhood basis of solid tori $\{T_j\}$ of genus 0, which means that they are all unknotted. This is precisely what we called unknotted toroidal sets earlier. For information about knot theory we refer the reader to the books by Burde and Zieschang [5], Lickorish [21] or Rolfsen [26].

The main theorem in this section is as follows.

THEOREM 6.1. Let $K \subseteq \mathbb{R}^3$ be a toroidal set. Then K is weakly tame if and only if the genus of K is finite and $\mathcal{N}(K) \sim 1$.

In fact, when the genus of *K* is strictly positive, the condition $\mathcal{N}(K) \sim 1$ can be replaced with a weaker one.

THEOREM 6.2. Let $K \subseteq \mathbb{R}^3$ be a toroidal set with positive genus. Then K is weakly tame if and only if the genus of K is finite and K is non-trivial.

Example 6.3. None of the (unknotted) generalized solenoids of Example 4.4 satisfies $N \sim 1$; thus, none of them is weakly tame.

We devote the rest of this section to proving Theorems 6.1 and 6.2. This requires some work. We begin with a criterion that allows one to recognize when a toroidal set is weakly tame in terms of any one of its standard neighbourhood bases. We recall that two nested tori $T_2 \subseteq T_1$ are *concentric* if there exists a homeomorphism $g: T_1 - \text{int } T_2 \longrightarrow (\partial T_1) \times [0, 1]$ such that for every $p \in \partial T_1$ one has $g(p) = (p, 0) \in (\partial T_1) \times [0, 1]$.

PROPOSITION 6.4. Let $K \subseteq \mathbb{R}^3$ be a toroidal set. Then the following assertions are equivalent.

- (i) *K* is weakly tame.
- (ii) There exists a standard basis $\{T_j\}$ for K such that T_{j+1} and T_j are concentric for all j.
- (iii) For any standard basis $\{T_j\}$ for K there exists j_0 such that T_{j+1} and T_j are concentric for all $j \ge j_0$.

Proof. (i) \Rightarrow (ii) By assumption there exists a homeomorphism $h : \mathbb{R}^3 - P \longrightarrow \mathbb{R}^3 - K$ for some compact polyhedron *P*. We may assume without loss of generality that *h* is piecewise linear [23, Theorem 2, p. 253]. Notice that

$$H^{q}(P;\mathbb{Z}) = \tilde{H}_{2-q}(\mathbb{R}^{3} - P;\mathbb{Z}) = \tilde{H}_{2-q}(\mathbb{R}^{3} - K;\mathbb{Z}) = \check{H}^{q}(K;\mathbb{Z})$$

where the first and last equalities follow from Alexander duality. This shows (setting q = 0) that *P* must be connected and $\check{H}^q(P; \mathbb{Z}) = 0$ for $q \ge 2$. For q = 1 we argue as follows. The only possibilities for $\check{H}^1(K; \mathbb{Z})$ are either 0, \mathbb{Z} , or a non-finitely generated group. Since compact polyhedra have finitely generated cohomology, it follows that $H^1(P; \mathbb{Z})$ is either 0 or \mathbb{Z} .

CLAIM. *h admits an extension to a homeomorphism* $\hat{h} : \mathbb{S}^3 - P \longrightarrow \mathbb{S}^3 - K$.

Proof of claim. Let $B \subseteq \mathbb{R}^3$ be a closed 3-ball so big that it contains P in its interior and denote by S its boundary 2-sphere. Clearly $\mathbb{R}^3 - S$ has two connected components: an unbounded one U (which is the complement of B) and a bounded one int B. Let us examine the connected components of $(\mathbb{R}^3 - P) - S$. Since P has zero cohomology in degree 2, it does not disconnect any connected open set that contains it (this follows from Alexander's duality). Writing $(\mathbb{R}^3 - P) - S = U \cup ((\text{int } B) - P)$ thus exhibits $(\mathbb{R}^3 - P) - S$ as the disjoint union of two connected sets, which are therefore its connected components. Notice that both have non-zero homology in dimension 2: the first one because it is just homeomorphic to $\mathbb{S}^2 \times \mathbb{R}$ by construction; the second one because it is the result of removing a non-empty compact set from the interior of an open set with trivial homology (formally, this follows again from an application of Alexander's duality).

Since the 2-sphere *S* is contained in $\mathbb{R}^3 - P$ we may transform it via *h* to obtain another 2-sphere S' := h(S). By the polyhedral Schönflies theorem [23, Theorem 12, p. 122], *S'* bounds a closed 3-ball *B'* in \mathbb{R}^3 . Notice that we do not know a priori whether *K* is contained in this ball; this is precisely what we want to prove now. Denote $U' := \mathbb{R}^3 - B'$. The same reasoning as used in the previous paragraph, but now taking into account that *K* may be contained in *U'* or in *B'*, leads to the conclusion that the connected components of $(\mathbb{R}^3 - K) - S'$ are either

$$U' - K$$
 and int B' (if $K \subseteq U'$)

or

$$U'$$
 and $(\text{int } B') - K$ $(\text{if } K \subseteq B').$

We mentioned earlier that both components of $(\mathbb{R}^3 - P) - S$ have non-zero homology in dimension 2, so the same must be true of the components of $(\mathbb{R}^3 - K) - S'$ because the two spaces are homeomorphic under *h*. This rules out the first alternative above, because int *B'* has trivial homology. Thus it must be the case that $K \subseteq \text{int } B'$ and the components of $(\mathbb{R}^3 - K) - S'$ are precisely U' and (int B') - K. Now, there are two possibilities for how *h* matches the components of $(\mathbb{R}^3 - P) - S$ and $(\mathbb{R}^3 - K) - S'$. Either we have

$$h(U) = U'$$
 and $h((\operatorname{int} B) - P) = (\operatorname{int} B') - K$

or we have

$$h(U) = (\operatorname{int} B') - K$$
 and $h((\operatorname{int} B) - P) = U'$

However, the second alternative is not possible. From h(U) = (int B') - K we would get $h(U \cup S) = B' - K$, and this would extend to a homeomorphism between the one-point compactifications of $U \cup S$ and B' - K. That of $U \cup S$ is just a 3-ball, whereas the one-point compactification of B' - K can be thought of as B'/K with [K] acting as the point at infinity. But then B'/K is a 3-ball, which implies that K is pointlike and by [7, Proposition 2.4.5, p. 61] that K is actually cellular, contradicting the definition of a toroidal set. We are left with h(U) = U'. Then $h(U \cup S) = U' \cup S$ and this can be extended to the point at infinity to yield the required \hat{h} . This concludes the proof of the claim.

Let N be a regular neighbourhood of P and define $T := \hat{h}(N - P) \cup K$. Clearly T contains K. In fact, the following claim holds.

CLAIM. T is a compact manifold that is a neighbourhood of K. Moreover, T is connected and ∂T is either a 2-sphere or a 2-torus.

Proof of claim. Begin by writing $\mathbb{S}^3 = (\mathbb{S}^3 - N) \uplus (N - P) \uplus P$, where \uplus means a union of disjoint sets. Then we see that $\mathbb{S}^3 = \hat{h}(\mathbb{S}^3 - N) \uplus \hat{h}(N - P) \uplus K = \hat{h}(\mathbb{S}^3 - N) \uplus T$, and this gives the convenient relation $\mathbb{S}^3 - T = \hat{h}(\mathbb{S}^3 - N)$.

To prove that *T* is a neighbourhood of *K*, suppose the contrary. Then there exists a sequence $\{q_n\}$ in $\mathbb{S}^3 - T$ that converges to some point in *K*. The sequence $\{p_n := \hat{h}^{-1}(q_n)\}$ is then contained in $\hat{h}^{-1}(\mathbb{S}^3 - T) = \mathbb{S}^3 - N$, and so after passing to a subsequence we may assume that it converges to some point $p \in \overline{\mathbb{S}^3 - N} = \mathbb{S}^3 - \text{ int } N$. But this set is still contained in the domain of \hat{h} , and so $q_n = \hat{h}(p_n)$ would converge to $\hat{h}(p)$, which is not possible because $\{q_n\}$ does not converge in $\mathbb{S}^3 - K$.

Writing $T = (T - K) \cup$ int *T* exhibits it as the union of two open (in *T*) sets. The first is a 3-manifold with boundary because it is homeomorphic to N - P via \hat{h}^{-1} by definition, whereas the second is a 3-manifold without boundary because it is open in \mathbb{S}^3 . Thus *T* is a compact 3-manifold with boundary. Resorting again to Alexander's duality and bearing in mind that $\mathbb{S}^3 - T$ and $\mathbb{S}^3 - N$ are homeomorphic via \hat{h} , we have

$$H^{q}(T;\mathbb{Z}) = H_{3-q}(\mathbb{S}^{3} - T;\mathbb{Z}) = H_{3-q}(\mathbb{S}^{3} - N;\mathbb{Z}) = H^{q}(N;\mathbb{Z}) = H^{q}(P;\mathbb{Z}),$$

where in the last step we have used that N is a regular neighbourhood of P and so collapses onto it. Recalling the computation of the cohomology of P at the beginning of

this proof, we conclude that *T* is connected, has vanishing cohomology in degrees $q \ge 2$, and has cohomology either 0 or \mathbb{Z} in dimension q = 1. A routine argument using the Poincaré–Lefschetz duality then shows that ∂T is either a 2-sphere or a 2-torus.

Now we repeat the same construction not just for a single *N*, but for a neighbourhood basis of *P* comprised of nested regular neighbourhoods N_j . As before, denote by $T_j = \hat{h}(N_j - P) \cup K$ the corresponding neighbourhoods of *K*. Since the sets $\mathbb{S}^3 - N_j$ clearly form an ascending sequence whose union is $\mathbb{S}^3 - P$, the sets $\hat{h}(\mathbb{S}^3 - N_j)$ also form an ascending sequence whose union is $\hat{h}(\mathbb{S}^3 - P) = \mathbb{S}^3 - K$. It then follows from the expression $\mathbb{S}^3 - T_j = \hat{h}(\mathbb{S}^3 - N_j)$ obtained above that the T_j form a decreasing sequence whose intersection is *K*. Thus $\{T_j\}$ is a nested neighbourhood basis of *K* comprised of compact, connected manifolds.

We established earlier that ∂T_j is either a 2-sphere or a 2-torus. In the first case, the Schönflies theorem for polyhedral spheres implies that T_j is a 3-ball. If this occurs for infinitely many indices j then K would be cellular, which contradicts the definition of a toroidal set. Thus we may assume without loss of generality that all the ∂T_j are 2-tori. Consider any one T_{j_0} . Since K is toroidal, it has a neighbourhood T which is a solid torus contained in the interior of T_{j_0} . Choose $j_1 > j_0$ so that $T_{j_1} \subseteq \text{int } T$. Observe that $T_{j_0} - \text{int } T_{j_1}$ is homeomorphic via h to $N_{j_0} - \text{int } N_{j_1}$, which is in turn homeomorphic to $(\partial N_{j_0}) \times [0, 1]$ by the annulus theorem for regular neighbourhoods [27, Corollary 3.18, p. 35]. Pulling back this homeomorphism via h shows that $T_{j_0} - \text{int } T_{j_1}$ is also homeomorphic to $(\partial T_{j_0}) \times [0, 1]$. A direct application of a concentricity theorem of Edwards [9, Theorem 2, p. 419] then ensures that T is concentric with both T_{j_0} and T_{j_1} , so in particular all three of them are homeomorphic; hence, they are all (concentric) solid tori. Thus $\{T_j\}$ is the required neighbourhood basis of K.

(ii) \Rightarrow (iii) Let $\{T_j\}$ and $\{T'_k\}$ be two neighbourhood bases of K comprised of nested solid tori. Assume that the T_j are all concentric. Choose k_0 big enough so that $T'_{k_0} \subseteq$ int T_1 . Pick any $k_1 > k_0$ and finally let j be big enough so that $T_j \subseteq$ int T'_{k_1} . Thus we have the nested tori $T_j \subseteq T'_{k_1} \subseteq T'_{k_0} \subseteq T_1$. Since T_1 and T_j are concentric by assumption, the concentricity theorem of Edwards mentioned in the previous paragraph ensures that T'_{k_0} is concentric with both T_1 and T_j . Then again the same theorem, this time applied to $T_j \subseteq T'_{k_1} \subseteq T'_{k_0}$, ensures that T'_{k_1} is concentric with T'_{k_0} . Thus the $\{T'_k\}$ are all concentric for $k \ge k_0$.

(iii) \Rightarrow (i) Let $\{T_j\}$ be a standard basis for *K* comprised of concentric tori. Denote by R_j each region T_j – int T_{j+1} , so that $T_1 - K = \bigcup R_j$. Since the $\{T_j\}$ are concentric, each R_j is homeomorphic to $(\partial T_j) \times [j, j+1]$ via some homeomorphism h_j such that $h_j(p, j) = p$ for every $p \in \partial T_j$. It is then easy to modify the h_j in such a way that they can all be pasted together to yield a homeomorphism from $\bigcup R_j$ onto $(\partial T_1) \times [1, +\infty)$. (See the proof of implication (ii) \Rightarrow (i) in [2, Theorem 3.11, p. 18] for more details.) The latter is, in turn, homeomorphic to $T_1 - \gamma$, where γ is a core curve of T_1 . Extending this by the identity to all of \mathbb{R}^3 yields a homeomorphism between $\mathbb{R}^3 - K$ and $\mathbb{R}^3 - \gamma$, where γ is a polyhedral simple closed curve. This shows that *K* is weakly tame.

Remark 6.5. Since a polyhedral simple closed curve is perhaps the simplest example of a toroidal set, it would also seem reasonable to define a toroidal set to be weakly tame if

its complement is homeomorphic to the complement of such a curve, rather than to the complement of an arbitrary polyhedron *P*. It follows from the proof of (iii) \Rightarrow (i) in the preceding proposition that both definitions are equivalent.

The proof of Theorem 6.1 is now very simple.

Proof of Theorem 6.1. Suppose first *K* is weakly tame. Then it has a standard basis of concentric tori $\{T_j\}$ by Proposition 6.4. Clearly concentric tori have the same genus and the geometric index $N(T_{j+1}, T_j)$ is 1. It follows that $g(K) < +\infty$ (by definition) and $\mathcal{N}(K) \sim 1$ by Proposition 4.1.

Now suppose $g(K) < +\infty$ and $\mathcal{N}(K) \sim 1$. By the definition of the genus of a toroidal set there exists a standard basis $\{T_j\}$ for K such that $g(T_j) = g(K)$ for every j. Also, the assumption that $\mathcal{N}(K) \sim 1$ implies, by Proposition 4.3, that $\mathcal{N}(T_{j+1}, T_j) = 1$ for large enough j. This condition on the geometric index entails (see [32, Satz 2, p. 171]) that the core curve of T_{j+1} is the connected sum of the core curve of T_j with some other knot γ_j . But, since the genera of T_j and T_{j+1} are equal and genus is additive under connected sums, it follows that the genus of γ_j must be 0. Therefore the core curves of T_j and T_{j+1} are equivalently knotted. A result of Edwards [10, Theorem 3, p. 4] then implies that T_j and T_{j+1} are concentric. Hence K is weakly tame by Proposition 6.4.

As for Theorem 6.2, we require still another previous lemma.

LEMMA 6.6. Let $T_2 \subseteq T_1$ be a nested pair of solid tori. Assume that:

- (i) the winding number w of T_2 inside T_1 is positive;
- (ii) the genera g of T_1 and T_2 are equal and positive.

Then T_1 and T_2 are concentric.

Before proving the lemma, recall that a spine of a polyhedral manifold N is a polyhedron $P \subseteq \operatorname{int} N$ such that N collapses onto P, which we denote by $N \searrow P$ as customary. We will need the following result of Hudson and Zeeman (see [16, Corollary 5, p. 727]): if P and P' are two polyhedra in int N that are related by a sequence of collapses and expansions in N (but not necessarily in int N) then P is a spine of N if and only if P' is a spine of N. In our case N will always be a neighbourhood of P in the ambient 3-manifold (so in particular its interior as a manifold coincides with its topological interior), and then saying that P is a spine of N is equivalent to saying that N is a regular neighbourhood of P (see [27, Corollary 3.30, p. 41]).

Proof of Lemma 6.6. Let γ_1 and γ_2 be core curves for T_1 and T_2 , respectively. Let also $\lambda_1 \subseteq \partial T_1$ be a longitude of T_1 .

CLAIM. It suffices to show that γ_2 and λ_1 cobound an annulus in T_1 .

Proof of claim. Let A' be the annulus cobounded by γ_2 and λ_1 in T_1 , and denote by A an annulus cobounded by γ_1 and λ_1 in T_1 (this always exists). Any annulus collapses onto each one of its boundary curves. Thus we may write $\gamma_1 \nearrow A \searrow \lambda_1 \nearrow A' \searrow \gamma_2$ within T_1 , and since γ_1 is a spine of T_1 , the result of Hudson and Zeeman mentioned earlier

implies that γ_2 is a spine of T_1 . This means that T_1 is a regular neighbourhood of γ_2 in \mathbb{R}^3 and, since T_2 is also a regular neighbourhood of γ_2 (the latter being a core for T_2), the regular neighbourhood annulus theorem (see, for instance, [16, Corollary 1, p. 725] or [27, Corollary 3.18, p. 36]) guarantees that T_2 and T_1 are concentric. This proves the claim.

Now we shall show γ_2 and λ_1 indeed cobound an annulus in T_1 . This follows from an examination of the proof of Schubert's relation between the genus of a satellite knot and its companion as given, for example, in the book by Burde and Zieschang [5]. In our setting γ_2 is a satellite of γ_1 and the relation just mentioned reads $g(T_2) \ge w \cdot g(T_1) + g'$, where g' is the genus of the pattern of T_2 inside T_1 . By assumption $g(T_1) = g(T_2) = g > 0$ and (since $g' \ge 0$ and $w \ge 1$), this inequality implies w = 1.

Let *S* be a Seifert surface of minimal genus that spans γ_2 . Without loss of generality we may assume that *S* is transversal to ∂T_1 . Let S_i and S_o be the parts of *S* that lie inside and outside T_1 , respectively; that is, $S_i := S \cap T_1$ and $S_o := S \cap (\mathbb{R}^3 - T_1)$. Both of these are (a priori, possibly non-connected) orientable surfaces with boundary. We may choose (see [5, Lemma 2.11, p. 21]) *S* so that: (i) it intersects ∂T_1 transversally in a longitude λ_1 ; and (ii) S_o consists of a single connected component (whose boundary is, therefore, precisely λ_1).

Since λ_1 is a longitude of T_1 , it cobounds an annulus in T_1 with its core curve γ_1 . The union of this annulus and S_o produces a Seifert surface for γ_1 whose genus is the same as that of S_o . Thus the genus of S_o is greater than or equal to the genus of γ_1 , namely g. In terms of the Euler characteristic, $\chi(S_o) \leq 1 - 2g$.

Recall that *S* was a minimal Seifert surface for γ_2 , which also has genus *g* by assumption. Thus we have $\chi(S) = 1 - 2g$. Then from $\chi(S) = \chi(S_i) + \chi(S_o)$ and the inequality of the previous paragraph we get $\chi(S_i) \ge 0$. Since S_i arose by cutting the connected surface *S* along ∂T_1 , the boundary of each component of S_i must have a non-empty intersection with ∂T_1 . But, since $S \cap \partial T_1$ consists of the single curve λ_1 , it follows that S_i is actually connected and its boundary has precisely two components; namely γ_2 and λ_1 . The only connected, orientable surface with two boundary components and non-negative Euler characteristic is the annulus. Thus S_i is the required annulus that cobounds γ_2 and the longitude λ_1 in T_1 .

Proof of Theorem 6.2. It follows from the definition of the genus that *K* has a standard basis $\{T_j\}$ such that $g(T_j) = g(K)$ for all *j*. Denote by w_j the winding number of T_{j+1} inside T_j . Since $\check{H}^1(K; \mathbb{Z}) \neq 0$ by assumption, we must have $w_j > 0$ for big enough *j*. It then follows from Lemma 6.6 that all the pairs (T_j, T_{j+1}) are concentric from some *j* onwards. Finally, Proposition 6.4 implies that *K* is weakly tame.

Conversely, if *K* is weakly tame then by Theorem 6.1 its genus is finite. Also, it has a neighbourhood basis of concentric tori by Proposition 6.4 and therefore clearly $\mathcal{N}(K) \sim 1$ (or use Proposition 4.3).

7. Applications to the realizability problem

We finally turn to the realizability problem for toroidal sets, and we begin by recalling some definitions from topological dynamics. We state them for the discrete case, but the case of flows is completely analogous. Let *f* be a homeomorphism of \mathbb{R}^3 . An *attractor*

(sometimes called asymptotically stable) for *f* is a compact invariant set $K \subseteq \mathbb{R}^3$ which is stable in the sense of Lyapunov and attracts all points in some neighbourhood *U* of *K*. Explicitly, these conditions have the following meanings.

- (i) K is invariant: f(K) = K.
- (ii) *K* attracts points in *U*: for every neighbourhood *V* of *K* and every $p \in U$ there exists $n_0 \in \mathbb{N}$ such that $f^n(p) \in V$ for every $n \ge n_0$.
- (iii) *K* is Lyapunov stable: for every neighbourhood *V* of *K* there exists another neighbourhood V_0 of *K* such that $f^n(V_0) \subseteq V$ for every $n \ge 0$.

The maximal neighbourhood U with property (ii) is called the *basin of attraction* of K and is an open invariant subset of \mathbb{R}^3 . We denote it by $\mathcal{A}(K)$.

The conjunction of (ii) and (iii) implies that *K* not only attracts points in $\mathcal{A}(K)$ but also neighbourhoods of points and in fact compacta *P* of the basin of attraction. This is fairly easy to check. Consider first a point $p \in \mathcal{A}(K)$. Given a neighbourhood *V* of *K*, by (iii) we may find another neighbourhood V_0 of *K* such that $f^n(V_0) \subseteq V$ for every $n \ge 0$. In turn by (ii) there exists $n_0 \in \mathbb{N}$ such that $f^{n_0}(p) \in \operatorname{int} V_0$ and, since f^{n_0} is continuous, there exists a neighbourhood W_p of *p* such that $f^{n_0}(W_p) \subseteq V_0$. Then $f^n(W_p) \subseteq f^{n-n_0}(V_0) \subseteq V$ for every $n \ge n_0$, which is a condition analogous to (ii) but now for the neighbourhood W_p of *p* instead of *p* alone. Now let *P* be a compact subset of $\mathcal{A}(K)$. Covering it with a finite number of the W_p and choosing n_0 to be the maximum of the n_0 s associated to these W_p , one sees that $f^n(P) \subseteq V$ for $n \ge n_0$. Thus *K* attracts compact subsets of $\mathcal{A}(K)$. (Actually in our case, where the phase space is locally compact, attracting compact subsets of $\mathcal{A}(K)$ is equivalent to the attractor being stable in the sense of Lyapunov.) It is this geometric property of *f* that we will make essential use of. For attractors that are not stable our results do not hold true in general.

The realization problems for flows and homeomorphisms are not equivalent, with the former being much easier than the latter. The reason is that the flow near an attractor is parallelizable, which entails that if U is an appropriate neighbourhood of the attractor K then U - K has the structure of a Cartesian product $\Sigma \times \mathbb{R}$ where Σ arises dynamically as a section of the flow in $\mathcal{A}(K) - K$. The converse is also true: if K is a compactum having a neighbourhood U such that U - K has such a product structure, then it can be realized as an attractor for a flow. In 3-manifolds this can be exploited to show that a compactum K can be realized as an attractor for a flow if and only if it is weakly tame [28, Theorem 11, p. 6169], which combined with Theorem 6.1 leads to our first result in §1.

THEOREM A. A toroidal set $K \subseteq \mathbb{R}^3$ can be realized as an attractor for a flow if and only if its genus is finite and $\mathcal{N}(K) \sim 1$.

Using this we may be more explicit about the claim made above that the realization problems for flows and homeomorphisms are not equivalent, since we can easily exhibit examples of toroidal sets that are attractors for homeomorphisms but cannot be realized as attractors for flows. For example, an *n*-adic solenoid *K* is one of the most paradigmatic attractors for a homeomorphism but it cannot be realized as an attractor for a flow since $\mathcal{N}(K) \not\sim 1$ (the prime divisors of $\mathcal{N}(K)$ are the prime divisors of *n* by Example 4.4). As another example, consider an unknotted solid torus $V_0 \subseteq \mathbb{R}^3$ and let $f : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$

be a homeomorphism such that the solid torus $f(V_0)$ lies inside the interior of V_0 in the pattern of a Whitehead curve (the innermost curve in Figure 1(a)). The positively invariant set V_0 contains the attractor $K := \bigcap_{j\geq 0} f^j(V_0)$, which is a classical object in geometric topology called the Whitehead continuum. The tori $T_j := f^j(T)$ form a neighbourhood basis for K and, since $N(T_{j+1}, T_j) = 2$ for each j, one has that $2|\mathcal{N}(K)$. Thus $\mathcal{N}(K) \not\sim 1$ and therefore K cannot be realized as an attractor for a flow.

For the rest of this section we concentrate on the realizability of toroidal sets as attractors for homeomorphisms. The usefulness of the self-index in this problem stems from the following theorem.

THEOREM B. Let K be a toroidal set that is an attractor for a homeomorphism f of \mathbb{R}^3 . Then $\mathcal{N}(K)$ is number-like. Moreover, $\mathcal{N}(K) \sim 1$ if and only if K can be realized as an attractor for a flow.

Before proving the theorem we include some corollaries. The following two characterize what toroidal sets can be realized as attractors for two wide families of sets: (i) non-trivial toroidal sets with positive genus; and (ii) toroidal sets with no prime factors in $\mathcal{N}(K)$. Both corollaries combine Theorem B with the result that an attracting toroidal set must have a finite genus (see [2, Theorem 3.1, p. 13]).

COROLLARY 7.1. Let $K \subseteq \mathbb{R}^3$ be a non-trivial toroidal set with positive genus. Then K can be realized as an attractor for a homeomorphism if and only if its genus is finite.

Proof. As just mentioned, it is known that toroidal attractors have finite genus; therefore, only (\Leftarrow) needs proof. By Theorem 6.2 the condition that *K* is non-trivial and has a positive and finite genus implies that it is weakly tame. Then it can be realized as an attractor for a flow and also for a homeomorphism (namely, the time-1 map of the flow).

COROLLARY 7.2. Let $K \subseteq \mathbb{R}^3$ be a toroidal set such that $\mathcal{N}(K)$ has no prime factors. Then K can be realized as an attractor for a homeomorphism if and only if its genus is finite and $\mathcal{N}(K) \sim 1$.

Proof. If *K* is an attractor for a homeomorphism, then $\mathcal{N}(K)$ is number-like. Since it does not have prime divisors, it must be $\mathcal{N}(K) \sim 1$. Conversely, if the genus of *K* is finite and $\mathcal{N}(K) \sim 1$ then *K* is weakly tame by Theorem 6.2. Therefore it can be realized as an attractor for a flow and hence also for a homeomorphism.

A result of Günther [14, Theorem 1, p. 653] shows that a generalized solenoid constructed in the manner described in Example 4.4(iii) cannot be realized as an attractor of a homeomorphism (in fact, of an arbitrary continuous map) of \mathbb{R}^3 . Our next corollary sharpens this.

COROLLARY 7.3. If a generalized solenoid can be realized as an attractor for a homeomorphism, then it must be an unknotted n-adic solenoid for some n.

Proof. Let K be a generalized solenoid that is an attractor for a homeomorphism. The fact that K is unknotted is a consequence of [2, Theorem 2.9(ii)]. Also, by Theorem

B the self-index of *K* is number-like; say $\mathcal{N}(K) \sim n$ for some *n*. The self-index of an *n*-adic solenoid *K'* also satisfies $\mathcal{N}(K') \sim n$, so by Proposition 3.3 the groups $\mathcal{N}(K)$ and $\mathcal{N}(K')$ are isomorphic. Then Remark 4.5 implies that *K* and the *n*-adic solenoid *K'* are homeomorphic.

Now suppose $K \subseteq \mathbb{R}^3$ is a non-trivial toroidal set. Let *T* be a neighbourhood of *K* that is a solid torus and such that the inclusion $K \subseteq T$ induces a non-zero map in cohomology (this happens as soon as *T* is sufficiently close to *K*). Let $e : T \longrightarrow \mathbb{R}^3$ be an embedding such that e(T) is non-trivially knotted. Then we say that K' := e(K) is the result of knotting *K* via the embedding *e*. Informally speaking, the following corollary shows that the chances of a set being realizable as an attractor only decrease under this knotting construction, and in fact only attractors for flows survive it.

COROLLARY 7.4. Let $K \subseteq \mathbb{R}^3$ be a non-trivial toroidal set and let K' be the result of knotting it as just described. Then the following assertions are equivalent.

- (i) *K* can be realized as an attractor for a flow.
- (ii) K' can be realized as an attractor for a flow.
- (iii) K' can be realized as an attractor for a homeomorphism.

Proof. (i) \Rightarrow (ii) Suppose *K* can be realized as an attractor for a flow. Then it is weakly tame, and so it has a neighbourhood basis of concentric tori. Since the knotting embedding *e* can be used to copy this basis (perhaps after discarding a finite number of initial neighbourhoods) onto a neighbourhood basis of *K'* and concentricity is clearly preserved by such copying, it follows that *K'* is also weakly tame. Thus it can be realized as an attractor for a flow.

(ii) \Rightarrow (iii) is trivial.

(iii) \Rightarrow (i) Suppose that K' is realizable as an attractor for a homeomorphism. Then we have that $\mathcal{N}(K')$ is number-like by Theorem B. The genus of K' is positive: if K'were unknotted, then e(T) should also be unknotted [2, Proposition 2.10, p. 10], but it is not by construction. It is also finite because K' can be realized as an attractor. Since the cohomology of K and K' is the same (non-trivial) it follows from Theorem 6.2 that K' is weakly tame. Then the argument of the previous paragraph run in the reverse shows that Kis also weakly tame and therefore realizable as an attractor for a flow.

As the last result we prove Theorem C from §1, which shows that there exist plenty of unknotted toroidal sets that cannot be realized as attractors. We will discuss briefly in the next section whether this can be extended to toroidal sets with positive genus.

THEOREM C. Let H be a feasible group. There exists an uncountable family $\{K_{\alpha}\}$ of toroidal sets such that:

- (i) none of the K_{α} can be realized as an attractor for a homeomorphism of \mathbb{R}^3 ;
- (ii) the K_{α} are pairwise different (that is, not ambient homeomorphic);
- (iii) each K_{α} is unknotted;
- (iv) each K_{α} has H as its first Čech cohomology group.

Proof. We prove the result in the case when no element in *H* is divisible by 2. The other case (when every element in *H* is divisible by 2) is completely analogous. Let the family $\{P_{\alpha}\}$ run over all infinite sets P_{α} of prime numbers such that $2 \notin P_{\alpha}$. Evidently $\{P_{\alpha}\}$ is an uncountable family. By Theorem 5.3 for each α there exists an unknotted toroidal set K_{α} such that $\check{H}^1(K_{\alpha}; \mathbb{Z}) = H$ and the prime divisors of $\mathcal{N}(K_{\alpha})$ are precisely the elements of P_{α} . Since each P_{α} is infinite, it follows that $\mathcal{N}(K_{\alpha})$ is not number-like and then from Theorem B we conclude that no K_{α} can be realized as an attractor for a homeomorphism of \mathbb{R}^3 . Finally, since $P_{\alpha} \neq P_{\beta}$ for $\alpha \neq \beta$, by Proposition 5.2 the toroidal sets K_{α} and K_{β} cannot be ambient homeomorphic (not even locally ambient homeomorphic).

We turn to the proof of Theorem B. Since the self-index is defined in terms of polyhedral solid tori, it is convenient to be able to replace the purely topological situation of the theorem with a piecewise linear one. This is accomplished by the following lemma.

LEMMA 7.5. Let $K \subseteq \mathbb{R}^3$ be an attractor for a homeomorphism f of \mathbb{R}^3 . Then K can be realized as an attractor for a homeomorphism of \mathbb{R}^3 that is piecewise linear on $\mathbb{R}^3 - K$.

In the proof of the lemma we will use the following notation: if $A \subseteq \mathbb{R}^3$ is a compact set and $\phi > 0$ is a positive number, we write $A + \phi$ to denote the set of points whose distance to *A* is less than or equal to ϕ . Obviously $A + \phi$ is also a compact set.

Proof of Lemma 7.5. Since *K* is a stable attractor, it has a compact neighbourhood *P* contained in its basin of attraction and such that f(P) is contained in the interior of *P*. Define $P_k := f^k(P)$ for $k \ge 0$. These sets form a decreasing neighbourhood basis for *K*. Also, since each P_{k+1} is contained in the interior of P_k , there exists a positive number $\phi_k > 0$ such that $P_{k+1} + \phi_k \subseteq P_k$. Clearly the ϕ_k can be chosen so that the sequence $\{\phi_k\}$ is strictly decreasing and converges to 0.

Let $U := \mathbb{R}^3 - K$. Notice that U is the union of the sets $(P_k - P_{k+1})$ together with $\mathbb{R}^3 - P_0$. Define a (non-continuous) mapping ϕ on U by

$$\phi(p) := \begin{cases} \phi_1 & \text{if } p \in \mathbb{R}^3 - P_0, \\ \phi_{k+1} & \text{if } p \in P_k - P_{k+1} \ (k \ge 0) \end{cases}$$

It is easy to check (using that $\{\phi_k\}$ is a decreasing sequence) that $\phi|_{\mathbb{R}^3 - P_k}$ is bounded below by ϕ_{k+1} . Since every compact subset of *U* is contained in a set of the form $\mathbb{R}^3 - P_k$, it follows that ϕ is bounded away from 0 on every compact subset of *U*. Thus ϕ is strictly positive in the sense of Moise [23, p. 46]. The map f^2 is a homeomorphism of *U*, and by the same approximation theorem that we invoked in the proof of Proposition 5.2 (namely [23, Theorem 1, p. 253]) there exists a piecewise linear homeomorphism *g* of *U* that is a ϕ -approximation of f^2 ; that is, such that $d(f^2(p), g(p)) < \phi(p)$ for every $p \in U$.

Extend g to a map \hat{g} on all of \mathbb{R}^3 by defining $\hat{g} = f^2$ on K (and of course $\hat{g} = g$ on U). Clearly \hat{g} is a bijection of \mathbb{R}^3 and it is continuous on U. We claim that \hat{g} is also continuous on each $p \in K$. To check this pick $p \in K$ and a sequence $\{p_n\}$ in U converging to p. By definition $\hat{g}(p) = f^2(p)$ and $\hat{g}(p_n) = g(p_n)$, so we may write

$$d(\hat{g}(p), \hat{g}(p_n)) = d(f^2(p), g(p_n)) \le d(f^2(p), f^2(p_n)) + d(f^2(p_n), g(p_n)) < d(f^2(p), f^2(p_n)) + \phi(p_n)$$

where in the last step we have used that g is a ϕ -approximation to f^2 on U. Now notice that $\{p_n\}$ eventually enters every P_k and so $\phi(p_n)$ eventually becomes less than or equal to ϕ_{k+1} (we are again using the fact that $\{\phi_k\}$ is decreasing). Thus $\{\phi(p_n)\}$ converges to 0 because the $\{\phi_k\}$ were chosen to converge to 0. Similarly $d(f^2(p), f^2(p_n))$ converges to 0 0 because f^2 is continuous. Hence the distance between $\hat{g}(p)$ and $\hat{g}(p_n)$ converges to 0 and so \hat{g} is continuous at p. In sum, \hat{g} is a continuous bijection of \mathbb{R}^3 and therefore (by the invariance of domain theorem) it is a homeomorphism. Evidently it is piecewise linear on $\mathbb{R}^3 - K$ by construction.

To prove the lemma it only remains to show that *K* is an attractor for \hat{g} . Since *g* is a ϕ -approximation to f^2 and $\phi|_{P_k-K} \leq \phi_{k+1}$, we have $g(P_k - K) \subseteq f^2(P_k - K) + \phi_{k+1}$. Using $f^2(P_k) = P_{k+2}$, we may then write

$$g(P_k - K) \subseteq f^2(P_k - K) + \phi_{k+1} \subseteq P_{k+2} + \phi_{k+1} \subseteq P_{k+1}.$$

Consequently $\hat{g}(P_k)$, which is the union of $g(P_k - K)$ and $\hat{g}(K) = f^2(K) = K$, is also contained in P_{k+1} . It follows that *K* is an attractor for \hat{g} .

Proof of Theorem B. By Lemma 7.5 we may assume that the homeomorphism f which realizes K as an attractor is piecewise linear on $\mathbb{R}^3 - K$. Denote by $\mathcal{A}(K)$ the basin of attraction of K. Since K is toroidal, it has a neighbourhood T that is a polyhedral solid torus contained in $\mathcal{A}(K)$. Let n be a sufficiently high iterate of f so that $f^n(T)$ is contained in the interior of T and define $T_j := f^{nj}(T)$ for $j \ge 0$. These $\{T_j\}$ form a nested family of polyhedral solid tori that provide a neighbourhood basis for K.

Now consider any pair $T_{j+1} \subseteq T_j$. The map f^{nj} provides a homeomorphism from the pair (T_0, T_1) onto the pair (T_j, T_{j+1}) which is piecewise linear on T_0 – int T_1 . Thus by Lemma 2.1 we have that $N(T_{j+1}, T_j) = N(T_1, T_0)$. It then follows from Proposition 4.1 that $\mathcal{N}(K)$ is number-like.

To conclude the proof observe that *K* has finite genus because all the T_j are ambient homeomorphic to each other and therefore have the same genus, and then Theorem 6.1 shows that $\mathcal{N}(K) \sim 1$ if and only if *K* is weakly tame. But the latter is equivalent to *K* being realizable as an attractor for a flow.

An alternative (and somewhat more elementary) argument for the last paragraph of the proof above can be obtained by resorting to [2, Theorem 3.11, p.19], where it is shown that a toroidal set can be realized as an attractor for a flow if and only if it has a neighbourhood basis of concentric solid tori. This is equivalent to requiring that K be weakly tame by Proposition 6.4.

8. Concluding remarks

In this final section we briefly discuss some loose ends.

8.1. *Topological invariance of the self-index.* One of the properties of the self-index is its invariance under ambient homeomorphisms (or in fact, under homeomorphisms of a neighbourhood of the toroidal set). There is no reason to expect that two homeomorphic but not ambient homeomorphic toroidal sets should have the same self-index; that is, that the self-index should be a topological invariant of toroidal sets. However, we do not know how to construct an example that illustrates this. Also, Proposition 5.1 does show that having 2 as a prime factor of the self-index is indeed a topological invariant. This prompts the question of whether the self-index enjoys some subtler sort of topological invariance property, perhaps involving only its prime factors or its number-like nature.

8.2. Dependence relations between Čech cohomology, the self-index and the genus. We now have three magnitudes associated to a toroidal set K: its Čech cohomology \check{H} , its self-index \mathcal{N} , and its genus g. We already showed that \check{H} and \mathcal{N} are essentially independent magnitudes beyond the elementary constraints between them discussed before Theorem 5.3. Something similar occurs for \check{H} and g. Theorems 6.1 and 6.2 entail that if a toroidal set has cohomology $\check{H} \neq 0$ and genus $0 < g < +\infty$, then its self-index must be $\mathcal{N} \sim 1$ and therefore $\check{H} \sim 1$ by Proposition 4.3. Beyond this condition, they are independent: ordinary knots provide examples of a toroidal set having $\check{H} \sim 1$ and a prescribed positive and finite genus, and solenoids provide examples of toroidal sets having a prescribed cohomology and 0 (if unknotted) or infinite (if knotted) genus. However, the interaction between g and \mathcal{N} is much more complicated, and in fact we do not know whether there exist toroidal sets with a prescribed genus $0 < g < +\infty$ and a prescribed self-index N.

A partial result in this direction is afforded by the following theorem, which uses a variation on the technique of Theorem 5.3.

THEOREM 8.1. Let $N \neq 0$ be a feasible group such that 2|N. Then there exists a toroidal set K such that $\mathcal{N}(K) = N$ and g(K) = 1.

The requirement that 2|N is necessary, otherwise $\check{H} \neq 0$ and by Theorems 6.1 and 6.2 we would have that $\mathcal{N} \sim 1$, while in general N is arbitrary.

Proof of Theorem 8.1. Write N in the form

$$N = \lim_{j \to \infty} \{ \mathbb{Z} \xrightarrow{\cdot n_j} \mathbb{Z} \}.$$

Since 2|N, arguing as in the proof of Theorem 5.3, we may assume that all the n_j are even; moreover, since $N \neq 0$ we may also assume $n_j \ge 2$ for every *j* (see Lemma 3.4).

We construct the required toroidal set as the intersection of a nested family of tori $\{T_j\}$ as follows. Let V be the standard unknotted torus in \mathbb{R}^3 and let $W \subseteq \operatorname{int} V$ be another solid torus arranged as a Whitehead curve (that is, as the innermost curve in Figure 1(a)). Now start with a torus $T_1 \subseteq \mathbb{R}^3$ knotted in a non-trivial way. Let $W_1 \subseteq \operatorname{int} T_1$ be another solid torus which lies inside T_1 according to the pattern (V, W). Now let $T_2 \subseteq \operatorname{int} W_1$ be a third solid torus that winds monotonically $n_1/2$ times inside W_1 (as in the generalized solenoids). Let again $W_2 \subseteq \operatorname{int} T_2$ be a solid torus which lies inside T_2 in the pattern (V, W) and then let $T_3 \subseteq \operatorname{int} W_2$ wind monotonically $n_2/2$ times inside W_2 . Continue

in this fashion and define $K := \bigcap_j T_j$. Notice that both $\{T_j\}$ and $\{W_j\}$ are standard bases for *K*.

Since the winding number of *W* inside *V* is 0, the same is true of every pair $W_j \subseteq T_j$. Thus $\check{H}^1(K; \mathbb{Z}) = 0$. Notice that $N(T_{j+1}, T_j) = N(T_{j+1}, W_j) \cdot N(W_j, T_j) = (n_j/2) \cdot 2 = n_j$ by construction. This implies that *K* is indeed a toroidal set (because it is not cellular by Proposition 4.1) and also that $\mathcal{N}(K) = N$ by Proposition 4.1.

Finally, we show that g(K) = 1. This is very similar to the proof that the Whitehead double of a knot has genus 1. First, since the core curve of W bounds a Seifert surface of genus 1 inside the torus V, each W_j also bounds a Seifert surface of genus 1 and therefore $g(K) \le 1$ because the W_j form a neighbourhood basis of K. To prove that g(K) > 0, suppose to the contrary that K were unknotted. Then K would have a neighbourhood basis of unknotted tori, and in particular we could interpolate an unknotted torus U between T_1 and T_j for some big enough j. Then $N(T_j, T_1) = N(T_j, U) \cdot N(U, T_1)$ and, since $N(T_j, T_1) = N(T_j, T_{j-1}) \cdot \cdots \cdot N(T_2, T_1) = n_{j-1} \cdot \cdots \cdot n_1 \neq 0$ by the computations of the previous paragraph, $N(U, T_1)$ is also non-zero. In particular, U is a satellite of T_1 , but this is impossible: the unknot cannot be a satellite of a non-trivial knot (see [5, Remark before Proposition 3.12, p. 39] or [26, Corollary 10, p. 113]).

8.3. A remark about the construction of homeomorphisms with a prescribed attractor. The self-index (and the genus) are very useful as obstructions for the realizability of a toroidal set as an attractor, but no so much as complete characterizations. This is due to the fact that even in the presence of the most convenient geometric hypotheses, defining a homeomorphism that realizes a given set K as an attractor is very difficult. Very roughly speaking, the main difference between the case of flows and homeomorphisms stems from the fact that a flow can be 'slowed down' near any prescribed set. Thus, if one has already defined a flow near K in such a way that it carries points towards K (using whatever geometric assumptions are available), then one can gradually slow it down and make it stationary on K. For homeomorphism behaves in a promising manner near K (again, moving points towards K), it is very difficult to ensure that it does not 'overshoot' K. This, for instance, explains that the proof of Corollaries 7.1 and 7.2 proceeds by showing that the toroidal sets are actually attractors for a flow. It is an open problem to find constructions of homeomorphisms that realize sets as attractors without proceeding through flows.

Acknowledgements. The authors are partially supported by the Spanish Ministerio de Ciencia, Innovación y Universidades (grant PGC2018-098321-B-I00). The second author is funded by the Ramón y Cajal programme (RYC2018-025843-I). The authors would like to thank the anonymous referees for their helpful suggestions, which have hopefully improved the readability of the paper.

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