



RESEARCH ARTICLE

# Edge Statistics for Lozenge Tilings of Polygons, II: Airy Line Ensemble

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## Abstract

We consider uniformly random lozenge tilings of simply connected polygons subject to a technical assumption on their limit shape. We show that the edge statistics around any point on the arctic boundary, that is not a cusp or tangency location, converge to the Airy line ensemble. Our proof proceeds by locally comparing these edge statistics with those for a random tiling of a hexagon, which are well understood. To realize this comparison, we require a nearly optimal concentration estimate for the tiling height function, which we establish by exhibiting a certain Markov chain on the set of all tilings that preserves such concentration estimates under its dynamics.

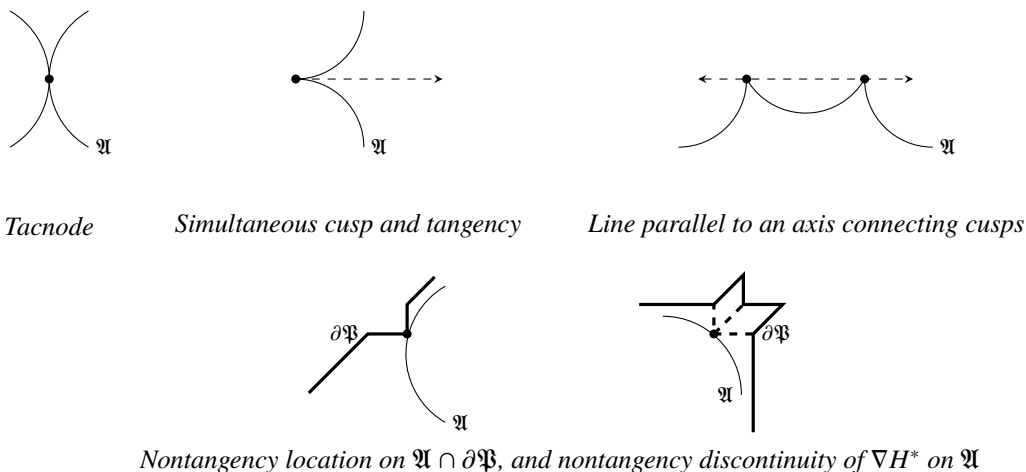
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## 1. Introduction

A central feature of random lozenge tilings is that they exhibit boundary-induced phase transitions. Depending on the shape of the domain, they can admit *frozen* regions, where the associated height function is flat almost deterministically, and *liquid* regions, where the height function appears more rough and random; the curve separating these two phases is called an *arctic boundary*. We refer to the papers [CLP98] and [CK01] for some of the earlier analyses of this phenomenon in lozenge tilings of hexagonal domains and to the book [Gor21] for a comprehensive review. A thorough study of arctic boundaries on arbitrary polygons was pursued in [KO07, ADPZ20], where it was shown that their limiting trajectories are algebraic curves.

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**Figure 1.** Depicted above are the four scenarios for arctic curve  $\mathfrak{A}$  forbidden by Assumption 2.8.

After realizing that these phase boundaries exist and admit limits, the next question is to understand their fluctuations, known as the *edge statistics*. On domains of diameter order  $n$ , the general prediction is that their fluctuations are of order  $n^{1/3}$  and  $n^{2/3}$  in the directions transverse and parallel to their limiting trajectories, respectively. Upon scaling by these exponents, it is further predicted that the boundary converges to the *Airy<sub>2</sub> process*, a universal scaling limit introduced in [PS02] that is believed to govern various phenomena related to the Kardar–Parisi–Zhang universality class. See [Joh18] for a detailed survey.

Following the initial works [Joh00, Joh02, Joh05] (where it was first proven in the related context of domino tilings for the Aztec diamond), this prediction has been established for random lozenge tilings of various families of domains. For example, we refer to [OR03, OR07, FS03] for certain  $q$ -weighted random plane partitions, [BKMM07] for tilings of hexagons and [Pet14, DM18] for tilings of trapezoids (hexagons with cuts along a single side). These results are all based on exact and analyzable formulas, specific to the domain of study, for the correlation kernel for which the tiling forms a determinantal point process. Although for lozenge tilings of arbitrary polygonals such explicit formulas are not known, it is believed under such generality that convergence to the *Airy<sub>2</sub> process* under the above scaling still holds; see [Gor21, Conjecture 18.7] and [ADPZ20, Conjecture 9.1].

In this paper, we prove this statement for simply connected polygonal domains subject to a certain technical assumption on their limit shape that we believe to hold generically (see Assumption 2.8 and Remark 2.9 below). Under the interpretation of lozenge tilings as nonintersecting random Bernoulli walks, we in fact more broadly consider the family of Bernoulli walks around the arctic boundary (not only the extreme one); we prove under the above scaling that it converges to the *Airy line ensemble*, a multilevel generalization of the *Airy<sub>2</sub> process*, introduced in [PS02, CH14]. An informal formulation of this result is provided as follows; see Theorem 2.10 below for a more precise statement.

**Theorem** (Theorem 2.10 below). *Consider a uniformly random lozenge tiling of a simply connected polygonal domain, whose arctic boundary does not exhibit any of the configurations depicted in Figure 1. Under appropriate rescaling, the family of associated nonintersecting Bernoulli walks in a neighborhood of any point (that is neither a cusp nor a tangency location) of the limiting arctic boundary converges to the Airy line ensemble.*

In the above theorem, we forbade specific (presumably nongeneric) behaviors for singular points of the arctic boundary associated with the domain. These include the presence of tacnodes and cuspidal turning points; see Assumption 2.8 for the exact condition. At some of these nongeneric singularities, the edge scaling limit is more exotic; see [OR06, DJM16, AJvM18b, AJvM18a, AvM18] for more

information. Still, it is believed that such behaviors should not disrupt the convergence to the Airy line ensemble elsewhere along the arctic boundary; that our theorem does not apply for these nongeneric polygons therefore seems to be an artifact of our proof method. Generic singularities along the arctic boundary (which do appear in almost any polygonal domain) are ordinary cusps. The scaling limits at such points are believed to be given by the Pearcey process [OR07]; we do not address this intriguing question here.<sup>1</sup>

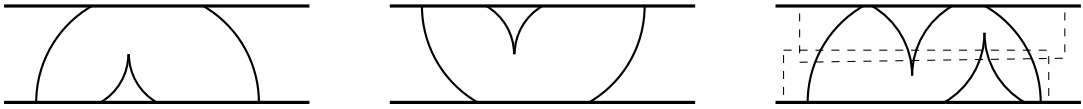
The above theorem can be viewed as a *universality* result for random lozenge tilings since it shows that their statistics converge to the Airy line ensemble at any point (that is not a cusp or tangency location) around the arctic boundary, regardless of the polygonal shape bounding the domain. Recently, universality results for lozenge tilings at other points inside the domain (where different limiting statistics appear) have been established. For example, it was shown that local statistics in the interior of the liquid region converge to the unique translation-invariant, ergodic Gibbs measure of the appropriate slope for hexagons [BKMM07, Gor08, ABR10], domains covered by finitely many trapezoids [Pet14, Gor17], bounded perturbations of these [Las19] and finally for general domains [Agg23]. It was also recently shown in [AG22] that, at tangency locations between the arctic boundary and sides of general domains, the limiting statistics converge to the corners process of the Gaussian unitary ensemble. Both of these phenomena were proven to be quite robust, and they in fact apply on domains beyond polygonal ones.

Although the  $\text{Airy}_2$  process also serves as the edge scaling limit in random lozenge tilings for certain classes of domains beyond polygons, the precise conditions under which it appears seem subtle. They are not determined by information about the macroscopic shape of the domain alone; microscopic perturbations of it can affect the edge statistics. Indeed, placing a single microscopic defect on an edge of a hexagonal domain corresponds to inserting a new walk in the associated nonintersecting Bernoulli walk ensemble. At the point where this new walk meets the arctic boundary for the original hexagon, the edge statistics should instead be given by the  $\text{Airy}_2$  process with a wanderer, introduced in [AFvM10].

We now outline our proof of the theorem. We will show a concentration estimate for the tiling height function on a simply connected polygon  $P$  (satisfying Assumption 2.8 below) of diameter order  $n$ , stating that with high probability it is within  $n^\delta$  of its limit shape, for any  $\delta > 0$ . Given such a bound, we establish the theorem by locally comparing the random tiling of  $P$  with that of a hexagon, around their arctic boundaries. More specifically, the concentration estimate implies that the extreme paths in the nonintersecting Bernoulli walk ensemble  $X$  associated with a random tiling of  $P$  remains close to its limiting trajectory. We then match the slope and curvature of this limiting curve with those of the arctic boundary for a suitably chosen hexagon  $P'$ . Using this, we exhibit a coupling between  $X$  and the nonintersecting Bernoulli walk ensemble associated with a random tiling of  $P'$ , in such a way that they likely nearly coincide, up to error  $o(n^{1/3})$ , around their arctic boundaries. Known results for random tilings on hexagonal domains [BKMM07, Pet14, DM18], coming from their exact solvability, show that the edge statistics of the random tiling of  $P'$  are given by the Airy line ensemble. It follows that the same holds for the random tiling of  $P$ .

The remainder of this paper is devoted to proving the above-mentioned concentration estimate, given by Theorem 3.10 below. Such a concentration phenomenon is ubiquitous in random matrix theory and is known as *eigenvalue rigidity*. In the context of Wigner matrices, it was first proven in [EYY12], and later for more general classes of random matrices [EKYY13, KY13, BEK<sup>+</sup>14, HKR18, BES17, AEK19, BES20]. To show this in our tiling context, we begin with a ‘preliminary’ concentration bound, Theorem 4.3 below, for a family of  $n$  nonintersecting random discrete bridges conditioned to start and end at specified locations (equivalently, random lozenge tilings of a strip). Assuming the initial and ending data for these Bernoulli walks are such that the limiting arctic boundary has at most one cusp (see the left and middle of Figure 2 for examples), this bound states that with high probability the associated height function is within  $n^\delta$  of its limit shape. Its proof is presented in part I of this series [Hua24], which proceeds by first using results of [Hua20] to approximate the random bridge model by a family of nonintersecting Bernoulli random walks with space- and time-dependent drifts. The latter walk model

<sup>1</sup>However, we mention that it was answered (subsequently to the present manuscript) in [JHZ23].



**Figure 2.** Shown to the left and middle are arctic boundaries exhibiting a single cusp. Shown to the right is an arctic boundary exhibiting two cusps that point in opposite directions and a decomposition of that strip into overlapping regions that each have (at most) one cusp.

can then be studied through a dynamical version of the loop equations and an analysis of the complex Burgers equation through the characteristic method.

Imposing that the arctic boundary has at most one cusp is a substantial constraint; it does not hold for lozenge tilings of most polygons. Its origin can be heuristically attributed to the fact that, while disjoint families of nonintersecting Bernoulli walks often merge, merged ones do not separate unless they are driven by a diverging drift (which much less amenable to analysis). As such, when comparing the bridge model to a family of nonintersecting Bernoulli walks with drift, one must ensure that these Bernoulli walks only merge and never separate. If the arctic boundary has only one cusp, then by suitably orienting the Bernoulli walks, this cusp can be interpreted as a location where families of Bernoulli walks merge; for example, this is the case if we orient the Bernoulli walks associated with the left and middle diagrams in Figure 2 north and south, respectively. If the arctic boundary for the bridge model exhibits two cusps ‘pointing in opposite directions’, as in the right side of Figure 2, then any choice of orientation will lead to at least one cusp serving as a point where the Bernoulli walks separate. This issue was circumvented in [Hua20] by restricting to a family of domains in which all cusps point in the same direction. However, on generic polygons, cusps pointing in opposite directions do appear, so this point must be addressed here.

To that end, we decompose our domain into a bounded number of (possibly overlapping) subregions that each have at most one cusp; see the right side of Figure 2. We then introduce a Markov chain, called the alternating dynamics (a form of the block dynamics), that uniformly resamples the tiling in one subregion and leaves it fixed in the others. Known estimates [RT00] for mixing times of Glauber dynamics, together with the censoring inequality of [PW13], imply that this Markov chain mixes to the uniform measure in time that is polynomial in  $n$  (for example,  $\mathcal{O}(n^{22})$ ).

Initiating the alternating dynamics from a profile approximating the limit shape, we show that the  $n^\delta$  concentration bound is with high probability preserved at each step of the alternating dynamics (from which the result follows by running these dynamics until they mix). The preliminary concentration result alone is insufficient to prove this since the  $n^\delta$  error it admits could in principle accumulate at each step. To overcome this, we introduce deterministic barrier functions, which we refer to as *tilted profiles*, and show (with the assistance of the preliminary concentration bound) that they likely bound the tiling height function from above and below throughout the dynamics. To prove that such tilted profiles exist, we exhibit them by perturbing solutions to the complex Burgers equation in a specific way.

The remainder of this paper is organized as follows. In Section 2, we define the model and state our main results. In Section 3, we state the concentration result for the tiling height function on the polygon  $P$  and establish the theorem assuming it. In Section 4, we state the preliminary concentration bound for nonintersecting Bernoulli walks, introduce the alternating dynamics Markov chain and bound its mixing time. In Section 5, we introduce and discuss properties of tilted height functions. In Section 6, we establish the concentration result for the tiling height function on  $P$ . In Section 7, we give the proof for the existence of tilted height functions.

### Notation

Throughout, we let  $\bar{\mathbb{C}} = \mathbb{C} \cup \{\infty\}$ ,  $\mathbb{H}^+ = \{z \in \mathbb{C} : \text{Im } z > 0\}$  and  $\mathbb{H}^- = \{z \in \mathbb{C} : \text{Im } z < 0\}$  denote the compactified complex plane, upper complex plane and lower complex plane, respectively. We further

denote by  $|u - v|$  the Euclidean distance between any elements  $u, v \in \mathbb{R}^2$ . For any subset  $\mathfrak{R} \subseteq \mathbb{R}^2$ , we let  $\partial\mathfrak{R}$  denote its boundary,  $\overline{\mathfrak{R}}$  denote its closure and  $\text{diam } \mathfrak{R} = \sup_{r, r' \in \mathfrak{R}} |r - r'|$  denote its diameter. For any additional subset  $\mathfrak{R}' \subseteq \mathbb{R}^2$ , we let  $\text{dist}(\mathfrak{R}, \mathfrak{R}') = \sup_{r \in \mathfrak{R}} \inf_{r' \in \mathfrak{R}'} |r - r'|$  denote the distance between  $\mathfrak{R}$  and  $\mathfrak{R}'$ . For any real number  $c \in \mathbb{R}$ , we also define the rescaled set  $c\mathfrak{R} = \{cr : r \in \mathfrak{R}\}$ , and for any  $u \in \mathbb{R}^2$ , we define the shifted set  $\mathfrak{R} + u = \{r + u : r \in \mathfrak{R}\}$ . For any  $u \in \mathbb{R}^2$  and  $r \geq 0$ , let  $\mathfrak{B}_r(u) = \mathfrak{B}(u; r) = \{v \in \mathbb{R}^2 : |v - u| \leq r\}$  denote the disk centered at  $u$  of radius  $r$ .

## 2. Results

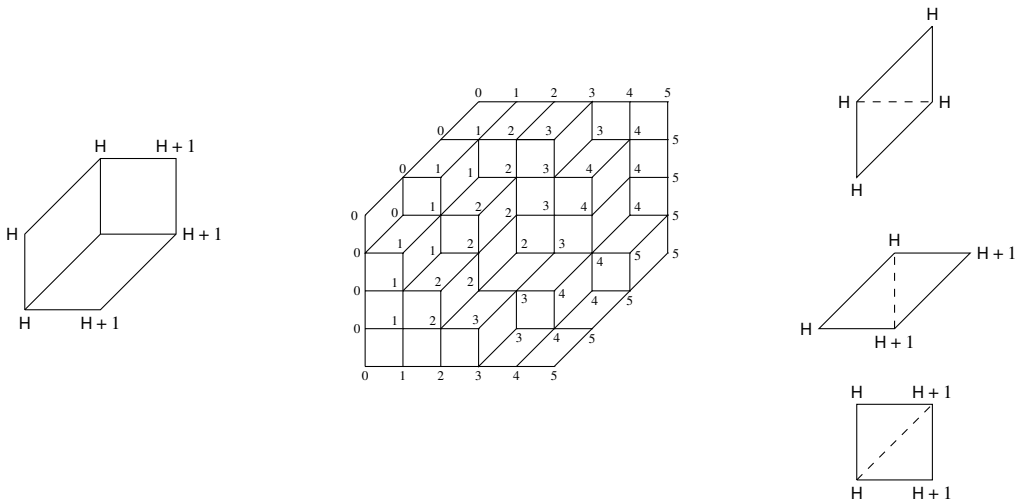
### 2.1. Tilings and height functions

We denote by  $\mathbb{T}$  the *triangular lattice*, namely, the graph whose vertex set is  $\mathbb{Z}^2$  and whose edge set consists of edges connecting  $(x, y), (x', y') \in \mathbb{Z}^2$  if  $(x' - x, y' - y) \in \{(1, 0), (0, 1), (1, 1)\}$ . The axes of  $\mathbb{T}$  are the lines  $\{x = 0\}, \{y = 0\}$  and  $\{x = y\}$ , and the faces of  $\mathbb{T}$  are triangles with vertices of the form  $\{(x, y), (x + 1, y), (x + 1, y + 1)\}$  or  $\{(x, y), (x, y + 1), (x + 1, y + 1)\}$ . A *domain*  $R \subseteq \mathbb{T}$  is a simply connected induced subgraph of  $\mathbb{T}$ . The *boundary*  $\partial R \subseteq R$  is the set of vertices  $v \in R$  adjacent to a vertex in  $\mathbb{T} \setminus R$ .

A *dimer covering* of a domain  $R \subseteq \mathbb{T}$  is defined to be a perfect matching on the dual graph of  $R$ . A pair of adjacent triangular faces in any such matching forms a parallelogram, which we will also refer to as a *lozenge* or *tile*. Lozenges can be oriented in one of three ways; see the right side of Figure 3 for all three orientations. We refer to the topmost lozenge there (that is, one with vertices of the form  $\{(x, y), (x, y + 1), (x + 1, y + 2), (x + 1, y + 1)\}$ ) as a *type 1* lozenge. Similarly, we refer to the middle (with vertices of the form  $\{(x, y), (x + 1, y), (x + 2, y + 1), (x + 1, y + 1)\}$ ) and bottom (vertices of the form  $\{(x, y), (x, y + 1), (x + 1, y + 1), (x + 1, y)\}$ ) ones there as *type 2* and *type 3* lozenges, respectively. A dimer covering of  $R$  can equivalently be interpreted as a tiling of  $R$  by lozenges of types 1, 2 and 3. Therefore, we will also refer to a dimer covering of  $R$  as a (*lozenge*) *tiling*. We call  $R$  *tileable* if it admits a tiling.

Associated with any tiling of  $R$  is a *height function*  $H : R \rightarrow \mathbb{Z}$ , namely, a function on the vertices of  $R$  that satisfies

$$H(v) - H(u) \in \{0, 1\}, \quad \text{whenever } u = (x, y) \text{ and } v \in \{(x + 1, y), (x, y - 1), (x + 1, y + 1)\},$$



**Figure 3.** Depicted to the right are the three types of lozenges. Depicted in the middle is a lozenge tiling of a hexagon. One may view this tiling as a packing of boxes (of the type depicted on the left) into a large corner, which gives rise to a height function (shown in the middle).

for some  $(x, y) \in \mathbb{Z}^2$ . We refer to the restriction  $h = H|_{\partial R}$  as a *boundary height function*. For any boundary height function  $h : \partial R \rightarrow \mathbb{Z}$ , let  $\mathcal{G}(h)$  denote the set of all height functions  $H : R \rightarrow \mathbb{Z}$  with  $H|_{\partial R} = h$ .

For a fixed vertex  $v \in R$  and integer  $m \in \mathbb{Z}$ , one can associate with any tiling of  $R$  a height function  $H : R \rightarrow \mathbb{Z}$  as follows. First, set  $H(v) = m$ , and then define  $H$  at the remaining vertices of  $R$  in such a way that the height functions along the four vertices of any lozenge in the tiling are of the form depicted on the right side of Figure 3. In particular, we require that  $H(x + 1, y) = H(x, y)$  if and only if  $(x, y)$  and  $(x + 1, y)$  are vertices of the same type 1 lozenge and that  $H(x, y) - H(x, y + 1) = 1$  if and only if  $(x, y)$  and  $(x, y + 1)$  are vertices of the same type 2 lozenge. Since  $R$  is simply connected, a height function on  $R$  is uniquely determined by these conditions (and the value of  $H(v) = m$ ).

We refer to the right side of Figure 3 for an example; as depicted there, we can also view a lozenge tiling of  $R$  as a packing of  $R$  by boxes of the type shown on the left side of Figure 3. In this case, the value  $H(u)$  of the height function associated with this tiling at some vertex  $u \in R$  denotes the height of the stack of boxes at  $u$ . Observe in particular that, if there exists a tiling  $\mathcal{M}$  of  $R$  associated with some height function  $H$ , then the boundary height function  $h = H|_{\partial R}$  is independent of  $\mathcal{M}$  and is uniquely determined by  $R$  (except for a global shift, which was above fixed by the value of  $H(v) = m$ ).

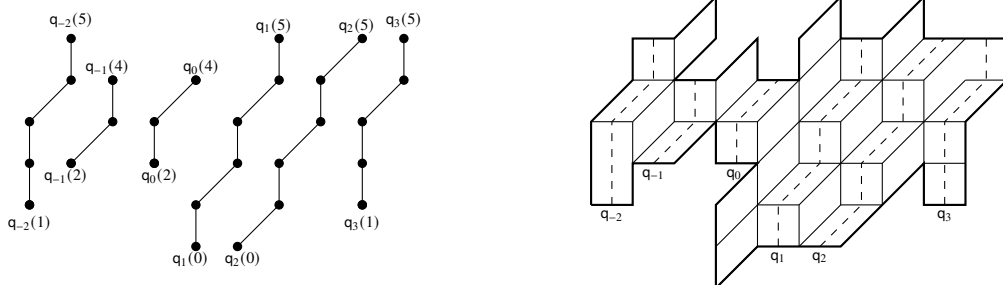
### 2.2. Nonintersecting Bernoulli walk ensembles

In this section, we explain the correspondence between tilings and nonintersecting Bernoulli walk ensembles, to which end we begin by defining the latter. A *Bernoulli walk* is a sequence  $q = (q(s), q(s + 1), \dots, q(t)) \in \mathbb{Z}_{\geq 0}^{t-s+1}$  such that  $q(r + 1) - q(r) \in \{0, 1\}$  for each  $r \in [s, t - 1]$ ; viewing  $r$  as a time index,  $(q(r))$  denotes the space-time trajectory for a discrete walk, which may either not move or jump to the right at each step. For this reason, the interval  $[s, t]$  is called the *time span* of the Bernoulli walk  $q$ , and a step  $(r, r + 1)$  of this Bernoulli walk may be interpreted as an ‘nonjump’ or a ‘right-jump’ if  $q(r + 1) = q(r)$  or  $q(r + 1) = q(r) + 1$ , respectively. A family of Bernoulli walks  $Q = (q_l, q_{l+1}, \dots, q_m)$  is called *nonintersecting* if  $q_i(r) < q_j(r)$  whenever  $l \leq i < j \leq m$  and  $r$  is in the time span of  $q_i$  and  $q_j$ .

Now, fix some tileable domain  $R \subset \mathbb{T}$ , with a height function  $H : R \rightarrow \mathbb{T}$  corresponding to a tiling  $\mathcal{M}$  of  $R$ . We may interpret  $\mathcal{M}$  as a family of nonintersecting Bernoulli walks by first omitting all type 1 lozenges from  $\mathcal{M}$  and then viewing any type 2 or type 3 tile as a right-jump or nonjump of a Bernoulli walk, respectively; see Figure 4 for a depiction.

It will be useful to set more precise notation on this correspondence. Since  $\partial_x H(x, t) \in \{0, 1\}$  for all  $(x, t)$ , there exist integers  $x_{a(t)}(t) < x_{a(t)+1}(t) < \dots < x_{b(t)}(t)$  such that

$$\partial_x H(x, t) = \sum_{i=a(t)}^{b(t)} \mathbf{1}(x \in [x_i(t), x_i(t) + 1]),$$



**Figure 4.** Depicted to the left is an ensemble  $Q = (q_{-2}, q_{-1}, q_0, q_1, q_2, q_3)$  consisting of six nonintersecting Bernoulli walks. Depicted to the right is an associated lozenge tiling.

which are those such that  $H(x_i(t) + 1, t) = H(x_i(t), t) + 1$ . This fixes the locations of  $x_i(t)$ , but in this way the indices  $a(t)$  and  $b(t)$  are defined up to an overall shift. We will fix this shift by stipulating that  $H(x_{a(t)} + 1, t) = a(t)$ ; this defines a Bernoulli walk  $x_i = (x_i(t))$ .<sup>2</sup> Ranging over  $i$ , we obtain a nonintersecting ensemble of Bernoulli walks  $X = (x_i, x_{i+1}, \dots, x_m)$  that are indexed through the height function  $H$ .

### 2.3. Limit shapes and arctic boundaries

To analyze the limits of height functions of random tilings, it will be useful to introduce continuum analogs of the notions considered in Section 2.1. So, set

$$\mathcal{T} = \{(s, t) \in (0, 1) \times \mathbb{R}_{<0} : s + t > 0\} \subset \mathbb{R}^2, \tag{2.1}$$

and its closure  $\overline{\mathcal{T}} = \{(s, t) \in [0, 1] \times \mathbb{R}_{\leq 0} : s + t \geq 0\}$ . We interpret  $\overline{\mathcal{T}}$  as the set of possible gradients, also called *slopes*, for a continuum height function;  $\mathcal{T}$  is then the set of ‘liquid’ slopes, whose associated tilings contain tiles of all types. For any simply connected open subset  $\mathfrak{R} \subset \mathbb{R}^2$ , we say that a function  $H : \mathfrak{R} \rightarrow \mathbb{R}$  is *admissible* if  $H$  is 1-Lipschitz and  $\nabla H(u) \in \overline{\mathcal{T}}$  for almost all  $u \in \mathfrak{R}$ . We further say a function  $h : \partial\mathfrak{R} \rightarrow \mathbb{R}$  admits an *admissible extension to  $\mathfrak{R}$*  if  $\text{Adm}(\mathfrak{R}; h)$ , the set of admissible functions  $H : \mathfrak{R} \rightarrow \mathbb{R}$  with  $H|_{\partial\mathfrak{R}} = h$ , is not empty.

We say that a sequence of domains  $R_1, R_2, \dots \subset \mathbb{T}$  converges to a simply connected subset  $\mathfrak{R} \subset \mathbb{R}^2$  if  $n^{-1}R_n \subseteq \mathfrak{R}$  for each  $n \geq 1$  and  $\lim_{n \rightarrow \infty} \text{dist}(n^{-1}R_n, \mathfrak{R}) = 0$ . We further say that a sequence  $h_1, h_2, \dots$  of boundary height functions on  $R_1, R_2, \dots$ , respectively, converges to a boundary height function  $h : \partial\mathfrak{R} \rightarrow \mathbb{R}$  if  $\lim_{n \rightarrow \infty} n^{-1}h_n(nv) = h(v)$  if  $v$  is any point in  $n^{-1}R_n$  for all sufficiently large  $n$ .

To state results on the limiting height function of random tilings, for any  $x \in \mathbb{R}_{\geq 0}$  and  $(s, t) \in \overline{\mathcal{T}}$  we denote the *Lobachevsky function*  $L : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$  and the *surface tension*  $\sigma : \overline{\mathcal{T}} \rightarrow \mathbb{R}^2$  by

$$L(x) = - \int_0^x \log |2 \sin z| dz; \quad \sigma(s, t) = \frac{1}{\pi} \left( L(\pi(1 - s)) + L(-\pi t) + L(\pi(s + t)) \right). \tag{2.2}$$

For any  $H \in \text{Adm}(\mathfrak{R})$ , we further denote the *entropy functional*

$$\mathcal{E}(H) = \int_{\mathfrak{R}} \sigma(\nabla H(z)) dz. \tag{2.3}$$

The following variational principle of [CKP01] states that the height function associated with a uniformly random tiling of a sequence of domains converging to  $\mathfrak{R}$  converges to the maximizer of  $\mathcal{E}$  with high probability.

**Lemma 2.1** [CKP01, Theorem 1.1]. *Let  $R_1, R_2, \dots \subset \mathbb{T}^2$  denote a sequence of tileable domains, with associated boundary height functions  $h_1, h_2, \dots$ , respectively. Assume that they converge to a simply connected subset  $\mathfrak{R} \rightarrow \mathbb{R}^2$  with piecewise smooth boundary, and a boundary height function  $h : \partial\mathfrak{R} \rightarrow \mathbb{R}$ , respectively. Denoting the height function associated with a uniformly random tiling of  $R_n$  by  $H_n$ , we have*

$$\lim_{n \rightarrow \infty} \mathbb{P} \left( \max_{v \in R_n} |n^{-1}H_n(v) - H^*(n^{-1}v)| > \varepsilon \right) = 0,$$

where  $H^*$  is the unique maximizer of  $\mathcal{E}$  on  $\mathfrak{R}$  with boundary data  $h$ ,

$$H^* = \operatorname{argmax}_{H \in \text{Adm}(\mathfrak{R}; h)} \mathcal{E}(H). \tag{2.4}$$

<sup>2</sup>It might in fact be a union of disconnected walks, but this point will have no effect on our discussion.

The fact that there is a unique maximizer described as in (2.4) follows from [DSS10, Proposition 4.5]. Under a suitable change of coordinates, this maximizer  $H^*$  solves a complex variant of the Burgers equation [KO07], which makes it amenable to further analysis; we will discuss this point in more detail in Section 3.1 below. For any simply connected open subset  $\mathfrak{R} \subset \mathbb{R}^2$  with Lipschitz boundary and boundary height function  $h : \partial\mathfrak{R} \rightarrow \mathbb{R}^2$  admitting an admissible extension to  $\mathfrak{R}$ , define the *liquid region*  $\mathfrak{L} = \mathfrak{L}(\mathfrak{R}; h) \subset \mathfrak{R}$

$$\mathfrak{L} = \{u = (x, t) \in \mathfrak{R} : (\partial_x H^*(u), \partial_t H^*(u)) \in \mathcal{T}\}, \tag{2.5}$$

and the *arctic boundary*  $\mathfrak{A} = \mathfrak{A}(\mathfrak{R}; h) \subset \overline{\mathfrak{R}}$  as the set of points  $u = (x, t) \in \partial\mathfrak{L}$  such that for any sequence of points  $u_n \in \mathfrak{L}$  converging to  $u$ ,

$$(\partial_x H^*(u_n), \partial_t H^*(u_n)) \rightarrow \partial\mathcal{T}, \tag{2.6}$$

where  $H^*$  is as in Equation (2.4). By [DSS10, Proposition 4.1], the set  $\mathfrak{L}$  is open. The complement of the liquid region  $\mathfrak{R} \setminus \mathfrak{L}$  is called the *frozen region*.

We will commonly be interested in the case when  $\mathfrak{R}$  is a polygonal domain, given as follows.

**Definition 2.2.** A subset  $\mathfrak{P} \subset \mathbb{R}^2$  is called *polygonal* if it is a simply connected polygon, and the boundary edges are in the axes directions of the triangular lattice. We assume the domain<sup>3</sup>  $\mathbb{P} = \mathbb{P}_n = n\overline{\mathfrak{P}} \cap \mathbb{T}$  is tileable and thus associated with a (unique, up to global shift) boundary height function  $h = h_n$ . By translating  $\mathfrak{P}$  if necessary, we will assume that  $\overline{\mathfrak{P}} \subset \mathbb{R} \times \mathbb{R}_{\geq 0}$  and that  $(0, 0) \in \partial\mathfrak{P}$ . Then by shifting  $h$  if necessary, we will further suppose that  $h(0, 0) = 0$ . Under this notation, we set  $h : \partial\mathfrak{P} \rightarrow \mathbb{R}$  by  $h(u) = n^{-1}h(nu)$  for each  $u \in \partial\mathfrak{P}$ . Moreover, we abbreviate  $\text{Adm}(\mathfrak{P}) = \text{Adm}(\mathfrak{P}; h)$ ,  $\mathfrak{L}(\mathfrak{P}) = \mathfrak{L}(\mathfrak{P}; h)$ , and  $\mathfrak{A}(\mathfrak{P}) = \mathfrak{A}(\mathfrak{P}; h)$ ; they do not depend on the above choice of global shift fixing  $h$ . We further define the maximizer  $H^* \in \text{Adm}(\mathfrak{R}; h)$  as in Equation (2.4).

We will make use of the following results from [KO07, ADPZ20] on the behavior of the limit shape  $H^*$  and arctic boundary  $\mathfrak{A}$  when  $\mathfrak{R}$  is polygonal. The first statement in the below lemma is given by [ADPZ20, Theorem 1.9] and the second by [ADPZ20, Theorem 1.2, Theorem 1.10] (see also [KO07, Theorem 2, Proposition 5]).

**Lemma 2.3** [KO07, ADPZ20]. *Adopt the notation of Definition 2.2, and assume that the domain  $\mathfrak{R} = \mathfrak{P}$  is polygonal with at least six sides. Then the following two statements hold.*

- (1) *On  $\mathfrak{P} \setminus \mathfrak{L}(\mathfrak{P})$ ,  $\nabla H^*(x, t)$  is piecewise constant, taking values in  $\{(0, 0), (1, 0), (1, -1)\}$ .*
- (2) *The arctic boundary  $\mathfrak{A}(\mathfrak{P})$  is an algebraic curve, and its singularities are all either ordinary cusps or tacnodes.*

The following is an integrality result for the limiting height function  $H^*$  outside of the associated liquid region. We provide its proof in Appendix B below.

**Proposition 2.4.** *Adopt the notation of Definition 2.2.*

- (1) *Fix  $(x, t) \in \mathfrak{P} \setminus \mathfrak{L}$  such that  $\nabla H^*(x, t) = (s, r)$  exists and  $\nabla H^*$  is continuous at  $(x, t)$ . If  $(s, r) \in \{(0, 0), (1, 0), (1, -1)\}$ , then  $n(H^*(x, t) - sx - rt) \in \mathbb{Z}$ .*
- (2) *For any point  $v \in (\mathfrak{P} \setminus \mathfrak{L}) \cap (n^{-1} \cdot \mathbb{Z})^2$ , we have  $n \cdot H^*(v) \in \mathbb{Z}$ .*

It will also be useful to further set notation for the local parabolic shape of  $\mathfrak{A}(\mathfrak{P})$  around any nonsingular point  $(x_0, y_0) \in \mathfrak{A}$ .

**Definition 2.5.** Fix a nonsingular point  $(x_0, y_0) \in \mathfrak{A} = \mathfrak{A}(\mathfrak{P})$ ; assume it is not a *tangency location* of  $\mathfrak{A}$ , which is a point on  $\mathfrak{A}$  whose tangent line to  $\mathfrak{A}$  has slope in  $\{0, 1, \infty\}$ . Define the *curvature parameters*  $(\mathbf{l}, \mathbf{r}) = (\mathbf{l}(x_0, y_0; \mathfrak{A}), \mathbf{r}(x_0, y_0; \mathfrak{A})) \in \mathbb{R}^2$  associated with  $(x_0, y_0)$  so that

$$x - x_0 = \mathbf{l}(y - y_0) + \mathbf{q}(y - y_0)^2 + \mathcal{O}((y - y_0)^3), \tag{2.7}$$

<sup>3</sup>We assume throughout that all vertices of  $n\partial\mathfrak{P}$  are in  $\mathbb{Z}^2$ .



for all  $(x, y) \in \mathfrak{A}$  in a sufficiently small neighborhood of  $(x_0, y_0)$ . Since  $(x_0, y_0)$  is nonsingular and is not a tangency location, the parameters  $(l, q)$  exist, with  $l \notin \{0, 1, \infty\}$  and  $q \notin \{0, \infty\}$ .

2.4. Edge statistics results

In order to state our results, we first require some notation on edge statistics.

**Definition 2.6.** For any  $s, t, x, y \in \mathbb{R}$ , the extended Airy kernel is given by

$$\begin{aligned} \mathcal{K}(s, x; t, y) &= \int_0^\infty e^{u(t-s)} \text{Ai}(x+u) \text{Ai}(y+u) du, & \text{if } s \geq t; \\ \mathcal{K}(s, x; t, y) &= - \int_{-\infty}^0 e^{u(t-s)} \text{Ai}(x+u) \text{Ai}(y+u) du, & \text{if } s < t, \end{aligned}$$

where we recall that the Airy function  $\text{Ai} : \mathbb{R} \rightarrow \mathbb{R}$  is given by

$$\text{Ai}(x) = \frac{1}{\pi} \int_{-\infty}^\infty \cos\left(\frac{z^3}{3} + xz\right) dz.$$

From this, we define the Airy line ensemble introduced in [PS02, CH14] (see also [AH23], which provides another, probabilistic interpretation for this object), which will be limits for our edge statistics.

**Definition 2.7.** The Airy line ensemble  $\mathcal{A} = (\mathcal{A}_1, \mathcal{A}_2, \dots)$  is an infinite collection of continuous curves  $\mathcal{A}_i : \mathbb{R} \rightarrow \mathbb{R}$ , ordered so that  $\mathcal{A}_1(t) > \mathcal{A}_2(t) > \dots$  for each  $t \in \mathbb{R}$  such that

$$\mathbb{P}\left(\bigcap_{j=1}^m \{(x_j, t_j) \in \mathcal{A}\}\right) = \det [\mathcal{K}(t_i, x_i; t_j, x_j)]_{1 \leq i, j \leq m} \prod_{j=1}^m dx_j, \tag{2.8}$$

for any  $(x_1, t_1), (x_2, t_2), \dots, (x_m, t_m) \in \mathbb{R}^2$ . Here, we have written  $(x, t) \in \mathcal{A}$  if there exists some integer  $k \geq 1$  such that  $\mathcal{A}_k(t) = x$ . The existence of such an ensemble was shown as [CH14, Theorem 3.1] (and the uniqueness follows from the explicit form (2.8) of its multipoint distributions).<sup>4</sup> We abbreviate  $\mathcal{R} = (\mathcal{A}_1(t) - t^2, \mathcal{A}_2(t) - t^2, \dots)$ , which may be viewed as a function  $\mathcal{R} : \mathbb{Z}_{>0} \times \mathbb{R} \rightarrow \mathbb{R}$  by setting  $\mathcal{R}(i, t) = \mathcal{R}_i(t) = \mathcal{A}_i(t) - t^2$ .

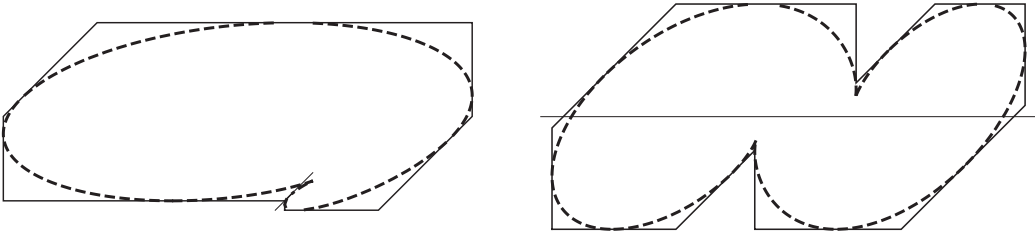
We next impose the following assumption of a polygonal subset  $\mathfrak{P} \subset \mathbb{R}^2$ , which excludes certain conditions on its arctic boundary.

**Assumption 2.8.** Under the notation of Definition 2.2, assume the following four properties hold.

- (1) The arctic boundary  $\mathfrak{A} = \mathfrak{A}(\mathfrak{P})$  has no tacnode singularities.
- (2) No cusp singularity of  $\mathfrak{A}$  is also a tangency location of  $\mathfrak{A}$ .
- (3) There exists an axis  $\ell$  of  $\mathbb{T}$  such that any line connecting two distinct cusp singularities of  $\mathfrak{A}$  is not parallel to  $\ell$ .
- (4) Any intersection point between  $\mathfrak{A}$  and  $\partial\mathfrak{P}$  must be a tangency location of  $\mathfrak{A}$ . Moreover,  $\nabla H^*(x, t)$  is continuous at any point on  $\mathfrak{A}$  that is not a tangency location.

We refer to Figure 1 above for depictions of the four forbidden scenarios. As we will show in Section 6, the polygonal region  $\mathfrak{P}$  satisfying Assumption 2.8 can be decomposed into small pieces that are either frozen or are ‘double-sided trapezoids’. These ‘double-sided trapezoids’ do not contain tacnodes or cusp singularities, which are also tangency locations. In this case, the optimal height function of such a region has been proven in [Hua24, Theorem 2.5] using a dynamical version of the loop equations.

<sup>4</sup>Its top curve  $\mathcal{A}_1$  is the Airy<sub>2</sub> process.



**Figure 5.** Shown to the left is the arctic boundary of an octagon, and shown to the right is the arctic boundary of a 12-gon. Both examples satisfy the constraints listed in Assumption 2.8.

**Remark 2.9.** It seems likely to us that the constraints listed in Assumption 2.8 hold for a generic polygonal domain with a fixed number of sides since each constraint should impose an algebraic relation between the side lengths of  $\mathfrak{P}$ . However, we will not pursue a rigorous proof of this here. We refer to Figure 5 for the arctic boundaries on a generic octagon and 12-gon (obtained by analytically solving for, and then plotting, the algebraic curves of the appropriate degrees tangent to all sides of these polygons); it is quickly seen that these arctic boundaries satisfy our assumption.

Now, we can state the following theorem on the convergence to the Airy line ensemble for edge statistics of uniformly random tilings on polygonal domains satisfying Assumption 2.8. In what follows, we recall the nonintersecting Bernoulli walk ensemble associated with any tiling of a domain from Section 2.2 and the curvature parameters from Definition 2.5. Observe that the quantity  $K$  defined in the below theorem is an integer by the first part of Proposition 2.4.

**Theorem 2.10.** *Adopt the notation of Definition 2.2 and the constraint from Assumption 2.8. Fix some point  $(x_0, t_0) \in \mathfrak{A}(\mathfrak{P})$  that is not a tangency or cusp location of  $\mathfrak{A}(\mathfrak{P})$ , and assume that  $\nabla H^*(x_0 + \varepsilon, t_0) = (0, 0)$  for all sufficiently small  $\varepsilon \geq 0$ . Denote the curvature parameters associated with  $(x_0, t_0)$  by  $(\mathfrak{l}, \mathfrak{q})$ , and set*

$$\mathfrak{s} = \left| \frac{\mathfrak{l}^{2/3}(1 - \mathfrak{l})^{2/3}}{4^{1/3}\mathfrak{q}^{1/3}} \right|; \quad \mathfrak{r} = \left| \frac{\mathfrak{l}^{1/3}(1 - \mathfrak{l})^{1/3}}{2^{1/3}\mathfrak{q}^{2/3}} \right|. \tag{2.9}$$

Let  $\mathcal{M}$  denote a uniformly random tiling of  $\mathbb{P}$ , which is associated with a (random) family  $(x_j(t))$  of nonintersecting Bernoulli walks. Denote  $K = nH^*(x_0, t_0)$ , and define the family of functions  $\mathcal{X}_n = (X_1, X_2, \dots)$  by, for each  $i \geq 0$ , setting

$$X_{i+1}(t) = \mathfrak{s}^{-1} n^{-1/3} \left( x_{K-i}(t_0 n + \mathfrak{r} n^{2/3} t) - n x_0 - \mathfrak{l} n^{2/3} t \right). \tag{2.10}$$

Then  $\mathcal{X}_n$  converges to  $\mathcal{R}$ , uniformly on compact subsets of  $\mathbb{Z}_{>0} \times \mathbb{R}$ , as  $n$  tends to  $\infty$ .

Observe that Theorem 2.10 stipulates  $\nabla H^*(x_0 + \varepsilon, t_0) = (0, 0)$  for small  $\varepsilon$ . Since for a polygonal domain  $\mathfrak{P} \subset \mathbb{R}^2$  we have  $\nabla H^*(x, y) \in \{(0, 0), (1, 0), (1, -1)\}$  for almost any  $(x, y) \notin \mathfrak{L}(\mathfrak{P})$  (by the first statement of Lemma 2.3), there are six possibilities for the behavior of  $\nabla H^*$  around any  $(x_0, t_0) \in \mathfrak{A}(\mathfrak{P})$ . Specifically, we either have  $\nabla H^*(x_0 + \varepsilon, t_0) \in \{(0, 0), (1, 0), (1, -1)\}$  or  $\nabla H^*(x_0 - \varepsilon, t_0) \in \{(0, 0), (1, 0), (1, -1)\}$ , with the former if  $(x_0, t_0)$  is on a ‘right part’ of the arctic boundary and the latter if it is on a ‘left part’. By rotating or reflecting the tileable domain  $\mathbb{P}$  if necessary, establishing convergence for the edge statistics in any one of these six situations also shows it for the remaining cases, and so for brevity we only stated Theorem 2.10 when  $\nabla H^*(x_0, t_0 + \varepsilon) = (0, 0)$ .

### 3. Convergence of edge statistics

In this section, we establish Theorem 2.10, assuming the concentration estimate Theorem 3.10 below. We begin in Section 3.1 by recalling complex analytic properties of tiling limit shapes in relation to the

complex Burgers equation; in Section 3.2, we discuss classical locations of these limit shapes. Next, in Section 3.3 we state a concentration bound for the tiling height function of polygonal domains satisfying Assumption 2.8, which we use in Section 3.4 to compare the edge statistics on such polygons to those on hexagonal domains. We then establish Theorem 2.10 in Section 3.5.

3.1. Complex slopes and complex Burgers equation

In this section, we recall from [KO07, ADPZ20] various complex analytic aspects of the tiling limit shapes discussed in Section 2.3; they will be briefly used in the proof of Lemma 3.7 below, and then more extensively in our discussion of tilted height profiles later. In what follows, we fix a simply connected open subset  $\mathfrak{R} \subset \mathbb{R}^2$  and a boundary height function  $h : \partial\mathfrak{R} \rightarrow \mathbb{R}$ . We recall the maximizer  $H^* \in \text{Adm}(\mathfrak{R}; h)$  of  $\mathcal{E}$  defined in Equation (2.4), as well as the liquid region  $\mathfrak{L} = \mathfrak{L}(\mathfrak{R}; h)$  and arctic boundary  $\mathfrak{A} = \mathfrak{A}(\mathfrak{R}; h)$  defined in Equations (2.5) and (2.6).

Then define the complex slope  $f : \mathfrak{L} \rightarrow \mathbb{H}^-$  by, for any  $u \in \mathfrak{L}$ , setting  $f(u) \in \mathbb{H}^-$  to be the unique complex number satisfying

$$\arg^* f(u) = -\pi \partial_x H^*(u); \quad \arg^* (f(u) + 1) = \pi \partial_y H^*(u), \tag{3.1}$$

where for any  $z \in \overline{\mathbb{H}^-}$  we have set  $\arg^* z = \theta \in [-\pi, 0]$  to be the unique number in  $[-\pi, 0]$  satisfying  $e^{-i\theta} z \in \mathbb{R}$ ; see Figure 6 for a depiction, where there we interpret  $1 - \partial_x H^*(u)$  and  $-\partial_y H^*(u)$  as the approximate proportions of tiles of types 1 and 2 around  $nu \in \mathbb{R}_n$ , respectively (which follows from the definition of the height function from Section 2.1).

The following result from [KO07] indicates that  $f$  satisfies the complex Burgers equation.

**Proposition 3.1** [KO07, Theorem 1]. *For any  $(x, t) \in \mathfrak{L}$ , let  $f_t(x) = f(x, t)$  we have*

$$\partial_t f_t(x) + \partial_x f_t(x) \frac{f_t(x)}{f_t(x) + 1} = 0. \tag{3.2}$$

**Remark 3.2.** As explained in [ADPZ20, Section 3.2.2], the composition  $\tilde{f} = M \circ f$  of  $f_t(z)$  with a certain Möbius transformation  $M$  solves the Beltrami equation  $\partial_{\bar{z}} \tilde{f} = \tilde{f} \cdot \partial_z \tilde{f}$ . Thus, after a change of variables, any solution of the complex Burgers equation also solves the Beltrami equation.

The following result from [KO07, ADPZ20] describes properties of the complex slope  $f_t(x)$  when  $\mathfrak{R}$  is polygonal.

**Proposition 3.3** [KO07, ADPZ20]. *Adopt the notation of Definition 2.2, and assume that the domain  $\mathfrak{R} = \mathfrak{P}$  polygonal with at least six sides. Then the following three statements hold.*

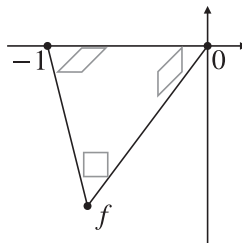


Figure 6. Shown above the complex slope  $f = f(u)$ .

- (1) The complex slope  $f_t(x)$  extends continuously to the arctic boundary  $\mathfrak{A}(\mathfrak{P})$ .
- (2) Fix  $(x_0, t_0) \in \overline{\mathfrak{D}}$ . There exists a neighborhood  $\mathfrak{U} \subset \mathbb{C}^2$  of  $(x_0, t_0)$  and a real analytic function  $Q_0 : \mathfrak{U} \rightarrow \mathbb{C}$  such that, for any  $(x, t) \in \mathfrak{U} \cap \overline{\mathfrak{D}}$ , we have

$$Q_0(f_t(x)) = x(f_t(x) + 1) - t f_t(x). \tag{3.3}$$

There exists a nonzero rational function  $Q : \mathbb{C}^2 \rightarrow \mathbb{C}^2$  such that, for any  $(x, t) \in \overline{\mathfrak{D}}$ , we have

$$Q\left(f_t(x), x - \frac{t f_t(x)}{f_t(x) + 1}\right) = 0. \tag{3.4}$$

- (3) For any  $(x, t) \in \mathfrak{U} \cap \overline{\mathfrak{D}}$ ,  $f_t(x)$  is a double root of Equation (3.3) if and only if  $(x, t) \in \partial\mathfrak{D}$ .

**Remark 3.4.** The first statement of Proposition 3.3 is [ADPZ20, Theorem 1.10]. The local existence of  $Q_0$  in Equation (3.3) in the second is [Gor21, Theorem 10.5] (see also [KO07, Corollary 2] or [ADPZ20, Theorem 5.2]), and the global existence of  $Q$  in Equation (3.4) is a quick consequence of the first part and Equation (3.3); see [Hua24, Proposition A.2(3)]. The third statement follows from the facts that  $(x, t) \in \mathfrak{A}(\mathfrak{P})$  if and only if  $f_t(x) \in \mathbb{R}$ , by Equation (3.1) and that any root of  $Q_0$  is real if and only if it is a double root, as  $Q_0$  is real analytic (see also the discussion at the end of [KO07, Section 1.6]).

### 3.2. Classical Locations

In the remainder of this section, we adopt the notation of Theorem 2.10. To establish Theorem 2.10, we will use a concentration estimate for the Bernoulli walk locations  $x_i$  associated with the uniformly random tiling  $\mathcal{M}$  of  $\mathbb{P}$ . To state this result, we require some additional notation that will be in use throughout the remainder of this paper.

**Definition 3.5.** For any integer  $i \in \mathbb{Z}$  and real number  $t \geq 0$ , define the classical location  $\gamma_i(t)$  to be the (deterministic) real number

$$\gamma_i(t) := \inf \{x \in \mathbb{R} : nH^*(x, t) = i\}, \tag{3.5}$$

if it exists (whenever this quantity is used, we will always implicitly assume that the parameters  $(i, t)$  are such that it exists).

We will use an estimate for the classical locations  $\gamma_i(t)$  around the arctic boundary.

**Lemma 3.6.** Recall Definition 2.5, and adopt the notation of Theorem 2.10. For any integer  $j \geq 0$  and  $t \in \mathbb{R}_{\geq 0}$ , we have

$$\gamma_{K-j}(t) = x_0 + \mathbf{I}(t - t_0) + \mathbf{q}(t - t_0)^2 - \mathfrak{s}^{3/2} \left(\frac{3\pi j}{2n}\right)^{2/3} + \mathcal{O}(jn^{-1} + |t - t_0|^3),$$

where the implicit constant in the error is uniform if  $(x_0, t_0)$  is bounded away from a singularity or tangency location of  $\mathfrak{A}(\mathfrak{P})$ .

To establish Lemma 3.6, we require the following lemma expressing the curvature parameters  $(\mathbf{I}, \mathbf{r})$  in terms of the analytic function  $Q_0$  from Proposition 3.3 (associated with some point  $(x_0, t_0) \in \overline{\mathfrak{D}}$ ). Its proof, which essentially follows from a Taylor expansion, is given in Appendix A below.

**Lemma 3.7.** Recall Definition 2.5, adopting the notation of Theorem 2.10, and abbreviate  $(x, t) = (x_0, t_0)$ . We have

$$\mathbf{I} = \frac{f_t(x)}{f_t(x) + 1}; \quad \mathbf{q} = -\frac{1}{2}(f_t(x) + 1)^{-3} Q_0''(f_t(x))^{-1}.$$

Now, we can establish Lemma 3.6.

*Proof of Lemma 3.6.* We may assume throughout that  $|t - t_0|$  and  $jn^{-1}$  are sufficiently small, for otherwise  $|t - t_0|^3 + jn^{-1}$  is of order 1 (and thus of  $\text{diam}(\mathfrak{P}) \geq \gamma_{K-j}(t)$ ). Then, observe that  $(\gamma_K(s), s) \in \mathfrak{A}(\mathfrak{P})$  for each  $s$  in a neighborhood of  $t_0$ . Indeed, since  $\nabla H^*(w, s) = (0, 0)$  for all  $(w, s) \in \mathfrak{P} \setminus \mathfrak{L}(\mathfrak{P})$  sufficiently close to  $(x_0, t_0)$ , we have  $nH^*(w, s) = nH(x_0, t_0) = K$  for each  $(w, s) \in \mathfrak{A}(\mathfrak{P})$  in a neighborhood of  $(x_0, t_0)$ , implying  $(\gamma_K(s), s) = (w, s) \in \mathfrak{A}(\mathfrak{P})$ .

Throughout this proof, set  $\tilde{x} = \gamma_{K-j}(t)$ . We first consider the case  $t = t_0$ . Fix some  $x \in [\tilde{x}, x_0]$ , and abbreviate  $f_0 = f_{t_0}(x_0)$  and  $f = f_{t_0}(x)$ . We will approximately express  $f$  in terms of  $f_0$ , and then we will use this with (3.1) to compare the classical locations  $\gamma_{K-j}(t_0)$  and  $\gamma_K(t_0) = x_0$ . To that end, the second part of Proposition 3.3 implies

$$Q_0(f_0) = x_0(f_0 + 1) - t_0 f_0; \quad Q_0(f) = x(f + 1) - t_0 f.$$

Subtracting these and applying a Taylor expansion yields

$$\begin{aligned} (f - f_0)Q'_0(f_0) + \frac{(f - f_0)^2}{2}Q''_0(f_0) + \mathcal{O}(|f - f_0|^3) &= Q_0(f) - Q_0(f_0) \\ &= (f + 1)(x - x_0) + (x_0 - t_0)(f - f_0), \end{aligned}$$

where the error depends on the first three derivatives of  $Q_0$  at  $f$ , which is uniformly bounded if  $(x_0, t_0)$  is bounded away from a singularity or tangency location of  $\mathfrak{A}(\mathfrak{P})$ . Since the third part of Proposition 3.3 gives  $Q'_0(f_0) = x_0 - t_0$ , we find that

$$(f - f_0)^2 = \frac{2(f_0 + 1)}{Q''_0(f_0)}(x - x_0) + \mathcal{O}(|f - f_0|^3).$$

In particular,  $|f_0 - f| = \mathcal{O}(|x - x_0|^{1/2})$  and, more specifically,

$$f - f_0 = \left( \frac{2(f_0 + 1)}{Q''_0(f_0)} \right)^{1/2} (x - x_0)^{1/2} + \mathcal{O}(|x - x_0|^{3/2}). \tag{3.6}$$

Since  $\gamma_{K-j}(t_0) = \tilde{x} \leq x \leq x_0 \leq \gamma_K(t_0)$ , we have  $(x - x_0)^{1/2} \in i\mathbb{R}$ . Since moreover  $f_0 \in \mathbb{R}$ , which implies  $Q''_0(f_0) \in \mathbb{R}$ , we deduce

$$\begin{aligned} \arg^* f &= f_0^{-1} \text{Im}(f - f_0) + \mathcal{O}(|f - f_0|^3 + |x - x_0|^{3/2}) \\ &= \left( \frac{2|f_0 + 1|}{f_0^2 |Q''_0(f_0)|} \right)^{1/2} (x_0 - x)^{1/2} + \mathcal{O}(|x_0 - x|^{3/2}). \end{aligned}$$

In particular, since  $nH^*(x_0, t_0) = K$  and  $nH^*(\tilde{x}, t_0) = K - j$ , this implies by Equation (3.1) that

$$\begin{aligned} \frac{j}{n} &= H^*(x_0, t_0) - H^*(\tilde{x}, t_0) = \int_{\tilde{x}}^{x_0} \partial_x H^*(w, t_0) dw \\ &= \frac{1}{\pi} \int_{\tilde{x}}^{x_0} \arg^* f_{t_0}(w) dw \\ &= \left( \frac{8|f_0 + 1|}{9\pi^2 f_0^2 |Q''_0(f_0)|} \right)^{1/2} (x_0 - \tilde{x})^{3/2} + \mathcal{O}(|x_0 - \tilde{x}|^{5/2}). \end{aligned}$$

Hence,

$$\gamma_K(t_0) - \gamma_{K-j}(t_0) = x_0 - \tilde{x} = \left( \frac{f_0^2 |Q_0''(f_0)|}{2|f_0 + 1|} \right)^{1/3} \left( \frac{3\pi j}{2n} \right)^{2/3} + \mathcal{O}(jn^{-1}), \tag{3.7}$$

which by Lemma 3.7 and the definition of  $\mathfrak{s}$  from (2.9) implies the lemma when  $t = t_0$ .

If  $t \neq t_0$ , then set  $\widehat{x}_0 = \gamma_K(t) \in \mathfrak{A}(\mathfrak{P})$  and  $\widehat{f}_0 = f_t(\widehat{x}_0)$ . Then, the same reasoning as used to deduce Equation (3.7) implies

$$\begin{aligned} \gamma_K(t) - \gamma_{K-j}(t) &= \left( \frac{\widehat{f}_0^2 |Q_0''(\widehat{f}_0)|}{2|\widehat{f}_0 + 1|} \right)^{1/3} \left( \frac{3\pi j}{2n} \right)^{2/3} + \mathcal{O}(jn^{-1}) \\ &= \left( \frac{f_0^2 |Q_0''(f_0)|}{2|f_0 + 1|} \right)^{1/3} \left( \frac{3\pi j}{2n} \right)^{2/3} + \mathcal{O}(|t - t_0|j^{2/3}n^{-2/3} + jn^{-1}), \end{aligned}$$

where in the last equality we used the fact that  $f_t$  is uniformly smooth in  $t$  around  $t_0$  along  $\mathfrak{A}(\mathfrak{P})$ . By Equation (2.7), it follows that

$$\begin{aligned} \gamma_{K-j}(t) &= \gamma_K(t) - \left( \frac{f_0^2 |Q_0''(f_0)|}{2|f_0 + 1|} \right)^{1/3} \left( \frac{3\pi j}{2n} \right)^{2/3} + \mathcal{O}(|t - t_0|j^{2/3}n^{-2/3} + jn^{-1}) \\ &= \gamma_K(t_0) + \mathfrak{l}(t - t_0) + \mathfrak{q}(t - t_0)^2 - \left( \frac{f_0^2 |Q_0''(f_0)|}{2|f_0 + 1|} \right)^{1/3} \left( \frac{3\pi j}{2n} \right)^{2/3} + \mathcal{O}(jn^{-1} + |t - t_0|^3), \end{aligned}$$

which implies the lemma due to Lemma 3.7 and Equation (2.9) again. □

### 3.3. Concentration estimate for the height function

In this section, we state a concentration estimate for the height function of a random tiling of  $\mathbb{P}$ . We begin with the following definition for events that hold with very high probability.

**Definition 3.8.** We say that an event  $\mathcal{E}_n$  occurs with overwhelming probability if the following holds. For any real number  $D > 1$ , there exists a constant  $C > 1$  (dependent on  $D$  and also possibly on other implicit parameters, but not  $n$ , involved in the definition of  $\mathcal{E}_n$ ) such that  $\mathbb{P}(\mathcal{E}_n) \geq 1 - n^{-D}$  for any integer  $n > C$ .

Recalling the notation of Theorem 2.10 and letting  $H$  denote the height function associated with the random tiling  $\mathcal{M}$  of  $\mathbb{P}$ , our concentration estimate will state that the following two points with overwhelming probability. First,  $H$  is within  $n^\delta$  of the deterministic function  $nH^*$  everywhere on  $\mathfrak{P}$ . Second,  $H$  is frozen (deterministic) at a ‘sufficiently far mesoscopic distance’ from the liquid region  $\mathfrak{L}(\mathfrak{P})$ . To make the latter point precise, we require the following definition.

**Definition 3.9.** Adopt the notation of Theorem 2.10, and abbreviate  $\mathfrak{L} = \mathfrak{L}(\mathfrak{P})$  and  $\mathfrak{A} = \mathfrak{A}(\mathfrak{P})$ . Then, define the augmented liquid region

$$\mathfrak{L}_+^\delta(\mathfrak{P}) = \mathfrak{L} \cup \bigcup_{u \in \mathfrak{A}} \mathfrak{B}(u; n^{\delta-2/3}).$$

Under this notation, the following theorem then provides a concentration bound for the height function associated with  $\mathcal{M}$ ; it will be established in Section 6.2 below.

**Theorem 3.10.** *Adopt the notation of Theorem 2.10, and let  $H : \mathbb{P} \rightarrow \mathbb{Z}$  denote the height function associated with  $\mathcal{M}$ . For any real number  $\delta > 0$ , the following two statements hold with overwhelming probability.*

- (1) We have  $|\mathbb{H}(nu) - nH^*(u)| < n^\delta$  for any  $u \in \overline{\mathfrak{P}}$ .
- (2) For any  $u \in \overline{\mathfrak{P}} \setminus \mathfrak{L}_+^\delta(\mathfrak{P})$ , we have  $\mathbb{H}(nu) = nH^*(u)$ .

Together with Lemma 3.6, Theorem 3.10 implies the following corollary that estimates trajectories for the random Bernoulli walks associated with  $\mathcal{M}$  (recall the Bernoulli walk locations associated with the uniformly random tiling  $\mathcal{M}$  of  $\mathbb{P}$  from Theorem 2.10 and Section 2.2) near the arctic boundary. The estimate is optimal up to the extra  $n^\delta$  factor and is reminiscent of the optimal rigidity estimates of edge eigenvalues in random matrix theory; see [EYY12, Theorem 2.2].

**Corollary 3.11.** *Adopt the notation of Theorem 2.10, and fix a real number  $\delta \in (0, 1/100)$ . For any integers  $j \in [1, 2n^{10\delta}]$  and  $s \in [-n^{2/3+20\delta}, n^{2/3+20\delta}]$ , we have with overwhelming probability that*

$$\left| \mathbf{x}_{K-j+1}(s + t_0n) - \left( x_0n + \mathbb{1}s + \mathbf{q}n^{-1}s^2 - \mathfrak{s}^{3/2} \left( \frac{3\pi j}{2} \right)^{2/3} n^{1/3} \right) \right| \leq j^{-1/3} n^{1/3+\delta}.$$

*Proof.* We first show that Theorem 3.10 implies, for any  $t$  in a sufficiently small (independent of  $n$ ) neighborhood of  $t_0$ , that with overwhelming probability we have

$$\gamma_{K-j-n^\delta+1}(t) - n^{-1} \leq n^{-1} \mathbf{x}_{K-j+1}(tn) \leq \min \{ \gamma_{K-j+n^\delta+1}(t), \gamma_K(t) + n^{\delta/2-2/3} \}, \tag{3.8}$$

where we recall the classical locations  $\gamma_i(t)$  from Definition 3.5 (and we assume that  $tn \in \mathbb{Z}$  for notational convenience). Let us only show the second bound in Equation (3.8), for the proof of the first is entirely analogous. Then, from the bijection between tilings and nonintersecting Bernoulli walk ensembles described in Section 2.2, we have  $n^{-1}(\mathbf{x}_{K-j+1}(tn)+1) \leq x$  if and only if  $\mathbb{H}(xn, tn) \geq K-j+1$ .

So, setting  $\gamma = \gamma_{K-j+n^\delta+1}(t)$ , the first part of Theorem 3.10 implies with overwhelming probability that  $\mathbb{H}(\gamma n, tn) \geq nH^*(\gamma n, tn) - n^\delta = K-j+1$ . Hence,  $\mathbf{x}_{K-j+1}(tn) \leq \gamma_{K-j+n^\delta+1}(t)$  holds with overwhelming probability. Moreover, denoting  $x' = \gamma_K(t) + N^{\delta/2-2/3}$ , we have by the second part of Theorem 3.10 that  $\mathbb{H}(x'n, tn) = nH^*(x', t) = nH^*(\gamma_K(t), t) = K$  with overwhelming probability, where in the second equality we used the fact that  $\nabla H^*(x, t) = (0, 0)$  for  $(x, t)$  in a neighborhood of  $(x_0, t_0)$  to the right of  $\mathfrak{A}$ . Hence,  $n^{-1} \mathbf{x}_{K-j+1}(t) \leq n^{-1} \mathbf{x}_K(t) \leq x' = \gamma_K(t) + N^{\delta/2-2/3}$  with overwhelming probability. This confirms Equation(3.8).

Now, Equation (3.8) and Lemma 3.6 together imply that

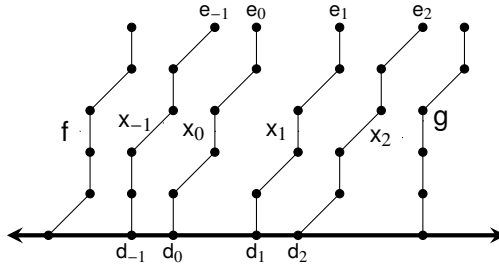
$$\begin{aligned} n^{-1} \mathbf{x}_{K-j+1}(tn) &= x_0 + \mathbb{1}(t - t_0) + \mathbf{q}(t - t_0)^2 - \mathfrak{s}^{3/2} \left( \frac{3\pi j}{2n} \right)^{2/3} \\ &\quad + \mathcal{O}(jn^{-1} + |t - t_0|^3 + j^{-1/3} n^{\delta-2/3}) \end{aligned} \tag{3.9}$$

holds for each  $j \in \mathbb{Z}$  and  $t \in \mathbb{R}$ , with overwhelming probability. Here, we have also used the fact that Lemma 3.6 implies the classical locations  $\gamma_j(t)$  (from Definition 3.5) with respect to  $\mathfrak{P}$  satisfy  $\gamma_j(t) - \gamma_{j-n^\delta}(t) = \mathcal{O}(j^{-1/3} n^{-2/3})$ . Since  $\delta \in (0, 1/100)$  and  $j \in [1, 2n^{10\delta}]$ , we have  $jn^{-1} + |t - t_0|^3 + j^{-1/3} n^{\delta-2/3} \leq 3j^{-1/3} n^{\delta-2/3}$  for  $j \in [1, 2n^{10\delta}]$  and  $|t - t_0| \leq n^{20\delta-2/3}$ . Setting  $s = (t - t_0)n$  in (3.9) then yields the corollary. □

### 3.4. Comparison to hexagonal edge statistics

We will prove Theorem 2.10 through a local comparison of a random tiling of  $\mathbb{P}$  with one of a suitably chosen hexagonal domain, whose universality of edge statistics has been proven in [Pet14, DM18, BKMM07, DDV23]. In this section, we set notation and state known properties for such hexagonal domains.

**Definition 3.12.** For any real numbers  $a, b, c > 0$ , let  $\mathfrak{E}_{a,b,c} \subset \mathbb{R}^2$  denote the  $a \times b \times c$  hexagon, that is, the polygon with vertices  $\{(0, 0), (a, 0), (a+c, c), (a+c, b+c), (c, b+c), (0, b)\}$ . By [CLP98, Theorem 1.1], its liquid region  $\mathfrak{L}_{a,b,c} = \mathfrak{L}(\mathfrak{E}_{a,b,c})$  is bounded by the ellipse inscribed in  $\mathfrak{E}_{a,b,c}$ .



**Figure 7.** Shown above is an ensemble of nonintersecting Bernoulli walks  $X = (x_{-1}, x_0, x_1, x_2)$  with initial data  $d = (d_{-1}, d_0, d_1, d_2)$ ; ending data  $e = (e_{-1}, e_0, e_1, e_2)$ ; left boundary  $f$ ; and right boundary  $g$ .

We refer to the middle of Figure 3 for a depiction when  $(a, b, c) = (5, 4, 3)$ . The following result from [Pet14, DM18, BKMM07, DDV23] is the case of Theorem 2.10 when  $P$  is a hexagon.

**Proposition 3.13** [Pet14, DM18, BKMM07, DDV23]. *Let  $a = a_n, b = b_n$  and  $c = c_n$  be real numbers bounded away from 0 and  $\infty$ , and set  $(a, b, c) = (a_n, b_n, c_n) = (na, nb, nc)$ ; assume that  $a, b, c \in \mathbb{Z}$ . Then Theorem 2.10 holds with the  $\mathfrak{P}$  there equal to the  $a \times b \times c$  hexagon (and  $P$  equal to the  $a \times b \times c$  hexagon).*

**Remark 3.14.** Since Proposition 3.13 does not appear to have been stated exactly in above form in the literature, let us briefly outline how it follows from known results. First, [DDV23, Theorem 4.1] (see also the proof of [DDV23, Theorem 1.5]) indicates that, to show uniform convergence of the normalized discrete nonintersecting Bernoulli walks  $X_i(t)$  from Equation (2.10) to the shifted Airy line ensemble  $\mathcal{R}$  from Definition 2.7, it suffices to establish convergence in the sense of distributions, that is,

$$\lim_{n \rightarrow \infty} \mathbb{P} \left( \bigcap_{i=1}^m \{X_{j_i}(t_i) \leq z_i\} \right) = \mathbb{P} \left( \bigcap_{i=1}^m \{\mathcal{R}_{j_i}(t_i) \leq z_i\} \right), \tag{3.10}$$

for any  $j_1, j_2, \dots, j_m \in \mathbb{Z}_{\geq 1}$  and  $t_1, t_2, \dots, t_m, z_1, z_2, \dots, z_m \in \mathbb{R}$ . Next, [Pet14, Theorem 8.1] and [DM18, Theorem 1.12] show that the nonintersecting Bernoulli walk ensemble  $(x_j(t))$  is a determinantal point process, whose correlation kernel under the scaling (2.10) converges to the extended Airy kernel from Definition 2.6. Since probabilities as in the left side of Equation (3.10) are expressible in terms of unbounded sums involving this correlation kernel (see, for example, [Joh05, Equation (3.9)]), to conclude the distributional convergence (3.10) from the kernel limit, it suffices to show one-point tightness of the extremal Bernoulli walk  $X_1$  (in order to effectively cut off<sup>5</sup> the sum mentioned above). This tightness is provided by [BKMM07, Theorem 3.14], which in fact shows that the one-point law of  $X_1$  converges to the Tracy–Widom distribution, originally derived from studying the largest eigenvalue of the Gaussian Unitary ensemble.

To proceed, we require some additional notation on nonintersecting Bernoulli walk ensembles. Let  $X = (x_l, x_{l+1}, \dots, x_m)$  denote a family of nonintersecting Bernoulli walks, each with time span  $[s, t]$ , so that  $x_j = (x_j(s), x_j(s + 1), \dots, x_j(t))$  for each  $j \in [l, m]$ . Given functions  $f, g : [s, t] \rightarrow \mathbb{R}$ , we say that  $X$  has  $(f; g)$  as a *boundary condition* if  $f(r) \leq x_j(r) \leq g(r)$  for each  $r \in [s, t]$ . We refer to  $f$  and  $g$  as a *left boundary* and *right boundary* for  $X$ , respectively, and allow  $f$  and  $g$  to be  $-\infty$  or  $\infty$ . We further say that  $X$  has *entrance data*  $d = (d_l, d_{l+1}, \dots, d_m)$  and *exit data*  $e = (e_l, e_{l+1}, \dots, e_m)$  if  $x_j(s) = d_j$  and  $x_j(t) = e_j$ , for each  $j \in [l, m]$ ; see Figure 7 for a depiction. Then, there is a finite number of nonintersecting Bernoulli walk ensembles with any given entrance and exit data  $(d; e)$  and (possibly infinite) boundary conditions  $(f; g)$ .

<sup>5</sup>One could alternatively prove sufficient decay of the kernel, as in [Joh05, Lemma 3.1(b)].



The below lemma from [CEP96] provides a monotonicity property for nonintersecting Bernoulli walk ensembles randomly sampled under the uniform measure on the set of such families with prescribed entrance, exit and boundary conditions. In what follows, for any functions  $f, f' : [s, t] \rightarrow \mathbb{R}$  we write  $f \leq f'$  if  $f(r) \leq f'(r)$  for each  $r \in [s, t]$ . Similarly, for any sequences  $\mathbf{d} = (d_1, d_{l+1}, \dots, d_m) \subset \mathbb{R}$  and  $\mathbf{d}' = (d'_1, d'_{l+1}, \dots, d'_m) \subset \mathbb{R}$ , we write  $\mathbf{d} \leq \mathbf{d}'$  if  $d_j \leq d'_j$  for each  $j \in [l, m]$ .

**Lemma 3.15** [CEP96, Lemma 18]. *Fix integers  $s \leq t$  and  $l \leq m$ ; functions  $f, g, g' : [s, t] \rightarrow \mathbb{R}$ ; and  $(m - l + 1)$ -tuples  $\mathbf{d}, \mathbf{d}', \mathbf{e}, \mathbf{e}'$  with coordinates indexed by  $[l, m]$ . Let  $X = (x_l, x_{l+1}, \dots, x_m)$  denote a uniformly random nonintersecting Bernoulli walk ensemble with boundary data  $(f, g)$ , entrance data  $\mathbf{d}$  and exit data  $\mathbf{e}$ . Define  $X' = (x'_l, x'_{l+1}, \dots, x'_m)$  similarly but with respect to  $(f'; g')$  and  $(\mathbf{d}'; \mathbf{e}')$ . If  $f \leq f', g \leq g', \mathbf{d} \leq \mathbf{d}'$  and  $\mathbf{e} \leq \mathbf{e}'$ , then there exists coupling between  $X$  and  $X'$  such that  $x_j \leq x'_j$  almost surely, for each  $j \in [l, m]$ .*

**Remark 3.16.** An equivalent way of stating Lemma 3.15 (as was done in [CEP96]) is through the height functions associated with the Bernoulli walk ensembles  $X$  and  $X'$ . Specifically, let  $D \subset \mathbb{T}$  be a finite domain, and let  $h, h' : \partial D \rightarrow \mathbb{Z}$  denote two boundary height functions such that  $h(v) \geq h'(v)$ , for each  $v \in \partial D$ . Let  $H, H' : D \rightarrow \mathbb{Z}$  denote two uniformly random height functions on  $D$  with boundary data  $H|_{\partial D} = h$  and  $H'|_{\partial D} = h'$ . Then, Lemma 3.15 implies (and is equivalent to) the existence of a coupling between  $H$  and  $H'$  such that  $H(u) \geq H'(u)$  almost surely, for each  $u \in D$ .

**Remark 3.17.** Due to the correspondence from Section 2.2 between tilings and nonintersecting Bernoulli walk ensembles, the uniform measure on the set of free tilings<sup>6</sup> of a strip domain of the form  $\mathbb{Z} \times [s, t] \subset \mathbb{T}$  is equivalent to that on the set of nonintersecting Bernoulli walk ensembles with time spans  $[s, t]$  under specified entrance, exit and boundary conditions. Moreover, if  $X = (x_l, x_{l+1}, \dots, x_m)$  is sampled under the uniform measure, then it is quickly verified that it satisfies the following Gibbs property<sup>7</sup> [Gor21, Section 13.2]. For any  $s \leq s' \leq t' \leq t$  and  $l \leq l' \leq m' \leq m$ , the law of  $(x_{l'}, x_{l'+1}, \dots, x_{m'})$  restricted to  $\mathbb{Z} \times [s', t']$  is uniform measure on those nonintersecting Bernoulli walk ensembles with entrance data  $(x_{l'}(s'), x_{l'+1}(s'), \dots, x_{m'}(s'))$ ; exit data  $(x_{l'}(t'), x_{l'+1}(t'), \dots, x_{m'}(t'))$ ; and boundary conditions  $(x_{l'-1}; x_{m'+1})$ .

### 3.5. Proof of Theorem 2.10

In this section, we establish Theorem 2.10. We begin with the following proposition that provides edge statistics for nonintersecting random Bernoulli walks with an approximately quadratic boundary condition.

**Proposition 3.18.** *Fix  $\delta \in (0, 1/100)$  and real numbers  $\mathfrak{q} = \mathfrak{q}_n$  and  $\mathfrak{l} = \mathfrak{l}_n$  bounded away from 0 and  $\infty$ . Define  $\mathfrak{s}, \mathfrak{r} \in \mathbb{R}$  from  $(\mathfrak{l}, \mathfrak{q})$  through Equation (2.9), set  $m = \lfloor n^{10\delta} \rfloor$  and  $T = \lfloor n^{2/3+20\delta} \rfloor$  and let  $f : [-T, T] \rightarrow \mathbb{R}$  be a function satisfying*

$$\sup_{s \in [-T, T]} |f(s) + K_0 - \mathfrak{l}s - \mathfrak{q}s^2 n^{-1}| < n^{1/3-\delta}, \quad \text{where} \quad K_0 = \mathfrak{s}^{3/2} n^{1/3} \left( \frac{3\pi m}{2} \right)^{2/3}. \tag{3.11}$$

Further, let  $\mathbf{d} = (d_1, d_2, \dots, d_m)$  and  $\mathbf{e} = (e_1, e_2, \dots, e_m)$  be integer sequences satisfying

$$|d_j - f(-T)| < n^{1/3+10\delta}; \quad |e_j - f(T)| < n^{1/3+10\delta}, \tag{3.12}$$

<sup>6</sup>Here, a free tiling of a domain  $D$  is a covering of  $D$  by disjoint tiles such that at least one (triangular) face of each tile lies inside  $D$ ; see [CKP01, Section 3].

<sup>7</sup>Informally, the Gibbs property is a statement of conditional uniformity. It indicates that that the law obtained by conditioning on some of the walks in an ensemble of nonintersecting Bernoulli walks, under the uniform measure, is also that of a uniformly random nonintersecting Bernoulli walk ensemble, whose boundary data are fixed by the conditioning.

for each  $j \in [1, m]$ . Let  $X = (x_1, x_2, \dots, x_m)$  denote a uniformly random ensemble of nonintersecting Bernoulli walks with time span  $[-T, T]$ ; boundary data  $(f; \infty)$ ; entrance data  $d$ ; and exit data  $e$ . Define the family of functions  $\mathcal{X}_n = (X_1, X_2, \dots, X_n)$  by

$$X_i(t) = s^{-1}n^{-1/3} \left( x_{m-i+1}(tn^{2/3}) - In^{2/3}t \right). \tag{3.13}$$

Then  $\mathcal{X}_n$  converges to  $\mathcal{R}$ , uniformly on compact subsets of  $\mathbb{Z}_{>0} \times \mathbb{R}$ , as  $n$  tends to  $\infty$ .

*Proof.* Throughout, we assume  $q > 0$ , as the proof when  $q < 0$  is entirely analogous. This proposition will follow from a comparison between the random Bernoulli walk ensemble  $X$  and the one associated with a random tiling of a suitably chosen hexagon. So, we begin by identifying real numbers  $a, b, c > 0$  and a point  $(x_0, t_0) \in \mathfrak{A}(a, b, c) = \partial\mathfrak{Q}_{a,b,c}$  on the ellipse inscribed in the hexagon  $\mathfrak{C}_{a,b,c}$  (recall Definition 3.12) whose curvature parameters are given by  $(I, q)$ . To that end, first observe that there are two points on  $\mathfrak{A}(1, 1, 1)$  at which a line with inverse slope  $I$  is tangent. Let  $(\tilde{x}, \tilde{t}) \in \mathfrak{A}(1, 1, 1)$  be the one whose curvature parameters  $(\tilde{I}, \tilde{q}) = (I, \tilde{q})$  are such that  $\text{sgn } \tilde{q} = \text{sgn } q = 1$ . Since  $\tilde{I} = I$  is bounded away from 0 and  $\infty$ , as is  $\tilde{q}$ . Then setting  $r = \tilde{q}q^{-1}$ ,  $(a, b, c) = (r, r, r)$  and  $(x_0, t_0) = (r\tilde{x}, r\tilde{t}) \in \mathfrak{A}(a, b, c)$ , the curvature parameters at  $(x_0, t_0)$  are  $(I, q)$ .

We will now perturb the quadratic curvature parameter of  $(x_0, t_0)$  with respect to  $\mathfrak{A}(\mathfrak{C}_{a,b,c})$  through scaling by  $\kappa$  and  $\nu$ , where

$$\kappa = 1 + n^{-20\delta}; \quad \nu = 1 - n^{-20\delta}.$$

Set  $(a', b', c') = (\kappa^{-1}a, \kappa^{-1}b, \kappa^{-1}c)$  and  $(a'', b'', c'') = (\nu^{-1}a, \nu^{-1}b, \nu^{-1}c)$ ; further, let  $(x'_0, t'_0) = (\kappa^{-1}x_0, \kappa^{-1}t_0)$  and  $(x''_0, t''_0) = (\nu^{-1}x_0, \nu^{-1}t_0)$ . Observe that the curvature parameters at  $(x'_0, t'_0)$  with respect to  $\mathfrak{A}(a', b', c')$  and at  $(x''_0, t''_0)$  with respect to  $\mathfrak{A}(a'', b'', c'')$  are given by  $(I', q') = (I, \kappa q)$  and  $(I'', q'') = (I, \nu q)$ , respectively.

Next, define  $(a', b', c') = (na', nb', nc')$  and  $(a'', b'', c'') = (na'', nb'', nc'')$ , which we assume for notational simplicity are integers. Denote the hexagons  $P' = \mathfrak{C}_{a',b',c'}$  and  $P'' = \mathfrak{C}_{a'',b'',c''}$ ; let  $\mathcal{M}'$  and  $\mathcal{M}''$  denote uniformly random tilings of  $P'$  and  $P''$ , which are associated with nonintersecting Bernoulli walk ensembles  $Y' = (y'_1, y'_2, \dots, y'_{a'})$  and  $Y'' = (y''_1, y''_2, \dots, y''_{a''})$ , respectively. Define the Bernoulli walk ensembles  $X' = (x'_1, x'_2, \dots, x'_m)$  and  $X'' = (x''_1, x''_2, \dots, x''_m)$  through a spacial and index shift of  $Y'$  and  $Y''$ , respectively; specifically, for each  $j$  and  $t$ , set

$$x'_j(t) = y'_{a'+j-m}(t + t'_0n) - x'_0n + 3n^{1/3-\delta}; \quad x''_j(t) = y''_{a''+j-m}(t + t''_0n) - x''_0n - 3n^{1/3-\delta}.$$

Given this notation, we will first use Lemma 3.15 to bound the ensemble  $X$  between  $X'$  and  $X''$ ; see Figure 8. Then, we will apply Proposition 3.13 to show that  $(X', X'')$  converges to the same Airy line ensemble under the normalization (3.13). To implement the former, define the sequences  $d', e', d'', e'' \in \mathbb{Z}^m$  by

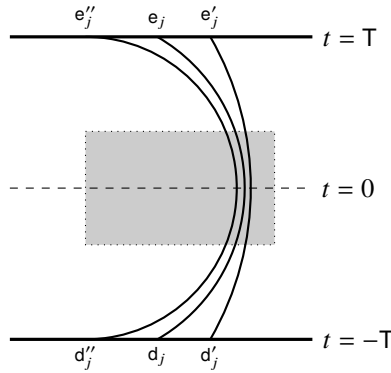
$$\begin{aligned} d' &= (x'_1(-T), x'_2(-T), \dots, x'_m(-T)); & e' &= (x'_1(T), x'_2(T), \dots, x'_m(T)); \\ d'' &= (x''_1(-T), x''_2(-T), \dots, x''_m(-T)); & e'' &= (x''_1(T), x''_2(T), \dots, x''_m(T)), \end{aligned}$$

and the functions  $f', f'' : [-T, T] \rightarrow \mathbb{Z}$  by

$$f'(t) = x'_0(t); \quad f''(t) = x''_0(t).$$

Then, by the Gibbs property described in Remark 3.17,  $X'$  is a uniformly random nonintersecting Bernoulli walk ensemble with entrance data  $d'$ , exit data  $e'$  and boundary conditions  $(x'_0; \infty)$ ; a similar statement holds for  $X''$ . Let us show with overwhelming probability that

$$d'' \leq d \leq d'; \quad e'' \leq e \leq e'; \quad f'' \leq f \leq f'. \tag{3.14}$$



**Figure 8.** Shown above trajectories for the paths  $x'_j \leq x_j \leq x''_j$  in the proof of Proposition 3.18; they approximately coincide in the shaded region.

To verify the first statement of Equation (3.14), observe for any  $j \in [1, m]$  that Equations (3.11) and (3.12) imply

$$d_j \leq qn^{-1}T^2 - IT + 5(s^2 + 1)n^{1/3+10\delta} \leq q'n^{-1}T^2 - IT - 5(s^2 + 1)n^{1/3+10\delta}. \tag{3.15}$$

To deduce the first bound, we used the facts that  $n^{1/3-\delta} \leq s^{-3/2}K_0 \leq 3m^{2/3}n^{1/3} \leq n^{1/3+10\delta}$  since  $m = \lfloor n^{10\delta} \rfloor$ ; to deduce the second, we used the facts that  $q' = \kappa q = (1 + n^{-20\delta})q$  and  $T = \lfloor n^{2/3+20\delta} \rfloor$ .

Moreover, Corollary 3.11 (applied with the P there equal to P' here) implies with overwhelming probability that

$$x'_{m-j}(-T) = y'_{a'-j}(t_0n - T) - x'_0n + 3n^{1/3-\delta} \geq q'n^{-1}T^2 - IT - 5(s^2 + 1)n^{1/3+10\delta}, \tag{3.16}$$

where we have again used the facts that  $n^{1/3-\delta} \leq s^{-3/2} \leq K_0 \leq 3m^{2/3}n^{1/3} \leq n^{1/3+10\delta}$ . Combining Equations (3.15) and (3.16), it follows that  $d \leq d'$ . The proof that  $d'' \leq d$  is entirely analogous, thereby establishing the first statement of Equation (3.14); the second is shown similarly.

The third statement of Equation (3.14) follows from the fact that for any  $t \in [-T, T]$  we have

$$\begin{aligned} f'(t) &= x'_0(t) = y'_{a'-m}(t + t'_0n) - x'_0n + 3n^{1/3-\delta} \\ &\geq It + q'n^{-1}t^2 - K'_0 - m^{-1/3}n^{1/3+\delta} + 3n^{1/3-\delta} \\ &\geq f(t) + K_0 - K'_0 + (q' - q)n^{-1}t^2 + n^{1/3-\delta} \geq f(t), \end{aligned} \tag{3.17}$$

where we have set

$$K'_0 = s'^{3/2}n^{1/3} \left( \frac{3\pi m}{2} \right)^{2/3} = \kappa^{-1/2}K_0,$$

and we have denoted

$$s' = \left| \frac{I^{2/3}(1 - I)^{2/3}}{4^{1/3}q^{1/3}} \right|; \quad r' = \left| \frac{I^{1/3}(1 - I)^{1/3}}{2^{1/3}q^{1/3}} \right|. \tag{3.18}$$

The first and second statements of Equation (3.17) follow from the definitions of  $f'$  and  $x'$ , the third from Corollary 3.11 (applied with  $j$  there equal to  $m$  here), the fourth from Equation (3.11) and the definition  $m = \lfloor n^{10\delta} \rfloor$  and the fifth from the facts that  $q' = \kappa q \geq q$  and that

$$|K_0 - K'_0| \leq |1 - \kappa^{-1/2}|K_0 \leq n^{-10\delta}K_0 \leq 5s'^{3/2}n^{1/3-10\delta}m^{2/3} = o(n^{1/3-\delta}),$$

as  $m \leq n^{10\delta}$ . Hence,  $f \leq f'$ ; similarly,  $f'' \leq f$ . This verifies that Equation (3.14) holds with overwhelming probability. So, it follows from Lemma 3.15 that there exists a coupling between  $(X, X', X'')$  such that  $x''_j \leq x_j \leq x'_j$  holds for each  $j \in [1, m]$ , with overwhelming probability.

Define normalizations of these Bernoulli walk ensembles, denoted  $\mathcal{X}'_n = (X'_1, X'_2, \dots, X'_m)$ ,  $\mathcal{X}''_n = (X''_1, X''_2, \dots, X''_m)$ ,  $\mathcal{W}'_n = (W'_1, W'_2, \dots, W'_m)$  and  $\mathcal{W}''_n = (W''_1, W''_2, \dots, W''_m)$  by (recall the notation from Equation (3.18)) setting

$$\begin{aligned} X'_i(t) &= s^{-1}n^{-1/3} \left( x'_{m-i+1}(rn^{2/3}t) - \ln^{2/3}t \right); & X''_i(t) &= s^{-1}n^{-1/3} \left( x_{m-i+1}(rn^{2/3}t) - \ln^{2/3}t \right); \\ W'_i(t) &= s'^{-1}n^{-1/3} \left( x'_{m-i+1}(r'n^{2/3}t) - \ln^{2/3}t \right); & W''_i(t) &= s''^{-1}n^{-1/3} \left( x_{m-i+1}(r''n^{2/3}t) - \ln^{2/3}t \right). \end{aligned}$$

Then, Proposition 3.13 implies that  $\mathcal{W}'_n$  and  $\mathcal{W}''_n$  converge to  $\mathcal{R}$ , uniformly on compact subsets of  $\mathbb{Z}_{>0} \times \mathbb{R}$ , as  $n$  tends to  $\infty$ . Since Equation (3.18) and the facts that  $(q, q') = (\kappa q, \nu q)$  and  $\kappa - 1 = 1 - \nu = n^{-20\delta} = o(1)$  imply  $s' = s(1 + o(1))$ ,  $r' = r(1 + o(1))$ ,  $s'' = s(1 + o(1))$  and  $r'' = r(1 + o(1))$ , we deduce that  $|W'_j(t) - X'_j(t)|$  and  $|W''_j(t) - X''_j(t)| = o(1)$  for each  $j \in [1, m]$ , uniformly on compact subsets of  $\mathbb{Z}_{>0} \times \mathbb{R}$ . Hence,  $\mathcal{X}'_n$  and  $\mathcal{X}''_n$  both converge to  $\mathcal{R}$ . Since  $x''_j \leq x_j \leq x'_j$ , it follows that  $X''_j \leq X_j \leq X'_j$ , and thus the same convergence holds for  $\mathcal{X}_n$ .  $\square$

We can now establish Theorem 2.10.

*Proof of Theorem 2.10.* This will follow from Proposition 3.18. Fix a real number  $\delta \in (0, 1/100)$ , and define  $m = n^{10\delta}$  and  $T = n^{2/3+20\delta}$  (as in Proposition 3.18), which we assume for notational convenience are integers. Define the nonintersecting Bernoulli walk ensemble  $Y = (y_1, y_2, \dots, y_m)$  by

$$y_i(t) = x_{K+i-m}(t_0n + t) - x_0n. \tag{3.19}$$

Denoting the sequences  $d, e \in \mathbb{Z}^m$  and function  $f : [-T, T] \rightarrow \mathbb{Z}$  by

$$\begin{aligned} d &= (y_1(-T), y_2(-T), \dots, y_m(-T)); & e &= (y_1(T), y_2(T), \dots, y_m(T)); \\ f(t) &= x_{K-m}(t_0n + t) - x_0n, \end{aligned}$$

it follows from the Gibbs property described in Remark 3.17 that  $Y$  is a uniformly random nonintersecting Bernoulli walk ensemble with entrance and exit data  $(d; e)$  and boundary conditions  $(f; \infty)$ . Let us verify that  $(d, e, f)$  satisfy Equations (3.12) and (3.11).

To that end, since  $m = n^{10\delta}$ , the  $j = m$  case of Corollary 3.11 implies with overwhelming probability that

$$\max_{s \in [-T, T]} \left| f(s) - Is - qn^{-1}s^2 + s^{3/2} \left( \frac{3\pi m}{2} \right)^{3/2} n^{1/3} \right| < m^{-1/3}n^{1/3+\delta} < n^{1/3-\delta}, \tag{3.20}$$

and so  $f$  satisfies Equation (3.11). Applying Corollary 3.11 with  $j \in [0, m - 1]$  and also using Equation (3.20) yields

$$|y_1(-T) - f(-T)| \leq 2s^{3/2} \left( \frac{3\pi m}{2} \right)^{2/3} n^{1/3} + 2n^{1/3} \leq n^{1/3+10\delta},$$

where to deduce the last inequality we used the fact that  $m = n^{10\delta}$ . This verifies that  $d$  satisfies (3.12) with overwhelming probability; the proof that  $e$  does as well is very similar and thus omitted.

Hence, Proposition 3.18 applies and gives that  $\mathcal{Y}_n = (Y_1, Y_2, \dots, Y_m)$  converges to  $\mathcal{R}$ , uniformly on compact subsets of  $\mathbb{Z}_{>0} \times \mathbb{R}$ , as  $n$  tends to  $\infty$ , where

$$Y_i(t) = s^{-1}n^{-1/3} \left( y_{m-i+1}(rn^{2/3}t) - \ln^{2/3}t \right).$$

By Equation (3.19),  $Y_i(t) = X_i(t)$ , meaning that  $\mathcal{Y}_n = \mathcal{X}_n$ , so the same convergence holds for  $\mathcal{X}_n$ .  $\square$

### 4. Mixing and concentration bounds

By the content in Section 3.5, it remains to establish Theorem 3.10. In this section, we collect several miscellaneous results that will be used in its proof, to appear in Section 6 below. More specifically, in Section 4.1 we state a preliminary concentration estimate for a class of tilings whose arctic boundaries are constrained to only have one cusp (in addition to other, less essential conditions); in Section 4.2, we state a mixing time bound for certain dynamics on the set of tilings, which we prove in Section 4.3.

#### 4.1. Preliminary concentration estimate

In this section, we state a concentration estimate for tiling height functions on ‘double-sided trapezoid domains’ (one may also view these as tilings of a strip). These domains are different from the ones considered in earlier works, such as [Pet14, Pet15, DM18] since they will accommodate nonfrozen boundary conditions along both their north and south edges (instead of only their south ones).

Throughout this section, we fix real numbers  $t_1 < t_2$  and denote  $t = t_2 - t_1$ . We fix linear functions  $\mathbf{a}, \mathbf{b} : [t_1, t_2]$  with  $\mathbf{a}'(s), \mathbf{b}'(s) \in \{0, 1\}$  such that  $\mathbf{a}(s) \leq \mathbf{b}(s)$  for each  $s \in [t_1, t_2]$ . Define the trapezoid domain

$$\mathfrak{D} = \mathfrak{D}(\mathbf{a}, \mathbf{b}; t_1, t_2) = \{(x, t) \in \mathbb{R} \times (t_1, t_2) : \mathbf{a}(t) < x < \mathbf{b}(t)\}, \tag{4.1}$$

and denote its four boundaries by

$$\begin{aligned} \partial_{\text{so}}(\mathfrak{D}) &= \{(x, t) \in \overline{\mathfrak{D}} : t = t_1\}; & \partial_{\text{no}}(\mathfrak{D}) &= \{(x, t) \in \overline{\mathfrak{D}} : t = t_2\}; \\ \partial_{\text{we}}(\mathfrak{D}) &= \{(x, t) \in \overline{\mathfrak{D}} : x = \mathbf{a}(t)\}; & \partial_{\text{ea}}(\mathfrak{D}) &= \{(x, t) \in \overline{\mathfrak{D}} : x = \mathbf{b}(t)\}. \end{aligned} \tag{4.2}$$

We refer to Figure 9 for a depiction.

Let  $h : \partial\mathfrak{D} \rightarrow \mathbb{R}$  denote a function admitting an admissible extension to  $\mathfrak{D}$ . We assume throughout that  $h$  is constant along both  $\partial_{\text{we}}(\mathfrak{D})$  and  $\partial_{\text{ea}}(\mathfrak{D})$ . Let  $H^* \in \text{Adm}(\mathfrak{D}; h)$  denote the maximizer of  $\mathcal{E}$  from Equation (2.3), as in Equation (2.4), and let the liquid region  $\mathfrak{L} = \mathfrak{L}(\mathfrak{D}; h)$  and arctic boundary  $\mathfrak{A} = \mathfrak{A}(\mathfrak{D}; h)$  be as in Equation (2.6). Recall that a point on  $\mathfrak{A}$  is a tangency location if the tangent line to  $\mathfrak{A}$  through it has slope either  $\{0, 1, \infty\}$ .

We may then define the complex slope  $f : \mathfrak{L} \rightarrow \mathbb{H}^-$  as in Equation (3.1), which upon denoting  $f_t(x) = f(x, t)$  satisfies the complex Burgers equation (3.2). Further let  $\mathfrak{L}_{\text{no}} = \mathfrak{L}_{\text{no}}(\mathfrak{D}; h)$  denote the interior of  $\mathfrak{L} \cap \partial_{\text{no}}(\mathfrak{D})$ , and let  $\mathfrak{L}_{\text{so}} = \mathfrak{L}_{\text{so}}(\mathfrak{D}; h)$  denote the interior of  $\mathfrak{L} \cap \partial_{\text{so}}(\mathfrak{D})$ ; these are the extensions of the liquid region  $\mathfrak{R}$  to the north and south boundaries of  $\mathfrak{L}$ . For all  $t \in (t_1, t_2)$ , we define slices of the liquid region (along the horizontal line  $y = t$ ) by

$$I_t = \{x : (x, t) \in \overline{\mathfrak{L}}\}; \quad I_{t_1} = \overline{\mathfrak{L}_{\text{so}}}; \quad I_{t_2} = \overline{\mathfrak{L}_{\text{no}}}.$$

For any real number  $\delta > 0$ , we define the augmented variant of  $\mathfrak{L}$  (as in Definition 3.9) by

$$\mathfrak{L}^\delta(\mathfrak{D}) = \mathfrak{L}_+^\delta(\mathfrak{D}; h) = \mathfrak{L} \cup \bigcup_{u \in \mathfrak{A}} \mathfrak{B}(u; n^{\delta-2/3}).$$

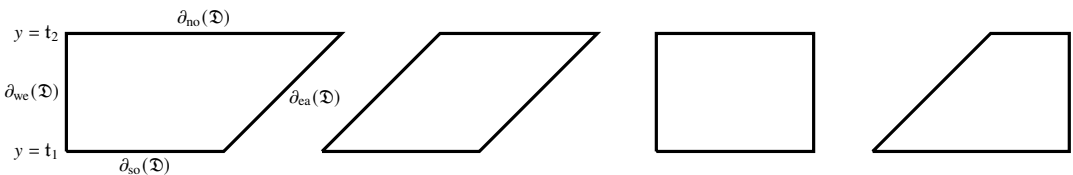
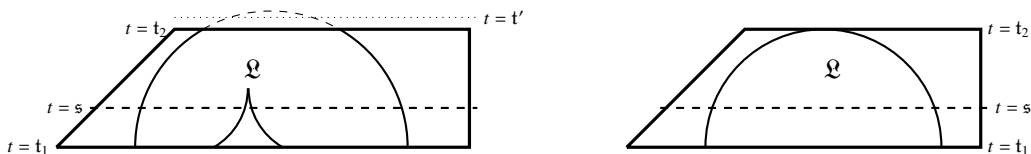


Figure 9. Shown above are the four possibilities for  $\mathfrak{D}$ .



**Figure 10.** Shown to the left is an example of limit shape admitting an extension to time  $t' > t_2$ ; shown to the right is a liquid region that is packed with respect to  $h$ .

Next, let us formulate certain conditions on the limit shape  $H^*$ . For any  $t' \geq t_2$ , we say that  $H^*$  can be extended to time  $t'$  if there exists a simply connected, open subset  $\tilde{\mathcal{Q}} \subset \mathbb{R}^2$  containing  $\mathcal{Q}$  such that the set  $\{x : (x, t) \in \tilde{\mathcal{Q}}\}$  is nonempty and connected for each  $t \in [t_2, t']$ , and there exists an extension  $\tilde{f} : \tilde{\mathcal{Q}} \rightarrow \mathbb{H}^-$  of  $f_t(x)$  satisfying the complex Burgers equation (3.2). In this case,  $\mathcal{Q}_{no} = I_{t_2}$  is a single interval. We also call  $\partial_{no}(\mathcal{D})$  packed (with respect to  $h$ ) if  $\partial_x h(v) = 1$  for each  $v \in \partial_{no}(\mathcal{D})$ ; in this case,  $\tilde{\mathcal{Q}} \cap \partial_{no}(\mathcal{D})$  constitutes at most a single point, and so  $\mathcal{Q}_{no}$  is empty. We refer to Figure 10 for a depiction.

Now, let  $n \geq 1$  be an integer; denote  $t_1 = t_1 n$ , and  $t_2 = t_2 n$ . Suppose  $D = n\mathcal{D} \subset \mathbb{T}^2$  so that  $t_1, t_2 \in \mathbb{Z}_{>0}$ . Let  $h : \partial D \rightarrow \mathbb{Z}$  denote a boundary height function. We next stipulate the following assumption on the continuum limit shape  $H^*$ . Here, we fix a real number  $\delta > 0$  and a (large) positive integer  $n$ . Below, we view the quantities  $t_1 < t_2 < t'$ ; functions  $\mathfrak{a}, \mathfrak{b}$ ; and polygonal domain  $\mathfrak{P}$  as independent of  $n$ . In what follows, a horizontal tangency location of  $\partial\tilde{\mathcal{Q}}$  is a tangency location on  $\mathfrak{A}$  at which the tangent line is horizontal (parallel to the  $x$ -axis).

**Assumption 4.1.** Assume the following constraints hold.

- (1) The boundary height function  $h$  is constant along both  $\partial_{ea}(\mathcal{D})$  and  $\partial_{we}(\mathcal{D})$ .
- (2) Either  $\partial_{no}(\mathcal{D})$  is packed with respect to  $h$  or there exists  $t' > t_2$  such that  $H^*$  admits an extension to time  $t'$ .
- (3) There exists  $\tilde{t} \in [t_1, t_2)$  such that the following holds. For  $t \in [t_1, \tilde{t})$ , the set  $I_t$  consists of two nonempty disjoint intervals, and for  $t \in [\tilde{t}, t_2]$ , the set  $I_t$  consists of one nonempty interval.<sup>8</sup>
- (4) Any tangency location along  $\partial\tilde{\mathcal{Q}}$  is of the form  $\min I_t$  or  $\max I_t$ , for some  $t \in (t_1, t_2)$ . At most one tangency location is of the form  $\min I_t$ , and at most one is of the form  $\max I_t$ .
- (5) There exists an algebraic curve  $Q$  such that, for any  $(x, t) \in \tilde{\mathcal{Q}}$ , we have

$$Q\left(f_t(x), x - \frac{t f_t(x)}{f_t(x) + 1}\right) = 0.$$

Furthermore, the curve  $Q$  ‘approximately comes from a polygonal domain’ in the following sense. There exists a polygonal domain  $\mathfrak{P}$  satisfying Assumption 2.8 with liquid region  $\mathcal{L}(\mathfrak{P})$  and a real number  $\alpha = \alpha_n \in \mathbb{R}$  with  $|\alpha - 1| < n^{-\delta}$  such that, if  $Q_{\mathcal{L}(\mathfrak{P})}$  is the algebraic curve associated with  $\mathcal{L}(\mathfrak{P})$  from Proposition 3.3, then

$$Q(u, v) = \frac{u + 1}{\alpha^{-1}u + 1} Q_{\mathcal{L}(\mathfrak{P})}(\alpha^{-1}u, v).$$

Let us briefly comment on these constraints. The first guarantees that the associated tiling is one of a trapezoid, as depicted in Figure 9. The second and third guarantee that the arctic boundary for the tiling has only one cusp. The fourth implies that there are at most two tangency locations along the arctic boundary (and are along the leftmost and rightmost components of the arctic curve, if they exist); the fifth implies that the limit shape for the tiling is part of (an explicit perturbation of) one given by a polygonal domain. The last two conditions could in principle be weakened; we impose them since doing so will substantially simplify notation in the proofs later.

<sup>8</sup>In this way, if  $\tilde{t} = t_1$ , then  $I_t$  only consists of one nonempty interval for all  $t \in [t_1, t_2]$ .

The next assumption indicates how the tiling boundary data  $h$  approximate  $h$  along  $\partial\mathcal{D}$ .

**Assumption 4.2.** Adopt Assumption 4.1, and assume the following on how  $h$  converges to  $h$ .

- (1) For each  $v \in \partial\mathcal{D}$ , we have  $|h(nv) - nh(v)| < n^{\delta/2}$ .
- (2) For each  $v \in \partial_{\text{ea}}(\mathcal{D}) \cup \partial_{\text{we}}(\mathcal{D})$ , and each  $v \in \partial_{\text{no}}\mathcal{D} \cup \partial_{\text{so}}\mathcal{D}$  such that  $v \notin \mathcal{L}_+^{\delta/2}(\mathcal{D})$ , we have  $h(nv) = nh(v)$ .

The first assumption states that  $h$  approximates its limit shape, and the second states that it coincides with its limit shape in the frozen region.<sup>9</sup> Recalling that  $\mathcal{G}(h)$  denotes the set of height functions on  $D$  with boundary data  $h$ . We can now state the following concentration estimate for a uniformly element of  $\mathcal{G}(h)$  from part I of this series [Hua24]. In particular, the below result appears as [Hua24, Theorem 2.5], where Assumption 2.3 there is verified by Assumption 4.1 and [Hua24, Proposition A.4].

**Theorem 4.3** [Hua24, Theorem 2.5]. *There exists a constant  $c = c(\mathfrak{P}) > 0$  such that the following holds. Adopt Assumption 4.1 and Assumption 4.2, and further assume that  $t_2 - t_1 < c$ . Let  $H : D \rightarrow \mathbb{Z}$  denote a uniformly random element of  $\mathcal{G}(h)$ . Then, the following two statements hold with overwhelming probability.*

- (1) We have  $|H(nu) - nH^*(u)| < n^\delta$ , for any  $u \in \mathcal{D}$ .
- (2) For any  $u \in \mathcal{D} \setminus \mathcal{L}_+^\delta(\mathcal{D})$ , we have  $H(nu) = nH^*(u)$ .

**Remark 4.4.** Recall from Section 2.2 that the height function  $H$  from Theorem 4.3 can equivalently be interpreted as a family of nonintersecting Bernoulli walks on  $D$ . The fact that  $h$  is constant along both  $\partial_{\text{ea}}(\mathcal{D})$  and  $\partial_{\text{we}}(\mathcal{D})$  implies that  $h$  is constant along the east and west boundaries of  $D$ . This is equivalent to not imposing any left or right boundary constraints  $(f; g)$  for these nonintersecting random Bernoulli walks (in the sense described in Section 3.4).

### 4.2. Mixing time estimates

As mentioned in Section 1, we will establish the general concentration estimate Theorem 3.10 by decomposing our domain into a bounded number of subregions that each satisfy Assumption 4.1. We introduce a Markov chain, called the alternating dynamics, that uniformly resamples the tiling in one subregion and leaves it fixed in the others. At each step of these dynamics, we show that our concentration bound is preserved with overwhelming probability, by using the preliminary concentration estimate Theorem 4.3. Theorem 3.10 would then follow by running the alternating dynamics until they mix.

A point of caution here is that Theorem 4.3 is not deterministic; there is some, subpolynomial, probability that the preliminary concentration estimate does not hold. So, if the number of steps required for the alternating dynamics to mix were sufficiently (superpolynomially) large, then in principle the concentration estimate could be lost at some point in these dynamics. In this section, we will indicate that this does not happen; after introducing the alternating dynamics (Definition 4.5), we will state that they mix in polynomial time (Proposition 4.6 below).

In what follows, we fix a domain  $R \subset \mathbb{T}$  and a boundary height function  $h : \partial R \rightarrow \mathbb{Z}$ . Let us introduce the following Markov dynamics on  $\mathcal{G}(h)$  that, given a certain decomposition of  $R$  as a union  $R = \bigcup_{i=1}^k R_i$  of domains, ‘alternate’ between uniformly resampling  $H \in \mathcal{G}(h)$  on each of the  $R_i$ .

**Definition 4.5.** Fix an integer  $k \geq 1$ , a domain  $R \subset \mathbb{T}$ , and a boundary height function  $h : \partial R \rightarrow \mathbb{Z}$ . Suppose that  $R \setminus \partial R$  and  $\mathcal{G}(h)$  are both nonempty and that  $k \leq \text{diam } R$ . Let  $R_1, R_2, \dots, R_k \subseteq R$  denote domains such that  $R = \bigcup_{i=1}^k R_i$  and such that any interior vertex of  $R$  is an interior vertex of some  $R_i$ , that is, for each  $v \in R \setminus \partial R$ , there exists  $i \in [1, k]$  for which  $v \in R_i \setminus \partial R_i$ . The *alternating dynamics* on  $R$  with respect to  $(R_1, R_2, \dots, R_k)$ , denoted by  $M_{\text{alt}}$ , is the discrete-time Markov chain on  $\mathcal{G}(h)$ , whose state  $H_{t+1} \in \mathcal{G}(h)$  at any time  $t + 1 \in \mathbb{Z}_{\geq 1}$  is defined from  $H_t$  as follows.

<sup>9</sup>Observe since  $\partial_x H \leq 1$  that, if  $\partial_{\text{no}}(\mathcal{D})$  is packed, then the second part of Assumption 4.2 implies that  $h(nv) = nh(v)$  for each  $v \in \partial_{\text{no}}(\mathcal{D})$ .

Let  $i \in [1, k]$  denote the integer such that  $k$  divides  $t - i + 1$ , and let  $h_{t+1} = H_t|_{\partial R_i}$ . Further, let  $F_{t+1} \in \mathcal{G}(h_{t+1})$  denote a uniformly random height function on  $R_i$ . Then, define  $H_{t+1} : R \rightarrow \mathbb{Z}$  by setting  $H_{t+1}|_{R_i} = F_{t+1}$  and  $H_{t+1}|_{R \setminus R_i} = H_t|_{R \setminus R_i}$ .

Observe (as is quickly verified by induction on  $|R|$ ) that the alternating dynamics are irreducible. Thus, they admit a unique stationary measure [LPW09, Corollary 1.17], which is the uniform one  $\mathcal{G}(h)$ .

We will bound the rate of convergence to stationarity for these alternating dynamics, so let us recall some notion on mixing times. Fix a discrete state space  $\mathcal{S}$ , and let  $\mathcal{P}(\mathcal{S})$  denote the set of probability measures on  $\mathcal{S}$ . The total variation distance between two measures  $\nu, \nu' \in \mathcal{P}(\mathcal{S})$  is

$$d_{TV}(\nu, \nu') = \max_{\mathcal{A} \subseteq \mathcal{S}} |\nu(\mathcal{A}) - \nu'(\mathcal{A})|.$$

In addition, fix an irreducible Markov chain  $M : \mathcal{P}(\mathcal{S}) \rightarrow \mathcal{P}(\mathcal{S})$  on  $\mathcal{S}$ , whose unique stationary measure is denoted by  $\rho$ . For any real number  $\varepsilon > 0$ , the *mixing time with respect to  $M$*  is given by

$$t_{\text{mix}}(\varepsilon; M) = \min \left\{ t \in \mathbb{Z}_{\geq 0} : \max_{\nu \in \mathcal{P}(\mathcal{S})} d_{TV}(M^t \nu, \rho) \leq \varepsilon \right\}, \tag{4.3}$$

which by [LPW09, Exercise 4.3] (which is a quick consequence of [LPW09, Proposition 4.7]) satisfies

$$d_{TV}(M^t \nu, \rho) \leq d_{TV}(M^{t_{\text{mix}}(\varepsilon; M)} \nu, \rho) \leq \varepsilon, \quad \text{whenever } t \geq t_{\text{mix}}(\varepsilon; M). \tag{4.4}$$

We now state the following (very coarse) estimate on the mixing time for the dynamics  $M_{\text{alt}}$ . Its proof will appear in Section 4.3 below.

**Proposition 4.6.** *There exists a constant  $C > 1$  such that the following holds. Adopt the notation of Definition 4.5, and set  $A = (\text{diam } R)^2$ . If  $A \geq C$ , then  $t_{\text{mix}}(e^{-A}; M_{\text{alt}}) \leq A^{11}$ .*

### 4.3. Proof of Proposition 4.6

There are likely many ways of establishing Proposition 4.6; the proof below will proceed through a comparison between the alternating dynamics and the Glauber (‘flip’) dynamics. To define the latter, given a height function  $H : R \rightarrow \mathbb{Z}$  and an interior vertex  $v \in R \setminus \partial R$ , we say  $v$  is *increasable with respect to  $H$*  if the function  $H' : R \rightarrow \mathbb{Z}$  defined by

$$H'(v) = H(v) + 1; \quad H'(u) = H(u), \quad \text{for } u \in R \setminus \{v\},$$

is a height function on  $R$ . In this case, we say that  $H'$  is the *unit increase* of  $H$  at  $v$ . We define *decreasable* vertices and *unit decreases* of  $H$  analogously. Observe that a vertex of  $R$  cannot simultaneously be *increasable* and *decreasable* with respect to a given height function  $H$  on  $R$ .

**Definition 4.7.** Given a height function  $H \in \mathcal{G}(h)$  and an interior vertex  $v \in R \setminus \partial R$ , the *random flip of  $H$  at  $v$*  is the random height function  $H' \in \mathcal{G}(h)$  defined as follows.

- If  $v$  is neither *increasable* nor *decreasable* with respect to  $H$ , then set  $H' = H$ .
- If  $v$  is *increasable* with respect to  $H$ , then with probability  $\frac{1}{2}$  set  $H'$  to be the unit increase of  $H$  at  $v$ . Otherwise, set  $H' = H$ .
- If  $v$  is *decreasable* with respect to  $H$ , then with probability  $\frac{1}{2}$  set  $H'$  to be the unit decrease of  $H$  at  $v$ . Otherwise, set  $H' = H$ .

Now, we define two Markov chains on  $\mathcal{G}(h)$ , the flip dynamics and the region-flip dynamics. Each update of either chain is obtained by applying a random flip to an interior vertex  $v$  of  $R$ . In the flip dynamics,  $v \in R \setminus \partial R$  is selected uniformly at random; in the region-flip dynamics  $v$  is selected uniformly at random from  $R_i \setminus \partial R_i$ , where  $i$  is determined from the time of the update.



**Definition 4.8.** The *flip dynamics* on  $R$ , denoted by  $M_{fl}$ , is the discrete-time Markov chain on  $\mathcal{G}(h)$  whose state  $H_{t+1}$  at time  $t + 1 \geq 1$  is defined from  $H_t$  as follows. Select an interior vertex  $v \in R \setminus \partial R$  uniformly at random, and set  $H_{t+1}$  to be the random flip of  $H_t$  at  $v$ .

The *region-flip dynamics* on  $R$  with respect to  $(R_1, R_2, \dots, R_k)$ , denoted by  $M_{rf}$ , is the discrete-time Markov chain on  $\mathcal{G}(h)$  whose state  $H_{t+1}$  at time  $t + 1 \geq 1$  is defined from  $H_t$  as follows. Let  $i \in [1, k]$  denote the integer such that  $(kt_0 + i - 1)A^5 < t + 1 \leq (kt_0 + i)A^5$ , for some  $t_0 \in \mathbb{Z}_{\geq 0}$ . Select a vertex  $v \in R_i \setminus \partial R_i$  uniformly at random, and set  $H_{t+1}$  to be the random flip of  $H_t$  at  $v$ .

We then have the following result from [RT00] bounding the mixing time for the flip dynamics.

**Proposition 4.9** [RT00, Theorem 5]. *Adopting the notation of Proposition 4.6, we have for any real number  $\varepsilon \in (0, 1)$  that*

$$t_{\text{mix}}(\varepsilon; M_{fl}) < CA^4 \log A + CA^3 \log A \log \varepsilon^{-1}.$$

We now state the following two lemmas, which will be established below.

**Lemma 4.10.** *Under the notation of Proposition 4.6,*

$$t_{\text{mix}}(e^{-2A}; M_{rf}) \leq 144A^{11} \cdot \left( t_{\text{mix}}\left(\frac{e^{-2A}}{32A^4}; M_{fl}\right) + 1 \right).$$

**Lemma 4.11.** *Under the notation of Proposition 4.6,  $A^5 t_{\text{mix}}(e^{-A}; M_{alt}) \leq t_{\text{mix}}(e^{-2A}; M_{rf})$ .*

Given these two results, we can quickly establish Proposition 4.6.

*Proof of Proposition 4.6.* This follows from Lemma 4.11, Lemma 4.10 and Proposition 4.9 (the last applied with the  $\varepsilon$  there equal to  $\frac{e^{-2A}}{32A^4}$  here). □

The proofs of Lemma 4.10 and Lemma 4.11 will use ‘weighted’ and ‘censored’ forms of the flip dynamics from Definition 4.8. To define these, adopting the notation of Definition 4.5, for each  $i \in [1, k]$  let

$$p_i = |R_i \setminus \partial R_i| \cdot \left( \sum_{j=1}^k |R_j \setminus \partial R_j| \right)^{-1} \in [0, 1]. \tag{4.5}$$

For any vertex  $v \in R \setminus \partial R$ , we further let

$$m(v) = \#\{j \in [1, k] : v \in R_j \setminus \partial R_j\}; \quad \mathfrak{M} = \sum_{v \in R \setminus \partial R} m(v) = \sum_{j=1}^k |R_j \setminus \partial R_j|; \quad m = \sum_{v \in R \setminus \partial R} m(v)^{-1}.$$

**Definition 4.12.** The *weighted flip dynamics*, denoted by  $M_{wfl}$ , is the discrete-time Markov chain on  $\mathcal{G}(h)$ , whose state  $H_{t+1}$  at time  $t + 1$  is defined from  $H_t$  as follows. Select an interior vertex  $v \in R \setminus \partial R$  with probability  $m(v) \cdot \mathfrak{M}^{-1}$ , and set  $H_{t+1}$  to be the random flip of  $H_t$  at  $v$ .

The *censored weighted flip dynamics*, denoted by  $M_{cwf}$ , is the discrete-time Markov chain on  $\mathcal{G}(h)$ , whose state  $H_{t+1}$  at time  $t + 1$  is defined from  $H_t$  as follows. Select an interior vertex  $v \in R \setminus \partial R$  with probability  $m(v) \cdot \mathfrak{M}^{-1}$ . Then set  $H_{t+1}$  to be the random flip of  $H_t$  at  $v$  with probability  $m(v)^{-1} \cdot m^{-1}$ , and set  $H_{t+1} = H_t$  with the complementary probability  $1 - m(v)^{-1} \cdot m^{-1}$ .

**Remark 4.13.** By Definition 4.12, we may interpret the censored weighted flip dynamics  $M_{cwf}$  as the following ‘lazy’ version of the flip dynamics from Definition 4.8. With probability  $1 - |R \setminus \partial R| \cdot (\mathfrak{M} \cdot m)^{-1}$ ,

we perform a *lazy* step and set  $H_{t+1} = H_t$ . Otherwise, we perform a *active* step, by selecting a vertex  $v \in R \setminus \partial R$  uniformly at random and setting  $H_{t+1}$  to be the random flip of  $H_t$  at  $v$ .

The following lemma compares the mixing time for  $M_{\text{cwf}}$  to that of the flip dynamics  $M_{\text{fl}}$ , using Remark 4.13.

**Lemma 4.14.** *For any real number  $\varepsilon \in (0, \frac{1}{2}]$ , we have*

$$t_{\text{mix}}(2\varepsilon; M_{\text{cwf}}) \leq 4A^3(\log \varepsilon^{-1})^2 \cdot (t_{\text{mix}}(\varepsilon; M_{\text{fl}}) + 1).$$

*Proof.* Throughout this proof, we recall the interpretation of  $M_{\text{cwf}}$  as a lazy version of  $M_{\text{fl}}$  from Remark 4.13; we also recall the notation of that remark and set  $T_0 = 4A^3(\log \varepsilon^{-1})^2 \cdot (t_{\text{mix}}(\varepsilon; M_{\text{fl}}) + 2 \leq 4A^3(\log \varepsilon^{-1})^2 \cdot (t_{\text{mix}}(\varepsilon; M_{\text{fl}}) + 1)$ . By Chernoff’s inequality, with probability at least  $1 - \varepsilon$ , the number of active steps in this walk after some time  $T \geq T_0 \geq 4A^3(\log \varepsilon^{-1})^2$  is at least

$$\frac{|R \setminus \partial R|}{m \cdot \mathfrak{M}} \cdot T - T^{1/2} \log \varepsilon^{-1} \geq \frac{T}{\mathfrak{M}} - T^{1/2} \log \varepsilon \geq A^{-3/2}T - (\log \varepsilon^{-1})T^{1/2} \geq \frac{T_0}{2A^{3/2}},$$

where we used the fact that  $m \leq |R \setminus \partial R|$  (as  $m(v) \geq 1$  for each  $v \in R \setminus \partial R$ ) in the first bound, the fact that  $\mathfrak{M} \leq k \cdot |R \setminus \partial R| \leq (\text{diam } R)^3 = A^{3/2}$  (as  $m(v) \leq k \leq \text{diam } R$  for each  $v \in R \setminus \partial R$ ) in the second and the fact that  $T \geq T_0 \geq 4A^3(\log \varepsilon)^2$  in the third. It follows for  $T \geq T_0$  that the number of active steps in these dynamics is at least  $t_{\text{mix}}(\varepsilon; M_{\text{fl}})$ , with probability at least  $1 - \varepsilon$ . Conditioning on this event, we find for any  $H_0 \in \mathcal{G}(h)$  that we may couple  $M_{\text{cwf}}^{[T_0]} H_0$  to coincide with a uniformly random element  $F \in \mathcal{G}(h)$  with probability  $1 - \varepsilon$ . Hence, by a union bound, we may couple  $M_{\text{cwf}}^{[T_0]} H_0$  to coincide with  $F$  with probability  $1 - 2\varepsilon$ , from which the lemma follows, as  $T_0 \leq 4A^3(\log \varepsilon^{-1})^2 \cdot (t_{\text{mix}}(\varepsilon; M_{\text{fl}}) + 1)$ .  $\square$

We further require a censored version of the region-flip dynamics from Definition 4.8.

**Definition 4.15.** The *censored region-flip dynamics*, denoted by  $M_{\text{crf}}$ , is the discrete-time Markov chain on  $\mathcal{G}(h)$  whose state  $H_{t+1}$  at time  $t + 1$  is defined from  $H_t$  as follows. First, let  $\mathcal{X} = (X_1, X_2, \dots) \in \mathbb{Z}_{\geq 1}$  denote the sequence of integer-valued random variables defined by first setting  $\mathbb{P}(X_1 = i) = p_i$  for each  $i \in [1, k]$ . Then, given  $X_r$ , we define  $X_{r+1} \in \{X_r + 1, X_r + 2, \dots, X_r + k\}$  by setting  $\mathbb{P}(X_{r+1} = X_r + i) = p_j$ , where  $j \in [1, k]$  is such that  $k$  divides  $X_r + i - j$ .

Now, let  $s \geq 1$  denote the integer such that  $(s - 1)A^5 < t + 1 \leq sA^5$ , and let  $i' \in [1, k]$  denote the integer such that  $kt_0 + i' = s$  for some  $t_0 \in \mathbb{Z}_{\geq 0}$ . If  $s \in \mathcal{X}$  and  $t = (s - 1)A^5$ , then select an interior  $v \in R_{t'} \setminus \partial R_{t'}$  uniformly at random, and let  $H_{t+1}$  denote the random flip of  $H_t$  at  $v$ . If instead  $s \notin \mathcal{X}$  or  $t - (s - 1)A^5 > 0$ , then set  $H_{t+1} = H_t$ .

The process  $M_{\text{crf}}$  censors any step in the region-flip dynamics  $M_{\text{rf}}$  from Definition 4.8 in the time interval  $[(s - 1)A^5 + 2, sA^5]$  and also the step at time  $(s - 1)A^5$  if  $s \notin \mathcal{X}$ .

Denote the maximal and minimal configurations of  $\mathcal{G}(h)$  by  $H^{\text{top}}, H^{\text{btm}} \in \mathcal{G}(h)$ , which for any  $H \in \mathcal{G}(h)$  satisfy  $H^{\text{top}}(v) \geq H(v) \geq H^{\text{btm}}(v)$ , for each  $v \in R$ . Further, let  $\delta_{H^{\text{top}}}, \delta_{H^{\text{btm}}} \in \mathcal{P}(\mathcal{G}(h))$  denote the delta masses at  $H^{\text{top}}$  and  $H^{\text{btm}}$ , respectively. The following result from [PW13] shows that the above censorings (weakly) increase the mixing time for these dynamics when started from the top configuration or the bottom one.<sup>10</sup>

**Proposition 4.16** [PW13, Theorem 1.1]. *Letting  $\rho$  denote the uniform measure on  $\mathcal{G}(h)$ , we have for any integer  $t \geq 0$  that*

$$\begin{aligned} d_{\text{TV}}(M_{\text{wf}}^t \delta_{H^{\text{top}}}, \rho) &\leq d_{\text{TV}}(M_{\text{cwf}}^t \delta_{H^{\text{top}}}, \rho); & d_{\text{TV}}(M_{\text{wf}}^t \delta_{H^{\text{btm}}}, \rho) &\leq d_{\text{TV}}(M_{\text{cwf}}^t \delta_{H^{\text{btm}}}, \rho); \\ d_{\text{TV}}(M_{\text{rf}}^t \delta_{H^{\text{top}}}, \rho) &\leq d_{\text{TV}}(M_{\text{crf}}^t \delta_{H^{\text{top}}}, \rho); & d_{\text{TV}}(M_{\text{rf}}^t \delta_{H^{\text{btm}}}, \rho) &\leq d_{\text{TV}}(M_{\text{crf}}^t \delta_{H^{\text{btm}}}, \rho). \end{aligned}$$

<sup>10</sup>This statement was only explicitly made in [PW13, Theorem 1.1] for starting the dynamics from the top configuration, but the fact that it also holds when started from the bottom one follows by symmetry.

Recalling the notation from Equation (4.3), we also denote for any irreducible Markov chain  $M : \mathcal{P}(\mathcal{Z}(h)) \rightarrow \mathcal{P}(\mathcal{Z}(h))$  the quantities (where below  $\rho$  denotes the stationary measure of  $M$ )

$$R(\varepsilon; M) = \min \left\{ t \in \mathbb{Z}_{\geq 0} : d_{TV}(M^t \delta_{H^{\text{top}}}, \rho) < \varepsilon \right\};$$

$$S(\varepsilon; M) = \min \left\{ t \in \mathbb{Z}_{\geq 0} : d_{TV}(M^t \delta_{H^{\text{btm}}}, \rho) < \varepsilon \right\}.$$

The following lemma bounds the mixing times of weighted flip and region-flip dynamics by the associated  $R$  and  $S$ .

**Lemma 4.17.** *For any  $\varepsilon \in (0, 1)$ , we have*

$$t_{\text{mix}}(\varepsilon, M_{\text{wf}}) \leq R\left(\frac{\varepsilon}{4A^2}; M_{\text{wf}}\right) + S\left(\frac{\varepsilon}{4A^2}; M_{\text{wf}}\right); \quad t_{\text{mix}}(\varepsilon, M_{\text{rf}}) \leq R\left(\frac{\varepsilon}{4A^2}; M_{\text{rf}}\right) + S\left(\frac{\varepsilon}{4A^2}; M_{\text{rf}}\right). \quad (4.6)$$

*Proof.* We only establish the second statement of Equation (4.6), as the proof of the first is entirely analogous. First, observe that there exists a grand coupling the region-flip dynamics  $M_{\text{rf}}$  over all choices of initial data in  $\mathcal{Z}(h)$  by running them under the same choices of sequences  $\mathcal{X} = (X_1, X_2, \dots)$  and vertices  $v$  (at which each flip is made) from Definition 4.15. It is quickly verified (see [Gor21, Proposition 25.7], for example) that this coupling is *monotone*, meaning that if for some  $H_1, H_2 \in \mathcal{Z}(h)$  we have  $H_1(v) \leq H_2(v)$  for each  $v \in R$ , then it holds that  $M_{\text{rf}}^t H_1(v) \leq M_{\text{rf}}^t H_2(v)$  for each  $t \geq 0$  and  $v \in R$ .

Observe that it suffices to show under these coupled dynamics that, with probability at least  $1 - \varepsilon$ , the models started at  $H^{\text{top}}$  and at  $H^{\text{btm}}$  coincide after time  $R\left(\frac{\varepsilon}{4A^2}, M_{\text{rf}}\right) + S\left(\frac{\varepsilon}{4A^2}, M_{\text{rf}}\right)$ , that is,

$$\mathbb{P}[M_{\text{rf}}^T H^{\text{top}} = M_{\text{rf}}^T H^{\text{btm}}] \geq 1 - \varepsilon, \quad \text{if } T \geq R\left(\frac{\varepsilon}{4A^2}; M_{\text{rf}}\right) + S\left(\frac{\varepsilon}{4A^2}; M_{\text{rf}}\right). \quad (4.7)$$

Indeed, given Equation (4.7), it follows since  $H^{\text{btm}} \leq F \leq H^{\text{top}}$  for each  $F \in \mathcal{Z}(h)$  that with probability at least  $1 - \varepsilon$  the  $M_{\text{rf}}^T F$  all, over every  $F \in \mathcal{Z}(h)$ , coincide for  $T \geq R\left(\frac{\varepsilon}{4A^2}, M_{\text{rf}}\right) + S\left(\frac{\varepsilon}{4A^2}, M_{\text{rf}}\right)$ . In particular, sampling  $F$  under the stationary measure  $\rho$  for  $M_{\text{rf}}$ , we deduce for any  $H \in \mathcal{Z}(h)$  that one can couple  $M_{\text{rf}}^T H$  to coincide with a height function sampled under  $\rho$ , with probability  $1 - \varepsilon$ ; hence,  $t_{\text{mix}}(\varepsilon; M_{\text{rf}}) \leq R\left(\frac{\varepsilon}{4A^2}, M_{\text{rf}}\right) + S\left(\frac{\varepsilon}{4A^2}, M_{\text{rf}}\right)$ , confirming the lemma.

It remains to verify Equation (4.7). Since  $T \geq R\left(\frac{\varepsilon}{4A^2}; M_{\text{rf}}\right)$ , we have by Equation (4.4) that it is possible to couple  $M_{\text{rf}}^T H^{\text{top}}$  with a height function  $F$  sampled under the stationary measure  $\rho$  of  $M_{\text{rf}}$  such that  $M_{\text{rf}}^T H^{\text{top}} = F$  with probability at least  $1 - \frac{\varepsilon}{4A^2}$ . Moreover, since  $M_{\text{rf}}^T H^{\text{top}}(u) = h(u) = F(u)$  for each  $u \in \partial R$  and since  $\text{diam } R \leq A$ , it follows (as  $H$  is 1-Lipschitz) that  $|M_{\text{rf}}^T H^{\text{top}}(v) - F(v)| \leq 2A$ . Combining these two statements, we deduce that  $\mathbb{E}[M_{\text{rf}}^T H^{\text{top}}(v)] \leq \mathbb{E}[F(v)] + \frac{\varepsilon}{2A}$ , for each  $v \in R$ . Similarly, we have  $\mathbb{E}[M_{\text{rf}}^T H^{\text{btm}}(v)] \leq \mathbb{E}[F(v)] - \frac{\varepsilon}{2A}$ .

Therefore,  $\mathbb{E}[M_{\text{rf}}^T H^{\text{top}}(v)] \leq \mathbb{E}[M_{\text{rf}}^T H^{\text{btm}}(v)] + \frac{\varepsilon}{A}$  for any  $v \in R$ . Together with the above grand coupling satisfying  $M_{\text{rf}}^T H^{\text{btm}} \leq M_{\text{rf}}^T H^{\text{top}}$ , the fact that any height function is integer-valued and a Markov inequality, we deduce that  $\mathbb{P}[M_{\text{rf}}^T H^{\text{top}}(v) \neq M_{\text{rf}}^T H^{\text{btm}}(v)] \leq \frac{\varepsilon}{A}$ , under this grand coupling. A union bound over all  $|R| \leq A$  vertices  $v \in R$  then yields Equation (4.7) and thus the lemma.  $\square$

Next, we have the following lemma that compares the mixing times of the flip and censored region-flip dynamics.

**Lemma 4.18.** *Adopting the notation of Proposition 4.6, and fixing a real number  $\varepsilon \in (0, \frac{1}{2}]$ , we have  $t_{\text{mix}}(8A^2\varepsilon; M_{\text{crf}}) \leq 8A^9(\log \varepsilon^{-1})^2 \cdot (t_{\text{mix}}(\varepsilon; M_{\text{fl}}) + 1)$ .*

*Proof.* We first bound the mixing time of  $M_{\text{crf}}$  in terms of that of  $M_{\text{wf}}$ . To that end, recall that the state  $H_t$  at time  $t \geq 1$  under  $M_{\text{wf}}$  is defined from  $H_{t-1}$  by performing a random flip at a vertex  $v \in R \setminus \partial R$  chosen with probability  $m(v) \cdot \mathfrak{M}^{-1}$ . Observe that we equivalently sample  $v$  by first selecting an index  $i \in [1, k]$  with probability  $p_i$  and then selecting  $v \in R_i \setminus \partial R_i$  uniformly at random. Recalling the random

sequence  $\mathcal{X} = (X_1, X_2, \dots)$  from Definition 4.15, this is in turn equivalent to sampling  $v \in \mathbb{R}_{X_t} \setminus \partial\mathbb{R}_{X_t}$  uniformly at random, where we have denoted  $\mathbb{R}_j = \mathbb{R}_i$  for  $i \in [1, k]$  the integer such that  $k$  divides  $j - i$ .

It follows that  $M_{\text{fl}}$  and  $M_{\text{crf}}$  can be coupled so that the former at time  $t$  coincides with the latter at time  $(X_t - 1)A^5 \leq ktA^5$ , where in the last equality we used the fact that  $X_t \leq kt$  (as  $X_t - X_{t-1} \leq k$ ). Hence,

$$t_{\text{mix}}(8A^2\varepsilon; M_{\text{crf}}) \leq kA^5 t_{\text{mix}}(8A^2\varepsilon; M_{\text{wf}}) \leq A^6 t_{\text{mix}}(8A^2\varepsilon; M_{\text{wf}}). \tag{4.8}$$

Moreover, we have

$$\begin{aligned} t_{\text{mix}}(8A^2\varepsilon; M_{\text{wf}}) &\leq R(2\varepsilon; M_{\text{wf}}) + S(2\varepsilon; M_{\text{wf}}) \leq 2t_{\text{mix}}(2\varepsilon; M_{\text{cwf}}) \\ &\leq 8A^3(\log \varepsilon^{-1})^2 \cdot (t_{\text{mix}}(\varepsilon; M_{\text{fl}}) + 1), \end{aligned}$$

where in the first inequality we applied Lemma 4.17, in the second we applied Proposition 4.16 and in the third we applied Lemma 4.14. Combining this with Equation (4.8) yields the lemma.  $\square$

Given the above, we can quickly establish Lemma 4.10 and Lemma 4.11.

*Proof of Lemma 4.10.* By Lemma 4.17, Proposition 4.16, and Lemma 4.18, we have for sufficiently large  $A$  that

$$\begin{aligned} t_{\text{mix}}(e^{-2A}; M_{\text{rf}}) &\leq R\left(\frac{e^{-2A}}{4A^2}, M_{\text{rf}}\right) + S\left(\frac{e^{-2A}}{4A^2}, M_{\text{rf}}\right) \\ &\leq R\left(\frac{e^{-2A}}{4A^2}, M_{\text{crf}}\right) + S\left(\frac{e^{-2A}}{4A^2}, M_{\text{crf}}\right) \\ &\leq 2t_{\text{mix}}\left(\frac{e^{-2A}}{4A^2}, M_{\text{crf}}\right) \leq 16A^9(3A)^2 \cdot \left(t_{\text{mix}}\left(\frac{e^{-2A}}{32A^4}; M_{\text{fl}}\right) + 1\right), \end{aligned}$$

which yields the lemma.  $\square$

*Proof of Lemma 4.11.* First, observe that for sufficiently large  $A$  we have  $t_{\text{mix}}\left(\frac{e^{-2A}}{4A^2}; M_{\text{fl}}\right) \leq \frac{A^5}{200}$ , by Proposition 4.9; thus, Lemma 4.10 implies that  $t_{\text{mix}}(e^{-2A}; M_{\text{rf}}) \leq A^{16}$ . So, to establish the lemma it suffices to couple the dynamics  $M_{\text{alt}}$  at time  $t$  to coincide with  $M_{\text{rf}}$  at time  $A^5t$  for each  $t \in [0, A^{11}]$ , away from an event of probability at most  $A^{11}e^{-2A} \leq e^{-A} - e^{-2A}$ .

To that end, let  $H_t$  denote the state after  $t \geq 0$  steps of the dynamics  $M_{\text{rf}}$ . Furthermore, for any integer  $s \geq 0$  and  $i \in [1, k]$  such that  $k$  divides  $s - i + 1$ , set  $H'_s = H_{sA^5}$  and  $h'_{s+1} = H_{sA^5} |_{\partial\mathbb{R}_i}$ . Then, Definition 4.8 implies  $H'_{s+1} \in \mathcal{G}(h'_{s+1})$  is obtained from  $H'_s \in \mathcal{G}(h'_s)$  from applying the flip dynamics  $M_{\text{fl}}$  on  $\mathbb{R}_i$  for time  $A^5$ . Hence, since  $t_{\text{mix}}(e^{-2A}; M_{\text{fl}}) \leq t_{\text{mix}}\left(\frac{e^{-2A}}{4A^2}; M_{\text{fl}}\right) \leq A^5$ , we may couple  $H'_s |_{\mathbb{R}_i}$  with a uniformly random element of  $\mathcal{G}(h'_s)$ , away from an event of probability at most  $e^{-2A}$ .

It follows that the sequence  $\{H'_0, H'_1, \dots, H'_s\}$  can be coupled with  $s$  steps of the alternating dynamics  $M_{\text{alt}}$  with initial data  $H_0$ , away from an event of probability at most  $se^{-2A}$ . Taking  $s = t_{\text{mix}}(e^{-2A}; M_{\text{fl}}) \leq A^{11}$  and recalling that  $H'_s = H_{sA^5}$ , we deduce the lemma.  $\square$

### 5. Tilted height functions and comparison estimates

In this section, we discuss how height functions can be ‘tilted’ in a specific way. Section 5.1 introduces the notion of a tilted height function and states results comparing tilted height functions to random tiling height functions; we prove the latter comparison results in Section 5.2 and Section 5.3.

#### 5.1. Tilted height functions

In this section, we describe a way of ‘tilting’ the height function of a random tiling that will enable us to apply Theorem 4.3 in an effective way. Throughout this section, we recall the notation from

Definition 2.2 and more generally from Section 2.3 and Section 3.1; this includes the polygonal domain  $\mathfrak{P}$  and associated boundary height function  $h : \partial\mathfrak{P} \rightarrow \mathbb{R}$ ; the liquid region  $\mathfrak{L}(\mathfrak{P})$  and arctic curve  $\mathfrak{A}(\mathfrak{P})$  from Equations (2.5) and (2.6); the associated complex slope  $f_t(x) = f(x, t)$  from Equation (3.1); the polygonal domain  $P = n\mathfrak{P} \cap \mathbb{T}^2$  and its associated boundary height function  $h : P \rightarrow \mathbb{Z}$ . For any  $(x, s) \in \mathfrak{L}(\mathfrak{P})$ , we also set

$$\Omega_s(x) = \frac{1}{\pi} \operatorname{Im} \frac{f_s(x)}{f_s(x) + 1} = \frac{1}{\pi} \frac{\operatorname{Im} f_s(x)}{|f_s(x) + 1|^2}; \quad \Upsilon_s(x) = \frac{f_s(x)}{(f_s(x) + 1)^2}, \tag{5.1}$$

and further set  $\Omega_s(x) = 0$  when  $(x, s) \notin \overline{\mathfrak{L}(\mathfrak{P})}$ . The parameters  $\Omega_s(x)$  and  $\Upsilon_s(x)$  will quantitatively govern how height functions change under ‘tilts’, to be described further in Proposition 5.4 below.

**Remark 5.1.** Observe that  $\Omega_s(x) \leq 0$  since  $f_s(x) \in \mathbb{H}^- \cup \mathbb{R}$ . Moreover, if  $(x, s) \in \mathfrak{A}(\mathfrak{P})$ , then  $f_s(x) \in \mathbb{R}$ , so  $\Upsilon_s(x) \in \mathbb{R}$ . Then  $\Upsilon_s(x) > 0$  holds if  $f_s(x) > 0$ , and  $\Upsilon_s(x) < 0$  holds if  $f_s(x) < 0$ . The former implies  $\arg^* f_s(x) = 0$ , which by Equation (3.1) implies  $\partial_x H^*(x, s) = 0$ . Similarly, the latter implies  $\partial_x H^*(x, s) = 1$ .

Throughout this section, we fix real numbers  $t_1 < t_2$  with  $t = t_2 - t_1$ ; linear functions  $\mathfrak{a}, \mathfrak{b} : [t_1, t_2] \rightarrow \mathbb{R}$ , with slopes in  $\{0, 1\}$ ; and the domain  $\mathfrak{D} = \mathfrak{D}(\mathfrak{a}, \mathfrak{b}; t_1, t_2)$  from Equation (4.1) with boundaries (4.2), as in Section 4.1. We view them all as independent from  $n$ . We will impose the following condition on  $\mathfrak{D}$  concerning its relation to  $\mathfrak{P}$  (see Figure 10 for possible depictions).

**Assumption 5.2.** Adopt the notation of Theorem 2.10, and suppose  $\mathfrak{D} \subseteq \mathfrak{P}$ , with  $D = n\mathfrak{D} \subseteq \mathbb{T}$ . Assume that the second, third and fourth constraints listed in Assumption 4.1 hold for  $\mathfrak{D}$  (with respect to  $H^*$ ). Further, suppose that either  $\partial_{\text{ea}}(\mathfrak{D})$  is disjoint with  $\overline{\mathfrak{L}(\mathfrak{P})}$  or that  $\partial_{\text{ea}}(\mathfrak{D}) \subset \partial\mathfrak{P}$ ; similarly, suppose that either  $\partial_{\text{we}}(\mathfrak{D})$  is disjoint with  $\overline{\mathfrak{L}(\mathfrak{P})}$  or that  $\partial_{\text{we}}(\mathfrak{D}) \subset \partial\mathfrak{P}$ . We denote the liquid region inside  $\mathfrak{D}$  as  $\mathfrak{L} = \mathfrak{L}(\mathfrak{P}) \cap \mathfrak{D}$ . Additionally, fix a real number  $s \in [t_1, t_2]$ , and assume that no cusp or tangency location of  $\mathfrak{A}(\mathfrak{P})$  in  $\overline{\mathfrak{D}}$  is of the form  $(x, y)$ , with  $x \in \mathbb{R}$  and  $y \in \{t_1, s, t_2\}$ .

**Remark 5.3.** Under Assumption 5.2,  $\Upsilon_t(x)$  is uniformly bounded away from 0 and  $\infty$ , for any  $(x, t) \in \mathfrak{A}(\mathfrak{P})$  with  $t \in \{t_1, s, t_2\}$ . This holds since  $(f_t(x) + 1)/f_t(x)$  is the slope of the tangent line to  $\mathfrak{A}(\mathfrak{P})$  at  $(x, t)$  (by Lemma 3.7), and since no tangency location of  $\mathfrak{A}(\mathfrak{P})$  has  $y$ -coordinate in  $\{t_1, s, t_2\}$ . Moreover, if  $u = (x, t) \in \mathfrak{L}(\mathfrak{P})$  satisfies  $t \in \{t_1, s, t_2\}$ , and we denote  $d = \operatorname{dist}(u, \mathfrak{A}(\mathfrak{P}))$ , then there exists a constant  $c = c(\mathfrak{P}, \mathfrak{D}) > 0$  such that  $cd^{1/2} \leq -\Omega_t(x) \leq c^{-1}d^{1/2}$ . This follows from the square root decay of  $\operatorname{Im} f_t(x)$  around smooth points of  $\mathfrak{A}(\mathfrak{P})$  (see Lemma A.1 below) and the fact that no cusp or tangency location of  $\mathfrak{A}(\mathfrak{P})$  in  $\overline{\mathfrak{D}}$  has  $y$ -coordinate in  $\{t_1, s, t_2\}$ .

Next, we state the following proposition, to be established in Section 7 below, indicating how a height function can be ‘tilted’. Here, the parameters  $\Omega_s(x)$  and  $\Upsilon_s(x)$  from Equation (5.1) will govern how the height function and edge of the liquid region change under such a tilt, respectively. In what follows, all implicit constants (including notions of being ‘sufficiently small’) will only depend on the parameters  $\mathfrak{P}, \mathfrak{D}$  and  $\varepsilon$  in the statement of the proposition. We also recall maximizers of  $\mathcal{E}$  from Equation (2.4), and the liquid regions  $\mathfrak{L}(\mathfrak{D}; g), \mathfrak{L}_{\text{no}}(\mathfrak{D}; g)$ , and  $\mathfrak{L}_{\text{so}}(\mathfrak{D}; g)$  for any function  $g : \partial\mathfrak{D} \rightarrow \mathbb{R}$  from Equations (2.5) and (2.6) and Section 4.1.

**Proposition 5.4.** Fix  $\varepsilon > 0$ , and adopt Assumption 5.2. Also, let  $\xi_1, \xi_2 \in \mathbb{R}$  be real numbers of the same sign (that is,  $\xi_1 \xi_2 \geq 0$ ), with  $|\xi_1|, |\xi_2|$  sufficiently small. Further, assume that  $|\xi_2 - \xi_1| \geq \varepsilon \max\{|\xi_1|, |\xi_2|\}$ , and define the function  $\omega : [t_1, t_2] \rightarrow \mathbb{R}$  interpolating  $\xi_1$  and  $\xi_2$ :

$$\omega(t) = \xi_2 \frac{y - t_1}{t_2 - t_1} + \xi_1 \frac{t_2 - t}{t_2 - t_1}. \tag{5.2}$$

Then there exists a function  $\widehat{h} : \partial\mathfrak{D} \rightarrow \mathbb{R}$  admitting an admissible extension to  $\mathbb{R}^2$  such that the maximizer  $\widehat{H}^* = \operatorname{argmax}_{F \in \operatorname{Adm}(\mathfrak{D}, \widehat{h})} \mathcal{E}(F)$  of  $\mathcal{E}$  satisfies the following properties. In the below, we fix one of three real numbers  $t \in \{t_1, s, t_2\}$ , and we abbreviate  $\widehat{\mathfrak{L}} = \mathfrak{L}(\mathfrak{D}; \widehat{h}) \cup \mathfrak{L}_{\text{no}}(\mathfrak{D}; \widehat{h}) \cup \mathfrak{L}_{\text{so}}(\mathfrak{D}; \widehat{h})$ .

(1) For any  $(x, t) \in \mathfrak{L} \cap \widehat{\mathfrak{L}}$ , we have

$$|\widehat{H}^*(x, t) - H^*(x, t) - \omega(t)\Omega_t(x)| = \mathcal{O}(|\xi_1|^{3/2} + |\xi_2|^{3/2}). \tag{5.3}$$

(2) Suppose  $\{x : (x, t) \in \mathfrak{L}\}$  is a union of  $k \geq 1$  disjoint open intervals  $(x_1, x'_1) \cup (x_2, x'_2) \cup \dots \cup (x_k, x'_k)$ . Then,  $\{x : (x, t) \in \widehat{\mathfrak{L}}\}$  is also a union of  $k$  disjoint open intervals  $(\widehat{x}_1, \widehat{x}'_1) \cup (\widehat{x}_2, \widehat{x}'_2) \cup \dots \cup (\widehat{x}_k, \widehat{x}'_k)$ . Moreover, for any index  $1 \leq j \leq k$ , we have

$$\widehat{x}_j - x_j = \omega(t)\Upsilon_t(x_j) + \mathcal{O}(\xi_1^2 + \xi_2^2); \quad \widehat{x}'_j - x'_j = \omega(t)\Upsilon_t(x'_j) + \mathcal{O}(\xi_1^2 + \xi_2^2), \tag{5.4}$$

and  $\widehat{H}^*(x, t) = H^*(x, t)$  whenever  $(x, t) \in \overline{\mathfrak{D}}$  and  $(x, t) \notin \mathfrak{L} \cup \widehat{\mathfrak{L}}$ .

(3) Under the notation of Equation (5.4), fix any endpoint  $x \in \bigcup_{i=1}^k \{x_i, x'_i\}$ ; set  $\widehat{x} = \widehat{x}_i$  or  $\widehat{x} = \widehat{x}'_i$  if  $x = x_i$  or  $x = x'_i$ , respectively. For any real number  $\Delta$  with  $|\Delta|$  sufficiently small, we have

$$\widehat{H}^*(\widehat{x} + \Delta) - \widehat{H}^*(\widehat{x}) = H^*(x + \Delta) - H^*(x) + \mathcal{O}((|\xi_1| + |\xi_2|)|\Delta|^{3/2} + \Delta^2). \tag{5.5}$$

(4) The domain  $\mathfrak{D}$  satisfies five assumptions listed in Assumption 4.1, with respect to  $\widehat{H}^*$ .

Let us briefly comment on Proposition 5.4. We view  $\omega(t)$  as quantifying how ‘tilted’  $\widehat{H}^*$  is with respect to  $H^*$  along a fixed horizontal slice  $t \in \{t_1, s, t_2\}$ . In particular,  $\xi_1$  and  $\xi_2$  parameterize this tiltedness along the north and south boundaries of  $\mathfrak{D}$ , respectively, and Equation (5.2) implies that this tiltedness linearly interpolates between these two boundaries. The first part of Proposition 5.4 quantifies how the height function in the liquid region tilts in terms of  $\Omega_s$ , and the second part quantifies how the edges of the liquid region tilt in terms of  $\Upsilon_s$ . The tilted function  $\widehat{H}^*$  will eventually be obtained by perturbing solutions of the complex Burgers equation (3.2), and these functions  $\Omega_s$  and  $\Upsilon_s$  can be viewed as derivatives arising from this procedure; see Lemma 7.2 and Lemma 7.3 below. The third part of Proposition 5.4 states that the gradient around the edges does not change too much under the tilting. The fourth part verifies properties of  $\widehat{H}^*$  that will enable us to later apply Theorem 4.3.

**Remark 5.5.** We will use notation such as  $H^*$  and  $\widehat{H}^*$  for deterministic height functions (which will be maximizers of  $\mathcal{E}$ ), and notation such as  $H$  and  $\widehat{H}$  for random height functions (which are associated with random tilings).

In view of Equations (5.3) and (5.4), we introduce the following more precise notion of tiltedness. It will be useful to define it through estimates, instead of the close approximations provided by Proposition 5.4.

**Definition 5.6.** Suppose  $\mathfrak{D} \subseteq \mathfrak{P}$ ; fix real numbers  $\xi, \mu, \zeta \geq 0$ ; and fix an admissible function  $H \in \operatorname{Adm}(\mathfrak{D})$ . For any  $(x, s) \in \overline{\mathfrak{D}}$ , we say that  $H$  is  $(\xi; \mu)$ -tilted with respect to  $H^*$  at  $(x, s)$  if (recalling that  $\Omega_s(x) \leq 0$  by Remark 5.1) we have

$$|H(x, s) - H^*(x, s)| \leq \mu - \xi\Omega_s(x).$$

We also say that the edge of  $H$  is  $\zeta$ -tilted with respect to  $H^*$  at level  $s$  if the following two conditions hold. For  $u = (x, s) \in \overline{\mathfrak{D}}$ , we let  $(x_0, s) \in \mathfrak{A}(\mathfrak{P})$  denote any point on  $\mathfrak{A}(\mathfrak{P})$  with  $|x - x_0|$  minimal so that  $\partial_x H^*(x_0, s) \in \{0, 1\}$  (that is,  $H^*$  is frozen at  $(x_0, s)$ ).

- (1) Fix any  $u = (x, s) \notin \mathfrak{L}$  with  $|x_0 - x| \geq \zeta |\Upsilon_s(x_0)|$ . We have  $H(u) = H^*(u)$ .
- (2) Fix any  $u = (x, s) \in \overline{\mathfrak{D}}$  with<sup>11</sup>  $|x_0 - x| \leq \zeta^{8/9}$ . If  $\partial_x H^*(x_0, s) = 0$  (so  $\Upsilon_s(x_0) > 0$  by Remark 5.1), then

$$H^*(x - \zeta \Upsilon_s(x_0), s) \leq H(x, s) \leq H^*(x + \zeta \Upsilon_s(x_0), s).$$

If instead  $\partial_x H^*(x_0, s) = 1$  (so  $\Upsilon_s(x_0) < 0$  by Remark 5.1), then

$$H^*(x - \zeta \Upsilon_s(x_0), s) + \zeta \Upsilon_s(x_0) \leq H(x, s) \leq H^*(x + \zeta \Upsilon_s(x_0), s) - \zeta \Upsilon_s(x_0).$$

We sometimes refer to the former notion described in Definition 5.6 as a ‘bulk’ form of tiltedness, and the latter as an ‘edge’ form. The bulk form imposes a bound on  $|H - H^*|$  of a similar form to Equation (5.4) in Proposition 5.4. The edge form constitutes two parts. The first is an estimate for the edge points of  $H$ , of a similar form to Equation (5.4); the second bounds  $|H - H^*|$  near these edge points (this is eventually related to (5.5)). We will often view the tiltedness parameters  $\xi, \mu, \zeta$  as small (decaying as a negative power of  $n$ ), even though this was not needed to formulate Definition 5.6.

To proceed, for any real number  $\delta > 0$ , we require the ‘reduced’ version of the liquid region inside  $\mathfrak{D}$

$$\mathfrak{L}^\delta = \{u \in \mathfrak{L} : \text{dist}(u, \mathfrak{A}(\mathfrak{P})) > n^{\delta-2/3}\}. \tag{5.6}$$

Given this notation, we will state two results concerning the tiltedness of a random height function on  $\mathfrak{D}$  along a middle horizontal slice, given its tiltedness on the north and south boundaries of  $\mathfrak{D}$ . Let us introduce the following notation and assumption to set this context.

**Assumption 5.7.** Adopt Assumption 5.2; fix  $\varepsilon, \varsigma, \delta \in (0, 1/50)$ , and suppose that  $\mathfrak{s} \in [t_1 + \varepsilon t, t_2 - \varepsilon t]$ . Let  $\tilde{h} : \partial\mathfrak{D} \rightarrow \mathbb{Z}$  denote a boundary height function that is constant along the east and west boundaries of  $\mathfrak{D}$ ; if  $\partial_{\text{no}}(\mathfrak{D})$  is packed with respect to  $h$ , then we further assume that  $\tilde{h} = h$  along  $\partial_{\text{no}}(\mathfrak{D})$ . Let  $\tilde{H} : \mathfrak{D} \rightarrow \mathbb{Z}$  denote a uniformly random element of  $\mathcal{G}(\tilde{h})$ , and define  $\tilde{H} \in \text{Adm}(\mathfrak{D})$  by setting  $\tilde{H}(u) = n^{-1} \tilde{H}(nu)$  for each  $u \in \overline{\mathfrak{D}}$ . Further, let  $\xi_1, \xi_2, \zeta_1, \zeta_2, \mu \in [0, n^{\delta-2/3}]$  be real numbers satisfying the inequalities  $\min\{\xi_1, \xi_2, |\xi_1 - \xi_2|\} \geq \varsigma(\xi_1 + \xi_2)$  and  $\min\{\zeta_1, \zeta_2, |\zeta_1 - \zeta_2|\} \geq \varsigma(\zeta_1 + \zeta_2)$ . Assume the following two statements hold for each  $j \in \{1, 2\}$ .

- (1) At each  $(x, t_j) \in \mathfrak{L}^\delta$ , we have that  $\tilde{H}$  is  $(\xi_j; \mu)$ -tilted with respect to  $H^*$ .
- (2) The edge of  $\tilde{H}$  is  $\zeta_j$ -tilted with respect to  $H^*$  at level  $t_j$ .

Observe that the latter two points in the above assumption are more constraints on the deterministic boundary data  $\tilde{h}$  (equivalently,  $h$ ) than on the random height function  $\tilde{H}$ . Indeed, the restriction of  $\tilde{H}$  to levels  $t_1$  and  $t_2$  is fully determined by  $\tilde{h}$  since these levels constitute the south and north boundaries of  $\mathfrak{D}$ , respectively.

Now, we state the following two results to be established in Section 5.2 and Section 5.3 below. Qualitatively, they both state that the tiltedness of  $\tilde{H}$  along the intermediate horizontal slice  $t = \mathfrak{s}$  lies between its tiltedness along the top and bottom boundaries of  $\mathfrak{D}$ . The two statements differ in that Proposition 5.8 addresses both the bulk and edge forms of tiltedness but imposes that its tiltedness parameters  $\zeta_1, \zeta_2 \gg n^{-2/3}$ ; Proposition 5.9 only addresses the bulk form of tiltedness but allows for smaller tiltedness parameters  $\xi_1, \xi_2 \gg n^{-1}$ .

**Proposition 5.8.** *Adopt Assumption 5.7, and set*

$$\zeta = \max \left\{ \frac{\varepsilon}{2} \zeta_1 + \left(1 - \frac{\varepsilon}{2}\right) \zeta_2, \left(1 - \frac{\varepsilon}{2}\right) \zeta_1 + \frac{\varepsilon}{2} \zeta_2 \right\}. \tag{5.7}$$

*Assume that  $\mu = 0$ , and that  $\xi_j \leq \zeta_j \leq n^{\delta/2-2/3}$  and  $\zeta_j \geq n^{\delta/100-2/3}$  for each  $j \in \{1, 2\}$ . Then, the following two statements hold with overwhelming probability.*

<sup>11</sup>The power  $\zeta^{8/9}$  is taken for convenience and should not be viewed as optimal in any way.

- (1) At each  $(x, \mathfrak{s}) \in \mathfrak{Q}_-^\delta$ , we have that  $\tilde{H}$  is  $(\zeta; 0)$ -tilted with respect to  $H^*$ .
- (2) The edge of  $\tilde{H}$  is  $\zeta$ -tilted with respect to  $H^*$  at level  $\mathfrak{s}$ .

**Proposition 5.9.** *Adopt Assumption 5.7, and set*

$$\xi = \max \left\{ \frac{\varepsilon}{2}\xi_1 + \left(1 - \frac{\varepsilon}{2}\right)\xi_2, \left(1 - \frac{\varepsilon}{2}\right)\xi_1 + \frac{\varepsilon}{2}\xi_2 \right\}.$$

Assume that  $\xi_j \leq n^{-2/3}$  and  $\zeta_j \leq n^{\delta/50-2/3}$  for each  $j \in \{1, 2\}$ . Further, fix  $U_0 = (X_0, \mathfrak{s}) \in \mathfrak{Q}_-^\delta$ , and assume that  $\xi_j \geq n^{\delta/4-1} \text{dist}(U_0, \mathfrak{A}(\mathfrak{P}))^{-1/2}$  for each  $j \in \{1, 2\}$ . Then,  $\tilde{H}$  is  $(\xi; \mu)$ -tilted with respect to  $H^*$  at  $U_0$ , with overwhelming probability.

**Remark 5.10.** By rotating  $\mathfrak{D}$ , Proposition 5.8 and Proposition 5.9 also hold if in Assumption 5.2 the constraints on  $\partial_{\text{no}}(\mathfrak{D})$  are instead imposed on  $\partial_{\text{so}}(\mathfrak{D})$ .

### 5.2. Proof of Proposition 5.8

In this section, we establish Proposition 5.8. Throughout this section, we adopt the notation of that proposition. For any  $u = (x, \mathfrak{s}) \in \mathfrak{D}$ , with  $(x_0, \mathfrak{s}) \in \mathfrak{A}(\mathfrak{P})$  denoting a point with  $|x - x_0|$  minimal, it suffices to show with overwhelming probability that

$$\begin{aligned} H^*(u) + \zeta\Omega_{\mathfrak{s}}(x) \leq \tilde{H}(u) \leq H^*(u) - \zeta\Omega_{\mathfrak{s}}(x), & \quad \text{if } u \in \mathfrak{Q}_-^\delta; \\ \tilde{H}(u) = H^*(u), & \quad \text{if } u \notin \mathfrak{Q} \text{ and } |x - x_0| \geq \zeta|\Upsilon_{\mathfrak{s}}(x_0)|, \end{aligned} \tag{5.8}$$

and, if  $|x - x_0| \leq \zeta^{\delta/9}$ , that

$$\begin{aligned} H^*(x - \zeta\Upsilon_{\mathfrak{s}}(x_0), \mathfrak{s}) \leq \tilde{H}(u) \leq H^*(x + \zeta\Upsilon_{\mathfrak{s}}(x_0), \mathfrak{s}), & \quad \text{if } \partial_x H^*(x_0, \mathfrak{s}) = 0; \\ H^*(x - \zeta\Upsilon_{\mathfrak{s}}(x_0), \mathfrak{s}) + \zeta\Upsilon_{\mathfrak{s}}(x_0) \leq \tilde{H}(u) \leq H^*(x + \zeta\Upsilon_{\mathfrak{s}}(x_0), \mathfrak{s}) - \zeta\Upsilon_{\mathfrak{s}}(x_0), & \quad \text{if } \partial_x H^*(x_0, \mathfrak{s}) = 1. \end{aligned} \tag{5.9}$$

We only establish the upper bounds in Equations (5.8) and (5.9), as the proofs of the lower bounds are entirely analogous. In what follows, we will assume that  $\zeta_1 \geq \zeta_2$ , as the proof in the complementary case  $\zeta_1 < \zeta_2$  is entirely analogous. Let us also fix a small real number  $\theta \in (0, 1/50)$  (it suffices to take  $\theta = 1/100$ ), and we define slightly larger versions of  $\zeta_1, \zeta_2$  by

$$\zeta'_1 = (1 + \theta\varepsilon)\zeta_1; \quad \zeta'_2 = (1 + \theta\varepsilon)\zeta_2. \tag{5.10}$$

Throughout, we further set  $\tilde{h} = \tilde{H}|_{\partial\mathfrak{D}}$  from Assumption 5.7.

Before continuing, let us briefly outline how we will proceed. First, we use Proposition 5.4 to obtain a  $(-\zeta'_1, -\zeta'_2)$ -tilted boundary function  $\hat{h} : \partial\mathfrak{D} \rightarrow \mathbb{R}$ , with associated maximizer  $\hat{H}^* \in \text{Adm}(\mathfrak{D}; \hat{h})$  of  $\mathcal{E}$ ; properties of this tilting from Proposition 5.4 will imply  $\hat{h} \geq \tilde{h}$ . Next, we consider a tiling of  $\mathfrak{D}$  whose (scaled) boundary height function is given by  $\hat{h}$ . Applying Theorem 4.3, we will deduce that the (scaled) height function  $\hat{H}$  associated with this tiling is close to  $\hat{H}^*$ . Together with the bound  $\hat{h} \geq \tilde{h}$  and the monotonicity result Lemma 3.15, this will essentially imply that  $\hat{H}^* \approx \hat{H} \geq \tilde{H}$ . This, with the fact (implied by Proposition 5.4) that  $\hat{H}^*$  is approximately  $\zeta$ -tilted with respect to  $H^*$ , will yield the upper bounds in Equations (5.8) and (5.9).

Now, let us implement this procedure in detail. Apply Proposition 5.4 with the  $(\xi_1, \xi_2)$  there equal to  $(-\zeta'_1, -\zeta'_2)$  here. This yields a function  $\hat{h} : \partial\mathfrak{D} \rightarrow \mathbb{R}$  and its associated maximizer  $\hat{H}^* \in \text{Adm}(\mathfrak{D}; \hat{h})$  of  $\mathcal{E}$  satisfying the four properties listed there. Define its discretization  $\hat{h} : \partial\mathfrak{D} \rightarrow \mathbb{Z}$  of  $\hat{h}$  by setting  $\hat{h}(nv) = \lfloor n\hat{h}(v) \rfloor$ , for each  $v \in \partial\mathfrak{D}$ .

**Lemma 5.11.** *For each  $v \in \partial\mathfrak{D}$ , we have that  $\tilde{h}(v) \leq \hat{h}(v)$ .*



*Proof.* Let us first verify the lemma when  $v = n^{-1}v \in \partial_{\text{ea}}(\mathfrak{D}) \cup \partial_{\text{we}}(\mathfrak{D})$ . In this case, Assumption 5.2 implies that the four corners  $\{(\mathbf{a}(t_1), t_1), (\mathbf{b}(t_1), t_1), (\mathbf{a}(t_2), t_2), (\mathbf{b}(t_2), t_2)\}$  of  $\mathfrak{D}$  are outside of  $\bar{\mathfrak{Q}}$ ; they are thus bounded away from  $\bar{\mathfrak{Q}}$  (recall we view  $\mathfrak{D}$  and  $\mathfrak{P}$  as fixed with respect to  $n$ ). Since  $\zeta_1, \zeta_2 \leq n^{\delta-2/3}$ , the edge of  $\tilde{H}$  is  $n^{\delta-2/3} \ll 1$  tilted with respect to  $H^*$  at levels  $t_1$  and  $t_2$ . Hence,  $\tilde{H}(v) = H^*(v)$  at these four corners, so  $\tilde{h}(nv) = \tilde{H}(nv) = nH^*(v) = nh(v) = h(nv)$  there. The second part of Proposition 5.4, together with the fact that  $\zeta_j \Upsilon_{t_j}(x) + \mathcal{O}(\zeta_j^2) = \mathcal{O}(n^{\delta-2/3})$ , implies that the edge of  $\tilde{H}^*$  is also  $n^{\delta-2/3} \ll 1$  tilted with respect to  $H^*$ . So, similar reasoning gives  $\tilde{h}(v) = h(v)$  at these four corners, yielding  $\tilde{h}(nv) = h(nv) = \tilde{h}(nv)$  there. Since  $\tilde{h}$  is constant along the east and west boundaries of  $\mathfrak{D}$ , it follows that  $\tilde{h}(v) = h(v) = \tilde{h}(v)$  there.

We next verify  $\tilde{h}(v) \leq \hat{h}(v)$  when  $v = n^{-1}v \in \partial_{\text{no}}(\mathfrak{D}) \cup \partial_{\text{so}}(\mathfrak{D})$ . Set  $v = (x, t_j)$ , and let  $v_0 = (x_0, t_j) \in \partial\mathfrak{A}(\mathfrak{P})$  denote a point with  $|x - x_0|$  minimal.

First, suppose  $|x - x_0| \geq (\zeta'_j)^{8/9}$  and  $v \notin \bar{\mathfrak{Q}}$ . Then, by Remark 5.3 and the bound  $|\zeta_j| = \mathcal{O}(n^{\delta-2/3})$ , we have  $|x - x_0| \geq \zeta'_j |\Upsilon_{t_j}(x_0)|$  for sufficiently large  $n$ . Since the edges of  $\tilde{H}$  and  $\tilde{H}^*$  are  $\zeta'_j$ -tilted with respect to  $H^*$  at level  $t_j$  (as  $\zeta_j \leq \zeta'_j$ ), we have  $\tilde{h}(v) = h(v) = \hat{h}(v)$ , so  $\tilde{h}(v) = \hat{h}(v)$ .

Next, suppose that  $|x - x_0| \leq (\zeta'_j)^{8/9}$ . Then,  $v_0 = (x_0, t_j)$  is either a left or right endpoint of  $\mathfrak{A}(\mathfrak{P})$ , and  $\partial_x H^*(v_0) \in \{0, 1\}$ . We assume in what follows that  $v_0$  is a right endpoint of  $\mathfrak{A}(\mathfrak{P})$  and that  $\partial_x H^*(v_0) = 0$ , as the alternative cases are entirely analogous. Define  $\hat{x}_0 \in \mathbb{R}$  such that  $\hat{v}_0 = (\hat{x}_0, t_j)$  denotes an endpoint of  $\mathfrak{Q}_{\text{so}}(\mathfrak{D}; \hat{h})$  or  $\mathfrak{Q}_{\text{no}}(\mathfrak{D}; \hat{h})$  (depending on whether  $j = 1$  or  $j = 2$ , respectively) such that  $|\hat{x}_0 - x_0|$  is minimal. By Equation (5.4), we have  $\hat{x}_0 - x_0 + \zeta'_j \Upsilon_{t_j}(x_0) = \mathcal{O}(\zeta_1^2 + \zeta_2^2)$  (recall that the  $\xi_j$  there is  $-\zeta_j$  here). In particular, since  $\Upsilon_{t_j}(x_0)$  is positive (by Remark 5.1) and bounded away from 0 (by Remark 5.3), we have  $\hat{x}_0 \leq x_0$  and  $x_0 - \hat{x}_0 = \mathcal{O}(\zeta_1 + \zeta_2)$ .

If  $x \geq \hat{x}_0$ , then  $v = (x, t_j) \notin \bar{\mathfrak{Q}}$  (as  $(\hat{x}_0, t_j)$  must be a right endpoint of  $\bar{\mathfrak{Q}}$ ). Since  $x_0 \geq \hat{x}_0$  and  $\partial_x \tilde{H}^*(x', t_j) = \partial_x H^*(x_0, t_j) = 0$  for  $x' > \hat{x}_0$ , this implies  $\tilde{H}^*(x, t_j) = \tilde{H}^*(x_0, t_j) = H^*(x_0, t_j)$  (where the last equality follows from Equation (5.4) of Proposition 5.4, since  $(x_0, t_j) \notin \mathfrak{Q} \cup \bar{\mathfrak{Q}}$ ). Hence,  $\tilde{h}(v) = h(x_0, t_j)$ . Since the edge of  $\tilde{H}$  is  $\zeta_j$ -tilted with respect to  $H^*$  and  $\zeta_j = o(n^{1/2})$ , we also have  $\tilde{h}(v) \leq \tilde{h}(x+n^{-1/2}, t_j) = H^*(x+n^{-1/2}, t_j) = H^*(x_0, t_j) = h(x_0, t_j)$ . Thus  $\tilde{h}(v) \leq h(v) = \hat{h}(v)$ , meaning  $\hat{h}(v) \geq \tilde{h}(v)$  if  $x \geq \hat{x}_0$ .

If instead  $x < \hat{x}_0$ , then

$$\begin{aligned} \hat{H}^*(x, t_j) &\geq \hat{H}^*(\hat{x}_0, t_j) + H^*(x + x_0 - \hat{x}_0, t_j) - H^*(x_0, t_j) + \mathcal{O}(\zeta_1^{16/9}) \\ &= H^*(x + x_0 - \hat{x}_0, t_j) + \mathcal{O}(\zeta_1^{16/9}) \geq H^*(x + \zeta'_j \Upsilon_{t_j}(x_0), t_j) + \mathcal{O}(\zeta_1^{16/9}). \end{aligned} \tag{5.11}$$

Here, the first statement follows from Equation (5.5) and the fact that  $|x - \hat{x}_0| = \mathcal{O}(|x - x_0| + |x_0 - \hat{x}_0|) = \mathcal{O}(\zeta_1^{8/9})$ ; the second from the fact that  $\hat{H}^*(\hat{x}_0, t_j) = \hat{H}^*(x_0, t_j) = H^*(x_0, t_j)$ , which holds by the equality  $\partial_x \hat{H}^*(\hat{x}_0, t_j) = \partial_x H^*(x_0, t_j) = 0$  (as  $x_0 \geq \hat{x}_0$ ) and the second part of Proposition 5.4; and the third from the facts that  $H^*$  is 1-Lipschitz and that  $\hat{x}_0 - x_0 + \zeta'_j \Upsilon_{t_j}(x_0) = \mathcal{O}(\zeta_1^2)$  by Equation (5.4).

Next, observe that  $(x, t_j) \in \mathfrak{Q} \cap \bar{\mathfrak{Q}}$  since  $x < \hat{x}_0 \leq x_0$  and  $|x - \hat{x}_0| = \mathcal{O}(\zeta_1^{8/9})$ . By Remark A.2 concerning the square root decay of  $\partial_x H^*$  around  $\mathfrak{A}(\mathfrak{P})$ , and the fact that  $\partial_x H^*(x_0, t) = 0$ , we therefore deduce the existence of a constant  $c = c(\mathfrak{P}, \mathfrak{D}, \theta) > 0$  such that

$$H^*(x + \zeta'_j \Upsilon_{t_j}(x_0), t_j) \geq H^*(x_0 + \zeta_j \Upsilon_{t_j}(x_0), t_j) + c\zeta_j^{3/2}, \tag{5.12}$$

where we have used the fact (5.10) that  $\zeta'_j - \zeta_j = \theta\zeta_j$  (as well as the fact that  $\Upsilon_{t_j}(x_0)$  is bounded away from 0, from Remark 5.3). Inserting Equation (5.12) into Equation (5.11) yields

$$\hat{H}^*(x, t_j) \geq H^*(x + \zeta_j \Upsilon_{t_j}(x_0), t_j) + c\zeta_j^{3/2} + \mathcal{O}(\zeta_1^{16/9}) \geq \tilde{H}(x, t_j) + c\zeta_j^{3/2} + \mathcal{O}(n^{-1}) \geq \tilde{H}(x, t_j),$$

where the second inequality holds since  $|\zeta_1| \leq n^{\delta-2/3}$ , and the third follows from the facts that the edge of  $\tilde{H}$  is  $\zeta_j$ -tilted and that  $\zeta_j \leq n^{\delta/100-2/3}$ . Hence,  $\widehat{h}(v) \geq \tilde{h}(v)$ , meaning  $\widehat{h}(v) \geq \tilde{h}(v)$ .

It thus remains to consider the case when  $|x - x_0| \geq (\zeta'_j)^{8/9}$  and  $v = (x, t_j) \in \mathfrak{L}$ . In particular,  $|x - x_0| \geq \zeta'_j \Upsilon_{t_j}(x_0) + \mathcal{O}(\zeta_j^2)$ , which implies by Equation (5.4) that  $v = (x, t_j) \in \mathfrak{L} \cap \widehat{\mathfrak{L}}$ . Thus, Equation (5.3) yields

$$\widehat{H}^*(v) \geq H^*(v) - \zeta'_j \Omega_{t_j}(x) + \mathcal{O}((\zeta'_1 + \zeta'_2)^{3/2}) \geq \tilde{H}(v) - \theta \zeta_j \Omega_{t_j}(x) + \mathcal{O}(\zeta_1^{3/2}),$$

where to deduce the last inequality we used the facts that  $\zeta'_j = (1 + \theta)\zeta_j$  and that  $\tilde{H}$  is  $(\zeta_j; 0)$ -tilted at  $v$  (since  $v \in \mathfrak{L}_-$ , as  $|x - x_0| \geq (\zeta'_j)^{8/9} \geq n^{\delta-2/3}$  and  $\xi_j \leq \zeta_j$ ). By Remark 5.3, there exists a constant  $c = c(\mathfrak{B}) > 0$  such that  $-\Omega_{t_j}(x) \geq c|x - x_0|^{1/2}$ . In particular, since  $|x - x_0| \geq (\zeta'_j)^{8/9} \geq n^\delta \zeta_1$  (as  $\zeta_j \leq n^{\delta/2-2/3}$  and  $\delta < 1/50$ ), we deduce that  $-\Omega_{t_j}(x) \geq n^{\delta/3} \zeta_1^{1/2}$ . So,

$$\widehat{H}^*(v) \geq \tilde{H}(v) + c\theta \zeta_j |x - x_0|^{1/2} + \mathcal{O}(\zeta_1^{3/2}) \geq \tilde{H}(u),$$

which once again implies that  $\widehat{h}(v) \geq \tilde{h}(v)$  so that  $\widehat{h}(v) \geq \tilde{h}(v)$ . This verifies the lemma in all cases.  $\square$

Given this lemma, we can establish Proposition 5.8.

*Proof of Proposition 5.8.* Let  $\widehat{H} : \mathcal{D} \rightarrow \mathbb{Z}$  denote a uniformly random element of  $\mathcal{G}(\widehat{h})$ . By Lemma 5.11 and Lemma 3.15 (alternatively, Remark 3.16), we may couple  $\widehat{H}$  with  $\tilde{H}$  such that  $\widehat{H}(u) \geq \tilde{H}(u)$ , for each  $u \in \mathcal{D}$ . In particular, denoting  $\widehat{H} : \mathcal{D} \rightarrow \mathbb{R}$  by  $\widehat{H}(u) = n^{-1}\widehat{H}(nu)$  for each  $u \in \mathcal{D}$ , we have  $\widehat{H}(u) \geq \tilde{H}(u)$ .

Apply Theorem 4.3, with the  $(h; H^*; H; \delta)$  there equal to  $(\widehat{h}; \widehat{H}^*; \widehat{H}; \delta/500)$  here. By the fourth part of Proposition 5.4, Assumption 4.1 applies. Moreover, Assumption 4.2 applies since  $\widehat{h}(nv) = \lfloor n\widehat{h}(v) \rfloor$  for each  $v \in \partial\mathcal{D}$ . Then, letting  $\mathcal{E}$  denote the event on which

$$\begin{aligned} |\widehat{H}(u) - \widehat{H}^*(u)| &< n^{\delta/500-1}, & \text{for each } u \in \overline{\mathcal{D}}; \\ \widehat{H}(u) &= \widehat{H}^*(u), & \text{if } u \notin \widehat{\mathfrak{L}} \text{ and } \text{dist}(u, \partial\widehat{\mathfrak{L}}) \geq n^{\delta/500-2/3}, \end{aligned} \tag{5.13}$$

Theorem 4.3 implies that  $\mathcal{E}$  holds with overwhelming probability. In what follows, let us fix  $u = (x, \mathfrak{s}) \in \overline{\mathcal{D}}$ , and let  $u_0 = (x_0, \mathfrak{s}) \in \mathfrak{A}(\mathfrak{B})$  denote a point with  $|x - x_0|$  minimal. We will show that the upper bounds in Equations (5.8) and (5.9) hold on  $\mathcal{E}$ .

First, assume that  $u \in \mathfrak{L}_-$ , in which case  $u \in \mathfrak{L}$  and  $|x - x_0| \geq n^{\delta-2/3} \geq (\zeta_1 + \zeta_2) \Upsilon_{\mathfrak{s}}(x)$ . Hence, (5.4) implies that  $u \in \widehat{\mathfrak{L}}$ , and so Equation (5.3) applies and gives

$$\widehat{H}(x, \mathfrak{s}) \leq \widehat{H}^*(x, \mathfrak{s}) + n^{\delta/500-1} \leq H^*(x, \mathfrak{s}) - \omega(\mathfrak{s}) \Omega_{\mathfrak{s}}(x) + n^{\delta/500-1} + \mathcal{O}(\zeta_1^{3/2}), \tag{5.14}$$

where  $\omega : [t_1, t_2] \rightarrow \mathbb{R}$  is given by

$$\omega(t) = \zeta'_2 \frac{t - t_1}{t_2 - t_1} + \zeta'_1 \frac{t_2 - t}{t_2 - t_1}.$$

In particular, since  $(1 - \varepsilon)t_1 + \varepsilon t_2 = t_1 + \varepsilon t \leq \mathfrak{s} \leq t_2 - \varepsilon t = \varepsilon t_1 + (1 - \varepsilon)t_2$ , we have (recalling the definition (5.7) of  $\zeta$ , as well as the bounds  $\zeta_1 \geq \zeta_2$ ,  $\zeta_1 - \zeta_2 \geq \zeta(\zeta_1 + \zeta_2)$  and  $\theta < 1/50$ ) that

$$\omega(\mathfrak{s}) \leq (1 - \varepsilon)\zeta'_1 + \varepsilon\zeta'_2 \leq (1 - 3\theta\varepsilon)\zeta. \tag{5.15}$$

Together, Equations (5.14) and (5.15) (with the fact that  $n^{\delta/500-1} \leq \zeta_1^{3/2}$ ) yield on  $\mathcal{E}$  that

$$\tilde{H}(u) \leq \widehat{H}(x, \mathfrak{s}) \leq H^*(x, \mathfrak{s}) - (1 - 3\theta\varepsilon)\zeta \Omega_{\mathfrak{s}}(x) + \mathcal{O}(\zeta_1^{3/2}) \leq H^*(x, \mathfrak{s}) - \zeta \Omega_{\mathfrak{s}}(x) = H^*(u) - \zeta \Omega_{\mathfrak{s}}(x),$$

where the third inequality follows from the fact that Remark 5.3 implies  $-\Omega_s(x) \geq |x - x_0|^{1/2}$  and  $|x - x_0| \geq n^{\delta-2/3} \geq n^{\delta/4}(\zeta_1 + \zeta_2)$  (as  $\zeta_1, \zeta_2 \leq n^{\delta/2-2/3}$ ). This verifies the upper bound in the first statement of (5.8).

To verify the second, assume that  $u \notin \mathfrak{Q}$  and  $|x - x_0| \geq \zeta|\Upsilon_s(x)|$ . Since  $\zeta_1, \zeta_2 \geq n^{\delta/100-2/3}$ , we deduce  $\text{dist}(u, \mathfrak{A}(\mathfrak{P})) \gg n^{\delta/500-2/3}$ ; by Equation (5.13) this implies  $\widehat{H}(u) = \widehat{H}^*(u)$  on the event  $\mathcal{E}$ . Additionally, the second of Proposition 5.4 implies that  $\widehat{H}^*(u) = H^*(u)$  if  $|x - x_0| \geq \omega(s)|\Upsilon_s(x_0)| + \mathcal{O}(\zeta_1^2)$ . Since Equation (5.15) yields  $\omega(s) \leq (1 - 3\theta\varepsilon)\zeta$ , we obtain  $|x - x_0| \geq \zeta|\Upsilon_s(x_0)| \geq \omega(s)|\Upsilon_s(x_0)| + \mathcal{O}(\zeta_1^2)$ , and so this condition is satisfied. Hence, on  $\mathcal{E}$ , we have  $\widetilde{H}(u) \leq \widehat{H}(u) = H^*(u)$ , and so the upper bound in the second statement of (5.8) holds.

It thus remains to assume  $|x - x_0| \leq \zeta^{8/9}$  and verify that the upper bound in Equation (5.9) holds on  $\mathcal{E}$ . To that end, we assume in what follows that  $(x_0, \mathfrak{s})$  is a right endpoint of  $\mathfrak{A}(\mathfrak{P})$  and that  $\partial_x H^*(x_0, \mathfrak{s}) = 0$ , as the proofs in all other cases are entirely analogous. Then, let  $(\widehat{x}_0, \mathfrak{s}) \in \widehat{\mathfrak{Q}}$  denote the point such that  $|x - \widehat{x}_0|$  is minimal. By Equation (5.4), we have  $x_0 - \widehat{x}_0 = \omega(\mathfrak{s})\Upsilon_s(x_0) + \mathcal{O}(\zeta_1^2)$ . In particular, since  $\Upsilon_s(x_0) > 0$  (by Remark 5.3), it follows that  $x_0 \geq \widehat{x}_0$  and  $x_0 - \widehat{x}_0 = \mathcal{O}(\zeta)$ .

Let us first assume that  $x \geq \widehat{x}_0 - \theta\varepsilon\zeta\Upsilon_s(x_0)$ . Then, since  $\partial_x \widehat{H}^*(x', \mathfrak{s}) = \partial_x H^*(x_0, \mathfrak{s})$  for  $x' \geq \widehat{x}_0$ , we have

$$\widehat{H}^*(x, \mathfrak{s}) \leq \widehat{H}^*(\widehat{x}_0, \mathfrak{s}) \leq \widehat{H}^*(x_0, \mathfrak{s}) = H^*(x_0, \mathfrak{s}) \leq H^*(x + \zeta\Upsilon_s(x_0), \mathfrak{s}). \tag{5.16}$$

Here, the first inequality follows from the fact that either  $x \leq \widehat{x}_0$  (in which case  $\widehat{H}^*(x, \mathfrak{s}) \leq \widehat{H}^*(\widehat{x}_0, \mathfrak{s})$ ) or  $x > \widehat{x}_0$  (in which case  $\widehat{H}^*(x, \mathfrak{s}) = \widehat{H}^*(\widehat{x}_0, \mathfrak{s})$ ); the second inequality holds since  $x_0 \geq \widehat{x}_0$ . The equality follows from the second statement of Equation (5.4), and the last inequality follows from the fact that

$$x + \zeta\Upsilon_s(x_0) \geq \widehat{x}_0 + (1 - \theta\varepsilon)\zeta\Upsilon_s(x_0) \geq \widehat{x}_0 + \omega(\mathfrak{s})\Upsilon_s(x_0) + \mathcal{O}(\zeta_1^2) \geq x_0,$$

where we have used Equation (5.4). Additionally, Equation (5.13) implies that  $\widehat{H}(x, \mathfrak{s}) = \widehat{H}^*(x, \mathfrak{s})$ , since  $|x - \widehat{x}_0| \gg \zeta^{1+\delta/500} \gg n^{\delta/500-2/3}$ . Together with Equation (5.16), this implies that on  $\mathcal{E}$  we have  $\widehat{H}(u) \leq \widehat{H}(x, \mathfrak{s}) = \widehat{H}^*(x, \mathfrak{s}) = H^*(x + \zeta\Upsilon_s(x_0), \mathfrak{s})$ , thereby verifying the upper bound in Equation (5.9).

So, let us instead assume that  $x < \widehat{x}_0 - \theta\varepsilon\zeta\Upsilon_s(x_0)$ . Then the bound  $x_0 - \widehat{x}_0 = \omega(\mathfrak{s})\Upsilon_s(x_0) + \mathcal{O}(\zeta^2)$ , together with Equation (5.5) and the fact that  $H^*$  is 1-Lipschitz, implies

$$\begin{aligned} \widehat{H}^*(u) &\leq \widehat{H}^*(\widehat{x}_0, \mathfrak{s}) + H^*(x + x_0 - \widehat{x}_0, \mathfrak{s}) - H^*(x_0, \mathfrak{s}) + \mathcal{O}(\zeta_1^2) \\ &\leq H^*(x + \omega(\mathfrak{s})\Upsilon_s(x_0), \mathfrak{s}) + \widehat{H}^*(\widehat{x}_0, \mathfrak{s}) - H^*(x_0, \mathfrak{s}) + \mathcal{O}(\zeta^2) \\ &= H^*(x + \omega(\mathfrak{s})\Upsilon_s(x_0), \mathfrak{s}) + \mathcal{O}(\zeta^2). \end{aligned} \tag{5.17}$$

Here, to deduce the last equality we used the fact that  $\widehat{H}^*(\widehat{x}_0, \mathfrak{s}) = \widehat{H}^*(x_0, \mathfrak{s}) = H^*(x_0, \mathfrak{s})$ , which holds since  $x_0 \geq \widehat{x}_0$ , since  $\partial_x \widehat{H}^*(x', \mathfrak{s}) = \partial_x H^*(x_0, \mathfrak{s}) = 0$  for  $x' \geq \widehat{x}_0$ , and by the second statement of Proposition 5.4. Next, since  $\omega(\mathfrak{s}) \leq (1 - 3\theta\varepsilon)\zeta$  (by Equation (5.15)), the square root decay of  $\partial H^*$  around  $\mathfrak{A}(\mathfrak{P})$  (see Remark A.2) yields a constant  $c = c(\mathfrak{P}, \mathfrak{D}, \varepsilon, \theta) > 0$  such that

$$H^*(x + \omega(\mathfrak{s})\Upsilon_s(x_0), \mathfrak{s}) \leq H^*(x + \zeta\Upsilon_s(x_0), \mathfrak{s}) - c\zeta^{3/2}.$$

This, together with Equations (5.13) and (5.17), implies on  $\mathcal{E}$  that

$$\begin{aligned} \widetilde{H}(u) \leq \widehat{H}(u) &\leq \widehat{H}^*(u) + n^{\delta/500-1} \leq H^*(x + \zeta\Upsilon_s(x_0), \mathfrak{s}) - c\zeta^{3/2} + n^{\delta/500-1} + \mathcal{O}(\zeta^2) \\ &\leq H^*(x_0 + \zeta\Upsilon_s(x_0), \mathfrak{s}), \end{aligned}$$

where for the last bound we used the fact that  $\zeta \geq n^{\delta/100-2/3}$ . Thus, the upper bound in Equation (5.9) holds in  $\mathcal{E}$ . As mentioned earlier, the proofs of all lower bounds are entirely analogous and therefore omitted; this establishes the proposition. □

5.3. Proof of Proposition 5.9

In this section, we establish Proposition 5.9.

*Proof of Proposition 5.9 (Outline).* Since the proof of this proposition is similar to that of Proposition 5.8, we only outline it. It suffices to show that, with overwhelming probability, we have

$$H^*(X_0, s) + \xi\Omega_s(X_0) - \mu \leq H(X_0, s) \leq H^*(X_0, s) - \xi\Omega_s(X_0) + \mu. \tag{5.18}$$

We only establish the upper bound in Equation (5.18), as the proof of the lower bound is entirely analogous. Throughout, we set  $\tilde{h} = \tilde{H}|_{\partial\mathfrak{D}}$  from Assumption 5.7.

To do this, we apply Proposition 5.4 with the  $(\xi_1, \xi_2)$  there equal to  $(-\xi_1, -\xi_2)$  here. This yields a function  $\widehat{h} : \partial\mathfrak{D} \rightarrow \mathbb{R}$  and its associated maximizer  $\widehat{H}^* \in \text{Adm}(\mathfrak{D}; \widehat{h})$  of  $\mathcal{E}$  satisfying the four properties listed there. Define  $\check{h} : \partial\mathfrak{D} \rightarrow \mathbb{R}$ ; the associated maximizer  $\check{H}^* \in \text{Adm}(\mathfrak{D}; \check{h})$  of  $\mathcal{E}$ ; and the discretization  $\check{h} : \partial\mathfrak{D} \rightarrow \mathbb{Z}$  of  $\check{h}$  by setting

$$\check{h}(v) = \widehat{h}(v) + \mu + n^{\delta/20-1}, \quad \text{so that} \quad \check{H}^*(u) = \widehat{H}^*(u) + \mu + n^{\delta/20-1}, \quad \text{and} \quad \check{h}(nv) = \lfloor n\check{h}(v) \rfloor, \tag{5.19}$$

for each  $u \in \overline{\mathfrak{D}}$  and  $v \in \partial\mathfrak{D}$ . We claim that  $\tilde{h}(v) \leq \check{h}(v)$ , for each  $v \in \partial\mathfrak{D}$ .

The proof that this holds when  $v = n^{-1}v \in \partial_{\text{ea}}(\mathfrak{D}) \cup \partial_{\text{we}}(\mathfrak{D})$  is very similar to that in the proof of Lemma 5.11, so it is omitted. Thus, suppose that  $v = (x, t_j) \in \partial_{\text{no}}(\mathfrak{D}) \cup \partial_{\text{so}}(\mathfrak{D})$ . If  $v \notin \mathfrak{Q}$  and  $\text{dist}(v, \mathfrak{A}(\mathfrak{P})) \geq \zeta_j^{8/9}$ , then the proof is again entirely analogous to that in the proof of Lemma 5.11.

So, let us first assume that  $v = (x, t_j) \in \mathfrak{Q}_-^{\delta}$ . Since  $\tilde{H}$  is  $(\xi_j; \mu)$ -tilted at  $v$ , we have

$$\tilde{H}(v) \leq H^*(v) - \xi_j\Omega_{t_j}(x) + \mu.$$

This, together with Equations (5.3), (5.19) and the bound  $\xi_j \leq n^{-2/3}$  gives

$$\begin{aligned} \check{H}^*(v) &= \widehat{H}^*(v) + \mu + n^{\delta/20-1} \geq H^*(v) - \xi_j\Omega_{t_j}(x) + \mu + n^{\delta/20-1} + \mathcal{O}(\xi_j^{3/2}) \\ &\geq \tilde{H}(v) + n^{\delta/20-1} + \mathcal{O}(\xi_j^{3/2}) \geq \tilde{H}(v) + n^{-1}. \end{aligned} \tag{5.20}$$

Hence,  $n\check{h}(v) \geq n\tilde{h}(v) + 1$ , and so  $\check{h}(v) \geq \tilde{h}(v)$  whenever  $v = n^{-1}v \in \mathfrak{Q}_-^{\delta}$ .

Thus, assume instead  $v \notin \mathfrak{Q}_-^{\delta}$  and  $\text{dist}(v, \mathfrak{A}(\mathfrak{P})) \leq \zeta_j^{8/9}$ , and let  $v_0 = (x_0, t_j) \in \mathfrak{A}(\mathfrak{P})$  be such that  $|x - x_0|$  is minimal. We suppose that  $v_0$  is a right endpoint of  $\mathfrak{A}(\mathfrak{P})$  and that  $\partial_x H^*(v_0) = 0$ , as the alternative cases are entirely analogous; then,  $Y_{t_j}(x_0) > 0$  by Remark 5.1. The fact that the edge of  $\tilde{H}$  is  $\zeta_j$ -tilted with respect to  $H^*$  at level  $t_j$  implies that  $\tilde{H}(x, t_j) \leq H^*(x + \zeta_j Y_{t_j}(x_0), t_j)$ . Applying the square root decay of  $\partial_x H^*$  around  $\mathfrak{A}(\mathfrak{P})$  from Remark A.2 (and the fact that  $\partial_x H^*(x_0, t_j) = 0$ ), we therefore deduce the existence of a constant  $c = c(\mathfrak{P}, \mathfrak{D}) > 0$  such that

$$\tilde{H}(x, t_j) \leq H^*(x + \zeta_j Y_{t_j}(x_0), t_j) \leq H^*(x, t_j) + c\zeta_j^{3/2} \leq H^*(v) + \mathcal{O}(n^{\delta/30-1}). \tag{5.21}$$

Now, let us compare  $\widehat{H}^*(v)$  and  $H^*(v)$ . To that end, define  $\widehat{x}_0 \in \mathbb{R}$  such that  $\widehat{v}_0 = (\widehat{x}_0, t_j)$  is an endpoint of  $\partial_{\text{so}}(\mathfrak{Q})$  or  $\partial_{\text{no}}(\mathfrak{Q})$  and  $|\widehat{x}_0 - x_0|$  is minimal. By Equation (5.4), we have  $\widehat{x}_0 - x_0 = -\xi'_j Y_{t_j}(x_0) + \mathcal{O}(\xi_1^2 + \xi_2^2)$ . In particular,  $\widehat{x}_0 \leq x_0$  and  $x_0 - \widehat{x}_0 = \mathcal{O}(\xi_j)$ , the former of which implies that  $v_0 = (x_0, t_j) \notin \mathfrak{Q} \cup \widehat{\mathfrak{Q}}$ . Hence, the second statement of Proposition 5.4 implies that  $\widehat{H}^*(x_0, t_j) = \widehat{H}^*(\widehat{x}_0, t_j)$ . Since  $\partial_x \widehat{H}^*(x, t_j) = 0$  for  $x \geq \widehat{x}_0$ , we find that  $\widehat{H}^*(\widehat{x}_0, t_j) = \widehat{H}^*(x_0, t_j) = H^*(x_0, t_j)$ , and so Equation (5.5) yields

$$\begin{aligned} \widehat{H}^*(x, t_j) &= \widehat{H}^*(\widehat{x}_0, t_j) + H^*(x - \widehat{x}_0 + x_0, t_j) - H^*(x_0, t_j) + \mathcal{O}((\xi_1 + \xi_2)(x - \widehat{x}_0)^{3/2} + (x - \widehat{x}_0)^2) \\ &= H^*(x - \widehat{x}_0 + x_0, t_j) + \mathcal{O}(\xi_1^2) \geq H^*(x, t_j) - c(\widehat{x}_0 - x_0)^{3/2} - n^{-1} \geq H^*(v) + \mathcal{O}(n^{-1}) \end{aligned} \tag{5.22}$$

after decreasing  $c$  if necessary. Here, to deduce the third statement we used Remark A.2 and to deduce the fourth we used the facts that  $x_0 - \widehat{x}_0 = \mathcal{O}(\xi_j) = \mathcal{O}(n^{-2/3})$ . Combining Equations (5.20), (5.21) and (5.22) then gives

$$\begin{aligned} \check{h}(v) &= \check{H}^*(v) = \widehat{H}^*(v) + \mu + n^{\delta/20-1} \geq H^*(v) + n^{\delta/20-1} + \mathcal{O}(n^{\delta/30-1}) \\ &\geq \widetilde{H}(v) + n^{\delta/20-1} + \mathcal{O}(n^{\delta/30-1}) \\ &\geq \widetilde{H}(v) + n^{-1} = \widetilde{h}(v) + n^{-1}, \end{aligned}$$

which again gives  $\check{h}(v) = \lfloor n\check{h}(v) \rfloor \geq \lfloor n\widetilde{h}(v) \rfloor = \widetilde{h}(v)$ . This verifies  $\check{h}(v) \geq \widetilde{h}(v)$ , for each  $v \in \partial D$ .

Now, let  $\check{H} : D \rightarrow \mathbb{Z}$  denote a uniformly random element of  $\mathcal{G}(\check{h})$ , and set  $\check{H}(u) = n^{-1}\check{H}(nu)$  for each  $u \in \overline{D}$ . By Lemma 3.15 (and Remark 3.16), we may couple  $\check{H}(u) \geq \widetilde{H}(u)$ , for each  $u \in D$ ; thus, under this coupling we have  $\check{H}(u) \geq \widetilde{H}(u)$  for each  $u \in \overline{D}$ .

Let us next apply Theorem 4.3, with the  $(h; H^*; H; \delta)$  there equal to the  $(\check{h}; \check{H}^*; \check{H}; \delta/30)$ . This yields with overwhelming probability that

$$\widetilde{H}(U_0) \leq \check{H}(U_0) \leq \check{H}^*(X_0, \mathfrak{s}) + n^{\delta/30-1} \leq \widehat{H}^*(X_0, \mathfrak{s}) + \mu + 2n^{\delta/20-1}. \tag{5.23}$$

Defining  $\omega : [t_1, t_2] \rightarrow \mathbb{R}$  as in Equation (5.2), the first property listed there yields

$$\widehat{H}^*(X_0, \mathfrak{s}) \leq H^*(X_0, \mathfrak{s}) - \omega(\mathfrak{s})\Omega_{\mathfrak{s}}(X_0) + \mathcal{O}(\xi_1^{3/2} + \xi_2^{3/2}). \tag{5.24}$$

The hypotheses of the proposition and Remark 5.3 together imply (after decreasing  $c$  if necessary) that

$$\begin{aligned} \omega(\mathfrak{s}) &\leq \max \{ (1 - \varepsilon)\xi_1 + \varepsilon\xi_2, \varepsilon\xi_1 + (1 - \varepsilon)\xi_2 \} < \left(1 - \frac{\varepsilon}{10}\right)\xi \leq \left(1 - \frac{\varepsilon}{10}\right)n^{\delta/10-1} \text{dist}(U_0, \mathfrak{A}(\mathfrak{P}))^{-1/2}; \\ &-\Omega_{\mathfrak{s}}(X_0) \geq c \text{dist}(U_0, \mathfrak{A}(\mathfrak{P}))^{1/2}; \quad \xi_1^{3/2} + \xi_2^{3/2} = \mathcal{O}(n^{\delta/30-1}). \end{aligned}$$

Together with Equations (5.23) and (5.24), this gives

$$\begin{aligned} \widetilde{H}(U_0) &\leq H^*(X_0, \mathfrak{s}) - \xi\Omega_{\mathfrak{s}}(X_0) + \mu + (\xi - \omega(\mathfrak{s}))\Omega_{\mathfrak{s}}(X_0) + \mathcal{O}(n^{\delta/30-1}) \\ &\leq H^*(X_0, \mathfrak{s}) - \xi\Omega_{\mathfrak{s}}(X_0) + \mu - \frac{c\varepsilon}{10}n^{\delta/10-1} + \mathcal{O}(n^{\delta/30-1}) \leq H^*(U_0) - \xi\Omega_{\mathfrak{s}}(X_0) + \mu, \end{aligned}$$

which confirms the upper bound in Equation (5.18). □

### 6. Proof of concentration estimate on polygons

In this section, we establish Theorem 3.10. Before proceeding, let us briefly outline the proof; we adopt the notation of Theorem 3.10 throughout this section.

Since the preliminary concentration result Theorem 4.3 is in itself too restrictive to this end, we will first decompose our polygonal subset  $\mathfrak{P} = \bigcup_{i=1}^k \mathfrak{R}_i$  into subregions such that each  $\mathfrak{R}_i$  is either frozen (outside the liquid region of  $\mathfrak{P}$ ) or is a ‘double-sided trapezoid’  $\mathfrak{D}(\mathfrak{a}, \mathfrak{b}; t_1, t_2)$  from Equation (4.1). Scaling by  $n$ , this induces a decomposition  $P = \bigcup_{i=1}^k R_i$  on our (tileable) polygonal domain. We then apply the alternating dynamics from Section 4.2 to this decomposition. Each step corresponds to a resampling of our tiling on some  $R_i$  (conditioned on its restriction to  $P \setminus R_i$ ), to which Theorem 4.3 applies and shows that its tiling height function is within  $n^\delta$  of its limit shape. Unfortunately, Proposition 4.6 shows that these dynamics only mix after about  $n^{22}$  steps, which could in principle allow the previously mentioned  $n^\delta$  error to accumulate macroscopically.

To remedy this, we use the notion of tiltedness from Section 5.1. In particular, we introduce parameters quantifying the tiltedness of certain horizontal levels  $P$  (that include the north and south boundaries of any  $R_i$ ). Then Proposition 5.8 and Proposition 5.9 will imply that, under any step of the alternating dynamics to some  $R_i$ , the tiltedness along a middle row of  $R_i$  is likely bounded between those along its north and south boundaries. Since the tiltedness along  $\partial P$  is zero, we will be to show in this way that ‘small tiltedness’ is preserved under the alternating dynamics with high probability. Running these dynamics until they mix, this indicates that the uniformly random tiling height function  $H : P \rightarrow \mathbb{Z}$  has small tiltedness, which will establish Theorem 3.10.

6.1. Decomposition of  $P$

In this section, we explain a decomposition of  $P = n\mathfrak{P}$  into subregions that are either frozen or where Theorem 4.3 will eventually apply. Recall that we have adopted the notation of Theorem 3.10; let us abbreviate the liquid region  $\mathfrak{L} = \mathfrak{L}(\mathfrak{P})$  and arctic boundary  $\mathfrak{A} = \mathfrak{A}(\mathfrak{P})$ . By Assumption 2.8, there exists an axis  $\ell$  of  $\mathbb{T}$  such that no line connecting two distinct cusp singularities of  $\mathfrak{A}$  is parallel to  $\ell$ . By rotating  $\mathfrak{P}$  if necessary, we may assume that  $\ell$  is the  $x$ -axis. We also distinguish a tangency location of  $\mathfrak{A}$  to be *horizontal* if the tangent line to  $\mathfrak{A}$  through it is parallel the  $x$ -axis (has slope 0). In what follows, we recall the trapezoid  $\mathfrak{D} = \mathfrak{D}(a, b; t_1, t_2)$  from Equation (4.1) and its boundaries Equation(4.2).

We begin with the following definition that will (partially) constrain what types of regions can be our decomposition; observe that the assumptions below are similar to Assumption 4.1.

**Definition 6.1.** A trapezoid  $\mathfrak{D}$  is *adapted to  $H^*$*  if the following five conditions hold.

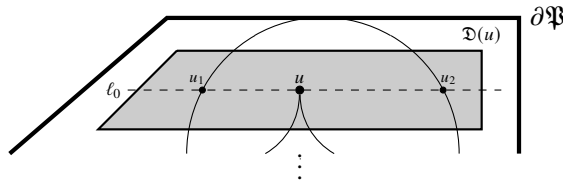
- (1) The boundary  $\partial_{ea}(\mathfrak{D})$  is disjoint with  $\overline{\mathfrak{L}}$ , unless  $\partial_{ea}(\mathfrak{D}) \subset \partial\mathfrak{P}$  and  $\mathfrak{A}$  is tangent to  $\partial_{ea}(\mathfrak{D})$ ; the same must hold for  $\partial_{we}(\mathfrak{D})$ .
- (2) The function  $H^*$  is constant along  $\partial_{ea}(\mathfrak{D})$  and along  $\partial_{we}(\mathfrak{D})$ .
- (3) There exists  $\tilde{t} \in [t_1, t_2]$  such that one of the following two conditions holds.
  - (a) For  $t \in [t_1, \tilde{t}]$ , the set  $I_t$  consists of one nonempty interval, and for  $t \in (\tilde{t}, t_2]$  the set  $I_t$  consists of two nonempty disjoint intervals.
  - (b) For  $t \in [t_1, \tilde{t})$ , the set  $I_t$  consists of two nonempty disjoint intervals, and for  $t \in (\tilde{t}, t_2]$  the set  $I_t$  consists of one nonempty interval.
- (4) Any tangency location of  $\mathfrak{A} \cap \overline{\mathfrak{D}}$  is of the form  $\max I_t$  or  $\min I_t$ , for some  $t \in (t_1, t_2)$ . Moreover, at most one is of the form  $\max I_t$ , and at most one is of the form  $\min I_t$ .
- (5) We have  $t_1 - t_2 \leq c$ , where  $c = c(\mathfrak{P}) > 0$  is given by Theorem 4.3.

**Lemma 6.2.** *If  $u \in \overline{\mathfrak{L}}$  is not a tangency location of  $\mathfrak{A}$ , then there exists a trapezoid  $\mathfrak{D}(u)$  adapted to  $H^*$ , containing  $u$  in its interior.*

*Proof.* Let  $u = (x_0, t_0)$  and  $\ell_0 = \{t = t_0\} \subset \mathbb{R}^2$  denote the line through  $u$  parallel to the  $x$ -axis. To create  $\mathfrak{D}(u) = \mathfrak{D}(a, b; t_1, t_2)$ , we will first specify segments containing its east and west boundaries, and then specify  $(t_1, t_2)$  to make it sufficiently ‘short’ (that is, with  $t_2 - t_1$  small).

To that end, first assume that  $u$  is a cusp of  $\mathfrak{A}$ ; we refer to Figure 11 for a depiction. Let  $x_1 \in \mathbb{R}$  be maximal and  $x_2 \in \mathbb{R}$  be minimal such that  $x_1 < x_0 < x_2$ ;  $u_1 = (x_1, t_0) \in \mathfrak{A}$ , and  $u_2 = (x_2, t_0) \in \mathfrak{A}$ . By Assumption 2.8, neither  $u_1$  nor  $u_2$  is a cusp of  $\mathfrak{A}$ . If  $u_1 \in \partial\mathfrak{P}$ , then it is a (nonhorizontal) tangency location of  $\mathfrak{A}$ , so it lies along a side of  $\partial\mathfrak{P}$  with slope 1 or  $\infty$ . We may then let this side contain the west boundary of  $\mathfrak{D}(u)$ . If instead  $u_1 \notin \partial\mathfrak{P}$ , then there exists a real number  $\varepsilon = \varepsilon(\mathfrak{P}, u) \in (0, 1)$  such that  $(x, t_0) \in \mathfrak{P} \setminus \overline{\mathfrak{L}}$  for each  $x_1 - \varepsilon^{1/2} < x < x_1$ , and such that either  $((x_1 - \varepsilon^{1/2}, x_2 + \varepsilon^{1/2}) \times (t_0, t_0 + \varepsilon)) \cap \mathfrak{L}$  or  $((x_1 - \varepsilon^{1/2}, x_2 + \varepsilon^{1/2}) \times (t_0 - \varepsilon, t_0)) \cap \mathfrak{L}$  is connected (see Figure 11).

Next, recall from the first statement in Lemma 2.3 that, on  $\mathfrak{P} \setminus \mathfrak{L}(\mathfrak{P})$ ,  $\nabla H^*$  is piecewise constant, taking values in  $\{(0, 0), (1, 0), (1, -1)\}$ . If  $(x_1, t_0) \in \mathfrak{A}$  is a continuous point of  $\nabla H^*$ , then (upon decreasing  $\varepsilon$  if necessary) there exists  $\lambda = \lambda(\mathfrak{P}, u) > 0 \in (0, \varepsilon)$  such that the disk  $\mathfrak{B}_\lambda(x_1 - \varepsilon^{1/2}, t_0)$  does not intersect  $\overline{\mathfrak{L}}$ , and  $\nabla H^*(x_1, t_0)$  is constant on  $\mathfrak{B}_\lambda(x_1 - \varepsilon^{1/2}, t_0)$ . Then, depending on whether  $\nabla H^*(x_1, t_0) = (1, -1)$  or  $\nabla H^*(x_1, t_0) \in \{(0, 0), (1, 0)\}$ , the west boundary of  $\mathfrak{D}(u)$  is contained in the segment obtained as



**Figure 11.** Shown above is an example of the trapezoid  $\mathfrak{D}(u)$  from Lemma 6.2; only part of the polygon  $\mathfrak{P}$  and its liquid region  $\mathfrak{L}$  are depicted.

the intersection between  $\mathfrak{B}_\lambda(x_1 - \varepsilon^{1/2}, t_0)$  and the line passing through  $(x_1 - \varepsilon^{1/2}, t_0)$  with slope 1 or  $\infty$ , respectively; then,  $H^*$  is constant along this line.

If  $(x_1, t_0) \in \mathfrak{A}$  is a discontinuity point of  $\nabla H^*$ , then, by Assumption 2.8,  $(x_1, t_0) \in \mathfrak{A}$  is a tangency location. From our choice of  $x_1$ ,  $(x_1, t_0)$  cannot be a horizontal tangency location. Thus, its tangent line has slope 1 or  $\infty$ . For  $\varepsilon$  small enough, the part of the tangent line between  $t = t_0 - \varepsilon$  and  $t = t_0 + \varepsilon$  is contained in the  $\mathfrak{P} \setminus \mathfrak{L}(\mathfrak{P})$ . By the relations (3.1) between  $\nabla H^*$  and the complex slope, and the Equation (3.7) between the complex slope and the slope of the tangent line of the arctic curve, if the tangent line has slope 1, then  $\nabla H^* \in \{(0, 0), (1, -1)\}$ , and if the tangent line has slope  $\infty$ , then  $\nabla H^* \in \{(0, 0), (1, 0)\}$ . In both cases  $H^*$  is constant along the tangent line. This again specifies a segment containing the west boundary of  $\mathfrak{D}(u)$  where  $H^*$  is a constant along it, and one containing its east boundary can be specified similarly.

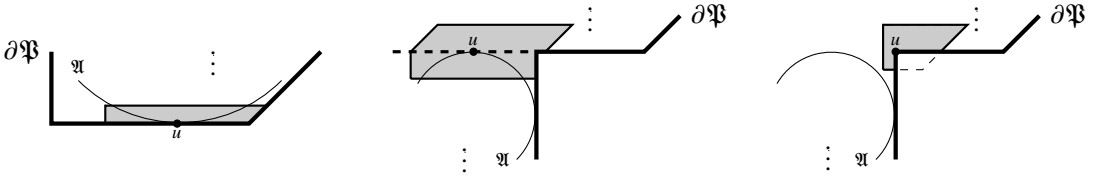
In either case (whether  $(x_1, t_0)$  is a continuity or discontinuity point of  $\nabla H^*$ ), we let  $t_1 = t_0 - \lambda_0$  and  $t_2 = t_0 + \lambda_0$ , where  $\lambda_0$  is chosen sufficiently small so that the east and west boundary of  $\mathfrak{D}(u)$  are contained in the segments specified above and so that  $\mathfrak{D}$  satisfies the third, fourth and fifth conditions of Definition 6.1. This determines  $\mathfrak{D}(u)$ , which contains  $u$  in its interior and is quickly seen to be adapted to  $H^*$ .

The proof is similar if instead  $u$  is not a cusp of  $\mathfrak{A}$ , so we only outline it. If  $u \in \mathfrak{L}$ , then the above reasoning applies, unless either  $u_1$  or  $u_2$  is a cusp of  $\mathfrak{A}$ . Assuming for example that the former is, there exists a trapezoid  $\mathfrak{D}(u_1)$  adapted to  $H^*$  that contains  $u_1$  in its interior. Then  $\mathfrak{D}(u_1)$  must also contain  $u$  in its interior since  $l_0$  passes through  $u$  before intersecting  $\mathfrak{A}$ , so we may set  $\mathfrak{D}(u) = \mathfrak{D}(u_1)$ . If instead  $u \in \mathfrak{A}$  and is not a cusp, then the above reasoning (in the case when  $u$  is cusp) again applies, with the mild modification that we allow  $u = u_1$  or  $u = u_2$ , depending on whether  $u$  is a left or right boundary point of  $\mathfrak{A}$ , respectively. □

Now, for each point  $u \in \overline{\mathfrak{P}}$ , in the following, we define an open subset  $\mathfrak{R}(u) \subset \mathfrak{P}$  such that  $u \in \mathfrak{R}(u)$  if  $u \in \mathfrak{P}$ , and  $u \in \overline{\mathfrak{R}(u)}$  if  $u \in \partial\mathfrak{P}$ . In each case,  $\mathfrak{R}(u)$  will be the union of at most two trapezoids (intersected with  $\mathfrak{P}$ ). We always assume (by applying a small shift if necessary) that the north and south boundaries of any such trapezoid does not contain any cusps or tangency locations of  $\mathfrak{A}$ , except for possibly if  $u$  is a horizontal tangency location.

- (1) If  $u \in \overline{\mathfrak{L}}$  is not a horizontal tangency location of  $\mathfrak{A}$ , then let  $\mathfrak{R}(u) \subseteq \mathfrak{P}$  denote a trapezoid adapted to  $H^*$ , containing  $u$  in its interior.
- (2) If  $u \in \mathfrak{A}$  is horizontal tangency location on  $\mathfrak{A} \cap \partial\mathfrak{P}$ , then let  $\mathfrak{R}(u) \subseteq \mathfrak{P}$  denote a trapezoid adapted to  $H^*$  such that  $u$  is in the interior of either  $\partial_{\text{no}}(\mathfrak{D})$  or  $\partial_{\text{so}}(\mathfrak{D})$ .
- (3) If  $u \in \mathfrak{A}$  is a horizontal tangency location on  $\mathfrak{A}$  not in  $\partial\mathfrak{P}$ , then let  $\mathfrak{R}(u) = \mathfrak{D}_1(u) \cup \mathfrak{D}_2(u)$ . Here,  $\mathfrak{D}_1 = \mathfrak{D}_1(u)$  and  $\mathfrak{D}_2 = \mathfrak{D}_2(u)$  are trapezoids adapted to  $H^*$  such that  $u$  is in the interior of  $\partial_{\text{no}}(\mathfrak{D}_2)$  and of  $\partial_{\text{so}}(\mathfrak{D}_1)$  and such that either  $\mathfrak{D}_1$  or  $\mathfrak{D}_2$  is disjoint with  $\mathfrak{L}$ .
- (4) If  $u \notin \overline{\mathfrak{L}}$ , then let  $\mathfrak{R}(u) = \overline{\mathfrak{D}(u)} \cap \mathfrak{P}$ , for some trapezoid  $\mathfrak{D}(u) \subset \mathbb{R}^2$  containing  $u$  in its interior such that  $\mathfrak{D}(u)$  is disjoint with  $\mathfrak{L}$ .

We may further assume (after applying a small shift, if necessary) that  $n\mathfrak{R}(u) \subset \mathbb{T}$ , for each  $u \in \mathfrak{P}$ . The existence of these regions  $\mathfrak{R}_i$  follows from Lemma 6.2 in the first case and is quickly verified from



**Figure 12.** Shown to the left, middle and right are examples of the  $\mathfrak{R}(u)$  (shaded) when  $u \in \partial\mathfrak{P}$  is a horizontal tangency location of  $\mathfrak{A}$ , when  $u \notin \mathfrak{A}$  is a horizontal tangency location of  $\mathfrak{A}$ , and when  $u \notin \mathfrak{L}$ , respectively. In all cases, only part of the polygon  $\mathfrak{P}$  and its liquid region  $\mathfrak{L}$  are depicted.

the definitions in all other cases.<sup>12</sup> We refer to Figure 11 for a depiction in the first case and to Figure 12 for depictions in the remaining three cases.

Since  $\overline{\mathfrak{P}}$  is compact, the  $\mathfrak{R}(u)$  are open, and  $\bigcup_{u \in \overline{\mathfrak{P}}} \overline{\mathfrak{R}(u)} = \overline{\mathfrak{P}}$ , there exists a finite subcover  $\bigcup_{i=1}^k \overline{\mathfrak{R}_i} = \overline{\mathfrak{P}}$ ; here, each  $\mathfrak{R}_i = \mathfrak{R}(u_i)$  for some  $u_i \in \overline{\mathfrak{P}}$ . In what follows, we fix such a cover and let  $t_0 < t_1 < \dots < t_m$  denote all real numbers for which either a north or south boundary of some  $\mathfrak{R}_i$  lies along a line  $\{t = t_j\}$ . Observe that, if such a boundary of some  $\mathfrak{R}_i$  lies along  $\{t = t_0\}$  or  $\{t = t_m\}$ , then it must lie along  $\partial\mathfrak{P}$ . Moreover, since the  $t_j$  are pairwise distinct, there exists a constant  $\varepsilon_0 = \varepsilon_0(\mathfrak{P}) > 0$  such that, for each  $1 \leq j \leq m$ ,

$$\min_{1 \leq j \leq m} (t_j - t_{j-1}) \geq \varepsilon_0(t_m - t_0). \tag{6.1}$$

Further, let  $R_i = n\mathfrak{R}_i \subset \mathbb{T}$  for each  $1 \leq i \leq k$ . Observe, since the  $\mathfrak{R}_i$  are open and cover  $\mathfrak{P}$ , that any interior vertex of  $P$  is an interior vertex of some  $R_i$ . Thus, we may consider the alternating dynamics (from Definition 4.5) on  $P$  with respect to  $(R_1, R_2, \dots, R_k)$ . In particular, let us fix the height function  $H_0 \in \mathcal{G}(h)$  by setting  $H_0(u) = \lfloor nH^*(n^{-1}u) \rfloor$ , for each  $u \in P$ ; observe that  $H_0(u) = nH^*(n^{-1}u)$  for each  $u \in P \setminus (n \cdot \mathfrak{L})$ , by Proposition 2.4. Then, run the alternating dynamics on  $\mathcal{G}(h)$  with initial state  $H_0$ . For each integer  $r \geq 0$ , let  $H_r \in \mathcal{G}(h)$  denote the state of this Markov chain at time  $r$ ; define its scaled version  $H_r \in \text{Adm}(\mathcal{D}; h)$  by  $H_r(u) = n^{-1}H_r(nu)$  for each  $u \in \mathcal{D}$ .

**6.2. Proof of Theorem 3.10**

In this section, we establish Theorem 3.10. To that end, recalling the notation from Section 6.1, we define for any integer  $r \geq 0$  the events

$$\begin{aligned} \mathcal{F}_r &= \bigcap_{u \in \overline{\mathfrak{P}}} \left\{ |H_r(u) - H^*(u)| < n^{\delta-1} \right\} \cap \bigcap_{u \in \overline{\mathfrak{P}} \setminus \mathfrak{L}_+^\delta(\mathfrak{P})} \{H_r(u) = H^*(u)\}; \\ \mathcal{F}_\infty &= \bigcap_{u \in \overline{\mathfrak{P}}} \left\{ |H(nu) - nH^*(u)| < n^\delta \right\} \cap \bigcap_{u \in \overline{\mathfrak{P}} \setminus \mathfrak{L}_+^\delta(\mathfrak{P})} \{H(nu) = nH^*(u)\}. \end{aligned} \tag{6.2}$$

Then, Theorem 3.10 indicates that  $\mathcal{F}_\infty$  should hold with overwhelming probability. As  $r$  becomes large, the alternating dynamics tend to stationarity, so  $nH_r(u)$  converges in law to  $H(nu)$ ; hence, it instead suffices to show that  $\mathcal{F}_r$  likely holds for large  $r$ . We would like to proceed inductively by showing that  $\mathcal{F}_r$  implies  $\mathcal{F}_{r+1}$  with high probability. It is not transparent to us how to do this directly; we instead prove a stronger version of this implication involving the notion of tilting, which we recall from Definition 5.6.

<sup>12</sup>For the third, we are using the fact that no horizontal tangency location of  $\mathfrak{A}$  is also a cusp of  $\mathfrak{A}$  (and that  $\mathfrak{A}$  has no tacnode singularities), as stipulated by Assumption 2.8.



We first require some notation. Recall that  $\varepsilon_0 = \varepsilon_0(\mathfrak{P}) > 0$  satisfies Equation (6.1), and set

$$v_i = 1 - \left(\frac{\varepsilon_0}{10}\right)^{i+1}, \quad 0 \leq i \leq m. \tag{6.3}$$

Also, recall the subset  $\mathfrak{Q}_-^\delta = \mathfrak{Q}_-^\delta(\mathfrak{P}) \subset \mathfrak{Q}$  from Equation (5.6).

For any real number  $z \geq n^{-1}$ , define the functions

$$\kappa(z) = n^{\delta/12-1} z^{-1}; \quad \varpi(z) = n^{\delta/12-1} \log(nz). \tag{6.4}$$

The explicit forms of  $\kappa$  and  $\varpi$  above will not be central for our purposes, but a useful point will be that  $A\kappa(z) + \varpi(z)$  is minimized when  $z = A$ .

Now, recall the subset  $\mathfrak{Q}_-^\delta = \mathfrak{Q}_-^\delta(\mathfrak{P}) \subset \mathfrak{Q}$  from Equation (5.6), and for any integers  $r \geq 0$  and  $0 \leq i \leq m$  define the events

$$\begin{aligned} \mathcal{E}_r^{(1)}(i) &= \{ \text{The edge of } H_r \text{ is } v_i n^{\delta/240-2/3} \text{-tilted with respect to } H^* \text{ at level } t_i \}; \\ \mathcal{E}_r^{(2)}(i) &= \bigcap_{(x, t_i) \in \mathfrak{Q}_-^{\delta/4}} \{ \text{At } (x, t_i), H_r \text{ is } (v_i n^{\delta/240-2/3}; 0) \text{-tilted with respect to } H^* \}. \end{aligned} \tag{6.5}$$

For any  $x \in \mathbb{R}$  such that  $(x, t_i) \in \mathfrak{Q}_-^{\delta/4}$ , further define the event

$$\begin{aligned} \mathcal{E}_r^{(3)}(i; x) &= \left\{ \sup_{z \geq n^{-1}} \left( H^*(x, t_i) + v_i \kappa(z) \Omega_{t_i}(x) - \varpi(z) \right) \right. \\ &\quad \left. \leq H_r(x, t_i) \leq \inf_{z \geq n^{-1}} \left( H^*(x, t_j) - v_i \kappa(z) \Omega_{t_i}(x) + \varpi(z) \right) \right\}, \end{aligned} \tag{6.6}$$

where we recall  $\Omega_s(x)$  from Equation (5.1), and let

$$\mathcal{E}_r^{(3)}(i) = \bigcap_{(x, t_i) \in \mathfrak{Q}_-^{\delta/4}} \mathcal{E}_r^{(3)}(i; x).$$

Then define the events

$$\mathcal{E}_r(i) = \mathcal{E}_r^{(1)}(i) \cap \mathcal{E}_r^{(2)}(i) \cap \mathcal{E}_r^{(3)}(i); \quad \mathcal{E}_r = \bigcap_{i=0}^m \mathcal{E}_r(i); \quad \mathcal{A}_r = \mathcal{E}_r \cap \mathcal{F}_r. \tag{6.7}$$

Under this notation, we have the following proposition.

**Proposition 6.3.** *For any real number  $D > 1$ , there exists a constant  $C = C(\mathfrak{P}, D) > 1$  such that the following holds whenever  $n > C$ . For any integer  $r \geq 0$ , we have  $\mathbb{P}(\mathcal{A}_{r+1}) \geq \mathbb{P}(\mathcal{A}_r) - n^{-D}$ .*

Given Proposition 6.3, we can quickly establish Theorem 3.10.

*Proof of Theorem 3.10.* First, observe that  $\mathcal{A}_0$  holds deterministically since  $H_0(u) = n^{-1}H_0(nu)$  and  $H(nu) = \lfloor nH^*(u) \rfloor$  hold for each  $u \in \overline{\mathfrak{D}}$  (and  $H_0(u) = H^*(u)$  for each  $u \in \mathfrak{P} \setminus \mathfrak{Q}$ , by Proposition 2.4). Then, inductively applying Proposition 6.3, with the  $D$  there equal to  $2D + 45$  here, yields  $\mathbb{P}(\mathcal{A}_{n^{40}}) \geq 1 - n^{-2D}$  for sufficiently large  $n$ . By the definition (6.7) of  $\mathcal{A}_r$ , this implies  $\mathbb{P}(\mathcal{F}_{n^{40}}) \geq 1 - n^{-2D}$ . Since  $\text{diam } \mathbb{R} = n \text{ diam } \mathfrak{X}$ , the bound Proposition 4.6 on the mixing time for the alternating dynamics (together with the definitions (6.2) of  $\mathcal{F}_r$  and  $\mathcal{F}_\infty$ ) gives

$$\mathbb{P}(\mathcal{F}_\infty) \geq \mathbb{P}(\mathcal{F}_{n^{40}}) - e^{-n} \geq 1 - n^{-2D} - e^{-n} \geq 1 - n^{-D},$$

for sufficiently large  $n$ . Since this holds for any  $D$  (if  $n$  is sufficiently large), this implies the theorem.  $\square$

### 6.3. Proof of Proposition 6.3

In this section, we establish Proposition 6.3.

*Proof of Proposition 6.3.* Throughout this proof, we restrict to the event  $\mathcal{A}_r$ ; it suffices to show that  $\mathcal{A}_{r+1}$  holds with overwhelming probability. In what follows, we will frequently use the equality

$$H_r(u) = H^*(u), \quad \text{if } u \in \overline{\mathfrak{P}} \setminus \overline{\mathfrak{Q}} \text{ is bounded away from } \mathfrak{Q}, \tag{6.8}$$

which holds since we have restricted to the event  $\mathcal{F}_r \subseteq \mathcal{A}_r$  from Equation (6.2).

Updating  $H_r$  to  $H_{r+1}$  involves resampling it on a subdomain  $R_j = n\mathfrak{R}_j$ , for some index  $1 \leq j \leq m$ , in the decomposition  $P = \bigcup_{j=1}^k R_j$ . Recall from Section 6.1 that  $\mathfrak{R}_j = \mathfrak{R}(u_j)$ , for some  $u_j \in \overline{\mathfrak{P}}$ , and that there are four possible cases for  $\mathfrak{R}(u_j)$ , depending on whether  $u_j \in \overline{\mathfrak{Q}}$  is not a tangency location of  $\mathfrak{A}$ ;  $u_j \in \mathfrak{A}$  is a tangency location of  $\mathfrak{A}$  that lies on  $\partial\mathfrak{P}$ ;  $u_j \in \mathfrak{A}$  is a tangency location that does not lie on  $\partial\mathfrak{P}$ ; or  $u \notin \overline{\mathfrak{Q}}$  is outside the liquid region. We will address each of these cases.

To that end, first consider the fourth case when  $u_j \notin \overline{\mathfrak{Q}}$ . Then,  $\mathfrak{R}_j \subseteq \overline{\mathfrak{P}} \setminus \overline{\mathfrak{Q}}$ ; in particular, it is bounded away from  $\overline{\mathfrak{Q}}$ , so Equation (6.8) implies  $H_r(nu) = nH^*(u)$  for each  $u \in \mathfrak{R}_j$ . Since  $\nabla H^*(u) \in \{(1, 0), (1, -1), (-1, -1)\}$  for almost every  $u \notin \mathfrak{Q}$  (by the first statement of Lemma 2.3), it follows that there is only one height function on  $R_j$  with boundary data  $H_r|_{\partial R_j}$ , that is, this domain is frozen. This implies that  $H_{r+1} = H_r$ , so each of the estimates involved in the definitions of the events in Equations (6.2), (6.5), (6.6) for  $H_{r+1}$  follow from their counterparts for  $H_r$  guaranteed by  $\mathcal{A}_r$ . Thus,  $\mathcal{A}_{r+1}$  holds deterministically in this case.

Next, we consider the first or second case, namely, when  $u_j \in \overline{\mathfrak{Q}}$  and is not a horizontal tangency location outside of  $\partial\mathfrak{P}$ . If  $u_j$  is a horizontal tangency location of  $\mathfrak{A}$ , then we assume  $u_j \in \partial_{\text{no}}(\mathfrak{R}_j)$ , as the proof when  $u_j \in \partial_{\text{so}}(\mathfrak{R}_j)$  is entirely analogous by rotation (see Remark 5.10). Then  $\mathfrak{R}_j = \mathfrak{R}(u_j)$  is a double-sided trapezoid satisfying the conditions of Assumption 5.2 since it is adapted with respect to  $H^*$  (recall Definition 6.1). By Equation (6.7), suffices to show that  $\mathcal{E}_{r+1}$  and  $\mathcal{F}_{r+1}$  both hold with overwhelming probability.

We begin with the former. Fix an index  $1 \leq i_0 \leq m$ ; we must show  $\mathcal{E}_{r+1}(i_0)$  holds with overwhelming probability. Define indices  $1 \leq i, i' \leq m$  so that  $\partial_{\text{so}}(\mathfrak{R}_j)$  and  $\partial_{\text{no}}(\mathfrak{R}_j)$  are contained in the horizontal lines  $\{y = t_i\}$  and  $\{y = t_{i'}\}$ , respectively. Without loss of generality, we assume that  $i < i'$ . Since the update from  $H_r$  to  $H_{r+1}$  only affects its restriction to  $\mathfrak{R}_j \subset \{(x, y) \in \mathfrak{P} : t_i < t < t_{i'}\}$ , for  $i_0 \notin (i, i')$  the event  $\mathcal{E}_{r+1}(i_0)$  holds deterministically if  $\mathcal{E}_r(i_0)$  does. Hence, we may assume that  $i < i_0 < i'$ . In what follows, we further denote the restrictions  $h_r = H_r|_{\mathfrak{R}_j}$  and  $\mathfrak{h}_r = H_r|_{R_j}$ .

We first verify that  $\mathcal{E}_{r+1}^{(1)}(i_0)$  and  $\mathcal{E}_{r+1}^{(2)}(i_0)$  from Equation (6.5) both hold with overwhelming probability by suitably applying Proposition 5.8. To that end, observe that Assumption 5.7 holds with the parameters  $(\varepsilon, \varsigma, \delta; \mathfrak{D}, D; \mathfrak{s}; t_1, t_2; \mathfrak{h}, \mathfrak{H}; \xi_1, \xi_2; \zeta_1, \zeta_2; \mu)$  there equal to

$$\left( \varepsilon_0, \left(\frac{\varepsilon_0}{20}\right)^{m+1}, \frac{\delta}{4}; \mathfrak{R}_j, R_j; t_{i_0}, t_i, t_{i'}; \mathfrak{h}_r, H_{r+1}; \nu_i n^{\delta/240-2/3}, \nu_{i'} n^{\delta/240-2/3}; \nu_i n^{\delta/240-2/3}, \nu_{i'} n^{\delta/240-2/3}; 0 \right), \tag{6.9}$$

here. To see this, first observe that  $h_r$  is constant along the east and west boundaries of  $\partial R_j$ . Indeed, Equation (6.8) and the fact that  $\partial_{\text{ea}}(\mathfrak{R}_j)$  and  $\partial_{\text{we}}(\mathfrak{R}_j)$  are either subsets of  $\partial\mathfrak{P}$  or bounded away from  $\overline{\mathfrak{Q}}$ , together imply that  $H_r = H^*$  along  $\partial_{\text{ea}}(\mathfrak{R}_j) \cup \partial_{\text{we}}(\mathfrak{R}_j)$ . In particular,  $h_r(nv) = nh_r(v) = nh(v) = nH^*(v)$  holds for each  $v \in \partial_{\text{ea}}(\mathfrak{R}_j) \cup \partial_{\text{we}}(\mathfrak{R}_j)$ . So, since  $\mathfrak{R}_j$  is adapted to  $H^*$ ,  $h$  is constant both  $\partial_{\text{ea}}(\mathfrak{R}_j)$  and  $\partial_{\text{we}}(\mathfrak{R}_j)$ ; thus,  $h_r$  is as well. Next, the inequalities on  $(t_1, \mathfrak{s}, t_2)$  with respect to  $\varepsilon$  and on  $(\xi_1, \xi_2)$  and  $(\zeta_1, \zeta_2)$  with respect to  $\varsigma$ , in Assumption 5.7 follow from Equations (6.1) and (6.3). Moreover, the edge-tiltedness for  $H_r$  with respect to  $H^*$  along  $\partial_{\text{so}}(\mathfrak{R}_j) \cup \partial_{\text{no}}(\mathfrak{R}_j)$  is a consequence of our restriction to the event  $\mathcal{E}_r^{(1)}(i) \cap \mathcal{E}_r^{(1)}(i') \subseteq \mathcal{A}_r$ . Similarly, the bulk-tiltedness of  $H_r$  with respect to  $H^*$  at each  $(x, t_i), (x, t_{i'}) \in \mathfrak{L}_{\delta/4}$  holds follows from our restriction to  $\mathcal{E}_r^{(2)}(i) \cap \mathcal{E}_r^{(2)}(i') \subseteq \mathcal{A}_r$ .

Thus, Proposition 5.8 applies. Under the choice of parameters (6.9), the  $\zeta$  in Proposition 5.8 equals

$$v' = \frac{\varepsilon_0}{2} v_i + \left(1 - \frac{\varepsilon_0}{2}\right) v_{i'} < v_{i_0}, \tag{6.10}$$

where to deduce the last inequality we used Equation (6.3) and the fact that  $i < i_0 < i'$ . In particular, Proposition 5.8 implies with overwhelming probability that the edge of  $H_{r+1}$  is  $v_{i_0} n^{\delta/240-2/3}$ -tilted with respect to  $H^*$  at level  $t_{i_0}$ , and that  $H_{r+1}$  is  $(v_{i_0} n^{\delta/240-2/3}; 0)$ -tilted with respect to  $H^*$  at any  $(x, t_{i_0}) \in \mathfrak{Q}_i^{\delta/4}$ . So, by Equation (6.5),  $\mathcal{E}_{r+1}^{(1)}(i_0)$  and  $\mathcal{E}_{r+1}^{(2)}(i_0)$  both hold with overwhelming probability.

Next, let us show that  $\mathcal{E}_{r+1}^{(3)}(i_0)$  holds with overwhelming probability. To that end, we fix  $x \in \mathbb{R}$  such that  $(x, t_{i_0}) \in \mathfrak{Q}_-^{\delta/4}$ , and set

$$\lambda = -v' \Omega_{t_{i_0}}(x) \geq n^{-1}, \tag{6.11}$$

where the latter inequality follows from Remark 5.3 (and we recall  $v'$  from Equation (6.10)). We will first use Proposition 5.9 to show with overwhelming probability that

$$H^*(x, t_{i_0}) + v' \varkappa(\lambda) \Omega_{t_{i_0}}(x) - \varpi(\lambda) \leq H_{r+1}(x, t_{i_0}) \leq H^*(x, t_{i_0}) - v' \varkappa(\lambda) \Omega_{t_{i_0}}(x) + \varpi(\lambda), \tag{6.12}$$

which since  $A\varkappa(z) + \varpi(z)$  is minimized at  $z = A$  implies

$$\begin{aligned} \sup_{z \geq n^{-1}} \left( H^*(x, t_{i_0}) + v' \varkappa(z) \Omega_{t_{i_0}}(x) - \varpi(z) \right) \\ \leq H_{r+1}(x, t_{i_0}) \leq \inf_{z \geq n^{-1}} \left( H^*(x, t_{i_0}) + v' \varkappa(z) \Omega_{t_{i_0}}(x) - \varpi(z) \right). \end{aligned} \tag{6.13}$$

We will then deduce that the event  $\mathcal{E}_{r+1}^{(3)}(i_0)$  likely holds by taking a union bound over  $x$ .

To implement this, first observe that Assumption 5.7 applies, with the parameters

$$(\varepsilon, \mathfrak{S}, \delta; \mathfrak{D}, D; \mathfrak{s}; t_1, t_2; \tilde{h}, \tilde{H}; \xi_1, \xi_2; \zeta_1, \zeta_2; \mu),$$

there equal to

$$\left( \varepsilon_0, \left(\frac{\varepsilon_0}{20}\right)^{m+1}, \frac{\delta}{4}; \mathfrak{R}_j, \mathfrak{R}_j; t_{i_0}; t_i, t_{i'}; h_r, H_{r+1}; v_i \varkappa(\lambda), v_{i'} \varkappa(\lambda); v_i n^{\delta/240-2/3}, v_{i'} n^{\delta/240-2/3}; \varpi(\lambda) \right), \tag{6.14}$$

here, where we recall that  $\lambda = -v' \Omega_{t_{i_0}}(x) \geq n^{-1}$ . The verification that this assumption holds is very similar to that in the previous setting, except that the  $(\xi; \mu)$ -tiltedness condition now follows from the fact that we restricted to the event  $\mathcal{E}_r^{(3)}(i) \cap \mathcal{E}_r^{(3)}(i') \subseteq \mathcal{A}_r$ . To verify that the parameters (6.14) satisfy the inequalities stipulated in Proposition 5.9, let  $d = \min \{|x - x'| : (x', t_{i_0}) \in \mathfrak{A}\}$ ; then Remark 5.3 implies the existence of a constant  $c = c(\mathfrak{B}) > 0$  such that  $cd^{1/2} < \lambda < c^{-1}d^{1/2}$ . Under our choice Equation (6.11) of  $\lambda$  and the definitions (6.4) of  $\varkappa$  and  $\varpi$ , we have

$$\varkappa(\lambda) \geq cn^{\delta/12-1} d^{-1/2} \geq n^{\delta/16-2/3} d^{-1/2}; \quad \varkappa(\lambda) \leq c^{-1} n^{\delta/12-1} d^{-1/2} \leq n^{-2/3},$$

where in the second inequality we used the fact that  $d \geq n^{\delta/4-2/3}$ , since  $(x, t_{i_0}) \in \mathfrak{Q}_-^{\delta/4}$ .

Thus, we may apply Proposition 5.9 to deduce that  $H_{r+1}$  is  $(v' \varkappa(\lambda), \varpi(\lambda))$ -tilted at  $(x, t_{i_0})$  with overwhelming probability, where  $v'$  is given by Equation (6.10). This implies with overwhelming probability that Equation (6.12) holds, which as mentioned above yields Equation (6.13) with overwhelming probability. This applies to a single  $x$ , so from a union bound, it follows that Equation (6.13) holds

simultaneously for all  $x \in n^{-2}\mathbb{Z}$  such that  $(x, t_{i_0}) \in \mathcal{Q}_-^{\delta/4}$ . From the 1-Lipschitz property of  $H_{r+1}$ , we deduce with overwhelming probability that, for all  $x \in \mathbb{R}$  such that  $(x, t_{i_0}) \in \mathcal{Q}_-^{\delta/4}$ , we have

$$\begin{aligned} \sup_{z \geq n^{-1}} \left( H^*(x, t_{i_0}) + v' \kappa(z) \Omega_{t_{i_0}}(x) - \varpi(z) - n^{-2} \right) \\ \leq H_{r+1}(x, t_{i_0}) \leq \inf_{z \geq n^{-1}} \left( H^*(x, t_{i_0}) + v' \kappa(z) \Omega_{t_{i_0}}(x) - \varpi(z) + n^{-2} \right). \end{aligned}$$

Using the fact (6.10) that  $v' < v_{i_0}$  and that  $\Omega_{t_{i_0}}(x) \geq n^{-1}$  for  $(x, t_{i_0}) \in \mathcal{Q}_-^{\delta/4}$ , it follows that  $\mathcal{E}_{r+1}^{(3)}(i_0)$  holds with overwhelming probability.

This shows that the event  $\mathcal{E}_r^{(1)}(i_0) \cap \mathcal{E}_r^{(2)}(i_0) \cap \mathcal{E}_r^{(3)}(i_0)$  holds with overwhelming probability, for any index  $0 \leq i_0 \leq m$ . By a union bound, we deduce that the event  $\mathcal{E}_r$  (from Equation (6.7)) holds with overwhelming probability. So, it remains to show that  $\mathcal{F}_r$  does as well.

This will follow from an application of Theorem 4.3; let us verify that  $(h, H^*; h_r; \mathfrak{R}_j, \mathfrak{R}_j)$  satisfies the constraints on  $(h, H^*; h; \mathfrak{D}, \mathfrak{D})$  listed in Assumption 4.1 and Assumption 4.2. First, observe, if  $u_j \in \partial_{\text{no}}(\mathfrak{R}_j)$  is a tangency location for  $\mathfrak{A}$ , then  $\partial_{\text{no}}(\mathfrak{R}_j) \subset \partial\mathfrak{P}$ . Thus,  $H_{r+1}(nv) = nh(v)$ , and  $\partial_{\text{no}}(\mathfrak{R}_j)$  is packed with respect to  $h$ . Otherwise,  $\mathfrak{Q}$  extends beyond  $\partial_{\text{no}}(\mathfrak{R}_j)$  and  $\partial_{\text{so}}(\mathfrak{R}_j)$ , and so  $H^*$  admits an extension beyond the north and south boundaries of  $\mathfrak{R}_j$ . This shows that  $\mathfrak{R}_j$  satisfies the second condition on  $\mathfrak{D}$  in Assumption 4.1. The first, third and fourth follow from the adaptedness of  $\mathfrak{R}_j$  to  $H^*$ ; the fifth follows from taking the  $(\mathfrak{P}, 1)$  there equal to  $(\mathfrak{P}, 1)$  here.

To verify that it satisfies Assumption 4.2, observe by Equation (6.8), the fact that  $\partial_{\text{ea}}(\mathfrak{R}_j)$  and  $\partial_{\text{we}}(\mathfrak{R}_j)$  are either subsets of  $\partial\mathfrak{P}$  or bounded away from  $\bar{\mathfrak{V}}$  gives  $H_r = H^*$  along  $\partial_{\text{ea}}(\mathfrak{R}_j) \cup \partial_{\text{we}}(\mathfrak{R}_j)$ . In particular,  $h_r(nv) = nh_r(v) = nh(v)$  for each  $v \in \partial_{\text{ea}}(\mathfrak{R}_j) \cup \partial_{\text{we}}(\mathfrak{R}_j)$ . Since  $\mathfrak{R}_j$  is adapted to  $H^*$ ,  $h$  is constant both  $\partial_{\text{ea}}(\mathfrak{R}_j)$  and  $\partial_{\text{we}}(\mathfrak{R}_j)$ . Further, observe since we have restricted to  $\mathcal{E}_r^{(1)}(i) \cap \mathcal{E}_r^{(1)}(i')$  that the edge of  $H_r$  is  $n^{\delta/240-2/3}$ -tilted with respect to  $H^*$ . This implies that  $h_r(nv) = nh_r(v) = nh(v)$  for any  $v \notin \mathfrak{Q}$  and  $\text{dist}(v, \mathfrak{A}) \geq \mathcal{O}(n^{\delta/200-2/3})$ . In particular, this holds for any  $v \notin \mathcal{Q}_+^{\delta/2}$ , thereby verifying the second property listed in Assumption 4.2.

It remains to verify the first one, namely that  $|h_r(nv) - nh(nv)| \leq n^{\delta/2}$  for each  $v \in \partial\mathfrak{R}_j$ . This is already implied by the second property for  $v \in \partial_{\text{ea}}(\mathfrak{R}_j) \cup \partial_{\text{we}}(\mathfrak{R}_j)$ , so we must show it for  $v \in \partial_{\text{no}}(\mathfrak{R}_j) \cup \partial_{\text{so}}(\mathfrak{R}_j)$ . We only consider  $v \in \partial_{\text{so}}(\mathfrak{R}_j)$  since the case when  $v \in \partial_{\text{no}}(\mathfrak{R}_j)$  is entirely analogous. To that end, observe since since we restricted to the event  $\mathcal{E}_r^{(3)}(i)$  that

$$\sup_{z \geq n^{-1}} \left( H^*(x, t_i) + v_i \kappa(z) \Omega_{t_i}(x) - \varpi(z) \right) \leq H_r(x, t_i) \leq \inf_{z \geq n^{-1}} \left( H^*(x, t_i) - v_i \kappa(z) \Omega_{t_i}(x) + \varpi(z) \right),$$

holds for each  $(x, t_i) \in \mathcal{Q}_-^{\delta/4}$ . In particular, we may take  $z = -\Omega_{t_i}(x) \geq n^{-1}$ , which by (6.4) gives

$$|H_r(x, t_i) - H^*(x, t_i)| \leq n^{\delta/12-1} + n^{\delta/12-1} \log n \leq 2n^{\delta/12-1} \log n \leq n^{\delta/2-1},$$

for any  $(x, t_i) \in \partial_{\text{so}}(\mathfrak{R}_j)$ . This yields the first property listed in Assumption 4.2 so that assumption holds. In particular, Theorem 4.3 applies (with the  $(h, H)$  there equal to  $(h_r, H_{r+1})$  here), implying that  $\mathcal{F}_{r+1}$  holds with overwhelming probability. Hence,  $\mathcal{E}_{r+1} \cap \mathcal{F}_{r+1} = \mathcal{A}_{r+1}$  holds with overwhelming probability upon restricting to  $\mathcal{A}_r$ , thereby establishing the proposition if  $\mathfrak{R}_j$  is of the first or second type listed in Section 6.1.

It remains to consider the case when  $\mathfrak{R}_j = \mathfrak{R}(u_j)$  is of the third type listed in Section 6.1, that is, when  $u_j$  is a horizontal tangency location of  $\mathfrak{A}$  that does not lie on  $\partial\mathfrak{P}$ . Then,  $\mathfrak{R}_j = \mathfrak{D}_1 \cup \mathfrak{D}_2$  for two trapezoids  $\mathfrak{D}_1 = \mathfrak{D}_1(u_j)$  and  $\mathfrak{D}_2(u_j)$  that contain  $u_j$  in the interiors of their south and north boundaries, respectively; set  $\mathfrak{D}_1 = n\mathfrak{D}_1 \subset \mathbb{T}$  and  $\mathfrak{D}_2 = n\mathfrak{D}_2 \subset \mathbb{T}$ . Either  $\mathfrak{D}_1$  or  $\mathfrak{D}_2$  is disjoint with  $\mathfrak{Q}$ ; let us assume the former is, as the proof in the alternative case is entirely analogous.

Then, the top three boundaries  $\partial_{\text{no}}(\mathfrak{D}_1) \cup \partial_{\text{ea}}(\mathfrak{D}_1) \cup \partial_{\text{ea}}(\mathfrak{D}_1)$  of  $\mathfrak{D}_1$  are bounded away from  $\bar{\mathfrak{D}}$ . By Equation (6.8), this yields  $h_r(v) = H^*(v)$  for any  $v \in \partial_{\text{no}}(\mathfrak{D}) \cup \partial_{\text{ea}}(\mathfrak{D}) \cup \partial_{\text{we}}(\mathfrak{D})$ . Moreover  $\nabla H^*$  is

constant,<sup>13</sup> and an element of  $\{(0, 0), (1, 0), (1, -1)\}$ , along  $\partial_{\text{no}}(\mathfrak{D}) \cup \partial_{\text{ea}}(\mathfrak{D}) \cup \partial_{\text{we}}(\mathfrak{D})$ . Hence, the same holds for  $\nabla H_r$ , from which it follows that there is only one height function on  $\mathfrak{D}_1$  with boundary data  $H_r|_{\mathfrak{D}_1}$ . Hence,  $H_{r+1}(nv) = nH^*(v) = H_r(nv)$ , for each  $v \in \mathfrak{D}_1$ . The inequalities (6.2), (6.5) and (6.6) hold deterministically inside  $\mathfrak{D}_1$ .

Furthermore, the fact that  $H_r(nv) = nH^*(v)$  for  $v \in \mathfrak{D}_1$  implies that the  $\partial_{\text{so}}(\mathfrak{D}_1)$  is packed with respect to  $h_r$ ; thus, the same statement holds for  $\partial_{\text{no}}(\mathfrak{D}_2)$ . Therefore, the same reasoning as applied above in the second case for  $\mathfrak{R}_j$  listed in Section 6.1 (when  $u$  is a horizontal tangency location of  $\mathfrak{A}$  that lies on  $\partial\mathfrak{B}$ ) applies to show that the inequalities (6.2), (6.5) and (6.6) hold with overwhelming probability inside  $\mathfrak{D}_2$ . It follows that these inequalities hold with overwhelming probability on  $\mathfrak{D}_1 \cup \mathfrak{D}_2 = \mathfrak{R}_j$ . This implies that  $\mathcal{A}_{r+1}$  holds with overwhelming probability, which yields the proposition.  $\square$

### 7. Existence of tilted height functions

In this section, we establish Proposition 5.4. Instead of directly producing the tilted height function  $\widehat{H}^*$  as described there, we first in Section 7.1 define its complex slope as a solution to Equation (3.3), with the function  $Q_0$  there modified in an explicit way. In Section 7.2, we solve this equation perturbatively and compare its solution to the original one. We then define the tilted height function from its complex slope using Equation (3.1) and establish Proposition 5.4 in Section 7.3.

#### 7.1. Modifying $Q$

In this section, we introduce a function  $\mathcal{F}_t(x; \alpha_0)$  that will eventually be the complex slope for our tilted height profile. Throughout this section, we adopt the notation from Proposition 5.4, recalling in particular the complex slope  $f_t(x)$  associated with  $H^*$ , defined for  $(x, t) \in \mathfrak{L}(\mathfrak{B})$ . We denote the liquid region inside  $\mathfrak{D}$  as  $\mathfrak{L} = \mathfrak{D} \cap \mathfrak{L}(\mathfrak{B})$ .

The function  $\mathcal{F}_t(x; \alpha_0)$  may be interpreted as the solution to the complex Burgers equation

$$\partial_t \mathcal{F}_t(x; \alpha_0) + \partial_x \mathcal{F}_t(x; \alpha_0) \frac{\mathcal{F}_t(x; \alpha_0)}{\mathcal{F}_t(x; \alpha_0) + 1} = 0, \quad \text{with initial data } \mathcal{F}_0(x; \alpha_0) = \alpha_0 f_{t_0}(x), \quad (7.1)$$

for suitable real numbers  $\alpha_0 = 1 + \mathcal{O}(|\xi_1 + \xi_2|)$  and  $t_0$ ; stated alternatively, we first time-shift the solution  $f_t(x)$  of Equation (3.2) by  $t_0$  and then multiply its initial data by a ‘drift’  $\alpha_0$ . However, making this precise would involve justifying the existence and uniqueness of a solution to Equation (7.1). To circumvent this, we instead define  $\mathcal{F}_t(x; \alpha_0)$  as the solution to an ‘ $\alpha_0$ -deformation’ of Equation (7.7).

To implement this, we define real numbers  $t_0$  and  $\alpha_0$  by

$$t_0 = \frac{\xi_2 t_1 - \xi_1 t_2}{\xi_2 - \xi_1}; \quad \alpha_0 = \frac{\xi_2 - \xi_1}{t_2 - t_1} + 1 = \frac{\xi_1}{t_1 - t_0} + 1 = \frac{\xi_2}{t_2 - t_0} + 1 \quad (7.2)$$

so that  $\alpha_0 = 1 + \mathcal{O}(|\xi_1 + \xi_2|)$ . We next introduce a time-shifted variant of  $f_t(x)$  given by

$$\mathcal{F}_s(x; 1) = f_{s+t_0}(x), \quad \text{whenever } (x, s + t_0) \in \overline{\mathfrak{L}}. \quad (7.3)$$

Although the complex slope for the tilted height function  $\widehat{H}^*$  from Proposition 5.4 will eventually be related to an  $\alpha_0$ -deformation of  $\mathcal{F}_s(x; 1)$  with  $\alpha_0$  given explicitly by Equation (7.2), it will be useful to define this deformation (denoted by  $\mathcal{F}_t(x; \alpha)$ ) for any  $\alpha \in \mathbb{R}$  with  $|\alpha - 1|$  sufficiently small. To that end, recalling the rational function  $Q : \mathbb{C}^2 \rightarrow \mathbb{C}$  satisfying Equation (3.4) with respect to  $f_t$ , we also define its time-shift  $\mathcal{Q}_1$  and  $\alpha$ -deformation  $\mathcal{Q}_\alpha$ , for any  $\alpha \in \mathbb{R}$  by

$$\mathcal{Q}_1(u, v) = Q\left(u, v - \frac{t_0 u}{u + 1}\right); \quad \mathcal{Q}_\alpha(u, v) = \frac{u + 1}{\alpha^{-1} u + 1} \mathcal{Q}_1(\alpha^{-1} u, v),$$

<sup>13</sup>This holds since  $\mathfrak{A}$  has no singularities that are simultaneously cusps and tangency locations; recall Assumption 2.8.

observing in particular that Equations (3.4) and (7.3) together imply

$$\mathcal{Q}_1 \left( \mathcal{F}_t(x; 1), x - \frac{t\mathcal{F}_t(x; 1)}{\mathcal{F}_t(x; 1) + 1} \right) = 0. \tag{7.4}$$

If  $|\alpha - 1|$  is sufficiently small (in a way only dependent on  $\mathfrak{F}$ ), this implies the existence of an analytic function  $\mathcal{F}_t(x; \alpha)$ , defined for  $(x, t + t_0)$  in an open subset of  $\mathfrak{L}$ , that is continuous in  $\alpha$  and satisfies

$$\mathcal{Q}_\alpha \left( \mathcal{F}_t(x; \alpha), x - \frac{t\mathcal{F}_t(x; \alpha)}{\mathcal{F}_t(x; \alpha) + 1} \right) = 0. \tag{7.5}$$

For example, recall from the third part of Proposition 3.3 that there exists a real analytic function  $\mathcal{Q}_{0,1}$ , locally defined around any solution of Equation (7.4) (obtained by solving Equation (7.4)) such that

$$\mathcal{Q}_{0,1}(\mathcal{F}_t(x; 1)) = x(\mathcal{F}_t(x; 1) + 1) - t\mathcal{F}_t(x; 1).$$

Then, we may set

$$\mathcal{Q}_{0,\alpha}(u) = \frac{u + 1}{\alpha^{-1}u + 1} \mathcal{Q}_{0,1}(\alpha^{-1}u), \tag{7.6}$$

for  $u$  in the domain of  $\mathcal{Q}_{0,1}$  and let  $\mathcal{F}_t(x; \alpha)$  denote the root of

$$\mathcal{Q}_{0,\alpha}(\mathcal{F}_t(x; \alpha)) = x(\mathcal{F}_t(x; \alpha) + 1) - t\mathcal{F}_t(x; \alpha), \tag{7.7}$$

chosen so that it is continuous in  $\alpha$ ; it is directly verified that it satisfies Equation (7.5). Such a root is well defined on a nonempty open subset of  $\mathfrak{L}$  that contains no double root of Equation (7.5) or equivalently of Equation (7.7) (such a subset exists for  $|\alpha - 1|$  sufficiently small). Since any double root of Equation (7.5) is real, we may extend  $\mathcal{F}_t(x; \alpha)$  to the  $\alpha$ -deformed liquid region  $\mathfrak{L}_\alpha$  and its arctic curve  $\mathfrak{A}_\alpha$ , defined by

$$\begin{aligned} \mathfrak{L}_\alpha &= \{(x, t) \in \mathbb{R}^2 : (x, t + t_0) \in \mathfrak{D}, \mathcal{F}_t(x; \alpha) \in \mathbb{H}^-\}; \\ \mathfrak{A}_\alpha &= \{(x, t) \in \partial\mathfrak{L}_\alpha : \mathcal{F}_t(x; \alpha) \in \mathbb{R}\}, \end{aligned}$$

where we observe for  $|\alpha - 1|$  sufficiently small that  $\mathfrak{L}_\alpha$  is simply connected since  $\mathfrak{L}$  (and thus  $\mathfrak{L}_1$ ) is.

We next have the below lemma that, given a solution of an equation of the type (7.7), evaluates its derivatives with respect to  $x$  and  $t$ , and shows that it satisfies the complex Burgers equation. Its proof essentially follows from a Taylor expansion and will be provided in Appendix A below.

**Lemma 7.1.** *Fix  $(x_0, t_0) \in \mathbb{R}^2$ ; let  $\mathcal{F}_t(x)$  denote a function that is real analytic in a neighborhood of  $(x_0, t_0)$ , and let  $\mathcal{Q}_0$  denote a function that is real analytic in a neighborhood of  $\mathcal{F}_{t_0}(x_0)$ . Assume in a neighborhood of  $(x_0, t_0)$  that*

$$\mathcal{Q}_0(\mathcal{F}_t(x)) = x(\mathcal{F}_t(x) + 1) - t\mathcal{F}_t(x). \tag{7.8}$$

Then for all  $(x, t)$  in a neighborhood of  $(x_0, t_0)$  we have

$$\partial_x \mathcal{F}_t(x) = \frac{\mathcal{F}_t(x) + 1}{\mathcal{Q}'_0(\mathcal{F}_t(x)) - x + t}; \quad \partial_t \mathcal{F}_t(x) = -\frac{\mathcal{F}_t(x)}{\mathcal{Q}'_0(\mathcal{F}_t(x)) - x + t}, \tag{7.9}$$

and in particular

$$\partial_t \mathcal{F}_t(x) + \partial_x \mathcal{F}_t(x) \frac{\mathcal{F}_t(x)}{\mathcal{F}_t(x) + 1} = 0. \tag{7.10}$$

7.2. Comparison between  $\mathcal{F}_t(x; \alpha)$  and  $\mathcal{F}_t(x; 1)$

In this section, we provide two estimates comparing  $\mathcal{F}_t(x; \alpha)$  and  $\mathcal{F}_t(x; 1)$ . The first (given by Lemma 7.2 below) compares their logarithms, where in what follows, we take the branch of the logarithm to be so that  $\text{Im} \log u \in [-\pi, \pi)$ . The second (given by Lemma 7.3 below) compares the endpoints of their arctic boundaries. These results will eventually be the sources of the quantities  $\Omega$  and  $\Upsilon$  from Equation (5.1).

**Lemma 7.2.** *Suppose  $|\alpha - 1|$  is sufficiently small, and  $v = (x, t) \in \mathfrak{L}_1 \cap \mathcal{L}_\alpha$  is any point bounded away from a cusp or tangency location of  $\mathfrak{A}_1$ . Setting  $d = \text{dist}(v, \mathfrak{A}_1)$ , we have the following estimates, where the implicit constants in the error below only depend on the first three derivatives of  $\mathcal{Q}_{0;1}$  at  $\mathcal{F}_t(x; 1)$ .*

1. If  $d \geq |\alpha - 1|$ , then

$$\log \mathcal{F}_t(x; \alpha) - \log \alpha - \log \mathcal{F}_t(x; 1) = t(1 - \alpha) \partial_x \left( \frac{\mathcal{F}_t(x; 1)}{\mathcal{F}_t(x; 1) + 1} \right) \left( 1 + \mathcal{O}(d^{-1}|\alpha - 1| + |\alpha - 1|^{1/2}) \right).$$

2. For any  $d > 0$ , we have  $|\log \mathcal{F}_t(x; \alpha) - \log \alpha - \log \mathcal{F}_t(x; 1)| = \mathcal{O}(|\alpha - 1|^{1/2})$ .

*Proof.* Letting  $\mathcal{F} = \mathcal{F}_t(x; 1)$  and  $\mathcal{F}' = \mathcal{F}_t(x; \alpha)$ , we have by Equation (7.7) that

$$\mathcal{Q}_{0;1}(\mathcal{F}) = x(\mathcal{F} + 1) - t\mathcal{F}; \quad \mathcal{Q}_{0;\alpha}(\mathcal{F}') = x(\mathcal{F}' + 1) - t\mathcal{F}'. \tag{7.11}$$

Next, Equation (7.6) implies for  $(u, x - tu/(u + 1))$  in a neighborhood of  $(\mathcal{F}', x - t\mathcal{F}'/(\mathcal{F}' + 1))$  that

$$\mathcal{Q}_{0;\alpha}(u) = \frac{u + 1}{\alpha^{-1}u + 1} \mathcal{Q}_{0;1}(\alpha^{-1}u).$$

Letting  $\tilde{\mathcal{F}} = \alpha^{-1}\mathcal{F}'$ , we deduce from the second statement of Equation (7.11) that

$$\mathcal{Q}_{0;1}(\tilde{\mathcal{F}}) + \frac{(\alpha - 1)\tilde{\mathcal{F}}}{\tilde{\mathcal{F}} + 1} \mathcal{Q}_{0;1}(\tilde{\mathcal{F}}) = \mathcal{Q}_{0;\alpha}(\mathcal{F}') = x(\tilde{\mathcal{F}} + 1) - t\tilde{\mathcal{F}} + (\alpha - 1)(x - t)\tilde{\mathcal{F}}.$$

Together with the first statement of Equation (7.11), this gives

$$\mathcal{Q}_{0;1}(\tilde{\mathcal{F}}) - \mathcal{Q}_{0;1}(\mathcal{F}) = (\tilde{\mathcal{F}} - \mathcal{F})(x - t) + \frac{(1 - \alpha)\tilde{\mathcal{F}}}{\tilde{\mathcal{F}} + 1} \mathcal{Q}_{0;1}(\tilde{\mathcal{F}}) + (\alpha - 1)(x - t)\tilde{\mathcal{F}}. \tag{7.12}$$

By a Taylor expansion, we have

$$\mathcal{Q}_{0;1}(\tilde{\mathcal{F}}) - \mathcal{Q}_{0;1}(\mathcal{F}) = (\tilde{\mathcal{F}} - \mathcal{F})\mathcal{Q}'_{0;1}(\mathcal{F}) + \frac{1}{2}(\tilde{\mathcal{F}} - \mathcal{F})^2\mathcal{Q}''_{0;1}(\mathcal{F}) + \mathcal{O}(|\tilde{\mathcal{F}} - \mathcal{F}|^3),$$

and which by Equation (7.12) implies, since  $\mathcal{F}$  is bounded away from  $\{-1, 0, \infty\}$  (as  $(x, t)$  is bounded away from a tangency location of  $\mathfrak{A}_1$ ), that

$$\begin{aligned} & (\tilde{\mathcal{F}} - \mathcal{F})(\mathcal{Q}'_{0;1}(\mathcal{F}) - x + t) + \frac{1}{2}(\tilde{\mathcal{F}} - \mathcal{F})^2\mathcal{Q}''_{0;1}(\mathcal{F}) \\ &= (\alpha - 1) \left( (x - t)\mathcal{F} - \frac{\mathcal{F}}{\mathcal{F} + 1} \mathcal{Q}_{0;1}(\mathcal{F}) \right) + \mathcal{O}(|\alpha - 1||\tilde{\mathcal{F}} - \mathcal{F}| + |\tilde{\mathcal{F}} - \mathcal{F}|^3) \\ &= \frac{(1 - \alpha)t\mathcal{F}}{\mathcal{F} + 1} + \mathcal{O}(|\alpha - 1||\tilde{\mathcal{F}} - \mathcal{F}| + |\tilde{\mathcal{F}} - \mathcal{F}|^3), \end{aligned} \tag{7.13}$$

where to deduce the last equality we used the first statement of Equation (7.11).

Now, if  $d < \delta$  for some  $\delta = \delta(\mathfrak{B}) > 0$ , then  $\mathcal{Q}''_{0;1}(\mathcal{F})$  is bounded away from 0 since  $(x, t)$  is bounded away from a cusp of  $\mathfrak{A}_1$ , so Equation (7.13) implies  $|\tilde{\mathcal{F}} - \mathcal{F}| = \mathcal{O}(|\alpha - 1|^{1/2})$ . If instead  $d \geq \delta$ , then

$\text{Im } \mathcal{Q}'_{0;1}(\mathcal{F})$  is bounded away from 0, which implies that  $|\widetilde{\mathcal{F}} - \mathcal{F}| = \mathcal{O}(|\alpha - 1|)$ . In either case, this gives  $|\widetilde{\mathcal{F}} - \mathcal{F}| = \mathcal{O}(|\alpha - 1|^{1/2})$ , which verifies the second statement of the lemma.

Next, observe from the first statement of Equation (7.9) that

$$\frac{1}{\mathcal{Q}'_{0;1}(\mathcal{F}) - x + t} = \frac{\partial_x \mathcal{F}}{\mathcal{F} + 1}. \tag{7.14}$$

By the square root decay of  $\mathcal{F}_t(x)$  as  $(x, t)$  nears  $\mathfrak{A}_1$  (see Remark A.2 below), there exist constants  $c = c(\mathfrak{B}) > 0$  and  $C = C(\mathfrak{B}) > 1$  such that  $cd^{-1/2} < \partial_x \mathcal{F}_t(x; 1) < Cd^{-1/2}$ . After decreasing  $c$  and increasing  $C$  if necessary, Equation (7.14) then implies

$$cd^{1/2} < \mathcal{Q}'_{0;1}(\mathcal{F}) - x + t < Cd^{1/2}.$$

This, together with Equation (7.13), the bound  $|\widetilde{\mathcal{F}} - \mathcal{F}| = \mathcal{O}(|\alpha - 1|^{1/2})$  and the fact that  $\mathcal{Q}''_{0;1}(\mathcal{F})$  is bounded away from 0 for  $(x, t)$  sufficiently close to  $\mathfrak{A}_1$  quickly gives for  $d \geq |\alpha - 1|$  that

$$\frac{\widetilde{\mathcal{F}} - \mathcal{F}}{\mathcal{F}} = t(1 - \alpha) \frac{\partial_x \mathcal{F}}{(\mathcal{F} + 1)^2} \left( 1 + \mathcal{O}(d^{-1}|\alpha - 1| + |\alpha - 1|^{1/2}) \right).$$

It follows that

$$\begin{aligned} \log \left( \frac{\widetilde{\mathcal{F}}}{\mathcal{F}} \right) &= \frac{\widetilde{\mathcal{F}}}{\mathcal{F}} - 1 + \mathcal{O}((\widetilde{\mathcal{F}} - \mathcal{F})^2) \\ &= t(1 - \alpha) \left( \frac{\partial_x \mathcal{F}_t(x; 1)}{(\mathcal{F}_t(x; 1) + 1)^2} \right) \left( 1 + \mathcal{O}(d^{-1}|\alpha - 1| + |\alpha - 1|^{1/2}) \right), \end{aligned}$$

which implies the first statement of the lemma. □

Next, we show that if no cusp or tangency location of  $\mathfrak{A}_1$  is of the form  $(x, t)$  with  $x \in \mathbb{R}$ , then the time slices  $\{x : (x, t) \in \mathfrak{L}_1\}$  and  $\{x : (x, t) \in \mathfrak{L}_\alpha\}$  contain the same number of intervals; we also estimate the distance between their endpoints.

**Lemma 7.3.** *The following holds for  $|\alpha - 1|$  sufficiently small.*

- (1) *Let  $(x_0, t) \in \mathfrak{A}_1$  denote a right (or left) boundary point of  $\mathfrak{A}_1$ , bounded away from a cusp or horizontal tangency location of  $\mathfrak{A}_1$ . Then, there exists  $(x'_0, t) \in \mathfrak{A}_\alpha$ , which is a right (or left, respectively) boundary point of  $\mathfrak{A}_\alpha$  so that*

$$x'_0 - x_0 = t(\alpha - 1) \frac{\mathcal{F}_t(x_0)}{(\mathcal{F}_t(x_0) + 1)^2} + \mathcal{O}(|\alpha - 1|^2). \tag{7.15}$$

- (2) *Fix  $t \in \mathbb{R}$ ; suppose that  $\{x : (x, t) \in \mathfrak{L}_1\}$  is a union of  $k \geq 1$  disjoint open intervals  $(x_1, x'_1) \cup (x_2, x'_2) \cup \dots \cup (x_k, x'_k)$ , and that it is bounded away from a cusp or horizontal tangency location of  $\mathfrak{A}_1$ . Then,  $\{x : (x, t) \in \mathfrak{L}_\alpha\}$  is also a union of  $k$  disjoint open intervals  $(\widehat{x}_1, \widehat{x}'_1) \cup (\widehat{x}_2, \widehat{x}'_2) \cup \dots \cup (\widehat{x}_k, \widehat{x}'_k)$ . Moreover, for any index  $j \in [1, k]$ , we have*

$$\begin{aligned} \widehat{x}_j - x_j &= t(\alpha - 1) \frac{\mathcal{F}_t(x_j)}{(\mathcal{F}_t(x_j) + 1)^2} + \mathcal{O}(|\alpha - 1|^2) \\ \widehat{x}'_j - x'_j &= t(\alpha - 1) \frac{\mathcal{F}_t(x'_j)}{(\mathcal{F}_t(x'_j) + 1)^2} + \mathcal{O}(|\alpha - 1|^2). \end{aligned} \tag{7.16}$$



*Proof.* For the first statement, we will only prove the case that  $(x_0, t)$  is a left boundary point of  $\mathfrak{A}_1$ , as the proof of the case that it is a right boundary point is entirely analogous. Observe by the second and third parts of Proposition 3.3 that  $(x, t) \in \mathfrak{A}_\alpha$  if and only if

$$\mathcal{Q}_{0,\alpha}(\mathcal{F}_t(x; \alpha)) = x(\mathcal{F}_t(x; \alpha) + 1) - t\mathcal{F}_t(x; \alpha); \quad \mathcal{Q}'_{0,\alpha}(\mathcal{F}_t(x; \alpha)) = x - t,$$

that is, if and only if

$$\mathcal{Q}_{0,\alpha}(\mathcal{F}_t(x; \alpha)) = (\mathcal{F}_t(x; \alpha) + 1)\mathcal{Q}'_{0,\alpha}(\mathcal{F}_t(x; \alpha)) + t; \quad x = \mathcal{Q}'_{0,\alpha}(\mathcal{F}_t(x; \alpha)) + t. \tag{7.17}$$

In particular, Equation (7.17) holds if  $(x, \alpha) = (x_0, 1)$ . Let us produce a solution to Equation (7.17) for  $\alpha$  close to 1 by perturbing around  $x_0$ . To that end, abbreviate  $\mathcal{F} = \mathcal{F}(x_0; 1)$ , let  $x$  be close to  $x_0$  and abbreviate  $\mathcal{F}' = \mathcal{F}(x; \alpha)$ . Then recall from the first statement of Equations (7.7) and (7.6) that for  $|\alpha - 1|$  sufficiently small and  $(u, x - tu/(u + 1))$  in a neighborhood of  $(\mathcal{F}, x - t\mathcal{F}/(\mathcal{F} + 1))$ , we have

$$\mathcal{Q}_{0,\alpha}(u) = \frac{u + 1}{\alpha^{-1}u + 1} \mathcal{Q}_{0,1}(\alpha^{-1}u) = \alpha \mathcal{Q}_{0,1}(\alpha^{-1}u) + \frac{\alpha(1 - \alpha)}{u + \alpha} \mathcal{Q}_{0,1}(\alpha^{-1}u)$$

so that

$$\mathcal{Q}'_{0,\alpha}(u) = \mathcal{Q}'_{0,1}(\alpha^{-1}u) + \frac{\alpha - 1}{u + \alpha} \left( \frac{\alpha}{u + \alpha} \mathcal{Q}_{0,1}(\alpha^{-1}u) - \mathcal{Q}'_{0,1}(\alpha^{-1}u) \right). \tag{7.18}$$

Thus, denoting  $\tilde{\mathcal{F}} = \alpha^{-1}\mathcal{F}'$ , the first statement of Equation (7.17) holds if and only if

$$\frac{\alpha\tilde{\mathcal{F}} + 1}{\tilde{\mathcal{F}} + 1} \mathcal{Q}_{0,1}(\tilde{\mathcal{F}}) = (\alpha\tilde{\mathcal{F}} + 1) \left( \mathcal{Q}'_{0,1}(\tilde{\mathcal{F}}) + \frac{\alpha - 1}{\alpha\tilde{\mathcal{F}} + \alpha} \left( \frac{1}{\tilde{\mathcal{F}} + 1} \mathcal{Q}_{0,1}(\tilde{\mathcal{F}}) - \mathcal{Q}'_{0,1}(\tilde{\mathcal{F}}) \right) \right) + t.$$

This is equivalent to

$$\begin{aligned} \mathcal{Q}_{0,1}(\tilde{\mathcal{F}}) &= (\tilde{\mathcal{F}} + \alpha^{-1})\mathcal{Q}'_{0,1}(\tilde{\mathcal{F}}) + \frac{\alpha - 1}{\alpha\tilde{\mathcal{F}} + \alpha} \mathcal{Q}_{0,1}(\tilde{\mathcal{F}}) + \frac{t(\tilde{\mathcal{F}} + 1)}{\alpha\tilde{\mathcal{F}} + 1} \\ &= (\tilde{\mathcal{F}} + 1)\mathcal{Q}'_{0,1}(\tilde{\mathcal{F}}) + t + (\alpha - 1) \left( \frac{\mathcal{Q}_{0,1}(\tilde{\mathcal{F}})}{\alpha\tilde{\mathcal{F}} + \alpha} - \frac{t\tilde{\mathcal{F}}}{\alpha\tilde{\mathcal{F}} + 1} - \alpha^{-1}\mathcal{Q}'_{0,1}(\tilde{\mathcal{F}}) \right), \end{aligned}$$

which upon subtracting from the  $(x, \alpha) = (x_0, 1)$  case of Equation (7.17) is true if and only if

$$\begin{aligned} \mathcal{Q}_{0,1}(\mathcal{F}) - (\mathcal{F} + 1)\mathcal{Q}'_{0,1}(\mathcal{F}) - \mathcal{Q}_{0,1}(\tilde{\mathcal{F}}) - (\tilde{\mathcal{F}} + 1)\mathcal{Q}'_{0,1}(\tilde{\mathcal{F}}) \\ = (1 - \alpha) \left( \frac{\mathcal{Q}_{0,1}(\tilde{\mathcal{F}})}{\alpha\tilde{\mathcal{F}} + \alpha} - \frac{t\tilde{\mathcal{F}}}{\alpha\tilde{\mathcal{F}} + 1} - \alpha^{-1}\mathcal{Q}'_{0,1}(\tilde{\mathcal{F}}) \right). \end{aligned} \tag{7.19}$$

Now, observe that the derivative of  $\mathcal{Q}_{0,1}(z) - (z + 1)\mathcal{Q}'_{0,1}(z)$  is  $-(z + 1)\mathcal{Q}''_{0,1}(z)$ , which is bounded away from 0 for  $z = \mathcal{F}$  since  $(x, t)$  is bounded away from a horizontal tangency location or singularity of  $\mathfrak{A}$ . Hence, the implicit function theorem implies that, for  $|\alpha - 1|$  sufficiently small, Equation (7.19) admits a solution with  $|\tilde{\mathcal{F}} - \mathcal{F}| = \mathcal{O}(|\alpha - 1|)$ . Taylor expanding then gives

$$\begin{aligned} (\tilde{\mathcal{F}} - \mathcal{F})(\mathcal{F} + 1)\mathcal{Q}''_{0,1}(\mathcal{F}) &= \frac{1 - \alpha}{\mathcal{F} + 1} (\mathcal{Q}_{0,1}(\mathcal{F}) - (\mathcal{F} + 1)\mathcal{Q}'_{0,1}(\mathcal{F}) - t\mathcal{F}) + \mathcal{O}(|\alpha - 1|^2) \\ &= \frac{t(\alpha - 1)(\mathcal{F} - 1)}{\mathcal{F} + 1} + \mathcal{O}(|\alpha - 1|^2), \end{aligned} \tag{7.20}$$

where in the last equality we used the first statement of Equation (7.17). Inserting this into the second statement of Equation (7.17) and applying Equation (7.18) yields

$$\begin{aligned} x - x_0 &= \mathcal{Q}'_{0;\alpha}(\mathcal{F}') - \mathcal{Q}'_{0;1}(\mathcal{F}) \\ &= \mathcal{Q}'_{0;1}(\tilde{\mathcal{F}}) - \mathcal{Q}'_{0;1}(\mathcal{F}) + \frac{\alpha - 1}{\alpha\tilde{\mathcal{F}} + \alpha} \left( \frac{\mathcal{Q}_{0;1}(\tilde{\mathcal{F}})}{\tilde{\mathcal{F}} + 1} - \mathcal{Q}'_{0;1}(\tilde{\mathcal{F}}) \right) \\ &= (\tilde{\mathcal{F}} - \mathcal{F})\mathcal{Q}''_{0;1}(\mathcal{F}) + \frac{\alpha - 1}{\mathcal{F} + 1} \left( \frac{\mathcal{Q}_{0;1}(\mathcal{F})}{\mathcal{F} + 1} - \mathcal{Q}'_{0;1}(\mathcal{F}) \right) + \mathcal{O}(|\alpha - 1|^2) \\ &= \frac{t(\alpha - 1)\mathcal{F}}{(\mathcal{F} + 1)^2} + \mathcal{O}(|\alpha - 1|^2), \end{aligned}$$

where in the last equality we applied Equation (7.20) and first statement of Equation (7.17). Setting  $x'_0 = x$  implies the first statement of Equation (7.3).

The second statement of Lemma 7.3 that  $\{x : (x, t) \in \mathfrak{L}_\alpha\}$  is a union of  $k$  disjoint open intervals follows from the first statement and the fact that  $\mathcal{L}_\alpha$  is continuous in  $\alpha$ . The estimates (7.16) follow from Equation (7.15) and the assumption that  $\{x : (x, t) \in \mathfrak{L}_1\}$  is bounded away from a cusp or horizontal tangency location of  $\mathfrak{A}_1$ . □

### 7.3. Proof of Proposition 5.4

In this section, we establish Proposition 5.4; throughout, we recall the notation from that proposition and from Section 7.1. In particular,  $t_0$  and  $\alpha_0$  are given by Equation (7.2). We first define a height function  $H_\alpha$  from  $\mathcal{F}_t(x; \alpha)$  for  $\alpha \in \mathbb{R}$  with  $|\alpha - 1|$  sufficiently small, whose complex slope is given by  $\mathcal{F}_{t-t_0}(x; \alpha)$ . The eventual tilted height function  $\widehat{H}^* : \overline{\mathfrak{D}} \rightarrow \mathbb{R}$  given by Proposition 5.4 will be defined by setting  $\widehat{H}^* = H_{\alpha_0}$ .

To that end, first set  $H_\alpha(v_0) = H^*(v_0)$  for  $v_0 = (a(t_1), t_1)$  equal to the southwest corner of  $\partial\mathfrak{D}$ . To define  $H_\alpha$  on the remainder of  $\overline{\mathfrak{D}}$ , it suffices to fix its gradient almost everywhere. Similarly to in Equation (3.1), for any  $u = (x, s) \in \overline{\mathfrak{D}}$  such that  $(x, s - t_0) \in \mathfrak{L}_\alpha$ , define  $\nabla H_\alpha(u) = (\partial_x H_\alpha(u), \partial_t H_\alpha(u))$  by setting

$$\partial_x H_\alpha(u) = -\pi^{-1} \arg^* \mathcal{F}_{s-t_0}(x; \alpha); \quad \partial_t H_\alpha(u) = \pi^{-1} \arg^* (\mathcal{F}_{s-t_0}(x; \alpha) + 1), \tag{7.21}$$

where we observe that we are implementing the same shift by  $t_0$  as in Equation (7.3).

If instead  $u = (x, s) \in \overline{\mathfrak{D}}$  satisfies  $(x, s - t_0) \notin \mathfrak{L}_\alpha$ , then define  $\nabla H_\alpha(u)$  as follows.

- (1) For  $\alpha = 1$ , set  $\nabla H_\alpha(u) = \nabla H^*(u) \in \{(0, 0), (1, 0), (1, -1)\}$ .
- (2) For  $\alpha \neq 1$  with  $|\alpha - 1|$  sufficiently small, define  $\nabla H_\alpha(u)$  so that it remains among the three frozen slopes  $\{(0, 0), (1, 0), (1, -1)\}$  and is continuous in  $\alpha$  at almost every  $u \in \overline{\mathfrak{D}}$ .

For  $|\alpha - 1|$  sufficiently small, the existence of  $\nabla H_\alpha(u)$  satisfying these properties follows from the fact that  $\mathfrak{A}_\alpha$  deforms continuously in  $\alpha$  (by Lemma 7.3); alternatively, it can be viewed as a consequence of [ADPZ20, Remark 8.6]. This determines  $\nabla H_\alpha(u)$  for almost all  $u \in \overline{\mathfrak{D}}$ , fixing  $H_\alpha : \overline{\mathfrak{D}} \rightarrow \mathbb{R}$ .

We then define  $\widehat{H}^* : \overline{\mathfrak{D}} \rightarrow \mathbb{R}$  and  $\widehat{h} : \partial\mathfrak{D} \rightarrow \mathbb{R}$  by setting

$$\widehat{H}^* = H_{\alpha_0}; \quad \widehat{h} = \widehat{H}^*|_{\partial\mathfrak{D}}.$$

By Lemma 7.1, the complex slope  $\mathcal{F}_t(x; \alpha_0)$  associated with  $\widehat{H}^*$  satisfies the complex Burgers equation (3.2). We will later use [ADPZ20, Remark 8.6] or [ADPZ20, Theorem 8.3] to show that  $\widehat{H}^* \in \text{Adm}(\mathfrak{D}; \widehat{h})$  is a maximizer of  $\mathcal{E}$ .

Recalling the liquid region  $\widehat{\mathfrak{V}}$  associated with  $\widehat{H}^*$  from Proposition 5.4, observe that

$$\widehat{\mathfrak{V}} = \{u \in \overline{\mathfrak{D}} : u - (0, t_0) \in \mathfrak{L}_\alpha\}. \tag{7.22}$$

Given these points, we can now establish Proposition 5.4. In the below, we will frequently use the identity

$$(\alpha_0 - 1)(t - t_0) = \omega(t), \quad \text{for any } t \in \mathbb{R}, \tag{7.23}$$

which follows from Equations (5.2) and (7.2).

*Proof of Proposition 5.4.* We will verify that  $\widehat{H}^*$  satisfies the second, third, first and fourth statement of the proposition, in this order. Throughout this proof, we fix  $t \in \{t_1, s, t_2\}$ .

We first establish the second statement of the proposition. To show Equation (5.4), observe from the  $(t, \alpha) = (t - t_0, \alpha)$  case of the second statement of Lemma 7.3 that the time slice  $\{x : (x, t - t_0) \in \mathcal{L}_\alpha\}$  is also a union of  $k$  disjoint open intervals  $(\widehat{x}_1, \widehat{x}'_1) \cup (\widehat{x}_2, \widehat{x}'_2) \cup \dots \cup (\widehat{x}_k, \widehat{x}'_k)$ . Moreover, for any index  $1 \leq i \leq k$ , we have

$$\begin{aligned} \widehat{x}_i - x_i &= (t - t_0)(\alpha - 1) \frac{\mathcal{F}_{t-t_0}(x_i; 1)}{(\mathcal{F}_{t-t_0}(x_i; 1) + 1)^2} + \mathcal{O}(|\alpha - 1|^2) \\ &= (t - t_0)(\alpha - 1) \frac{f_t(x_i)}{(f_t(x_i) + 1)^2} + \mathcal{O}(|\alpha - 1|^2) = (t - t_0)(\alpha - 1) \Upsilon_t(x_i) + \mathcal{O}(|\alpha - 1|^2), \end{aligned} \tag{7.24}$$

where to deduce the second equality we used Equation (7.3) and to deduce the third we used the definition (5.1) of  $\Upsilon_t$ . Implementing similar reasoning for the difference of  $\widehat{x}'_i - x'_i$ , setting  $\alpha = \alpha_0$  in Equation (7.24), applying Equations (7.23) and (7.22) and using the fact that  $|\alpha_0 - 1| = \mathcal{O}(|\xi_1| + |\xi_2|)$ , we deduce Equation (5.4).

We next show  $\widehat{H}^*(u) = H^*(u)$  for  $u \in \mathcal{D}$  with  $u \notin \mathcal{L} \cup \widehat{\mathcal{L}}$ . We will more generally prove  $H_\alpha(u) = H^*(u)$  for  $(x, t) = u \in \mathcal{D}$  satisfying  $(x, t - t_0) \notin \mathcal{L}_1 \cup \mathcal{L}_\alpha$ , for  $|\alpha - 1|$  sufficiently small. From this,  $\widehat{H}^*(u) = H^*(u)$  would follow by taking  $\alpha = \alpha_0$ .

First, we verify that  $H_\alpha(u)$  is constant for  $u \in \partial_{\text{ea}}(\mathcal{D})$  and for  $u \in \partial_{\text{we}}(\mathcal{D})$ ; we only consider the case  $u \in \partial_{\text{ea}}(\mathcal{D})$  as the proof is entirely analogous if  $u \in \partial_{\text{we}}(\mathcal{D})$ . By Assumption 5.2,  $\partial_{\text{ea}}(\mathcal{D})$  is either disjoint with  $\widehat{\mathcal{L}}$  or is a subset of  $\partial\mathfrak{B}$ . In the former case,  $\partial_{\text{ea}}(\mathcal{D})$  is bounded away from  $\widehat{\mathcal{L}}$ , so the first statement in Lemma 7.3 implies for  $|\alpha - 1|$  sufficiently small that  $\partial_{\text{ea}}(\mathcal{D})$  is disjoint from  $\mathcal{L}_\alpha + (0, t_0)$ . Since  $H_\alpha$  is Lipschitz,  $\nabla H_1(u) = \nabla H^*(u)$ , the gradient  $\nabla H_\alpha(u) \in \{(0, 0), (1, 0), (1, -1)\}$  and is continuous in  $\alpha$  for almost every  $u \notin \mathcal{L}_\alpha + (0, t_0)$  and  $H^*$  is constant along  $\partial_{\text{ea}}(\mathcal{D})$ , it follows that  $H_\alpha$  is also constant along  $\partial_{\text{ea}}(\mathcal{D})$ .

If instead  $\partial_{\text{ea}}(\mathcal{D})$  and  $\widehat{\mathcal{L}}$  are not disjoint, then  $\partial_{\text{ea}}(\mathcal{D}) \subset \partial\mathfrak{B}$ , so  $\partial_{\text{ea}}(\mathcal{D})$  is tangent to  $\widehat{\mathcal{L}}$  at some point  $(x_0, t_0)$ . In particular, the shift  $\partial_{\text{ea}}(\mathcal{D}) - (0, t_0)$  is tangent to  $\mathfrak{A}_1$  at  $(x_0, t_0 - t_0)$ . Then, it is quickly verified from Equations (7.6) and (7.7) that  $\partial_{\text{ea}}(\mathcal{D}) - (0, t_0)$  remains tangent to  $\mathfrak{A}_\alpha$ . In particular,  $\partial_{\text{ea}}(\mathcal{D})$  is disjoint from the open set  $\mathcal{L}_\alpha + (0, t_0)$ . Then following the same reasoning as above gives that  $H_\alpha$  is constant along  $\partial_{\text{ea}}(\mathcal{D})$ .

This verifies that  $H_\alpha$  and  $H^*$  are constant along  $\partial_{\text{ea}}(\mathcal{D})$ ; by similar reasoning, they are also constant along  $\partial_{\text{we}}(\mathcal{D})$ . This, together with the fact that they coincide at the southwest vertex of  $\widehat{\mathcal{D}}$ , implies that  $H_\alpha = H^*$  along  $\partial_{\text{we}}(\mathcal{D})$ . Since the definition of  $\nabla H_\alpha$  implies that  $\nabla H_\alpha(x, t) = \nabla H^*(x, t)$  whenever  $(x, t - t_0) \notin \mathcal{L}_1 \cup \mathcal{L}_\alpha$ , to show  $H_\alpha(x, t) = H^*(x, t)$  for  $(x, t - t_0) \notin \mathcal{L}_1 \cup \mathcal{L}_\alpha$ , it suffices to show that height differences are ‘conserved along liquid regions’ of  $\partial_{\text{no}}(\mathcal{D})$  and  $\partial_{\text{so}}(\mathcal{D})$ . More specifically, let us fix a left and right endpoint  $(E_1(\alpha), t - t_0), (E_2(\alpha), t - t_0) \in \mathfrak{A}_\alpha$ , respectively, such that  $E_j(\alpha)$  is continuous in  $\alpha$  for each  $j \in \{1, 2\}$  and such that  $(x, t - t_0) \in \mathcal{L}_\alpha$  for each  $E_1(\alpha) < x < E_2(\alpha)$ . Abbreviating  $E_1 = E_1(1)$  and  $E_2 = E_2(1)$ , we must show that

$$\begin{aligned} &\left( H_\alpha(E_2(\alpha), t) - H_\alpha(E_1(\alpha), t) \right) - \left( H^*(E_2, t) - H^*(E_1, t) \right) \\ &= (E_2(\alpha) - E_2) \partial_x H^*(E_2, t) - (E_1(\alpha) - E_1) \partial_x H^*(E_1, t). \end{aligned} \tag{7.25}$$

Indeed, the equality  $H_\alpha(u) = H^*(u)$  for  $(x, t) = u \in \overline{\mathfrak{D}}$  satisfying  $(x, t - t_0) \notin \mathfrak{L}_1 \cup \mathfrak{L}_\alpha$  would then follow from the fact that  $\nabla H_\alpha(u) = \nabla H^*(u)$  for all such  $u$  and the fact that  $H_\alpha$  and  $H^*$  coincide at the northwest and southwest corners of  $\overline{\mathfrak{D}}$ .

Observe that Equation (7.25) holds at  $\alpha = 1$ , since  $H_1 = H^*$ . Thus, it suffices to show that the derivatives with respect to  $\alpha$  of both sides of Equation (7.25) are equal, namely,

$$\partial_\alpha \left( H_\alpha(E_2(\alpha), t) - H_\alpha(E_1(\alpha), t) \right) = \partial_x H^*(E_2, t) \partial_\alpha E_2(\alpha) - \partial_x H^*(E_1, t) \partial_\alpha E_1(\alpha). \tag{7.26}$$

To do this, observe from Equation (7.21) that the left side of Equation (7.26) is given by

$$\begin{aligned} \partial_\alpha \left( H_\alpha(E_2(\alpha), t) - H_\alpha(E_1(\alpha), t) \right) &= \partial_\alpha \int_{E_1(\alpha)}^{E_2(\alpha)} \partial_x H_\alpha(x, t) dx \\ &= -\pi^{-1} \partial_\alpha \left( \int_{E_1(\alpha)}^{E_2(\alpha)} \text{Im} \log \mathcal{F}_{t-t_0}(x; \alpha) dx \right). \end{aligned}$$

Thus,

$$\begin{aligned} \partial_\alpha \left( H_\alpha(E_2(\alpha), t) - H_\alpha(E_1(\alpha), t) \right) &= -\pi^{-1} \text{Im} \int_{E_1(\alpha)}^{E_2(\alpha)} \partial_\alpha \log \mathcal{F}_{t-t_0}(x; \alpha) dx \\ &\quad + \pi^{-1} \text{Im} \left( \log \mathcal{F}_{t-t_0}(E_1(\alpha); \alpha) \right) \partial_\alpha E_1(\alpha) \\ &\quad - \pi^{-1} \text{Im} \left( \log \mathcal{F}_{t-t_0}(E_2(\alpha); \alpha) \right) \partial_\alpha E_2(\alpha). \end{aligned} \tag{7.27}$$

Letting  $|\alpha - 1|$  tend to 0 in the first statement of Lemma 7.2 gives

$$\partial_\alpha \log \mathcal{F}_{t-t_0}(x; \alpha) = (t - t_0) \partial_x \left( \frac{\mathcal{F}_t(x; \alpha)}{\mathcal{F}_t(x; \alpha) + 1} \right) + 1.$$

Inserting this into Equation (7.27), using the fact that  $\mathcal{F}_{t-t_0}(E_i(\alpha); \alpha) \in \mathbb{R}$ , using the equality (following from Equation (7.21) and the continuity of  $\nabla H_\alpha$  almost everywhere in  $\mathfrak{L}_\alpha + (0, t_0)$ )

$$\pi^{-1} \text{Im} \log \mathcal{F}_{t-t_0}(E_i(\alpha); \alpha) = -\partial_x H_\alpha(E_i(\alpha), t) = -\partial_x H^*(E_i, t)$$

and using the fact that

$$\begin{aligned} &\text{Im} \int_{E_1(\alpha)}^{E_2(\alpha)} \left( (t - t_0) \partial_x \left( \frac{\mathcal{F}_{t-t_0}(x; \alpha)}{\mathcal{F}_{t-t_0}(x; \alpha) + 1} \right) + 1 \right) dx \\ &= (t - t_0) \text{Im} \left( \frac{\mathcal{F}_{t-t_0}(E_2(\alpha))}{\mathcal{F}_{t-t_0}(E_2(\alpha)) + 1} - \frac{\mathcal{F}_{t-t_0}(E_1(\alpha))}{\mathcal{F}_{t-t_0}(E_1(\alpha)) + 1} + E_2(\alpha) - E_1(\alpha) \right) = 0, \end{aligned}$$

then yields Equation (7.26). As mentioned above, this implies Equation (7.25) and hence that  $\widehat{H}^*(x, t) = H^*(x, t)$  for  $(x, t) \in \overline{\mathfrak{D}}$  with  $(x, t) \notin \mathfrak{L} \cup \widehat{\mathfrak{L}}$ . This verifies that  $\widehat{H}^*$  satisfies the second statement of the proposition.

To show that  $\widehat{H}^*$  satisfies the third statement, we must verify Equation (5.5) for sufficiently small  $\Delta$ . Let us assume in what follows that  $(x, t)$  and  $(\widehat{x}, t)$  are right endpoints of  $\mathfrak{L}$  and  $\widehat{\mathfrak{L}}$ , respectively, as the proof in the case when they are left endpoints is entirely analogous. Then we may assume that  $\Delta \leq 0$ , for otherwise the fact that  $\partial_x H^*(x, t) = \partial_x \widehat{H}^*(\widehat{x}, t)$  (which holds by the almost everywhere continuity of  $\nabla H_\alpha$  in  $\alpha$ , together with the facts that  $(x, t) \notin \mathfrak{L}$  and  $(\widehat{x}, t) \notin \widehat{\mathfrak{L}}$ ) implies  $H^*(x + \Delta, t) - H^*(x, t) = \Delta \partial_x H^*(x, t) = \Delta \partial_x \widehat{H}^*(\widehat{x}, t) = \widehat{H}^*(\widehat{x} + \Delta, t) - \widehat{H}^*(\widehat{x}, t)$ .

So we must show Equation (5.5) for  $\Delta \leq 0$ . Since it holds at  $\Delta = 0$  and since  $|\alpha - 1| = \mathcal{O}(|\xi_1| + |\xi_2|)$ , it suffices to show that

$$\partial_x \widehat{H}^*(\widehat{x} + \Delta, t) = \partial_x H^*(x + \Delta, t) + \mathcal{O}(|\Delta|^{1/2}|\alpha_0 - 1| + |\Delta|),$$

for sufficiently small  $\Delta$ . In view of Equation (7.21), this is equivalent to showing that

$$\left| \operatorname{Im} \frac{\mathcal{F}_{t-t_0}(\widehat{x} + \Delta; \alpha_0)}{\mathcal{F}_{t-t_0}(\widehat{x}; \alpha_0)} - \operatorname{Im} \frac{\mathcal{F}_{t-t_0}(x + \Delta; 1)}{\mathcal{F}_{t-t_0}(x; 1)} \right| = \mathcal{O}(|\Delta|^{1/2}|\alpha_0 - 1| + |\Delta|). \tag{7.28}$$

To that end, observe from Equation (3.6) that

$$\begin{aligned} \mathcal{F}_{t-t_0}(x + \Delta; 1) - \mathcal{F}_{t-t_0}(x; 1) &= \left( \frac{2(\mathcal{F}_{t-t_0}(x; 1) + 1)}{\mathcal{Q}''_{0;1}(\mathcal{F}_{t-t_0}(x; 1))} \right)^{1/2} |\Delta|^{1/2} + \mathcal{O}(|\Delta|^{3/2}); \\ \mathcal{F}_{t-t_0}(\widehat{x} + \Delta; \alpha_0) - \mathcal{F}_{t-t_0}(\widehat{x}; \alpha_0) &= \left( \frac{2(\mathcal{F}_{t-t_0}(\widehat{x}; \alpha_0) + 1)}{\mathcal{Q}''_{0;\alpha_0}(\mathcal{F}_{t-t_0}(\widehat{x}; \alpha_0))} \right)^{1/2} |\Delta|^{1/2} + \mathcal{O}(|\Delta|^{3/2}). \end{aligned} \tag{7.29}$$

Now, observe, for uniformly bounded  $u \in \mathbb{C}$ , we have

$$|\mathcal{F}_{t-t_0}(\widehat{x}; \alpha_0) - \mathcal{F}_{t-t_0}(x; 1)| = \mathcal{O}(|\alpha_0 - 1|); \quad |\mathcal{Q}''_{0;\alpha_0}(u) - \mathcal{Q}''_{0;1}(u)| = \mathcal{O}(|\alpha_0 - 1|), \tag{7.30}$$

where the former estimate follows from Equation (7.20) and the latter from Equation (7.6). Applying the two approximations in Equations (7.29) and (7.30) (with the fact that  $\mathcal{F}_{t-t_0}(x, 1)$  and  $\mathcal{Q}''_{0;1}(\mathcal{F}_{t-t_0}(x; 1))$  are bounded away from 0) then yields Equation (7.28). As mentioned above, this implies Equation (5.4), thereby verifying that  $\widehat{H}^*$  satisfies the third statement of the proposition.

We next show that  $\widehat{H}^*$  satisfies the first statement of the proposition. To that end, observe from the second and third statements of the proposition (together with Remark A.2), it suffices to show for any  $(x, t), (x', t) \in \mathfrak{L} \cap \widehat{\mathfrak{L}}$  such that  $(z, t) \in \mathfrak{L} \cap \widehat{\mathfrak{L}}$  for each  $z \in [x, x']$  that

$$\widehat{H}^*(x', t) - \widehat{H}^*(x, t) = H^*(x', t) - H^*(x, t) + \omega(t)(\Omega_t(x') - \Omega_t(x)) + \mathcal{O}(|\alpha_0 - 1|^{3/2}). \tag{7.31}$$

This will follow from a suitable application of Lemma 7.2. Indeed, we have

$$\begin{aligned} &(\widehat{H}^*(x', t) - H^*(x', t)) - (\widehat{H}^*(x, t) - H^*(x, t)) \\ &= \int_x^{x'} (\partial_z \widehat{H}^*(z, t) - \partial_z H^*(z, t)) dz \\ &= \pi^{-1} \int_x^{x'} \operatorname{Im} (\log \mathcal{F}_{t-t_0}(z; 1) - \log \mathcal{F}_{t-t_0}(z; \alpha_0)) dz \\ &= \pi^{-1} (t - t_0)(\alpha_0 - 1) \operatorname{Im} \int_x^{x'} \partial_z \left( \frac{\mathcal{F}_{t-t_0}(z; 1)}{\mathcal{F}_{t-t_0}(z; 1) + 1} \right) dz + \mathcal{O}(|\alpha_0 - 1|^{3/2}) \\ &= \pi^{-1} \omega(t) \operatorname{Im} \left( \frac{f_t(x')}{f_t(x') + 1} - \frac{f_t(x)}{f_t(x) + 1} \right) + \mathcal{O}(|\alpha_0 - 1|^{3/2}) \\ &= \omega(t)(\Omega_t(x') - \Omega_t(x)) + \mathcal{O}(|\alpha_0 - 1|^{3/2}), \end{aligned}$$

where the second equality follows from Equation (7.21), the third from Lemma 7.2, the fourth from Equations (7.3) and (7.23) and the fifth from Equation (5.1). This confirms Equation (7.31) and thus the first statement of the proposition.

To establish the fourth statement of the proposition, we must verify that  $\mathfrak{D}$  satisfies the five assumptions listed in Assumption 4.1 with respect to  $\widehat{H}^*$ . We have already verified the first, namely, that  $\widehat{H}^*$  is constant along  $\partial_{\text{ea}}(\mathfrak{D})$  and  $\partial_{\text{we}}(\mathfrak{D})$ . That the third holds follows from Lemma 7.3, together with the fact

that  $\mathfrak{D}$  satisfies the third assumption in Assumption 4.1 with respect to  $H^*$  (by Assumption 5.2). That the fourth holds follows from the continuity of  $\mathcal{F}$  in  $\alpha$ , together with the fact that  $\mathfrak{D}$  satisfies the fourth assumption in Assumption 4.1 with respect to  $H^*$ . The fifth follows from the fact that  $\mathcal{F}_t(x; \alpha_0)$  was defined to satisfy Equation (7.5). To verify the second, first suppose that  $\partial_{\text{no}}(\mathfrak{D}) \cap \mathfrak{L}$  is connected and nonempty. Then,  $\mathfrak{L}$  admits an extension beyond the north boundary of  $\mathfrak{D}$ , and so  $H^*$  admits an extension to some time  $t' > t_2$ . That  $\widehat{H}^*$  does as well then follows from Lemma 7.3 and the continuity of  $H_\alpha$  in  $\alpha$ .

If instead  $\partial_{\text{no}}(\mathfrak{D})$  is packed with respect to  $h$ , then we must show that  $\widehat{h}(v) = H^*(v)$  for each  $v \in \partial_{\text{no}}(\mathfrak{D})$ . To that end, observe since the northwest corner  $(\mathfrak{a}(t_2), t_2)$  and northeast corner  $(\mathfrak{b}(t_2), t_2)$  of  $\overline{\mathfrak{D}}$  are outside of (and thus bounded away from)  $\overline{\mathfrak{L}}$ , it follows from the second statement of the proposition that  $H^*$  and  $\widehat{H}^*$  coincide on them. Since  $\partial_{\text{no}}(\mathfrak{D})$  is packed with respect to  $h$ , we must have that  $\partial_x H^*(v) = 1$  for each  $v \in \partial_{\text{no}}(\mathfrak{D})$ . Since  $\widehat{H}^*$  is 1-Lipschitz, it follows that  $\widehat{H}^*(v) = H^*(v)$  for each  $v \in \partial_{\text{no}}(\mathfrak{D})$ , implying that  $\partial_{\text{no}}(\mathfrak{D})$  is packed with respect to  $\widehat{h}$ . This shows that  $\widehat{H}^*$  satisfies the four properties listed by the proposition.

It remains to show that  $\widehat{H}^* \in \text{Adm}(\mathfrak{D}; \widehat{h})$  is a maximizer of  $\mathcal{E}$ . This follows from checking the frozen star ray property in [ADPZ20, Definition 8.2], from which the claim follows by [ADPZ20, Remark 8.6] or [ADPZ20, Theorem 8.3]. We only briefly outline this verification here, as it is very similar to what was done in [ADPZ20]. Item i), ii) and iii) of the frozen star ray property in [ADPZ20, Definition 8.2] are quickly verified in our setting since the domain  $\mathfrak{D}$  satisfies Assumption 4.1. Item iv) in [ADPZ20, Definition 8.2] may fail to hold in our setting since, if we parametrize the leftmost and rightmost arctic boundaries of  $\widehat{H}^*$  by  $\widehat{E}_1(t) = \inf \{x : (x, t) \in \widehat{\mathfrak{L}}\}$  by  $\widehat{E}_2(t) = \sup \{x : (x, t) \in \widehat{\mathfrak{L}}\}$ , then the two frozen regions  $\{(x, t) : \mathfrak{a}(t) \leq x \leq \widehat{E}_1(t)\}$  and  $\{(x, t) : \widehat{E}_2(t) \leq x \leq \mathfrak{b}(t)\}$  may not be covered by the family of rays as in [ADPZ20, Definition 8.2]. However, in this case the proof of [ADPZ20, Theorem 8.3] still applies. Indeed, in the region not covered by those rays, one can extend the function  $\Phi(z)$  appearing in [ADPZ20, Proposition 8.1] continuously to be a constant function, and the proofs of [ADPZ20, Proposition 8.1, Theorem 8.3, and Remark 8.6] still continue to go through. This idea was already applied in a completely analogous way in the short proof of [ADPZ20, Theorem 8.4] (where the same phenomenon arose), so we refer there for a more detailed discussion.  $\square$

### Appendix A. Complex Burgers equation

In this section, we collect some quantitative results on the complex Burgers equation and establish Lemma 3.7 and Lemma 7.1. We recall the polygonal domain  $\mathfrak{P}$  from Definition 2.2, the associated boundary height function  $h : \partial\mathfrak{P} \mapsto \mathbb{R}$ , the maximizer  $H^* \in \text{Adm}(\mathfrak{P}; h)$  of  $\mathcal{E}$  from Equation (2.4), the complex slope  $f_t(x)$  associated with  $H^*$  through Equation (3.1) and the liquid region  $\mathfrak{L} = \mathfrak{L}(\mathfrak{P}, h)$  and arctic boundary  $\mathfrak{A} = \mathfrak{A}(\mathfrak{P}, h)$  from Equations (2.5) and (2.6). We further recall that there exists an analytic function  $Q_0$  satisfying Equation (3.3). If  $(x, t) \in \mathfrak{A}$  and  $f_t(x)$  is a triple root of Equation (3.3), then  $(x, t)$  is a cusp of  $\mathfrak{A}$ . If the tangent line through a point  $u \in \mathfrak{A}$  to  $\mathfrak{A}$  has slope in the set  $\{0, 1, \infty\}$ , then  $u$  is a tangency location of  $\mathfrak{A}$ ; in this case, the slope of  $u$  is the slope of this tangent line.

Given this notation, the following result provides the behavior of the complex slope  $f_t(x)$  along generic points of  $\mathfrak{A}$ . It follows quickly from [KO07, Section 1.6] and [ADPZ20, Theorem 1.8(c)], together with the analyticity of  $f(x, t)$ , and it can be also deduced directly from (3.3) by a Taylor expansion, so its proof is omitted.

**Lemma A.1** [KO07, ADPZ20]. *For any fixed  $(x_0, t) \in \mathfrak{A}$  which is not a tangency location or cusp of  $\mathfrak{A}$ , there exists a constant  $C = C(x_0, t, \mathfrak{P}) > 0$  and a neighborhood  $\mathfrak{U} \subset \mathfrak{P}$  of  $(x_0, t)$  such that the following holds. For  $(x, t) \in \mathfrak{U} \cap \mathfrak{L}$ , we have*

$$f_t(x) = f_t(x_0) + (Cx - Cx_0)^{1/2} + \mathcal{O}(|x - x_0|^{3/2}),$$

where the implicit constant in the error only depends on  $\mathfrak{P}$  and the distance from  $(x, t)$  to a tangency location or cusp of  $\mathfrak{A}$ . Here, the branch of the root is so that it lies in  $\mathbb{H}^-$ .

**Remark A.2.** Suppose  $u = (x, t) \in \mathfrak{Q}$  is bounded away from a cusp or tangency location of  $\mathfrak{A}$ ; let  $d_u = \inf \{|x - x_0| : (x_0, t) \in \mathfrak{A}\}$ . Then, the fact that  $f_t(x_0) \in \mathbb{R}$  if  $(x_0, t) \in \mathfrak{A}$  (from (3.1)), Lemma A.1 and Equation (3.1) together imply that there exists a small constant  $\epsilon > 0$  such that  $\epsilon d^{1/2} < |\partial_x H^*(x, t) - \partial_x H^*(x_0, t)| < \epsilon^{-1} d^{1/2}$ .

Now, let us show Lemma 3.7.

*Proof of Lemma 3.7.* Throughout this proof, let  $(\tilde{x}, \tilde{t}) \in \mathfrak{A}$  be some point on the arctic boundary  $\mathfrak{A} = \mathfrak{A}(\mathfrak{P})$  near  $(x, t)$ . Abbreviating  $f = f_t(x)$  and  $\tilde{f} = f_{\tilde{t}}(\tilde{x})$ , Equation (3.3) and the third part of Proposition 3.3 together imply

$$Q_0(f) = x(f + 1) - tf; \quad Q'_0(f) = x - t; \quad Q_0(\tilde{f}) = x(\tilde{f} + 1) - t\tilde{f}; \quad Q'_0(\tilde{f}) = x - t. \tag{A.1}$$

From this, we deduce

$$Q_0(f) = (f + 1)Q'_0(f) + t; \quad Q_0(\tilde{f}) = (\tilde{f} + 1)Q'_0(\tilde{f}) + \tilde{t},$$

which together imply

$$Q_0(\tilde{f}) - Q_0(f) = (f + 1)(Q'_0(\tilde{f}) - Q'_0(f)) + (\tilde{f} - f)Q'_0(\tilde{f}) + \tilde{t} - t. \tag{A.2}$$

We will first use Equation (A.2) to approximately solve for  $\tilde{f}$  in terms of  $(f, \tilde{t}, t)$  and then use Equation (A.1) to solve for  $\tilde{x}$  in terms of  $(x, f, \tilde{t}, t)$ . To that end, applying a Taylor expansion in Equation (A.2) (and using the fact that  $(\tilde{x}, \tilde{t})$  is close to  $(x, t)$ , which implies that  $\tilde{f}$  is close to  $f$  by the analyticity of  $f_t(x)$  for  $(x, t) \in \mathfrak{Q}(\mathfrak{P})$ ) gives

$$\begin{aligned} (\tilde{f} - f)Q'_0(f) + \frac{(\tilde{f} - f)^2}{2}Q''_0(f) + \mathcal{O}(|\tilde{f} - f|^3) \\ = (f + 1)\left((\tilde{f} - f)Q''_0(f) + \frac{Q'''_0(f)}{2}(\tilde{f} - f)^2 + \mathcal{O}(|\tilde{f} - f|^3)\right) \\ + (\tilde{f} - f)Q'_0(f) + (\tilde{f} - f)^2Q''_0(f) + \mathcal{O}(|\tilde{f} - f|^3) + \tilde{t} - t. \end{aligned}$$

This implies

$$(\tilde{f} - f)(f + 1)Q''_0(f) + \frac{(\tilde{f} - f)^2}{2}(Q''_0(f) + (f + 1)Q'''_0(f)) + \mathcal{O}(|\tilde{f} - f|^3) = t - \tilde{t}.$$

In particular, it follows that  $\tilde{f} - f = \mathcal{O}(|\tilde{t} - t|)$  and, more precisely, that

$$\tilde{f} - f = \frac{t - \tilde{t}}{(f + 1)Q''_0(f)} - \frac{(t - \tilde{t})^2}{2(f + 1)^3Q''_0(f)^3}(Q''_0(f) + (f + 1)Q'''_0(f)) + \mathcal{O}(|t - \tilde{t}|^3). \tag{A.3}$$

Since Equation (A.1) indicates that

$$x = Q'_0(f) + t; \quad \tilde{x} = Q'_0(\tilde{f}) + \tilde{t},$$

subtracting, applying Equation (A.3) and Taylor expanding again gives

$$\begin{aligned} \tilde{x} - x &= Q'_0(\tilde{f}) - Q'_0(f) + \tilde{t} - t = (\tilde{f} - f)Q''_0(f) + (\tilde{f} - f)^2\frac{Q'''_0(f)}{2} + \tilde{t} - t + \mathcal{O}(|\tilde{f} - f|^3) \\ &= \frac{f(\tilde{t} - t)}{f + 1} - \frac{(\tilde{t} - t)^2}{2(f + 1)^3Q''_0(f)} + \mathcal{O}(|\tilde{t} - t|^3), \end{aligned}$$

which implies the lemma upon matching with Equation (2.7). □

Next, we establish Lemma 7.1.

*Proof of Lemma 7.1.* It suffices to establish Equation (7.9), as Equation (7.10) follows from it. Since the derivation of both statements of Equation (7.9) are similar, we only establish the former. To that end, let  $(x', t)$  be some point close to  $(x, t)$ , and set  $\mathcal{F} = \mathcal{F}_t(x')$ . Then, Equation (7.8) implies

$$Q_0(\mathcal{F}) = x(\mathcal{F} + 1) - t\mathcal{F}; \quad Q_0(\mathcal{F}') = x'(\mathcal{F}' + 1) - t\mathcal{F}',$$

from which it follows that

$$Q_0(\mathcal{F}') - Q_0(\mathcal{F}) = (\mathcal{F}' - \mathcal{F})(x - t) + (x' - x)(\mathcal{F}' + 1).$$

From a Taylor expansion, we deduce

$$(\mathcal{F}' - \mathcal{F})(Q'_0(\mathcal{F}) - x + t) = (x' - x)(\mathcal{F} + 1) + \mathcal{O}(|\mathcal{F}' - \mathcal{F}|^2 + |x' - x||\mathcal{F}' - \mathcal{F}|).$$

Letting  $|x' - x|$  tend to 0, it follows that

$$\partial_x \mathcal{F}_t(x) = \lim_{x' \rightarrow x} \frac{\mathcal{F}' - \mathcal{F}}{x' - x} = \frac{\mathcal{F} + 1}{Q'_0(\mathcal{F}) - x + t},$$

which yields the first statement of Equation (7.9). □

### Appendix B. Proof of Proposition 2.4

In this section, we establish Proposition 2.4; throughout, we adopt the notation from that proposition. Let us begin by recalling some results from [DSS10, ADPZ20]. There exist two functions  $m, M \in \text{Adm}(\mathfrak{B}; h)$  (sometimes called *obstacles*) such that

$$m(z) \leq H(z) \leq M(z), \quad \text{for any } H \in \text{Adm}(\mathfrak{B}) \text{ and } z \in \mathfrak{B}.$$

They are explicitly given by (see [ADPZ20, Equation (2.23)])

$$m(v) = \max_{u \in \partial \mathfrak{B}} \left( - \max_{p \in \overline{\mathcal{T}}} \langle p, u - v \rangle + h(u) \right), \quad M(v) = \min_{u \in \partial \mathfrak{B}} \left( \max_{p \in \overline{\mathcal{T}}} \langle p, v - u \rangle + h(u) \right), \tag{B.1}$$

where we recall the triangle  $\mathcal{T}$  from Equation (2.1). The following result due to [DSS10] indicates continuity properties for the gradient  $\nabla H^*$  of the maximizer  $H^*$  of  $\mathcal{E}$  on  $\mathfrak{B}$ , as well as convexity properties for its arctic boundary. In what follows, for any direction  $\omega \in \mathbb{R}^2 \setminus \{(0, 0)\}$ , the graph  $G \subset \mathbb{R}^2$  of a (possibly discontinuous) function (whose domain is possibly disconnected or empty) is said to be convex (or concave) in the  $\omega$  direction, if the following holds. Let  $\rho_\omega : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  denote the rotation such that  $\rho_\omega(\omega) \in \mathbb{R}_{>0} \cdot (0, 1)$  points vertically upwards. Then, each connected component of  $\rho_\omega(G)$  is convex (or concave, respectively).

**Proposition B.1** [DSS10, Theorem 1.3 and 4.2]. *The following two statements hold.*

- (1) *The gradient  $\nabla H^*$  exists and is continuous on the set  $\{z \in \mathfrak{B} : m(z) < H^*(z) < M(z)\}$ .*
- (2) *Fix a real number  $c \in \mathbb{R}$ ; a vertex  $p_0 \in \{(0, 0), (1, 0), (1, -1)\} \in \overline{\mathcal{T}}$ ; and a direction  $\omega \in \mathbb{R}^2 \setminus \{(0, 0)\}$  such that*

$$\omega \cdot (p - p_0) > 0, \quad \text{for all } p \in \overline{\mathcal{T}} \setminus \{p_0\}. \tag{B.2}$$

*Let  $S$  denote the interior of the set  $\{z \in \mathfrak{B} : H^*(z) = c + p_0 \cdot z\}$ ; assume that  $S \neq \emptyset$ . Then  $\partial S \cap \mathfrak{B}$  consists of the union of a convex graph (by above) and a concave graph (by below) in the  $\omega$  direction.*



The following lemma, which is a quick consequence of Definition 2.2, provides integrality properties for the boundary height function  $h : \partial\mathfrak{P} \rightarrow \mathbb{R}$ .

**Lemma B.2.** *The following two statements hold.*

- (1) For any  $(x, t) \in (n^{-1} \cdot \mathbb{Z})^2$ , we have  $h(x, t) \in n^{-1} \cdot \mathbb{Z}$ .
- (2) Along any edge of  $\partial\mathfrak{P}$  of slope 0, we have  $\partial_x h = 1$ .
- (3) Along any edge of  $\partial\mathfrak{P}$  of slope  $\infty$  or 1,  $h$  is constant and takes value  $h \in n^{-1} \cdot \mathbb{Z}$ .

*Proof.* Since (by Definition 2.2)  $\mathfrak{P}$  is a polygonal domain and  $(0, 0) \in \partial\mathfrak{P}$ , each corner vertex of the polygon  $\mathfrak{P}$  lies on  $(n^{-1} \cdot \mathbb{Z})^2$ . The fact that  $h$  is constant along any edge of  $\partial\mathfrak{P}$  of slope  $\infty$  or 1 and that  $\partial_x h = 1$  along any edge of  $\partial\mathfrak{P}$  of slope 0, follows from the fact that  $\mathfrak{P}$  is polygonal (together with the conventions relating tilings to height functions described in Section 2.1); this confirms Item B.2 and the first part of Item B.2 of the lemma. Using this, with the facts that  $h(0, 0) = 0$  and that each corner vertex of  $\mathfrak{P}$  lies on  $(n^{-1} \cdot \mathbb{Z})^2$ , it follows that  $h(x, t) \in n^{-1} \cdot \mathbb{Z}$  whenever  $(x, t) \in (n^{-1} \cdot \mathbb{Z})^2$ . This confirms Item B.2 of the lemma. Then the second part of Item B.2 of the lemma follows from the fact that  $h$  is constant along each edge of  $\partial\mathfrak{P}$  with slope  $\infty$  or 1, and again the fact that each corner vertex of  $\mathfrak{P}$  lies on  $(n^{-1} \cdot \mathbb{Z})^2$ . □

The below lemma states, at lattice points  $v \in (n^{-1} \cdot \mathbb{Z})^2$ , that  $n \cdot m(v)$  and  $n \cdot M(v)$  are integers.

**Lemma B.3.** *For any point  $v \in \overline{\mathfrak{P}} \cap (n^{-1} \cdot \mathbb{Z})^2$ , we have  $n \cdot m(v) \in \mathbb{Z}$  and  $n \cdot M(v) \in \mathbb{Z}$ .*

*Proof.* The proof follows from analyzing the two formulas (B.1). The proofs are the same for  $m$  and  $M$ , so we will only give the proof that  $n \cdot M(v) \in \mathbb{Z}$ . By Equation (B.1),

$$M(v) = \min_{u \in \partial\mathfrak{P}} \left( \max_{p \in \overline{\mathcal{T}}} \langle p, v - u \rangle + h(u) \right). \tag{B.3}$$

Let the minimum over  $u \in \partial\mathfrak{P}$  in Equation (B.3) be attained at  $u^* \in \partial\mathfrak{P}$  (if there are multiple such  $u^*$ , then we select one arbitrarily). Further observe that the maximum over  $p \in \overline{\mathcal{T}}$  in Equation (B.3) is attained at a vertex  $p^* \in \{(0, 0), (1, 0), (1, -1)\}$  of the triangle  $\mathcal{T}$ . Without loss of generality (for the proofs in the remaining cases are entirely analogous), we assume that

$$p^* = (0, 0), \quad \text{so that} \quad M(v) = h(u^*).$$

Then,

$$\max \left\{ \langle (1, 0), v - u^* \rangle, \langle (1, -1), v - u^* \rangle \right\} \leq \langle p^*, v - u^* \rangle = 0$$

so that

$$v - u^* \in \{(x, y) \in \mathbb{R}_{\leq 0} \times \mathbb{R} : x - y \leq 0\}. \tag{B.4}$$

Now, let us consider several cases, depending on the side  $\ell = \ell(u^*)$  of  $\partial\mathfrak{P}$  that  $u^*$  lies on. If the slope of  $\ell$  is either 1 or  $\infty$ , then Item B.2 of Lemma B.2 yields  $M(v) = h(u^*) \in n^{-1} \cdot \mathbb{Z}$ . Otherwise,  $\ell$  has slope 0 (that is,  $\ell$  is a horizontal edge of  $\partial\mathfrak{P}$ ), and  $u^*$  is not a corner vertex of  $\mathfrak{P}$ . Observe in this case that  $u^* \cdot (0, 1) \in n^{-1} \cdot \mathbb{Z}$ , that is, the second coordinate of  $u^*$  is in  $n^{-1} \cdot \mathbb{Z}$  (as the second coordinate of any horizontal edge of  $\partial\mathfrak{P}$  is in  $n^{-1} \cdot \mathbb{Z}$ ).

We claim that either  $v - u^* \in \mathbb{R}_{\geq 0} \cdot (0, 1)$  or  $v - u^* \in \mathbb{R}_{\geq 0} \cdot (-1, 1)$ . Otherwise, by Equation (B.4), there would exist some  $u' \in \{u + \mathbb{R}_{< 0} \cdot (1, 0)\} \cap \ell$  (that is, on  $\ell$  and to the left of  $u$ ) such that  $v - u' \in \{(x, y) \in \mathbb{R}_{\leq 0} \times \mathbb{R} : x - y \leq 0\}$ . Since  $\langle p, (-1, 0) \rangle \leq 0$  for each  $p \in \overline{\mathcal{T}}$ , it follows that  $\max_{p \in \overline{\mathcal{T}}} \langle p, v - u' \rangle \leq \max_{p \in \overline{\mathcal{T}}} \langle p, v - u^* \rangle = 0$ . Together with the fact that  $h(u') = h(u^*) + (1, 0) \cdot (u' - u) <$

$h(u^*)$  (by Item B.2 of Lemma B.2), this yields

$$\max_{p \in \overline{\mathcal{T}}} \langle p, v - u' \rangle + h(u') < \max_{p \in \overline{\mathcal{T}}} \langle p, v - u^* \rangle + h(u^*),$$

which is a contradiction. Hence,  $v - u^* \in \mathbb{R}_{\geq 0} \cdot (0, 1)$  or  $v - u^* \in \mathbb{R}_{\geq 0} \cdot (-1, 1)$ .

In the first situation  $v - u^* \in \mathbb{R}_{\geq 0} \cdot (0, 1)$ , the first coordinates of  $v$  and  $u^*$  coincide. Thus, the first coordinate of  $v$  is in  $n^{-1} \cdot \mathbb{Z}$ ; the same therefore holds for  $u^*$ . Together with the fact that  $u^* \cdot (0, 1) \in n^{-1} \cdot \mathbb{Z}$ , it follows that  $u^* \in (n^{-1} \cdot \mathbb{Z})^2$ , from which Item B.2 of Lemma B.2 yields  $M(v) = h(u^*) \in n^{-1} \cdot \mathbb{Z}$ . In the second situation  $v - u^* \in \mathbb{R}_{\geq 0} \cdot (0, 1)$ , we have  $u^* \cdot (1, 1) = v \cdot (1, 1) \in n^{-1} \cdot \mathbb{Z}$ . Again together with the fact that  $u^* \cdot (0, 1) \in n^{-1} \cdot \mathbb{Z}$ , this yields  $u^* \in (n^{-1} \cdot \mathbb{Z})^2$ , and so Item B.2 of Lemma B.2 gives  $M(v) = h(u^*) \in n^{-1} \cdot \mathbb{Z}$ . This finishes the proof of Lemma B.3.  $\square$

Now, we can establish Proposition 2.4.

*Proof of Proposition 2.4.* We begin by establishing the first statement of the proposition; observe that it suffices to address the case when  $(x, t) \in \mathfrak{P} \setminus \overline{\mathfrak{Q}}$ , for then the extension to the case  $(x, t) \in \partial \mathfrak{Q}$  would follow from the continuity of  $H^*$ . To that end, recall from Lemma 2.3 that  $\nabla H^*(x, t) \in \{(0, 0), (1, 0), (1, -1)\}$ , as  $(x, t) \in \mathfrak{P} \setminus \overline{\mathfrak{Q}}$ . Since  $\nabla H^*$  is continuous at  $(x, t)$ , there exists a small neighborhood  $\mathcal{N}(x, t) \subset \mathfrak{P}$  of  $(x, t)$  such that  $\nabla H^*$  is constant on  $\mathcal{N}(x, t)$ , on which it takes one of the values  $\{(0, 0), (1, 0), (1, -1)\}$ . We assume in what follows that  $\nabla H^*(u) = (0, 0)$  for each  $u \in \mathcal{N}(x, t)$ , for the other cases can be proven in an entirely analogous way.

Let  $S$  denote the interior of the connected component of  $\{u : H^*(u) = H^*(x, t)\}$  containing  $(x, t)$ ; then  $S$  is nonempty, and we may assume (after taking a subset of  $\mathcal{N}(x, t)$  if necessary) that  $\mathcal{N}(x, t) \subseteq S$ . Take any direction  $\omega \in \mathbb{R}^2$  such that

$$\omega \cdot p > 0, \quad \text{for all } p \in \overline{\mathcal{T}} \setminus \{(0, 0)\}. \tag{B.5}$$

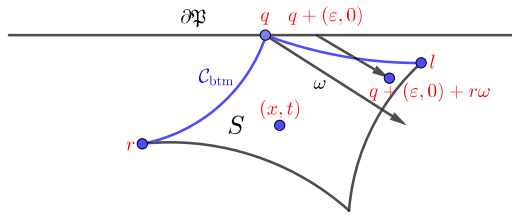
This is equivalent to the argument of  $\omega$  being in  $(-\pi/2, \pi/4)$ ; we may assume in what follows that the argument of  $\omega$  is in a small neighborhood of  $-\pi/8$ . Then  $H^*$  is nondecreasing in the  $\omega$  direction, and  $S$  is bounded (in the  $\omega$  direction) between two Lipschitz curves  $\mathcal{C}_{\text{top}}$  and  $\mathcal{C}_{\text{btm}}$ . We can assume that the left and right boundary of  $S$  (in  $\omega$  direction) are given by points  $l$  and  $r$ , respectively (as if they are given by segments in  $\omega$  direction, we can slightly perturb  $\omega$  to avoid such nongeneric situation). In this way, the two curves  $\mathcal{C}_{\text{top}}$  and  $\mathcal{C}_{\text{btm}}$  are from  $l$  to  $r$ .

First, observe that  $\mathcal{C}_{\text{top}}, \mathcal{C}_{\text{btm}} \not\subset \mathfrak{P}$ . Indeed, the second statement of Proposition B.1 would otherwise imply that  $\mathcal{C}_{\text{top}}$  is convex and  $\mathcal{C}_{\text{btm}}$  is concave in the  $\omega$  direction. Hence,  $\mathcal{C}_{\text{top}}$  lies below the line connecting  $l$  to  $r$  in the  $\omega$  direction, while  $\mathcal{C}_{\text{top}}$  lies above this line, which is impossible since  $\mathcal{C}_{\text{top}}$  bounds  $S$  from above and  $\mathcal{C}_{\text{btm}}$  bounds  $S$  from below in the  $\omega$  direction. Thus, we must instead have  $\mathcal{C}_{\text{top}} \cup \mathcal{C}_{\text{btm}} \not\subset \mathfrak{P}$ , meaning that there exists some point  $q \in (\mathcal{C}_{\text{top}} \cup \mathcal{C}_{\text{btm}}) \cap \partial \mathfrak{P} \neq \emptyset$ , with  $q \notin \mathcal{C}_{\text{top}} \cap \mathcal{C}_{\text{btm}}$ . If  $q$  belongs to a vertical boundary edge or a boundary edge with slope 1, then  $H^*(x, t) = h(q) \in n^{-1} \cdot \mathbb{Z}$  by Item B.2 of Lemma B.2.

Otherwise,  $q$  belongs to a horizontal edge  $\ell$  of  $\partial \mathfrak{P}$ , but it is not a corner vertex of  $\mathfrak{P}$ . Without loss of generality, we assume (by rotating  $\mathfrak{P}$  if necessary) that  $q \in \mathcal{C}_{\text{btm}}$ , meaning that  $q \notin \mathcal{C}_{\text{top}}$ . We can take a small  $\varepsilon > 0$  such that the short interval  $[q - (\varepsilon, 0), q + (\varepsilon, 0)]$  also belongs to the same edge  $\ell$  of  $\partial \mathfrak{P}$ . Since  $q \in \mathcal{C}_{\text{btm}} \setminus (\mathcal{C}_{\text{btm}} \cap \mathcal{C}_{\text{top}})$ , the point  $q$  is in the interior of  $\mathcal{C}_{\text{btm}}$ , and so we can take  $\varepsilon$  small enough so that there exists some  $r \geq 0$  such that  $q + (\varepsilon, 0) + r\omega \in S$ ; see Figure A1 for a depiction. This yields a contradiction, because

$$H^*(q + (\varepsilon, 0) + r\omega) \geq H^*(q + (\varepsilon, 0)) = h^*(q + (\varepsilon, 0)) > h^*(q) = H^*(q + (\varepsilon, 0) + r\omega),$$

where in the first statement we used the fact that, in the  $\omega$  direction,  $H^*$  is nondecreasing; in the second, we used that  $[q - (\varepsilon, 0), q + (\varepsilon, 0)]$  belongs to a horizontal boundary edge of  $\mathfrak{P}$ ; in the third, we used



**Figure A1.** If  $q \in C_{\text{btm}} \cap \partial\mathfrak{P}$  belongs to a horizontal boundary edge of  $\mathfrak{P}$ , then we can take  $\varepsilon$  small enough so that there exists some  $r \geq 0$  such that  $q + (\varepsilon, 0) + r\omega \in S$ .

Item B.2 of Lemma B.2, and in the fourth, we used that  $q, q + (\varepsilon, 0) + r\omega \in \bar{S}$ . This confirms that  $H^*(x, t) \in n^{-1} \cdot \mathbb{Z}$  and finishes the proof of the first statement in Proposition 2.4.

To establish the second statement, we set  $\Lambda = \{u \in \bar{\mathfrak{P}} : H^*(u) = m(u) \text{ or } H^*(u) = M(u)\}$ . If  $(x, t) \in \Lambda$  then it follows from Lemma B.3 that  $n \cdot H^*(x, t) \in \mathbb{Z}$ . Otherwise  $(x, t) \in \mathfrak{P} \setminus (\bar{\mathfrak{U}} \cup \Lambda)$ , and so the first statement in Proposition B.1 implies that  $\nabla H^*$  is continuous at  $(x, t)$ . Setting  $\nabla H^*(x, t) = (s, r) \in \{(0, 0), (1, 0), (1, -1)\}$ , the first statement of Proposition 2.4 implies that  $n(H^*(x, t) - sx - rt) \in \mathbb{Z}$ . By our assumption  $(x, t) \in (n^{-1} \cdot \mathbb{Z})^2$ , so  $n(sx + rt) \in \mathbb{Z}$  and we conclude that  $n \cdot H^*(x, t) \in \mathbb{Z}$ . This finishes the second statement of Proposition 2.4.  $\square$

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