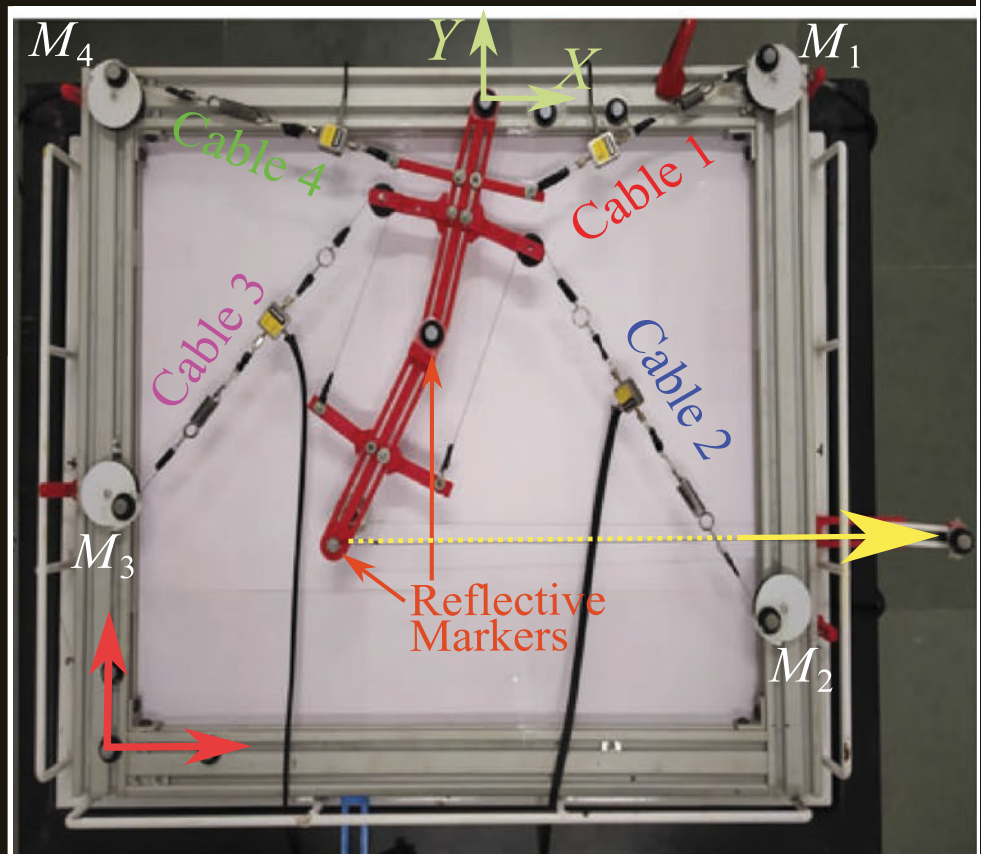


ROBOTICA



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Cover Image: Design and Implementation of a Cable Inspection Robot for Cable-Stayed Bridges by Zhipeng Wang, Bin He, Yanmin Zhou, Ke Liu and Chenghong Zhang. Figure 20 'Active vehicle obstacle climbing experiment (1.5 mm height obstacle)'.
