



# A Real-analytic Nonpolynomially Convex Isotropic Torus with no Attached Discs

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*Abstract.* We show by means of an example in  $\mathbb{C}^3$  that Gromov's theorem on the presence of attached holomorphic discs for compact Lagrangian manifolds is not true in the subcritical real-analytic case, even in the absence of an obvious obstruction, *i.e.*, polynomial convexity.

A compact set  $X \subset \mathbb{C}^n$  is called *polynomially convex* if, for every  $z \notin X$ , there is a holomorphic polynomial  $P$  such that  $|P(z)| > \sup_{x \in X} |P(x)|$ . It is known that no real compact  $n$ -dimensional submanifold  $M \subset \mathbb{C}^n$  (without boundary) can be polynomially convex. In the particular case when the inclusion  $\iota: M \hookrightarrow \mathbb{C}^n$  is maximally isotropic (or Lagrangian) with respect to  $\omega_{\text{st}} = i \sum_1^n dz_j \wedge d\bar{z}_j$ , *i.e.*,  $\iota^*(\omega_{\text{st}}) = 0$ , Gromov [5] proved a stronger statement: there is a holomorphic disc attached to  $M$ ; *i.e.*, there is a nonconstant holomorphic map from the unit disc  $\mathbb{D}$  to  $\mathbb{C}^n$  that is continuous up to the boundary and maps  $\partial\mathbb{D}$  into  $M$ . Gromov's result is not true in the subcritical case (when  $\dim M < n$ ), as there are several examples of polynomially convex isotropic surfaces in  $\mathbb{C}^3$ . It is natural to ask whether Gromov's result holds in the subcritical case in the absence of polynomial convexity. For  $\mathcal{C}^\infty$ -smooth manifolds, this is known to be false due to an example in [6] of a nonpolynomially convex two-torus in  $\mathbb{C}^3$  that does not have any analytic variety attached to it. Since this torus is the graph of a real-valued function over the standard torus in  $\mathbb{C}^2$ , it is isotropic in  $\mathbb{C}^3$  with respect to  $\omega_{\text{st}}$ . No such examples are known in the real-analytic case.

In this note, we produce an explicit real-analytic nonpolynomially convex two-torus  $T \subset \mathbb{C}^3$  that is isotropic with respect to  $\omega_{\text{st}}$ , but has no holomorphic discs attached to it. In view of the example in [6], we note that our example does have a holomorphic annulus attached to it. The isotropicity of  $T$  implies that it is both totally real and rationally convex (see [4]). Examples of totally real tori with no attached holomorphic discs have been given by Alexander [1] and Duval–Gayet [3] in  $\mathbb{C}^2$ , but such examples cannot be rationally convex in view of Duval–Sibony (see [4, Theorem 3.1]) and Gromov's result. In the case of manifolds with boundary, Duval has constructed an example of a nonpolynomially convex Lagrangian surface in  $\mathbb{C}^2$  that has no attached discs (see [2] or [4]).

**Theorem 1** *There is a real-analytic two-torus in  $\mathbb{C}^3$  that is isotropic with respect to  $\omega_{\text{st}}$ , not polynomially convex, but has no holomorphic discs attached to it.*

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**Proof** Let  $p(z, w) := 1 - 4z^2 + 4w^2 - z^2w^2$  and

$$T := \{ (z, w, \operatorname{Re} p(z, w)) \in \mathbb{C}^3 : z, w \in \partial\mathbb{D} \}.$$

Being the graph of a real-valued function on the torus  $\mathbb{T}^2 := \partial\mathbb{D} \times \partial\mathbb{D}$ ,  $T$  is isotropic with respect to  $\omega_{\text{st}}$ . We claim that  $T$  is not polynomially convex, and its polynomial hull (defined below) consists of  $T$  and an attached annulus.

Before we proceed, we fix some notation. If  $A \subset \overline{\mathbb{D}}^2$  and  $f: \overline{\mathbb{D}}^2 \rightarrow \mathbb{C}$ , then

$$\mathcal{G}_f(A) = \{ (z, w, f(z, w)) \in \mathbb{C}^3 : (z, w) \in A \}$$

denotes the graph of  $f|_A$ . If  $\zeta \in \overline{\mathbb{D}}^2$ , then  $\mathcal{G}_f(\{\zeta\})$  is simplified to  $\mathcal{G}_f(\zeta)$ . For a compact  $X \subset \mathbb{C}^n$ , the *polynomial hull* of  $X$  is the set

$$\widehat{X} = \{ z \in \mathbb{C}^n : |P(z)| \leq \sup_{x \in X} |P(x)| \text{ for all polynomials } P \}.$$

Now, let  $f(z, w) := \operatorname{Re}(p(z, w))$ . In our notation,  $T = \mathcal{G}_f(\mathbb{T}^2)$ . We first consider a related torus  $T_1 := \mathcal{G}_{\overline{p}}(\mathbb{T}^2)$ . We will show that  $T_1$  has all the required properties except that it is not isotropic with respect to  $\omega_{\text{st}}$ . It will then follow from a simple observation that  $T$  is indeed the required example.

We claim that

$$(1) \quad \widehat{T}_1 = T_1 \cup \mathcal{G}_p(\mathcal{Z}),$$

where  $\mathcal{Z} = \{ (z, w) \in \overline{\mathbb{D}}^2 : w^2 = \frac{4z^2-1}{4-z^2} \}$ . Since  $p|_{\mathcal{Z}} \equiv 0$ ,  $\mathcal{G}_p(\mathcal{Z})$  is isomorphic to  $\mathcal{Z}$ . Moreover, by a computation due to Rudin (see [8, proof of Theorem B])  $\mathcal{Z}$  is a connected finite Riemann surface of genus 0 with two boundary components in  $\mathbb{T}^2$ ; i.e,  $\mathcal{G}_p(\mathcal{Z})$  is an annulus attached to  $T_1$ .

To prove (1), we use a technique due to Jimbo (see [7]). Following the notation in [7], let

$$\begin{aligned} h(z, w) &= (zw)^{-2}(z^2w^2 - 4w^2 + 4z^2 - 1), \\ L &= (\overline{\mathbb{D}} \times \{0\}) \cup (\{0\} \times \overline{\mathbb{D}}), \\ V &= \{ (z, w) \in \overline{\mathbb{D}}^2 \setminus (\mathbb{T}^2 \cup L) : \overline{p(z, w)} = h(z, w) \}. \end{aligned}$$

Note that  $h(z, w) = \overline{p(z, w)}$  on  $\mathbb{T}^2$ . Next, we compute

$$\Delta(z, w) = \begin{vmatrix} \frac{\partial p}{\partial z}(z, w) & \frac{\partial p}{\partial w}(z, w) \\ \frac{\partial h}{\partial z}(z, w) & \frac{\partial h}{\partial w}(z, w) \end{vmatrix} = \begin{vmatrix} -8z - 2zw^2 & 8w - 2z^2w \\ \frac{8}{z^3} + \frac{2}{z^3w^2} & -\frac{8}{w^3} + \frac{2}{z^2w^3} \end{vmatrix},$$

to obtain  $\Delta(z, w) = -16(zw)^{-3}(z - iw)(z + iw)p(z, w)$ . Setting  $q_1 = (z - iw)$ ,  $q_2 = z + iw$ ,  $q_3 = p(z, w)$ , and  $Q_j := \{(z, w) \in \mathbb{T}^2 : q_j(z, w) = 0\}$ ,  $1 \leq j \leq 3$ , we have that

$$(2) \quad \begin{aligned} Q_1 &= \{(z, iz) \subset \mathbb{T}^2 : z \in \partial\mathbb{D}\}, \\ Q_2 &= \{(z, -iz) \subset \mathbb{T}^2 : z \in \partial\mathbb{D}\}, \\ Q_3 &= \mathcal{Z} \cap \mathbb{T}^2 = \partial\mathcal{Z}. \end{aligned}$$

In [7], Jimbo showed that if  $\Delta(z, w) \neq 0$  on  $\mathbb{D}^2 \setminus L$  and

$$J := \{1 \leq j \leq 3 : \emptyset \neq Q_j \neq \widehat{Q}_j, \widehat{Q}_j \setminus (\mathbb{T}^2 \cup L) \subset V\} \neq \emptyset,$$

then

$$\widehat{\mathcal{G}_{\bar{p}}(\mathbb{T}^2)} = \mathcal{G}_{\bar{p}}(\mathbb{T}^2) \cup \bigcup_{j \in J} \{(z, w, \overline{p(z, w)}) : (z, w) \in \widehat{Q}_j\},$$

and  $p$  restricts to a constant on each  $\widehat{Q}_j$ ,  $j \in J$ . In view of (2),  $J = \{3\}$ ,  $\widehat{Q}_3 = \mathcal{Z}$ , and, since  $p|_{\mathcal{Z}} = \bar{p}|_{\mathcal{Z}} = 0$ , (1) holds; i.e., there is only one annulus attached to  $T_1$ . Since  $\mathbb{T}^2$  is totally real and rationally convex, and  $\bar{p}$  is smooth,  $T_1 = \mathcal{G}_{\bar{p}}(\mathbb{T}^2)$  is totally real and rationally convex. Due to a result by Duval and Sibony (see [4]),  $T_1$  is isotropic with respect to some Kähler form on  $\mathbb{C}^3$ . But,  $\iota^*(\omega_{st}) \neq 0$ , where  $\iota: T_1 \hookrightarrow \mathbb{C}^3$  is the inclusion map.

We now return to  $T := \mathcal{G}_f(\mathbb{T}^2)$ . Note that the algebraic isomorphism

$$F(z, w, \eta) \mapsto \left(z, w, \frac{1}{2}(\eta + p(z, w))\right)$$

maps  $T_1$  onto  $T$  and fixes the variety  $\mathcal{G}_p(\mathcal{Z})$ . Thus,  $\widehat{T} = F(\widehat{T}_1) = T \cup \mathcal{G}_p(\mathcal{Z})$ . As there are no nontrivial holomorphic discs attached to an annulus, there are none attached to  $T$ . ■

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