

Finitely presented dynamical systems

DAVID FRIED

Department of Mathematics, Boston University, 111 Cummington Street, Boston, MA
 02215, USA

(Received 1 October 1986 and revised 12 January 1987)

Abstract We extend results of Bowen and Manning on systems with good symbolic dynamics. In particular we identify the class of dynamical systems that admit Markov partitions. For these systems the Manning-Bowen method of counting periodic points is explained in terms of topological coincidence numbers. We show, in particular, that an expansive system with a finite cover by rectangles has a rational zeta function.

We first recall some of the theory of expansive homeomorphisms, as presented for instance in [DGS]. Let Ω be a compact topological space, $f: \Omega \rightarrow \Omega$ a homeomorphism. We say f is *expansive* if there is a closed neighbourhood $V \subset \Omega \times \Omega$ of the diagonal Δ_Ω such that $F = f \times f: \Omega \times \Omega \rightarrow \Omega \times \Omega$ satisfies

$$\bigcap_{i \in \mathbb{Z}} F^{-i} V = \Delta_\Omega$$

One calls V an *expansive index* for f . We will see that f expansive $\Rightarrow \Omega$ metrizable (Lemma 2). In terms of a metric d on Ω this means that there is an *expansive constant* $c > 0$ such that

$$p, q \in \Omega, p \neq q \Rightarrow \text{for some } i \in \mathbb{Z}, d(f^i p, f^i q) > c$$

For $\varepsilon > 0$ and $x \in \Omega$ define the ε -stable set to be

$$W_\varepsilon^s(x) = \{y \mid d(f^i x, f^i y) \leq \varepsilon \text{ for } i \geq 0\}$$

and the ε -unstable set to be

$$W_\varepsilon^u(x) = \{y \mid d(f^i x, f^i y) \leq \varepsilon \text{ for } i \leq 0\}$$

If $\varepsilon \leq c/2$ then for any $x, y \in \Omega$ the intersection of $W_\varepsilon^s(x)$ with $W_\varepsilon^u(y)$ consists of at most one point. Let

$$D_\varepsilon = \{(x, y) \in \Omega \times \Omega \mid W_\varepsilon^s(x) \text{ meets } W_\varepsilon^u(y)\}$$

and define $[\cdot, \cdot]: D_\varepsilon \rightarrow \Omega$ so that

$$[x, y] \in W_\varepsilon^s(x) \cap W_\varepsilon^u(y)$$

Then D_ε is closed in $\Omega \times \Omega$ and $[\cdot, \cdot]$ is continuous, as is easily checked. We say $R \subset \Omega$ is a *rectangle* if $R \times R \subset D_\varepsilon$. Then if $x \in R$ one has the sets

$$W_\varepsilon^s(x, R) = R \cap W_\varepsilon^s(x), \quad W_\varepsilon^u(x, R) = R \cap W_\varepsilon^u(x)$$

and a natural homeomorphism (justifying the name rectangle)

$$R \cong W_\epsilon^u(x, R) \times W_\epsilon^s(x, R)$$

sending the point $y \in R$ to the pair $([y, x], [x, y])$ and the pair (y, z) to the point $[y, z]$ If Ω is a finite union of rectangles we say f is FR this is a local property of f , i.e. it is enough that every $x \in \Omega$ have a neighbourhood that is a finite union of rectangles

Next we study factors of subshifts Take \mathcal{S} a finite set of ‘symbols’ and consider the shift map $\sigma(s_n) = (s_{n+1})$ on sequences $(s_n), n \in \mathbb{Z}, s_n \in \mathcal{S}$ When the sequence space $\mathcal{S}^{\mathbb{Z}}$ is endowed with the product topology it is compact and metrizable and σ is expansive If $\Sigma \subset \mathcal{S}^{\mathbb{Z}}$ is a closed σ -invariant subset we say $\sigma: \Sigma \rightarrow \Sigma$ (or Σ itself) is a *subshift* with symbol set \mathcal{S} If $f: \Omega \rightarrow \Omega$ is a factor of Σ by a surjective semiconjugacy $\pi: \Sigma \rightarrow \Omega$ then the equivalence relation $E \subset \Sigma \times \Sigma \subset \mathcal{S}^{\mathbb{Z}} \times \mathcal{S}^{\mathbb{Z}} \cong (\mathcal{S} \times \mathcal{S})^{\mathbb{Z}}$

$$xEy \Leftrightarrow \pi x = \pi y$$

is $\sigma \times \sigma$ -invariant, so E is a subshift with symbol set $\mathcal{S} \times \mathcal{S}$ A subshift Σ is defined completely by saying which cylinders are disjoint from Σ , where a cylinder C is a closed-open subset of $\mathcal{S}^{\mathbb{Z}}$ whose coordinates are specified in finitely many places If there are finitely many cylinders C_i such that

$$\mathcal{S}^{\mathbb{Z}} - \Sigma = \bigcup_i \bigcup_{n \in \mathbb{Z}} \sigma^n C_i$$

then Σ is a *subshift of finite type* (SFT) If both Σ (as a subshift on \mathcal{S}) and E (as a subshift on $\mathcal{S} \times \mathcal{S}$) are of finite type we say f is *finitely presented* (FP) This is Gromov’s terminology, suggested by a loose analogy with groups Σ is analogous to the free group F on a finite set, E to the normal closure R of a finite set, so Σ/E is like the finitely presented group F/R

Suppose Σ is an SFT and Ω is a factor of Σ We will show

LEMMA 1 Ω is expansive $\Leftrightarrow E$ is of finite type

Thus if $\Omega \cong \Sigma/E \cong \Sigma'/E'$ is a factor of SFT’s in two ways and E is of finite type then E' is of finite type (In group theory, if $F/R \cong F'/R'$, with F, F' free groups on finitely many generators and R is the normal closure of a finite set then so is R' , so Gromov’s analogy holds up) Actually we will show

THEOREM 1 f is FP $\Leftrightarrow f$ is FR

so that FP systems have a local dynamical characterization and each FR system has a finite symbolic description

Following Bowen’s book [B1] we define a *Markov partition* for an expansive homeomorphism $f: \Omega \rightarrow \Omega$ to be a finite cover \mathcal{M} by proper rectangles (R is *proper* if $R = \overline{\text{int } R}$) with diameter $< \epsilon$ such that if $x \in \text{int } R, fx \in \text{int } R', R, R' \in \mathcal{M}$, then

$$(M) \quad f(W_\epsilon^s(x, R)) \subset R' \quad \text{and} \quad f^{-1}(W_\epsilon^u(fx, R')) \subset R$$

If f has a Markov partition we say it is MP We will show

THEOREM 2 f is FP $\Leftrightarrow f$ is MP

Here the backward implication is essentially a remark of Bowen ([B2, p 13]) from which the notion of a finitely presented system originates. Altogether we have

$$FP \Leftrightarrow FR \Leftrightarrow MP \Leftrightarrow \text{expansive factor of SFT}$$

The primary example of FP systems are Smale's Axiom A basic sets. Here Ω is expansive and has *canonical coordinates* (CC). U_ϵ is a neighbourhood of Δ_Ω so that $[x, y]$ makes sense if $x, y \in \Omega$ are sufficiently close (this reflects the uniform transversality of the stable and unstable manifolds). Also Ω has a metric d (induced from a well-chosen Riemannian metric) that contracts ϵ -stable sets and expands ϵ -unstable sets uniformly, i.e. $\exists \lambda \in (0, 1)$ so that if $y \in W_\epsilon^s(x)$ and $z \in W_\epsilon^u(x)$, $x, y, z \in \Omega$, then

$$(*) \quad d(fz, fy) \leq \lambda d(x, y), \quad d(f^{-1}x, f^{-1}z) \leq \lambda d(x, z)$$

From (*) and CC, Bowen deduced the pseudo-orbit tracing property (shadowing), and from this he exhibited Ω as a factor of an SFT. Then using this presentation and CC he obtained a Markov partition [B1]. We will essentially follow this last step in our proof of the forward implication in Theorem 2.

Ruelle defined a *Smale space* to be a compact metric space and an expansive homeomorphism, with CC and (*) [R]. He observed that these properties were enough to produce Markov partitions. In fact the metric comes for free. We will show

LEMMA 2 *Given an expansive system $f: \Omega \rightarrow \Omega$ there is a metric d on Ω such that (*) holds and f is a Lipschitz isomorphism. The Lipschitz class of d is determined by an expansive index V for f and the Holder class of d is uniquely determined by f . If $f': \Omega' \rightarrow \Omega'$ is another expansive system endowed with a metric d' in this natural Holder class then any semiconjugacy $\pi: \Omega \rightarrow \Omega'$ is Holder continuous.*

In particular there is an intrinsic notion of exponential convergence for an expansive system. These natural metrics will be used in our proof of Theorem 1. For a Smale space they were constructed in [F3] in terms of a finite presentation.

Our second motivating example arises when Ω is zero-dimensional. Then Ω is a subshift (partition Ω into finitely many small closed-open sets) and so we obtain the class of subshifts that are factors of SFT's. These are just Weiss's *sofic systems* ([We], [CP]). It is known that a sofic Ω has a finite-to-one extension $\pi: \Sigma \rightarrow \Omega$ with Σ an SFT that is *s-resolving*, i.e. π is 1-1 on each $W_\epsilon^s(x)$. For an FR Ω we will show the corresponding result.

LEMMA 3 *Ω has a finite-to-one s-resolving extension $G \rightarrow \Omega$ such that G has CC.*

This is also used in Theorem 1.

The third example of FP systems in the literature is Thurston's pseudo-Anosov homeomorphisms. These obviously satisfy FR. For them Markov partitions were first constructed by direct means [FLP]. Our method amounts to DAing, taking the Markov partition for the resulting hyperbolic repeller, and collapsing back down to a Markov partition for Ω itself, except that we work externally: the repeller is replaced by the s-resolution of Lemma 3.

The results discussed so far are proven in § 1 In § 2 we turn to counting periodic points The zeta function of an expansive $f: \Omega \rightarrow \Omega$

$$\zeta_f(t) = \exp \sum_{p>0} N_p \frac{t^p}{p},$$

$$N_p = |\{x \mid f^p x = x\}|,$$

is a generating function for the sequence of numbers of periodic points of various periods We will go over the Manning-Bowen argument for f FP to express N_p in terms of traces of certain linear maps ([M], [B2]) and we take a step towards comparing this method to the enumeration of N_p for a basic set Ω via the Lefschetz fixed point theorem ([G1], [F2]) Namely the traces give the coincidence number of a certain simplicial correspondence depending on the presentation $\Omega = \Sigma/E$, this coincidence number counts the components in the coincidence set of this correspondence and each component corresponds to a unique fixed point of f^p (see Theorem 3) This partially settles a question of Bowen ([B2, pp 14–15]) of how Manning’s work was related to Lefschetz theory (see also [R, problem B 9]) The end result is a formula for $\zeta_f(t)$ that shows it is rational in t

This paper is intended to add some steps to Bowen’s program of using symbolic dynamics to study basic sets ([B2, pp 10–15]) and to integrate the three FP examples cited above into one theory One can view FP systems as higher dimensional sofic systems or as a generalization of Smale spaces (every point has a neighbourhood that is a *finite union* of rectangles)

We thank Douady, Gromov, Kitchens and Marcus for their helpful conversations and Shishikura for his result cited in § 2 We are especially grateful to the late Rufus Bowen for his stimulation and encouragement

The author was partially supported by the National Science Foundation, the Sloan Foundation, the IHES, and the University of Warwick

1 *Proofs of Theorems 1 and 2*

We begin by deducing Theorem 1 from the above lemmas Suppose Ω is FP with a surjective semiconjugacy $\pi: \Sigma \rightarrow \Omega$ Lemma 1 shows Ω is expansive Partition Σ into cylinder sets C by specifying the coordinates of a sequence between $-n$ and n , n large Then each C is a rectangle since Σ has finite type If n is large enough then $\pi(C)$ will be a small rectangle The cover $\{\pi(C)\}$ shows f is FR

Conversely suppose Ω is FR Lemma 3 gives an extension X with CC Give X the metric of Lemma 2 Then X is a Smale space, hence Bowen’s arguments give shadowing and a finite presentation for X So Ω is a factor of an SFT, so Lemma 1 shows Ω is FP

To prove Lemma 1, recall that an invariant set I for a homeomorphism h is *isolated* if I is the largest invariant set in some open set U i.e. if $I = \bigcap_{i \in \mathbb{Z}} h^{-i} U$ One easily shows

(A) $f: \Omega \rightarrow \Omega$ is expansive $\Leftrightarrow \Delta_\Omega \subset \Omega \times \Omega$ is isolated for $h = f \times f: \Omega \times \Omega \rightarrow \Omega \times \Omega$

This is the definition of expansive with U an expansive index

(B) A subshift $\Sigma \subset \mathcal{G}^{\mathbb{Z}}$ is isolated for the full shift $h = \sigma$ on $\mathcal{G}^{\mathbb{Z}} \Leftrightarrow \Sigma$ is an SFT

This is the definition of SFT together with the fact that unions of cylinders form a neighbourhood basis for \mathcal{S}^Z

(C) Given a surjective semiconjugacy $\rho: X \rightarrow Y$ of homeomorphisms of compact

Hausdorff spaces and an invariant set $I \subset Y$, I is isolated $\Leftrightarrow \rho^{-1}I$ is isolated

This uses the definition of isolated and the fact that $\rho^{-1}I$ is the intersection of sets $\rho^{-1}\mathcal{O}$, \mathcal{O} open in Y . Now apply (C) to $\rho = \pi \times \pi: \Sigma \times \Sigma \rightarrow \Omega \times \Omega$ with $I = \Delta_\Omega$ and use

(A) and (B). Lemma 1 follows

Now we prove Lemma 2. Let $V_n = \bigcap_{i=-n}^n F^{-i}V$ for $n \geq 0$, with $F = f \times f$. Then each V_n is a neighbourhood of Δ_Ω and $\bigcap V_n = \Delta_\Omega$ so Ω is Hausdorff. Now a compact Hausdorff space has a unique uniformity consisting of all neighbourhoods of the diagonal [K]. Thus if n is sufficiently large $V_n \circ V_n \subset V$. We call the least $n \geq 1$ with this property the lag $n(V)$. We have $V_{n+k} \circ V_{n+k} \subset V_k$ for all $k \geq 0$, with $n = n(V)$. The sets $U_m = V_{2mn}$, $m \geq 0$, satisfy the condition

$$U_m \circ U_m \circ U_m \subset U_{m-1}$$

of the Frink Metrization Lemma ([K, p 185]) and so there is a metric d on Ω such that on $\Omega \times \Omega$

$$(F) \quad \{(x, y) \mid d(x, y) < 2^{-m}\} \subset U_m \subset \{(x, y) \mid d(x, y) < 2^{1-m}\}$$

Now take $f': \Omega' \rightarrow \Omega'$ expansive and in the same way construct d' from an expansive index V' with some lag n' . Then to any continuous semiconjugacy $\pi: \Omega \rightarrow \Omega'$ there is a μ such that $\rho = \pi \times \pi: \Omega \times \Omega \rightarrow \Omega' \times \Omega'$ satisfies $\rho V_\mu \subset V'$. Then $\rho V_{\mu+i} \subset V'_i$ for all $i \geq 0$ and so $\rho U_m \subset U'_m$ if $2m'n' \leq 2mn - \mu$. Given $(x, y) \in V$, $x \neq y$, we take $a \geq 0$ so that $m = an'$ satisfies $2^{-m-n'} \leq d(x, y) < 2^{-m}$. Then $(x, y) \in U_m$ and $\rho(x, y) \in U'_m$ with $m' = an - n_0$, with $n_0 \in \mathbb{Z}^+$ depending only on μ and n' . Thus

$$d'(\pi x, \pi y) < 2^{1-m'} \leq cd(x, y)^{n/n'}$$

where c depends only on μ , n and n' . Thus π is Holder with exponent n/n' the ratio of lags for V and V' .

As a special case suppose $\Omega' = \Omega$, $V' = V$, $\pi = \text{id}$. We see that 2 metrics d, d' satisfying (F) are Lipschitz equivalent, as $n/n' = 1$. If $\Omega' = \Omega$, $V' = V$, $\pi = f^{\pm 1}$ we see likewise that $f^{\pm 1}$ are Lipschitz. Finally changing V leaves the Holder class of d unchanged.

Next take $(x, y) \in V$ such that $y \in W_1^s(x)$. Then $(x, y) \in \bigcap_{-\infty}^0 F^i V$. If $d(x, y) < 2^{-m}$ then $(x, y) \in \bigcap_{-\infty}^{2mn} F^i V$. Thus if $a \in \mathbb{Z}^+$ one has

$$(f^{2na}x, f^{2na}y) \in \bigcap_{-\infty}^{2n(m+a)} F^i V \subset U_{m+a}$$

so that $d(f^{2na}x, f^{2na}y) < 2^{1-m-a}$. Assuming that $x \neq y$ and M is chosen so $d(x, y) \geq 2^{-1-m}$ this gives

$$d(f^{2na}x, f^{2na}y) \leq 4\left(\frac{1}{2}\right)^a d(x, y)$$

In particular the iterate f^{6n} contracts $W_1^s(x)$ by a factor $\frac{1}{2}$.

Now we use an argument of Mather to alter d within its Lipschitz class so that f contracts these stable sets directly. Take $\alpha = 2^{1/6n} > 1$ and define

$$e(x, y) = d(x, y) + \alpha d(fx, fy) + \dots + \alpha^{6n-1} d(f^{6n-1}x, f^{6n-1}y)$$

Then e and d are Lipschitz equivalent metrics and for (x, y) as above

$$e(fx, fy) = \alpha^{-1}(e(x, y) - d(x, y)) + \alpha^{6n-1}d(f^{6n}x, f^{6n}y) \leq \alpha^{-1}e(x, y)$$

Thus (*) holds for e with $\lambda = \alpha^{-1} = 2^{-1/6n}$ and ϵ sufficiently small This proves Lemma 2

We now prove Lemma 3 Take the metric d given in Lemma 2 and cover Ω by finitely many rectangles $R_s, s \in \mathcal{S}$ As D_ϵ is closed, the closure of any rectangle is again a rectangle and so we may assume that each R_s is closed Also we may suppose $\text{diam}(R_s) < c/10$, where c is an expansive constant To each $x \in \Omega$ we have a symbol set, a core, a star and a second star as follows

$$\begin{aligned} \mathcal{S}(x) &= \{s \in \mathcal{S} \mid x \in R_s\} \\ \text{Core}(x) &= \Omega - \bigcup_{t \in \mathcal{S} - \mathcal{S}(x)} R_t \\ \text{Star}(x) &= \bigcup_{s \in \mathcal{S}(x)} R_s \\ \text{Star}_2(x) &= \bigcup_{y \in \text{Star}(x)} \text{Star}(y) \end{aligned}$$

Clearly $x \in \text{Core}(x) \subset \text{Star}(x) \subset \text{Star}_2(x) \subset \Omega$ $\text{Core}(x)$ is open and $y \in \text{Core}(x) \Leftrightarrow \text{Star}(y) \subset \text{Star}(x) \Rightarrow \text{Star}_2(y) \subset \text{Star}_2(x)$ Choose $\delta > 0$ so that disjoint rectangles $R_s, R_t, s, t \in \mathcal{S}$, satisfy $d(R_s, R_t) > 2\delta$ and so that for any $z \in \Omega$ there is an $x \in \Omega$ with $B_{2\delta}(z) \subset \text{Core}(x)$, $1/\epsilon > 2\delta$ is a Lebesgue number for the open cover of Ω by cores The first property of δ implies that $B_{2\delta}(z) \subset \text{Star}_2(x)$

The relation $y \sim z \Leftrightarrow y \in W_\epsilon^u(z)$ defines an equivalence relation \sim on $\text{Star}_2(x)$ To $y \in \text{Star}_2(x)$ we define the projection $P(y, x) \subset \text{Star}_2(x)/\sim$ to be the image of $W_\epsilon^s(y) \cap \text{Star}_2(x)$ The set $\mathcal{P}(x) = \{P(y, x) \mid y \in \text{Star}_2(x)\}$ is finite and indeed so is

$$\sup_{x \in \Omega} |\mathcal{P}(x)| = K$$

We define an s -germ at x to be a sequence $P_i \in \mathcal{P}(f^i x), i \in \mathbb{Z}$, such that $\forall m, n \in \mathbb{Z}$ with $m \leq n, \exists y_{mn} \in \bigcap_{i=m}^n f^{-i} \text{Star}_2(f^i x)$ with $P(f^i y_{mn}, f^i x) = P_i$ for $m \leq i \leq n$ Clearly $P_i = P(f^i x, f^i x)$ defines an s -germ (take all $y_{mn} = x$) that we call trivial An s -germ at x describes a possible behaviour for the stable sets at points near x Clearly $g = (P_i)$ is determined by its values for large i Thus if G_x denotes the set of s -germs at $x, |G_x| \leq K$

Let $G = \bigcup_x G_x, x \in \Omega$, be the set of all s -germs and let $\pi: G \rightarrow \Omega$ be the natural projection We see that π is onto and has bounded fibers There is a natural bijection $h: G \rightarrow G$ that lifts f , namely $h(P_i) = (P_{i+1}) \in G_{fx}$ for $g = (P_i) \in G_x$ For $z \in \Omega$ define $V(z) \subset G \times G$ so that with the relation \sim on $\text{Star}_2(z), g = (P_i) \in G_x$ and $g' = (P'_i) \in G_x$ one has $(g, g') \in V(z)$ if

- (α) $B_\delta(x) \cup B_\delta(x') \subset \text{Core}(z)$,
- (β) $B_\delta(x, P_0)/\sim \subset P'_0/\sim$ and $B_\delta(x', P'_0)/\sim \subset P_0/\sim$,

where $B_\delta(x, P), P \in \mathcal{P}(x)$, denotes the intersection of P with the image of $W_\delta^s(x)$ We will regard $g, g' \in B$ as close if $(g, g') \in V(z)$ for some z more precisely we define $V = \bigcup_z V(z) \subset G \times G$ and $H = h \times h: G \times G \rightarrow G \times G$ and we prove that the sets $V_n = \bigcap_{i=-n}^n H^i V$ are a basis for a uniformity on Ω This defines a topology on Ω and we will see that the various properties required for Lemma 3 hold

First we show that if n is sufficiently large then $V_n \circ V_n \subset V$. Say $(g, g') \in V_n$ and $(g'', g''') \in V_n$. If n is large then $x = \pi g, x' = \pi g',$ and $x'' = \pi g''$ are very close and so by our choice of δ we can find $z' \in \Omega$ so that $B_{2\delta}(x) \cup B_{2\delta}(x') \subset \text{Core}(z')$. We also have $(h'g, h'g') \in V(z''), (h'g'', h'g''') \in V(z_i)$ for $z'', z_i \in \Omega, |i| \leq n$. By symmetry, it suffices to show that in $\text{Star}_2(z')/\sim,$ with $g = (P_i), g' = (P'_i)$ and $g'' = (P''_i)$ one has $B_\delta(x, P_0)/\sim \subset P''_0/\sim$. But if $w \in W_\delta^s(x)$ and $W_i^u(w)$ meets P_0 we have in $\text{Star}_2(z''_0)$ the relation $w \sim w', w' \in P'_0$ (use (β) on $(g, g') \in V(z''_0)$). Applying f^n gives $f^n w' \in B_\delta(f^n x', P'_n),$ if n is sufficiently large. Then $(h^n g', h^n g'') \in V(z_n)$ implies $f^n w' \sim f^n w''$ for some point $f^n w'' \in P''_n$. Thus $w'' = [x'', w]$ exists. Again we assume n large enough so that $d(x'', w'') < 2\delta$ (note (x'', w'') is near (x, w) for x'' close enough to x). Then, by our choice of δ, w'' is an interior point of $\text{Star}_2(x'')$. Thus $w'' \in P''_0$ and $w \sim w''$ in $\text{Star}_2(z'),$ as desired.

From $V_n \circ V_n \subset V$ follows $V_{n+k} \circ V_{n+k} \subset V_k$ for $k \geq 0,$ so the V_n are indeed a basis for a uniformity. Clearly $h: G \rightarrow G$ is a homeomorphism.

Next we show that $\Delta_G = \bigcap V_k$. Surely $(g, g') \in V$ for all $g \in G$ by our choice of δ . Thus $\Delta_G \subset V_k$ for all k . If $(h'g, h'g') \in V$ for all $i \in \mathbb{Z}$ then $g, g' \in G_x$ for some $x \in \Omega$ since $(\pi \times \pi)(V)$ is an expansive index for Ω (this also shows π is continuous). We have

$$B_\delta(f^i x, P_i) = B_\delta(f^i x, P'_i)$$

for $g = (P_i), g' = (P'_i), i \in \mathbb{Z}$. Taking $M \gg 0$ one sees that $P_{i-M} = P'_{i-M}$. Thus letting $i \rightarrow +\infty$ we see $g = g',$ as desired. (This also shows that distinct s -germs at x cannot be forward asymptotic, so π is 1-1 on stable sets.)

Next we show G is sequentially compact. Take $g^{(j)} \in G$. We may assume $\pi g^{(j)} = x_j \rightarrow x \in \Omega$. For j large, $x_j \in \text{Core}(x)$ and the $P_0^{(j)} \in \mathcal{P}(x_j) \subset \mathcal{P}(x)$ have a constant subsequence. A standard diagonal argument gives a subsequence $j_n \rightarrow \infty$ so that $x_{j_n} \in \bigcap_{-n}^n f^{-i} \text{Core}(f^i x)$ and $P_i^{(j_n)}/\sim \subset \text{Star}_2(f^i x)/\sim$ is constant for $n \geq i,$ for each $i \geq 0$. Then $g^{(j_n)}$ converges in G .

Thus we see that G is compact and h is an expansive homeomorphism. We next show h has CC. Say $(g, g') \in V(z)$ and $x = \pi g$ is close to $x' = \pi g'$. With $y_{mn} \rightarrow x$ and $y'_{mn} \rightarrow x'$ as in the definition of s -germ we see by (β) that $[y_{mn}, y'_{mn}] = y''_{mn}$ is defined for $m \ll 0, n \gg 0$. Thus $x'' = \lim y''_{mn} = [x, x']$ exists. Let $g'' \in G_x$ be $g'' = (P''_i)$ where P''_i is the value of $P(f^i y''_{mn}, f^i x'')$ for $m \ll 0, n \gg 0$. A little thought shows that P''_i is well defined, that $g'' \in G_x$ and that $g'' = [g, g']$. This gives a neighbourhood of Δ_G on which $[\ , \]$ is defined so h has CC. This finishes the proof of Lemma 3, so Theorem 1 is proven.

While the details of Lemma 3 are foul the idea is quite intuitive. Consider, say, the case Ω a surface, f pseudo-Anosov. Then we must break up the prongs since canonical coordinates break down there. But one cannot just alter the prongs: one must split open their stable sets, as shown in Figure 1. This can be done by distinguishing the different sides of these stable sets, which are just s -germs. The prong singularity p has 3 nontrivial s -germs, other points $x \in W^s(p)$ have only 2. Note that the shaded region $X \subset G$ is the closure of the singleton fibers of π . X can be identified with the DA repeller obtained by converting prongs into sinks. The canonical coordinates on G and the s -resolving property of π are plainly visible.

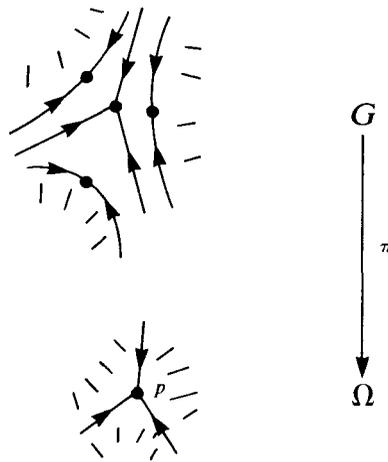


FIGURE 1

Remark 1 The s -germ extension $\pi: G \rightarrow \Omega$ constructed above is canonical. First suppose δ is changed to $\delta' < \delta$. Then the set G is unchanged and the new uniformity is defined by a V' that clearly contains V . As a continuous bijection of compact Hausdorff spaces is a homeomorphism, we see that the topology of G is independent of δ . Second, suppose one changes the cover $\{R_i\}$. It is enough to consider the case of adding a new rectangle. Then the cores become smaller and the stars become larger, so there is a restriction map $G' \rightarrow G$ from new s -germs to old ones (here we fix δ very small). One easily can check that this map is bijective and continuous, so G is unchanged. Likewise, one can alter the choice of d without changing G .

For sofic systems ($\dim \Omega = 0$) this sort of extension is known, but by explicit symbolic constructions [Kr]. We believe the s -germs represent the latent geometry in the notion of future-resolving extensions of sofic systems.

Now we will prove Theorem 2, $1 \Leftrightarrow MP \Leftrightarrow FP$. If \mathcal{M} is a Markov partition, then to each sequence $R_n \in \mathcal{M}$ for which $f(\text{int } R_n)$ meets $\text{int } R_{n+1}$ for all $n \in \mathbb{Z}$, there is a unique point $\pi(R_n) \in \bigcap_{n \in \mathbb{Z}} f^{-n} R_n$. These sequences form an SFT Σ with symbol set \mathcal{M} and π represents f as a factor. This is proven just like the basic set case, e.g. [B1, pp 84–86]. In this case the equivalence relation E on Σ defined by π is

$$(R_n)E(R'_n) \Leftrightarrow R_n \text{ meets } R'_n, \text{ all } n \in \mathbb{Z}$$

as noted by Bowen [B2, p 13]. Clearly E is an SFT. Thus $MP \Rightarrow FP$.

Conversely, suppose we are given an expansive $f: \Omega \rightarrow \Omega$ with expansive constant $c = 2\epsilon$, an SFT $\sigma: \Sigma \rightarrow \Sigma$, and a semiconjugacy $\pi: \Sigma \rightarrow \Omega$. We will follow [B1, pp 78–83], to construct a Markov partition.

By symbol splitting (i.e. passing to new symbols that are consecutive N -strings of old symbols, N large) we may suppose that Σ is defined by relations on consecutive pairs of symbols, i.e. by a graph $A \subset \mathcal{S} \times \mathcal{S}$ of allowed transitions

$$(s_n) \in \Sigma \Leftrightarrow s_n A s_{n+1}, \quad n \in \mathbb{Z}$$

We may also assume that for each $s \in \mathcal{S}$ the cylinder $C_s = \{(s_n) \in \Sigma \mid s_0 = s\}$ has an image $T_s = \pi(C_s)$ in Ω of diameter $< \varepsilon/2$. Then T_s is a closed rectangle, since $(s_n), (s'_n) \in C_s$ imply

$$[\pi(s_n), \pi(s'_n)] = \pi(s_n^*),$$

$$s_n^* = \begin{cases} s_n, & n \geq 0, \\ s'_n, & n \leq 0 \end{cases}$$

The T_s clearly form a cover \mathcal{T} of Ω . Also if $x \in T_s$ and sAt then the Markov property

(M) $fW_\varepsilon^s(x, T_s) \subset W_\varepsilon^s(fx, T_t), \quad f^{-1}W_\varepsilon^u(fx, T_t) \subset W_\varepsilon^u(x, T_s)$

holds. We must, however, modify \mathcal{T} to produce a Markov partition since we do not know whether the T_s are proper or have disjoint interiors.

Consider any closed rectangle T . We must analyze how T decomposes relative to the cover \mathcal{T} . For $k \in \mathcal{S}$ let the *unstable k -boundary* of T be

$$\partial_k^u T = \{x \in T \mid x = \lim x_i, x_i \in W_\varepsilon^s(x) \cap T_k - T\}$$

and define $\partial_k^s T$ accordingly (with $x_i \in W_\varepsilon^u(x)$). Then

$$\partial T = \bigcup_k (\partial_k^u T \cup \partial_k^s T)$$

For if $x \in \partial T$, say $x = \lim y_i, y_i \notin T$, then by passing to a subsequence we can assume all $y_i \in T_k$, some k . Then $x \in T_k$ and we can form $y'_i = [x, y_i] \in T_k$ and $y''_i = [y_i, x] \in T_k$. Since $[y''_i, y'_i] = y_i \notin T$ either $y'_i \notin T$ or $y''_i \notin T$. Passing to a subsequence, assume say that $y'_i \notin T$ for all i . Then $y'_i \in W_\varepsilon^s(x) \cap T_k - T, y'_i \rightarrow x$ so $x \in \partial_k^u T$. If $y''_i \notin T$ for all i then $x \in \partial_k^s T$.

From T we form the quotient space H in which $x, y \in T$ are identified if $x \in W_\varepsilon^s(y)$ and the corresponding space V of ε -unstable sets. The natural map $T \rightarrow H \times V$ is a homeomorphism and we will identify T with $H \times V$. For $k \in \mathcal{S}$ define closed subspaces $H_k^* \subset H_k \subset H$ to be the projections of $\partial_k^s T \subset T \cap T_k \subset T$, and define $V_k^* \subset V_k \subset V$ accordingly. Then one sees $\partial_k^s T = H_k^* \times V_k$ and $\partial_k^u T = H_k \times V_k^*$ are rectangles, as follows. Say $x = \lim x_i, x_i \in W_\varepsilon^u(x) \cap T_k - T$, and $y \in T_k \cap T$. Then $[x_i, y] \notin T$, since otherwise $x_i = [[x_i, y], x] \in T$. Thus $[x, y] = \lim [x_i, y], [x_i, y] \in W_\varepsilon^u([x, y]) \cap T_k - T$, so $[x, y] \in \partial_k^s T$.

Define rectangles $T_k^n \subset T$ by

$$T_k^1 = \text{int}_H (H_k - H_k^*) \times \text{int}_V (V_k - V_k^*)$$

$$T_k^2 = \text{int}_H (H - H_k) \times \text{int}_V (V_k)$$

$$T_k^3 = \text{int}_H (H_k) \times \text{int}_V (V - V_k)$$

$$T_k^4 = \text{int}_H (H - H_k) \times \text{int}_V (V - V_k)$$

where $\text{int}_H, \text{int}_V$ denote interior relative to H, V respectively. Then each T_k^n is open as a subset of T . For $\nu \in \mathcal{S} \rightarrow \{1, 2, 3, 4\}$ the rectangle $T^\nu = \bigcap_k T_k^{\nu(k)}$ is open in T and disjoint from $\partial T = \bigcup_k (H_k^* \times V_k) \cup (H_k \times V_k^*)$, hence T is open in Ω . Also the error set

$$\mathcal{E}(T) = \bigcup_{k \in \mathcal{S}} \left(T - \bigcup_{n=1}^4 T_k^n \right) = T - \bigcup_\nu T^\nu$$

is closed, nowhere dense in Ω and contains ∂T . See Figure 2

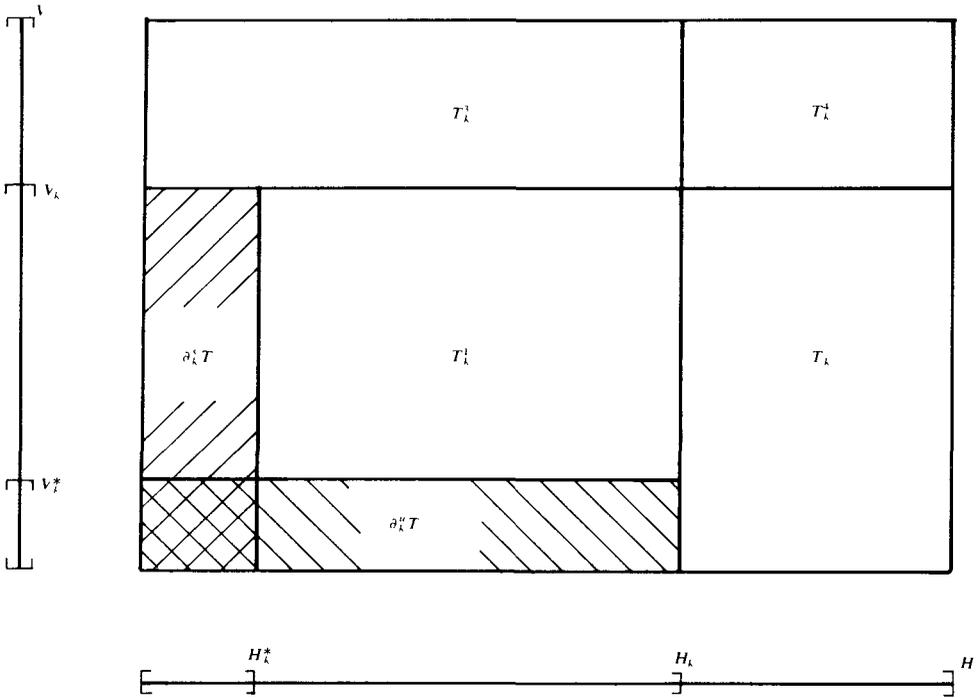


FIGURE 2

Now let $\mathcal{D} = \Omega - \bigcup_{j \in \mathcal{S}} \mathcal{E}(T_j)$. Then \mathcal{D} is open and dense. For $x \in \Omega$ we let $\mathcal{S}(x) \subset \mathcal{S}$ consist of those j for which $x \in T_j$. Then

$$\begin{aligned} x \in \mathcal{D} &\Leftrightarrow \forall j \in \mathcal{S}(x), x \notin \mathcal{E}(T_j) \\ &\Leftrightarrow \forall j \in \mathcal{S}(x), k \in \mathcal{S}, \exists n = n(x, j, k) \text{ such that } x \in (T_j)_k^n \end{aligned}$$

and for such x the rectangle $R(x)$ defined by

$$R(x) = \bigcap_{j \in \mathcal{S}(x)} \bigcap_{k \in \mathcal{S}} (T_j)_k^{n(x, j, k)}$$

is open and contains x . We have (cf [B1, pp 81-82])

LEMMA 4 For $x, y \in \mathcal{D}$, $R(x)$ and $R(y)$ are either disjoint or equal. The set $\mathcal{R} = \{\overline{R(x)} \mid x \in \mathcal{D}\}$ is a finite cover of Ω by proper rectangles with disjoint interiors.

LEMMA 5 For $x, y \in \mathcal{D} \cap f^{-1}\mathcal{D}$ with $R(x) = R(y)$ and $y \in W_\varepsilon^s(x)$ one has $R(fx) = R(fy)$.

Proof of Lemma 4 If $z \in \mathcal{D} \cap R(x)$ then $\mathcal{S}(z) = \mathcal{S}(x)$. Also if $j \in \mathcal{S}(x)$ and $k \in \mathcal{S}$ then $z \in (T_j)_k^n$ for the same value of n , i.e. $n(x, j, k) = n(z, j, k)$, so $R(x) = R(z)$. Thus if $R(x) \cap R(y) \neq \emptyset$ there is a $z \in \mathcal{D} \cap R(x) \cap R(y)$ so that $R(x) = R(z) = R(y)$.

Proof of Lemma 5 First we write $fx = \pi(\sigma(q_n))$ where $q_1 = j$, $q_0 = s$. Thus $fx \in T_j$, $x \in T_s$. As $y \in W_\varepsilon^s(x, T_s)$, (M) implies $fy \in W_\varepsilon^s(fx, T_j)$. So $fx \in T_j \Rightarrow fy \in T_j$, and, by symmetry, $\mathcal{S}(fx) = \mathcal{S}(fy)$.

Next we show $n(fx, J, k) = n(fy, J, k)$ for $k \in \mathcal{S}$. As $W_\varepsilon^s(fy, T_j) = W_\varepsilon^s(fx, T_j)$ we see these n 's are of the same parity. We must show that if $W_\varepsilon^u(fx, T_j)$ meets T_k then the same holds for fy . By symmetry, this will prove the lemma.

Say $fz \in T_k \cap W_\varepsilon^u(fx, T_j)$. By (M), $z \in W_\varepsilon^u(x, T_s)$. As $fz \in T_k$ we have $z = \pi(q'_n)$ with $q'_1 = k$. Let $t = q'_0 \in \mathcal{S}$. Again (M) gives

$$fW_\varepsilon^s(z, T_t) \subset W_\varepsilon^s(fz, T_k)$$

Since $T_s \in \mathcal{S}(x) = \mathcal{S}(y)$ and T_t meets $W_\varepsilon^u(x, T_s)$ at z , T_t also meets $W_\varepsilon^u(y, T_s)$ at some point z' . Let $z'' = [z, y]$. Then $z'' = [z, z'] \in W_\varepsilon^s(z, T_t) \cap W_\varepsilon^u(y, T_s)$. In T_j then $fz'' = [fz, fy] \in W_\varepsilon^s(fz, T_k) \cap W_\varepsilon^u(fy, T_j)$, showing $W_\varepsilon^u(fy, T_j)$ meets T_k , as desired.

By Lemma 4 we must only show \mathcal{R} has the Markov property. For $R_1, R_2 \in \mathcal{R}$ (i.e. $R_i = \overline{R(p_i)}$, $p_i \in \mathcal{D}$), $f^{-1}(\text{int } R_2)$ meets $\text{int } R_1 \Leftrightarrow f^{-1}R(p_2)$ meets $R(p_1)$. By continuity and symmetry (i.e. arguing with f^{-1} instead of f) it suffices to show for $x \in (R(p_1) \cap f^{-1}R(p_2)) = \emptyset$

$$fW_\varepsilon^s(x, R_1) \subset R_2$$

Say $z \in W_\varepsilon^s(x, R_1)$. Write $x = \lim w_i$, $w_i \in \mathcal{O} \cap \mathcal{D} \cap f^{-1}\mathcal{D}$ (\mathcal{O} is open and \mathcal{D} is dense). Then $[w_i, z] \rightarrow z$. Choose y_i very near $[w_i, z]$ so $y_i \in R(p_1) \cap \mathcal{D} \cap f^{-1}\mathcal{D}$ and so that $x_i = [y_i, w_i]$ is still in $\mathcal{O} \cap \mathcal{D} \cap f^{-1}\mathcal{D}$. Then $y_i \rightarrow z$, $x_i \rightarrow x$ and Lemma 6 above, applied to x_i and y_i , shows $fy_i \in R(p_2)$. Thus $fz = \lim fy_i \in R_2$, as was to be shown.

While this proof is substantially the same as the Bowen argument we note some differences. The major problem is that if T is a rectangle $\text{int}(T)$ may not be a rectangle! Indeed although each $\partial_k^i T$ is a rectangle there may be $x \in W_\varepsilon^s(y, T)$, $y \in \partial_k^i T$, with $x \in \text{int } T$. Our $(T_j)_k^n$ substitute for the $\text{int}(T_{j,k}^n)$ of [B1, p 81], which may not be rectangles in our setup. Also the set Z^* of [B1, p 80], may not be dense here so we have to use \mathcal{D} instead.

2 Cohomology and periodic points

We will introduce a refined symbolic dynamics to study the topology of a factor of a subshift, especially its Čech cohomology. This will enable us to analyze Manning's counting argument in terms of coincidence numbers. A useful reference for this section is the classic book of Eilenberg and Steenrod [ES].

Let Σ be a subshift on symbol set \mathcal{S} and Ω a factor of Σ . For $a \leq b$, $a, b \in \mathbb{Z}$, define an (a, b) cylinder set $v \subset \Sigma$ to be a nonempty subset of Σ obtained by specifying the sequence $(s_n) \in \Sigma$ for $n = a, \dots, b$. These form a partition \mathcal{S}_{ab} of Σ whose images form a finite cover \mathcal{T}_{ab} of Ω by compact sets $\pi(v)$ indexed by $v \in \mathcal{S}_{ab}$. Let N_{ab} be the nerve of \mathcal{T}_{ab} , so N_{ab} is the finite simplicial complex with one j -simplex for each $(j+1)$ -element subset of \mathcal{S}_{ab} whose images under π have nonempty intersection. Let F_{ab} be the filled-in complex with one j -simplex for every $(j+1)$ -element subset of \mathcal{S}_{ab} whose images under π intersect pairwise. The 1-skeleton Γ_{ab} of N_{ab} is also the 1-skeleton of F_{ab} and Γ_{ab} determines F_{ab} since a subset of \mathcal{S}_{ab} spans a simplex in F_{ab} if and only if its two element subsets span an edge in Γ_{ab} . We have

$$\mathcal{S}_{ab} \subset \Gamma_{ab} \subset N_{ab} \subset F_{ab}$$

If $\alpha \leq a \leq b \leq \beta$ then $\mathcal{S}_{\alpha\beta}$ refines \mathcal{S}_{ab} , $\mathcal{T}_{\alpha\beta}$ refines \mathcal{T}_{ab} and one has a simplicial map $\phi_{ab}^{\alpha\beta}: N_{\alpha\beta} \rightarrow N_{ab}$. These maps form an inverse system indexed by integer pairs

$a \leq b$ and we form the inverse limit space $N = \varprojlim N_{ab}$ in which a point $p = (p_{ab})$ consists of a point $p_{ab} \in N_{ab}$ for all $a \leq b$ such that $\phi_{ab}^{\alpha\beta} p_{\alpha\beta} = p_{ab}$. As the maps in the inverse system preserve skeleta N is filtered by the inverse limits N^i of the i -skeleta N_{ab}^i . Since $N_{ab}^0 = \mathcal{S}_{ab}$ we see that $N^0 = \Sigma$ is the shift we began with. We can likewise form the inverse system of simplicial maps $\psi_{ab}^{\alpha\beta} : F_{\alpha\beta} \rightarrow F_{ab}$ and take its inverse limit to obtain a space F , filtered by $F^i = \varprojlim F_{ab}^i$. We have so far

$$\begin{array}{cccc} \Sigma \subset N^1 \subset N^2 \subset & & & \subset N \\ \parallel & \parallel & \cap & \cap \\ \Sigma \subset F^1 \subset F^2 \subset & & & \subset F \end{array}$$

We can obtain more by embedding F in the space $M\Sigma$ of regular Borel measures on Σ as follows. To $q = (q_{ab}) \in F$ we associate the measure $\mu_q \in M\Sigma$ whose value on the cylinder set $v \in \mathcal{S}_{ab}$ is the barycentric coordinate of q_{ab} at the vertex v

$$\mu_q(v) = q_{ab}(v) \quad (a, b \in \mathbb{Z}, a \leq b, v \in \mathcal{S}_{ab})$$

Since barycentric coordinates are a probability measure on the vertex set \mathcal{S}_{ab} and since $\psi_{ab}^{\alpha\beta} q_{\alpha\beta} = q_{ab}$, those assignments of measures to cylinder sets satisfy Kolmogorov's consistency conditions ([DGS, p 41]) and so determine a measure on $\mathcal{S}^{\mathbb{Z}}$ with support on Σ , which gives the desired μ_q .

Let $\text{Supp}(q_{ab}) \subset \mathcal{S}_{ab}$ be the support of the measure q_{ab} . Then the set

$$\tau_{ab} = \bigcup_{v \in \text{Supp}(q_{ab})} \pi(v) \subset \Omega$$

has small diameter if $b \gg 0 \gg a$ since then each $\pi(v)$ has small diameter and any two $\pi(v)$ in this union intersect. If $\alpha \leq a \leq b \leq \beta$ then $\tau_{\alpha\beta} \subset \tau_{ab}$. Thus there is a unique point $\xi(q) \in \Omega$ that lies in all the τ_{ab} , $a \leq b$. One sees easily that the pushed forward measure $(M\pi)\mu_q$ on Ω is the point mass at $\xi(q)$. If $M_\pi \subset M\Sigma$ denotes the closed set of measures on Σ that are supported on level sets of π then we see that $\mu_q \in M_\pi$ for all $q \in F$.

Next given a measure $\mu \in M_\pi$ we let p_{ab} be the probability measure on \mathcal{S}_{ab} with $p_{ab}(v) = \mu(v)$. Then $\text{Supp}(p_{ab}) \subset \{v | x \in \pi(v)\}$ so $p_{ab} \in N_{ab}$. Clearly the point $p_\mu = (p_{ab})$ belongs to N and defines an embedding of M_π in N . We have shown altogether that $F \simeq N \simeq M_\pi$. A little thought shows that the subspace M_π^i of measures with support on at most $i+1$ points and contained in some level set of π is closed and that our isomorphisms identify F^i and N^i with M_π^i . We have then (identifying F with N)

$$\begin{array}{ccccc} \Sigma \subset N^1 \subset & & \subset N \simeq M_\pi \subset M\Sigma \\ & \searrow \pi & \downarrow \xi & \swarrow M\pi & \\ & & \Omega \subset M\Omega & & \end{array}$$

This ξ is the refined symbolic dynamics mentioned earlier. A level set $\xi^{-1}(x)$ consists of all the formal averages of the symbolic names of a point x , i.e. the simplex with vertices $\pi^{-1}(x)$.

The advantage of ξ over π is that it induces an isomorphism ξ^* on Čech cohomology (with any coefficient group G). Namely the covers τ_{ab} have mesh that

tends to zero as $a \rightarrow -\infty, b \rightarrow +\infty$ and so

$$\check{H}^* \Omega = \varinjlim H^* N_{ab} = \check{H}^* N$$

by the continuity property of Čech cohomology. The advantage of F over N is that F is a priori determined by the inverse system of graphs Γ_{ab} , so higher order intersections can be ignored when computing $\check{H}^* \Omega = \varinjlim H^* F_{ab}$.

Of course the cohomology $\check{H}^* \Omega$ carries more structure than that of a group (or algebra, if G is a ring) namely it has an automorphism f^* . This can also be identified in these inverse limits as the cohomology automorphism induced by the shift homeomorphism

$$(p_{ab}) \mapsto (p_{a+1, b+1})$$

of N . We can group the N_{ab} with a fixed value of $b - a$ together and identify $H^* N_{ab}$ with $t^a H^*_{0, b-a}$ for some indeterminate t to obtain

$$\check{H}^* \Omega = \varinjlim H^* N_{0, p} [t, t^{-1}],$$

where the maps in the limit are of the form $A_p + tB_p$, with $A_p, B_p: H^* N_{0, p} \rightarrow H^* N_{0, p+1}$ induced by the simplicial maps

$$N_{0, p+1} \rightarrow N_{0, p}, \quad N_{0, p+1} \rightarrow N_{1, p+1} \cong N_{0, p}$$

respectively. Here the action of f^* on $\check{H}^* \Omega$ corresponds to multiplication by t on the direct limit. So, replacing N_{ab} by F_{ab} throughout, we see that the inverse system of graphs Γ_{ab} determines $\check{H}^* \Omega$ and the action of f^* .

Also one has a cochain complex for computing $\check{H}^* \Omega$ whose i th group is

$$\check{H}^i(M'_\pi, M'^{-1}_\pi) = \varinjlim C^i(N_{ab}) = \varinjlim C^i(F_{ab})$$

and whose coboundary operators arise from the triples $(M'^{+1}_\pi, M'_\pi, M'^{-1}_\pi)$. Thus the 'skeleta' M'_π play the same role as the skeleta of a finite complex for cohomology computations. Note that these relative cohomology groups carry the f^* action, unlike the finitely generated groups $C^i(N_{ab})$ and $C^i(F_{ab})$.

As an application we study the space $C\Omega$ of connected components of Ω , i.e. the largest zero-dimensional quotient of f . By Stone's theorem $C\Omega$ is the space of maximal ideals in the Boolean algebra of closed-open subsets of Ω , which in turn is just the cohomology group $H^0(\Omega, \mathbb{Z}_2)$. Thus the above cohomology computation implicitly computes $C\Omega$ and one obtains easily the explicit formula

$$C\Omega = \varinjlim C(\Gamma_{ab})$$

Here the map Cf on components corresponds to the shift map $(p_{ab}) \mapsto (p_{a+1, b+1})$ on the inverse limit. For $m \geq 0$ we identify all the $C(\Gamma_{ab})$ with $b - a = m$ with some finite set S_m , so (p_{ab}) determines a point $(p_{n, n+m}) \in S^z_m$. This defines a factor Σ_m of $C\Omega$ that is a subshift on symbol set S_m . One clearly has

$$C\Omega = \varinjlim \Sigma_m$$

and so Cf is an inverse limit of subshifts. Note that each map $\Sigma_{m+1} \rightarrow \Sigma_m$ is surjective.

We now show that $C\Omega$ is expansive $\Leftrightarrow \Sigma_m$ is eventually constant. More generally, given an inverse system of expansive systems X_m with $X_{m+1} \rightarrow X_m$ surjective, the inverse limit X is expansive $\Leftrightarrow X_{m+1} \rightarrow X_m$ is bijective for m sufficiently large. For consider the equivalence relation $E_m \subset X \times X$ defined by the surjective $X \rightarrow X_m, E_m$.

is isolated, $E_{m+1} \subset E_m$ and $\bigcap E_m = \Delta$ is the diagonal in $X \times X$. Thus Δ is isolated $\Leftrightarrow \Delta = E_m$ for m large, as desired.

This criterion suggests that for most FP Ω the system $C\Omega$ is not expansive, yet no example of this behavior is in the literature. In particular all the usual Axiom A basic sets have an SFT as their component map. Indeed if Ω has canonical coordinates and $C\Omega$ is expansive then $C\Omega$ is an SFT.

Counterexamples can be found by using a construction of Guckenheimer. Begin with the Julia set J for a hyperbolic rational map f and form the inverse limit Ω of $\dots \rightarrow J \xrightarrow{f} J \xrightarrow{f} J$. Then Ω is a basic set [G2]. Shishikura has shown us, however, that for f a polynomial, $C\Omega$ is expansive \Leftrightarrow either J is connected or J is zero dimensional. In all other cases there is an infinite component Y of J which surrounds a critical point of f , and one can choose a one-point component $\{z\} \subset J$ arbitrarily near fY . Then z has distinct preimages z', z'' which lie very near Y . In CJ the points z', z'' are very close and become equal after one iterate, so CJ is not positively expansive. Even upon passage to the inverse limit certain prehistories of z', z'' stay very close in $C\Omega$ and so violate expansiveness.

Note that for $\deg f$ large the generic behavior seems to be for $C\Omega$ *not* to be expansive, as suggested by the above analysis. The symbolic description of CJ for cubic polynomials has been carried out by Blanchard and Branner-Hubbard, where already this nonexpansive behaviour arises [BI], [BH].

Now we consider the FP case and show how to compute cohomology from transition and incidence data. Suppose $\Omega = \Sigma_A/E$ where $A \subset \mathcal{S} \times \mathcal{S}$ is a transition relation and where the equivalence relation $E = E_I$ is

$$(s_n)E(s'_n) \Leftrightarrow s_n I s'_n, \quad \text{all } n \in \mathbb{Z},$$

where $I \subset \mathcal{S} \times \mathcal{S}$ is a generalized incidence relation. We do not require that I be the actual incidence relation defined by the cover of Ω by images of cylinder sets in \mathcal{S}_∞ (cf the proof of Theorem 2), although I must clearly include the latter relation. There is a certain compatibility necessary between I and A to make E an equivalence relation, a situation analyzed in [F3].

A cylinder set $v \in \mathcal{S}_{ab}$ corresponds to a sequence of specified values $s_n \in \mathcal{S}$, $a \leq n \leq b$, with $s_n A s_{n+1}$, $a \leq n \leq b$. We denote this by $v(s_a, \dots, s_b)$. Define a symmetric, reflexive relation I_{ab} on \mathcal{S}_{ab} by

$$v(s_a, \dots, s_b) I_{ab} v(s'_a, \dots, s'_b) \Leftrightarrow s_n I s'_n, \quad a \leq n \leq b$$

Then I_{ab} determines a 1-complex $\tilde{\Gamma}_{ab}$ with vertex set \mathcal{S}_{ab} and an edge joining $v, v' \in \mathcal{S}_{ab}$ if and only if $v \neq v'$ and $v I_{ab} v'$. Clearly $\Gamma_{ab} \subset \tilde{\Gamma}_{ab}$. We fill in $\tilde{\Gamma}_{ab}$ to obtain a finite complex K_{ab} with an i -simplex for every set of $i+1$ vertices v any two of which are I related. Clearly $F_{ab} \subset K_{ab}$ and $\tilde{\Gamma}_{ab}$ is the 1-skeleton of K_{ab} . $\tilde{\Gamma}_{ab}$ and K_{ab} are inverse systems of simplicial complexes and one sees easily that

$$\varprojlim \Gamma_{ab} \subset \varprojlim \tilde{\Gamma}_{ab} \subset M^1_\pi$$

For the relation $s_n I s'_n$, $n \in \mathbb{Z}$, implies $\pi(s_n) = \pi(s'_n)$ and so the measure determined by a point $(r_{ab}) \in \varprojlim \tilde{\Gamma}_{ab}$ is supported on at most 2 points in the same fiber of π .

Thus $\varprojlim \tilde{\Gamma}_{ab}^i = M_\pi^1$ Similarly

$$\varprojlim K_{ab}^i = M_\pi^1, \quad \varprojlim K_{ab} = M_\pi$$

and consequently

$$\check{H}^* \Omega = \varprojlim H^* K_{ab} = \varprojlim H^* K_{0p}[t, t^{-1}]$$

This gives an expression for $\check{H}^* \Omega$ in terms of the incidence and transition data I, A alone, in which f^* corresponds as before to multiplication by t

Now consider a simplicial map $L: X \rightarrow Y$ of two finite simplicial complexes. For each $i \geq 0$ one has induced maps $L_i^*: C^i(Y) \rightarrow C^i(X)$, $L_{i*}: C_i(X) \rightarrow C_i(Y)$ and natural identifications $C^i(Y) = C_i(Y)$, $C^i(X) = C_i(X)$ where C^i denotes i -dimensional cochains, C_i denotes i -dimensional chains and we use \mathbb{Z} coefficients. Then if $R: X \rightarrow Y$ is another simplicial map we can define $(L, R)_i = \text{Tr } L_i^* R_{i*} = \text{Tr } L_{i*} R_i^*$ to be the i -dimensional inner product of L and R . The alternating sum $\#(L, R) = \sum (-1)^i (L, R)_i$, is the *coincidence number* of the simplicial correspondence $Y \xleftarrow{L} X \xrightarrow{R} Y$. If the maps in question are understood we write $\#(T \leftarrow X \rightarrow Y)$ for this coincidence number.

In our setting the most important case is $Y = K_{aa} = K_{bb}$, $X = K_{ab}$ for $a \leq b$, L is the natural map $K_{ab} \rightarrow K_{aa}$, and R is the natural map $K_{ab} \rightarrow K_{bb}$. If $m = b - a$ we write $\#_m$ for $\#(K_{aa} \leftarrow K_{ab} \rightarrow K_{bb})$.

There is in fact a commutative diagram of simplicial maps of finite complexes where the left-bound arrows represent the maps L and right-bound arrows represent

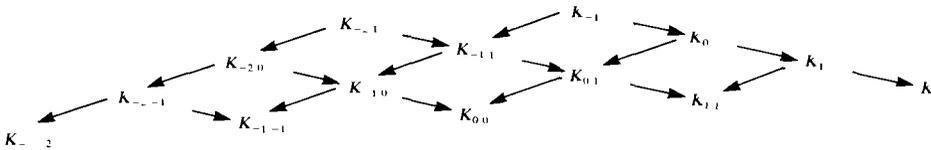
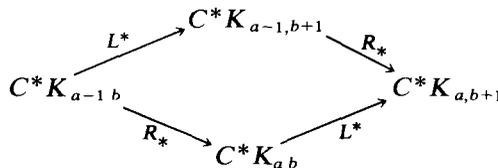


FIGURE 3

the maps R (Figure 3). The numbers $\#_m$ measure coincidences between complexes on the bottom row with spacing m , as we shall see.

Consider the diagram



This diagram commutes thanks to the construction of K . For instance a 1-simplex in $K_{a-1,b}$ is a figure

$$\begin{array}{cc} s_{a-1} A s_a A & A s_b \\ I & I \\ s'_{a-1} A s'_a A & A s'_b \end{array}$$

where the horizontal rows are A related and the vertical columns are I related, as

shown This maps (either through R_*L^* or L^*R_*) to the sum of all 1-simplices

$$\begin{array}{ccc} s_a A & A s_b A s_{b+1} & \\ I & I & I \\ s_a A & A s'_b A s'_{b+1} & \end{array}$$

for $s_{b+1}, s'_{b+1} \in \mathcal{S}$ satisfying the indicated A, I relations

This commutativity allows one to replace the inverted V composition $L^*L^* \quad L^*R_*R_* \quad R_*(m R's, m L's)$ in the definition of $\#_m$ by the zigzag $L^*R_*L^*R_* \quad L^*R_*$ Under our identifications of all the \tilde{F}_{aa} to one complex we can view L^*R_* as a chain map of the complex K_{00} and find

$$\#_m = \sum (-1)^i \text{Tr} (L_i^* R_{i,*})^m$$

The right hand side of this expression resembles a Lefschetz number of the m th iterate of a map it is, however, the coincidence number of the m th iterate of the self-correspondence

$$K_{00} \leftarrow K_{01} \rightarrow K_{11} = K_{00}$$

This alternating sum is exactly that found by Bowen [B2] in his interpretation of the Manning formula for the number of fixed points of f^m We now have a chain level interpretation of this sum as a coincidence number and must explain why it in fact counts fixed points To do so, we must assume that $\pi \Sigma_A \rightarrow \Omega$ has finite fibers

Consider again a simplicial self-correspondence $X \xleftarrow{L} Y \xrightarrow{R} X$ Define the *coincidence set* $\{y \in Y \mid Ly = Ry\} = \mathcal{C}(L, R) = \mathcal{C}(X \leftarrow Y \rightarrow X)$ $\mathcal{C}(L, R)$ meets every simplex of Y in a convex subspace and Y could be subdivided so as to make $\mathcal{C}(L, R)$ a subcomplex Instead we consider the smallest subcomplex $\hat{\mathcal{C}}(L, R)$ of Y that contains $\mathcal{C}(L, R)$

LEMMA 6 *If $\hat{\mathcal{C}}(L, R)$ is the union of disjoint simplices $\Delta_i, i = 1, \dots, k$, and L, R are 1-1 on each Δ_i then $\#(L, R) = k$ is the number of components of $\mathcal{C}(L, R)$*

Proof One immediately reduces to the case $Y = \bigcup \Delta_i$, since other simplices contribute neither to $\mathcal{C}(L, R)$ nor to $\#(L, R)$ Then one must have $L\Delta_i = R\Delta_i$, since $L\Delta_i \cap R\Delta_i$ contains $L(\Delta_i \cap \mathcal{C}(L, R))$ and no subsimplex of Δ_i contains $\Delta_i \cap \mathcal{C}(L, R)$ By the Lefschetz fixed point formula applied to the simplicial isomorphism RL^{-1} of the simplex $L\Delta_i$, Δ_i contributes 1 to $\#(L, R)$, as desired

Note that we used exactly the trivial case of the Lefschetz formula that Bowen predicted would help topologize the Manning formula [B2] For a related application of the Lefschetz formula for a simplex to Axiom A flows see [F1] Note that simplicial maps $L \neq R$ from a 3-simplex Y to a 1-simplex X that are two to one on vertices have $\#(L, R) = 2$, so one must assume L, R 1-1 on Δ_i in Lemma 6

We now show that Lemma 6 applies to the correspondence $K_{00} \xleftarrow{L} K_{0m} \xrightarrow{R} K_{mm} = K_{00}$ and that each component of $\mathcal{C}(L, R)$ corresponds to a fixed point of f^m Take a coincidence point $y \in K_{0m}$ The support of y consists of certain vertices $v_i = (v_0^{(i)}, \dots, v_m^{(i)}) \in \mathcal{S}_{0m}$, and the following coincidence condition holds

$$\sum y(v_i) v_0^{(i)} = \sum y(v_i) v_m^{(i)}$$

Take some v , for which $y(v_i)$ is smallest By the above equation $v_m^{(i)}$ is $v_0^{(j)}$ for some

$J, v_m^{(j)}$ is $v_0^{(k)}$ for some k , etc By forming a nonrepeating cycle i, j, k, \dots, i and subtracting $y(v_i)(v_0^{(i)} + v_0^{(j)} + v_0^{(k)} + \dots)$ from both sides one obtains a similar equation with fewer terms In this way one finds that y is a convex combination of certain barycenters b with $\text{Supp } b \subset \text{Supp } y$, and where each b has the form

$$b = \frac{1}{n} \sum_l v_l \quad l \in \text{Supp } b, \quad n = |\text{Supp } b|$$

and where all the $v_0^{(l)}$ are distinct and equal (as a set) to the $v_m^{(l)}$ Then b determines a cycle of transitions of length mn by concatenating the sequences $v_0^{(l)}, \dots, v_m^{(l)} = v_0^{(l)}, \dots, v_m^{(l)}$, and hence a periodic point z in Σ_A fixed by σ^{mn} The points $z, \sigma^m z, \dots, \sigma^{m(n-1)} z$ are a periodic orbit of σ^m that projects to a periodic orbit of f^m but by expansiveness (in the form $(s_i)I(s'_i)$ all $i \mapsto \pi(s_i) = \pi(s'_i)$) this orbit is in fact a single point $x_b \in \text{Fix}(f^m)$ For the same reason the fixed points x_b arising from the various barycenters occurring in y must all be equal, so $x_b = x_y$ The coincidence points y with a given value of $x, x = x$ must lie in the simplex $\Delta_x \subset N_{0m}$ spanned by the various cylinders that meet $\pi^{-1}x$ By expansiveness Δ_x and $\Delta_{x'}$ are disjoint for $x, x' \in \text{Fix}(f^m), x' \neq x$ Conversely each $x \in \text{Fix}(f^m)$ is covered by a periodic point of σ^m which determines a barycenter $b \in \Delta_x \cap \hat{\mathcal{C}}(L, R)$ So fixed points correspond to components of $\hat{\mathcal{C}}(L, R)$ and we have shown all but the assertion that L, R are 1-1 on each simplex in $\hat{\mathcal{C}}(L, R)$

Only here must we use our assumption that π is finite to one If say L is not 1-1 on the set $\Delta_x \cap \hat{\mathcal{C}}(L, R)$ then Δ_x contains two barycenters as above

$$b = \frac{1}{n} \sum v_l \quad b' = \frac{1}{n'} \sum v_{l'}$$

with $v_0^{(l)} = v_0^{(l')}$ for some l, l' But then one can splice the periodic sequences in Σ corresponding to b, b' at any common occurrence of $v_0^{(l)}$ to obtain infinitely many distinct sequences in $\pi^{-1}x$, a contradiction Thus we have (with $A_i = L_i^* R_{i*}$)

THEOREM 3 For $\Omega = \Sigma_A / E_I$ with the equivalence classes of E_I finite

$$|\text{Fix } f^m| = |\mathcal{C}\mathcal{C}(K_{00} \leftarrow K_{0m} \rightarrow K_{mm})| = \#_m = \sum (-1)^i \text{Tr}(A_i)^m$$

Moreover $\zeta_f(t) = \Pi, \det(I - tA_i)^{(-1)^{i+1}}$ is rational in t

Only the last equation needs to be shown but it follows as usual from the standard algebraic result

$$\exp \sum \text{Tr}(B^m) \frac{t^m}{m} = \det(I - tB)^{-1},$$

together with the Manning-Bowen formula

$$|\text{Fix } f^m| = \sum (-1)^i \text{Tr}(A_i)^m$$

that we have just reproven To those already familiar with their formula it will be clear that all we have done is to make evident the inverse system of finite complexes K_{ab} whose ghost haunted their purely combinatorial arguments

Remark 2 The transformation $A_0 = L_0^* R_{0*}$ is just the transition matrix of the transition relation A For large m it makes the dominant contribution to the alternating sum and one can view the other terms as higher dimensional corrections

Remark 3 Suppose I is transitive. Then the equivalence classes form a set \mathcal{S}/I and Ω embeds in the shift $(\mathcal{S}/I)^{\mathbb{Z}}$ and so is sofic. Conversely every sofic Ω can be presented with I transitive. Then the matrix A decomposes as a sum of blocks B_{jk} , $j, k \in \mathcal{S}/I$. The exterior powers $\Lambda^i B_{jk}$ of these blocks form a block decomposition of A_i , and so

$$\zeta_f(t) = \prod_{i \geq 0} \det(I - t(\Lambda^i B_{jk}))^{(-1)^{i+1}}$$

This is a readily computable formula for the zeta function of a sofic system.

Remark 4 When π has bounded fibers, a theorem of Hurewicz [H] implies that Ω has finite dimension. In particular this holds for $\text{FP } \Omega$. In fact one only needs Ω expansive [Ma]. A more direct proof for FP systems can be found in the exercises in [R, Chap 7], and it also follows from the fact that the dimension of the complexes in the inverse system K_{ab} are bounded. We conjecture that the metric d of Lemma 2 has finite Hausdorff dimension.

Remark 5 We mention a simple formula for the cohomology of a finite complex K . Form the exterior ring EK^0 with generators the vertices v of K and the relations $v^2 = vv' + v'v = 0$. Thus EK^0 is a free abelian group of rank $2^{|K^0|}$. Let $\mathcal{F} \subset EK^0$ be the span of the products of nonincident vertices, i.e. sets of vertices that do not span a simplex. Clearly \mathcal{F} is an ideal in EK^0 , which we call the *nonincidence ideal*. The quotient ring EK^0/\mathcal{F} is the cochain complex of K with \mathbb{Z} coefficients. The differential d is multiplication by the vertex sum $\sum_{v \in K^0} v$.

For a complex such as F_{ab} , K_{ab} defined by filling in a graph, the nonincidence ideal \mathcal{F} is generated by quadratic relations $vv' = 0$ for v, v' not joined by an edge. This gives a simple presentation of the cochain complexes used in this section.

REFERENCES

- [B1] P. Blanchard, Symbols for cubics and other polynomials. To appear in *Trans Amer Math Soc*
- [B1] R. Bowen, *Equilibrium States and the Ergodic Theory of Anosov Diffeomorphisms*. Springer Lecture Notes in Maths **470** 1975.
- [B2] R. Bowen, *On Axiom A Diffeomorphisms*. CBMS Reg. Conf. 35, A.M.S., Providence, 1978.
- [BH] B. Branner & J. Hubbard, The iteration of cubic polynomials. Preprint.
- [CP] E. Coven & M. Paul, Sofic systems. *Israel J. Math.* **20** (1975) 165–177.
- [DGS] M. Denker, C. Grillenberger & K. Sigmund, *Ergodic Theory on Compact Spaces*. Springer Lecture Notes in Maths **527** 1976.
- [ES] S. Eilenberg & N. Steenrod, *Foundations of Algebraic Topology*. Princeton U.P., 1952.
- [FLP] A. Fathi, F. Laudenbach & V. Poenaru, Travaux de Thurston sur les surfaces. *Asterisque* **66–67** 1979.
- [F1] D. Fried, Zeta functions of Ruelle and Selberg, I. *Ann. Sci. ENS.* **19** (1986), 491–517.
- [F2] D. Fried, Rationality for isolated expansive sets. *Advances in Math.* **65** (1987), 35–38.
- [F3] D. Fried, Natural metrics on Smale spaces. *C.R.A.S.* **297** (1983) 77–79.
- [G1] J. Guckenheimer, Axiom A and no cycles imply $\zeta_f(t)$ rational. *Bull. Amer. Math. Soc.* **76** (1970) 592–594.
- [G2] J. Guckenheimer, Endomorphisms of the Riemann sphere. *Proc. Symp. Pure Math.* **14** A.M.S., Providence, 1970, 95–123.
- [H] W. Hurewicz, Über dimensionerhöhende stetige Abbildungen. *J. für Math.* **169** (1933) 71–78.
- [K] J. Kelley, *General Topology*. Van Nostrand, 1955.
- [Kr] W. Krieger, On sofic systems I. *Israel J. Math.* **48** (1984) 305–330.

- [Ma] R Mañé Expansive homeomorphisms and topological dimension *Trans Amer Math Soc* **252** (1979) 313–319
- [M] A Manning Axiom A diffeomorphisms have rational zeta functions *Bull London Math Soc* **3** (1971) 215–220
- [R] D Ruelle *Thermodynamic Formalism* Addison Wesley, Reading, 1978
- [We] B Weiss Subshifts of finite type and sofic systems *Monatsh Math* **77** (1973), 462–478