

ERRATUM

Dynamics modeling of human–machine control interface for underwater teleoperation – ERRATUM

Giovanni Gerardo Muscolo^{1*}, Simone Marcheschi², Marco Fontana³, and Massimo Bergamasco²

¹DIMEAS-Department of Mechanical and Aerospace Engineering, Politecnico di Torino, Corso Duca degli Abruzzi, 24, 10129, Torino, Italy, ²TeCIP Institute, Sant’Anna School of Advanced Studies, Via Alamanni 13B, San Giuliano Terme, Pisa, 56010, Italy and ³Dipartimento di Ingegneria Industriale, University of Trento, Via Sommarive, 9, 38123 Povo, Trento, Italy

*Corresponding author. Email: giovanni.muscolo@polito.it

DOI: <https://doi.org/10.1017/S0263574720000624>, Published online by Cambridge University Press: 22 July 2020.

In the original version of this paper the name of the first author was incorrectly published as Muscolo Giovanni Gerardo. The correct name is Giovanni Gerardo Muscolo.

The Publisher apologises for this error.

Reference

- [1] G.G. Muscolo, S. Marcheschi, M. Fontana and M. Bergamasco, “Dynamics Modeling of Human–Machine Control Interface for Underwater Teleoperation,” *Robotica*, 2020, **39**, 618–632 (2020).

Cite this article: G. G. Muscolo, S. Marcheschi, M. Fontana and M. Bergamasco (2022). “Dynamics modeling of human–machine control interface for underwater teleoperation – ERRATUM”, *Robotica* **40**, 1255. <https://doi.org/10.1017/S0263574721000576>