

A NOTE ON THE STABILITY AND THE APPROXIMATION OF SOLUTIONS FOR A DIRICHLET PROBLEM WITH $p(x)$ -LAPLACIAN

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Abstract

We show the stability results and Galerkin-type approximations of solutions for a family of Dirichlet problems with nonlinearity satisfying some local growth conditions.

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1. Introduction

The aim of this paper is to consider the existence and stability of solutions and their Galerkin-type finite-dimensional approximations for the family of Dirichlet problems given by

$$\begin{aligned} -\operatorname{div} (a_k(x) |\nabla u(x)|^{p(x)-2} \nabla u(x)) &= F_u^k(x, u(x)), \\ u(x)|_{\partial\Omega} &= 0, \quad u \in W_0^{1,p(x)}(\Omega) \end{aligned} \tag{1.1}$$

where $\Omega \subset R^N$ is a bounded region with Lipschitz boundary, $p, q \in C(\overline{\Omega})$ and $1/p(x) + 1/q(x) = 1$ for $x \in \Omega$; $W_0^{1,p(x)}(\Omega)$ denotes the generalized Orlicz-Sobolev space, see [6, 7]; and $a_k \in C(\overline{\Omega})$ with $a_0(x) \geq a_0 > 0$ on $\overline{\Omega}$ for $k = 0, 1, 2, \dots$. Let $p^- = \inf_{x \in \Omega} p(x) > N > 2$, $a_k \rightrightarrows a_0$.

The stability of the system (1.1) means that for each $k = 1, 2, \dots$ there exists a solution u_k to (1.1) and there exists $\bar{u} = \lim_{k \rightarrow \infty} u_k$ (weak in $W_0^{1,p(x)}(\Omega)$) solving

$$\begin{aligned} -\operatorname{div} (a_0(x) |\nabla \bar{u}(x)|^{p(x)-2} \nabla \bar{u}(x)) &= F_u^0(x, \bar{u}(x)), \\ \bar{u}(x)|_{\partial\Omega} &= 0, \quad \bar{u} \in W_0^{1,p(x)}(\Omega). \end{aligned} \tag{1.2}$$

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The idea of the approximation of solutions is based on the observation that each u_k solving (1.1) is approximated by a suitably selected minimizing sequence $\{u_k^n\}_{n=1}^\infty$ for the action functional $J_k : W_0^{1,p(x)}(\Omega) \rightarrow \mathbb{R}$

$$J_k(u) = \int_{\Omega} \frac{a_k(x)}{p(x)} |\nabla u(x)|^{p(x)} dx - \int_{\Omega} F^k(x, u(x)) dx.$$

We minimize J_k on a set X_k which has the following property: for all $u \in X_k$, the relation

$$\begin{aligned} -\operatorname{div}(a_k(x) |\nabla \tilde{u}(x)|^{p(x)-2} \nabla \tilde{u}(x)) &= F_u^k(x, u(x)), \\ \tilde{u}(x)|_{\partial\Omega} &= 0, \quad \tilde{u} \in W_0^{1,p(x)}(\Omega) \end{aligned} \quad (1.3)$$

implies $\tilde{u} \in X_k$. We later show that the minimizing sequence $\{u_k^n\}_{n=1}^\infty$ is such that

$$-\operatorname{div}(a_k(x) |\nabla u_k^n(x)|^{p(x)-2} \nabla u_k^n(x)) = F_u^k(x, z_k^n(x)), \quad (1.4)$$

where z_k^n for each $n = 1, 2, \dots$ is a certain element of X_k . Thus each u_k^n - being a solution to Equation (1.4) which has a fixed right-hand side - may be approximated by a Galerkin sequence. Consult [2] for details of Galerkin-type approximations for equations in Orlicz-Sobolev space, and Section 4. Now a solution is approximated by a minimizing sequence, whose elements in turn may be approximated by a sequence of finite-dimensional elements. Therefore by taking a diagonal sequence we obtain the sequence of finite-dimensional solutions to (1.2). The very same idea applies to approximation of the solution of (1.2).

Concerning the existence and stability of solutions with the use of a dual variational method we draw attention to our previous paper [8]. The following Dirichlet problem is investigated:

$$\begin{aligned} -\operatorname{div}(a(x) |\nabla u(x)|^{p(x)-2} \nabla u(x)) + b(x) |u(x)|^{p(x)-2} u(x) &= F_u^k(x, u(x)), \\ u(x)|_{\partial\Omega} &= 0, \quad u \in W_0^{1,p(x)}(\Omega), \end{aligned} \quad (1.5)$$

where $a, b \in L^\infty(\Omega)$ with $a(x) \geq a_0 > 0$ and $b(x) \geq b_0 \geq 0$ a.e. on Ω and with nonlinearity satisfying some local conditions being counterparts of our conditions 1–3 (see Section 2). In reaching the existence result one finds a set on which one may minimize the action functional for which (1.5) is the Euler-Lagrange equation. Later, a suitable minimizing sequence is chosen and its convergence investigated. In order to demonstrate that the limit of a minimizing sequence is actually a solution to (1.5), a duality theory is constructed. In doing so a dual action functional is introduced, its domain is constructed and both action functionals are minimized. Finally, the existence results are used to obtain stability of solutions to (1.5) in the sense described above. Galerkin-type approximations have not been considered in [8].

In the present paper we are concerned with the case when the function $a(x)$ from (1.5) may also vary with a numerical parameter k . In order to investigate the stability and approximation of solutions one should have suitable existence results first. Since in proving the existence result we find a minimizing sequence, there arose a question if any minimizing sequence - whose existence on a set X_k follows by the growth conditions - will allow us to obtain the approximation result. It appeared that property (1.4) for a minimizing sequence was required. Therefore we use some ideas from [8] concerning the construction of a dual action functional J_D^k with suitable modifications for selecting the minimizing sequence for J_k over X_k . In order to get property (1.4) we first find a minimizing sequence for a dual functional and later construct a suitable minimizing sequence for J_k over X_k . The present paper and paper [8] differ as far as the existence result is concerned in their approach towards selecting minimizing sequences. The existence of a minimizing sequence for J_D^k follows by the growth conditions which we use and the construction of the sets on which a dual action functional is minimized, while in [8] the action functional J_k was minimized. However, since the minimizing sequence for J_k over X_k must have property (1.4) we must use additional arguments and the form of proof used in [8] does not apply here.

For some other variational approaches see [3] and [5], where the existence of a weak solution to a $p(x)$ -Laplacian equation is considered. In both sources the direct variational method is used in order to get solutions in the sublinear case while the Palais-Smale condition is imposed and mountain pass geometry is employed to get the solution in the superlinear case.

Since problems with generalized-growth conditions are applied in elastic mechanics and electrorheological fluid dynamics, see [10, 11] and references therein, we believe that our results may contribute to that research.

2. The assumptions and auxiliary results

In what follows we denote the best Sobolev constant by C_S , where

$$\|u\|_{p(x)} \leq C_S \|\nabla u\|_{p(x)} \quad \text{for all } u \in W_0^{1,p(x)}(\Omega; R).$$

Since $W_0^{1,p(x)}(\Omega; R)$ is continuously embedded into $W_0^{1,p^-}(\Omega)$, [7], we have

$$\|\nabla u\|_{p^-} \leq C_1 \|\nabla u\|_{p(x)} \quad (2.1)$$

for some constant C_1 . Since $p^- > N$, by the Sobolev embedding theorem [1] we get

$$\max_{x \in \Omega} |u(x)| \leq C_2 \|\nabla u\|_{p^-} \quad \text{for all } u \in W_0^{1,p}(\Omega) \quad (2.2)$$

for a certain constant C_2 . Relation (2.2) is understood as follows: for every $u \in W_0^{1,p}(\Omega)$ there exists $u_0 \in C(\Omega)$ such that $u_0(x) = u(x)$ almost everywhere and $\max_{x \in \Omega} |u_0(x)| \leq C_2 \|\nabla u\|_{p^-}$.

Therefore by (2.1) and (2.2) for all $u \in W_0^{1,p(x)}(\Omega; R)$ we get

$$\max_{x \in \Omega} |u(x)| \leq C_2 \|\nabla u\|_{p^-} \leq C_1 C_2 \|\nabla u\|_{p(x)}.$$

We assume that the following hold for a function F^k .

Assumption 1. The relation $\|1\|_{q(x)}(1/p^- + 1/q^-)^{-1} \leq 1$ is satisfied; there exist positive numbers d_0, d_1, d_2, \dots such that $d_k \leq d_0$ for $k \in N$ and

$$\begin{aligned} C_S \operatorname{ess\,sup}_{x \in \Omega} |F_u^k(x, d_k)| &\geq 1, & C_S \operatorname{ess\,sup}_{x \in \Omega} |F_u^k(x, -d_k)| &\geq 1, \\ C_S C_1 C_2 \operatorname{ess\,sup}_{x \in \Omega} |F_u^k(x, d_k)| &\leq a_0 d_k, & C_S C_1 C_2 \operatorname{ess\,sup}_{x \in \Omega} |F_u^k(x, -d_k)| &\leq a_0 d_k. \end{aligned}$$

Assumption 2. There exists a positive number $d > d_0$ such that for all $k = 0, 1, 2, \dots$ and $I = [-d, d]: F_u^k(\cdot, d), F_u^k(\cdot, -d) \in L^\infty(\Omega), F^k : \Omega \times I \rightarrow R$ are Caratheodory functions and convex in u for a.e. $x \in \Omega, F_u^k : \Omega \times I \rightarrow R$ are Caratheodory functions and $F^k(x, u) := +\infty$ for $(x, u) \in \Omega \times (R - I)$.

Assumption 3. The function $F_u^k(x, 0) \neq 0$, for a.e. $x \in \Omega, x \mapsto F^k(x, 0)$ and $x \mapsto (F^k)^*(x, 0)$ are integrable on Ω .

Here $(F^k)^*$ denotes the Fenchel-Young conjugate of F^k , see [4]. Now it is obvious that $F^k : \Omega \times R \rightarrow R$ is convex and l.s.c.

Let $W = \{v \in L^{q(x)}(\Omega) | \operatorname{div} v \in L^{q(x)}(\Omega)\}$. The dual functional which we investigate reads $J_k^D : W \rightarrow R$

$$J_k^D(v) = \int_\Omega (F^k)^*(x, -\operatorname{div} v(x)) dx - \int_\Omega \frac{1}{(a_k(x))^{q(x)/p(x)}} \frac{1}{q(x)} |v(x)|^{q(x)} dx.$$

We put

$$X_k = \left\{ u \in W_0^{1,p(x)}(\Omega), \quad \|\nabla u\|_{p(x)} \leq \frac{d_k}{C_1 C_2}, \quad |u(x)| \leq d_k \right\}$$

and exactly as in [8] we prove that this set has property (1.3).

The dual functional J_k^D will be considered on a set X_k^d which is a set of these $v \in W$ for which there exists a $u \in X_k$ such that

$$-\operatorname{div} v(x) = F^k(x, u(x)) \tag{2.3}$$

and

$$a_k(x) |\nabla \tilde{u}(x)|^{p(x)-2} \nabla \tilde{u}(x) = v(x),$$

where \tilde{u} corresponds to u in (1.3).

We will investigate J_k on a set X_k and J_k^D on a set X_k^d on which sets these are well defined.

3. The existence and stability of solutions

THEOREM 3.1. *Assume Assumptions 1, 2 and 3 hold. For all $k = 0, 1, 2, \dots$ there exists $(u_k, v_k) \in X_k \times X_k^d$ such that*

$$-\operatorname{div} v_k(x) = F_u^k(x, u_k(x)) \quad \text{and} \tag{3.1}$$

$$a_k(x) |\nabla u_k(x)|^{p(x)-2} \nabla u_k(x) = v_k(x). \tag{3.2}$$

Moreover

$$\inf_{v \in X_k^d} J_k^D(v) = J_k^D(v_k) = J_k(u_k) = \inf_{u \in X_k} J_k(u). \tag{3.3}$$

PROOF. We fix $k = 0, 1, 2, \dots$. We observe that $\inf_{u \in X_k} J_k(u)$ is finite by Lemma 3.4 of [8]. Exactly as in [8] we can show that

$$\inf_{v \in X_k^d} J_k^D(v) = \inf_{u \in X_k} J_k(u). \tag{3.4}$$

By (3.4) since $\inf_{u \in X_k} J_k(u)$ is finite it follows that J_k^D is bounded from below on X_k^d . By the definition of X^d , see (2.3), by the properties of the Fenchel-Young transform it follows that there exists a constant $\eta_k > 0$ such that $\int_{\Omega} (F^k)^*(x, -\operatorname{div} v(x)) dx \leq \eta_k$ for all $v \in X_k^d$. Therefore by the definition of J_k^D and since $J_k^D(v) \geq \inf_{u \in X_k} J_k(u)$ for all $v \in X_k^d$ we get

$$\begin{aligned} \int_{\Omega} \frac{1}{(a_k(x))^{q(x)/p(x)}} \frac{1}{q(x)} |v(x)|^{q(x)} dx &\leq \int_{\Omega} (F^k)^*(x, -\operatorname{div} v(x)) dx - \inf_{u \in X_k} J_k(u) \\ &\leq \eta_k - \inf_{u \in X_k} J_k(u). \end{aligned}$$

By (2.3) and by Assumptions 1 and 2 we get for a.e. $x \in \Omega$, for any $h \in X_k$ that $F_u^k(x, -d_k) \leq F_u^k(x, h(x)) \leq F_u^k(x, d_k)$. Thus $F_u^k(\cdot, h(\cdot))$ is bounded in $L^\infty(\Omega)$ and so is $\operatorname{div} v(\cdot)$. Since the term $1/(a_k(x))^{q(x)/p(x)} \cdot 1/q(x)$ is bounded, it follows that X_k^d is bounded in W . Thus we may find a minimizing sequence $\{v_k^n\}_{n=1}^\infty$ for a restriction of a functional J_k^D to the set X_k^d which may be assumed to be weakly convergent in W .

We show that there exists a minimizing sequence $\{u_k^n\}_{n=1}^\infty$ for a restriction of functional J_k to the set X_k having the property for $n = 1, 2, \dots$

$$a_k(x) |\nabla u_k^n(x)|^{p(x)-2} \nabla u_k^n(x) = v_k^n(x). \tag{3.5}$$

Since $v_k^n \in X_k^d$ it follows that $u_k^n \in X_k$. We observe that for v_k^n and u_k^n , by (3.5) we

have by properties of the Fenchel-Young transform that

$$\begin{aligned} J_k^D(v_k^n) &= \int_{\Omega} (F^k)^*(x, -\operatorname{div} v_k^n(x)) dx - \int_{\Omega} \frac{1}{(a_k(x))^{q(x)/p(x)}} \frac{1}{q(x)} |v_k^n(x)|^{q(x)} dx \\ &= \int_{\Omega} (F^k)^*(x, -\operatorname{div} v_k^n(x)) dx + \int_{\Omega} \left(\operatorname{div} v(x) u_k^n(x) + \frac{a_k(x)}{p(x)} |\nabla u_k^n(x)|^{p(x)} \right) dx \\ &\geq \int_{\Omega} \frac{a_k(x)}{p(x)} |\nabla u_k^n(x)|^{p(x)} dx - \int_{\Omega} F^k(x, u_k^n(x)) dx = J_k(u_k^n). \end{aligned}$$

By the above and since $\{v_k^n\}_{n=1}^{\infty}$ is a minimizing sequence, we obtain that for any $\varepsilon > 0$ there exists n_0 such that for all $n > n_0$ we get

$$J_k(x_k^n) + \varepsilon \geq \inf_{u \in X_k} J_k(u) + \varepsilon \geq J_k^D(v_k^n) \geq J_k(u_k^n) \geq \inf_{u \in X_k} J_k(u).$$

Thus $\{u_k^n\}_{n=n_0}^{\infty}$ is a minimizing sequence. We renumber both sequences so that these start with $n = 1$. Sequence $\{u_k^n\}_{n=1}^{\infty}$ may be assumed to be weakly convergent in $W_0^{1,p(x)}(\Omega)$ and therefore, up to a subsequence, strongly in $L^{p^-}(\Omega)$. Thus a sequence $\{u_k^n\}_{n=1}^{\infty}$ contains a subsequence convergent a.e. We denote this subsequence by $\{u_k^n\}_{n=1}^{\infty}$ and its limit by u_k . We see that $\|\nabla u_k^n\|_{L^{p(x)}(\Omega)} \leq d_k/C_1C_2$ for all n and $\liminf_{n \rightarrow \infty} \|\nabla u_k^n\|_{L^{p(x)}(\Omega)} \geq \|\nabla u_k\|_{L^{p(x)}(\Omega)}$. Therefore $\|\nabla u_k\|_{L^{p(x)}(\Omega)} \leq d_k/C_1C_2$. By the definition of the sequence $\{u_k^n\}_{n=1}^{\infty}$ we also get $|u_k^n(x)| \leq d_k$. Since $\{u_k^n\}_{n=1}^{\infty}$ is convergent almost everywhere, we get $|u_k(x)| \leq d_k$. So $u_k \in X_k$. Since

$$W_0^{1,p(x)}(\Omega) \ni x \rightarrow \int_{\Omega} \frac{a_k(x)}{p(x)} |\nabla u(x)|^{p(x)} dx \in R$$

is convex and lower semicontinuous, it is weakly lower semicontinuous [4] and since $\lim_{n \rightarrow \infty} \int_{\Omega} F_u^k(x, u_k^n(x)) dx = \int_{\Omega} F_u^k(x, u_k(x)) dx$ we get $\liminf_{n \rightarrow \infty} J_k(u_k^n) \geq J_k(u_k)$. Thus J_k is weakly lower semicontinuous on X_k and $J_k(u_k) = \inf_{u \in X_k} J_k(u)$.

Since $u_k \in X_k$ we may take $v_k \in X_k^d$ such that (3.1) holds. By the Fenchel-Young inequality

$$\int_{\Omega} \frac{a_k(x)}{p(x)} |\nabla u_k(x)|^{p(x)} dx \geq \int_{\Omega} \left(v_k(x) \nabla u_k(x) - \frac{1}{(a_k(x))^{q(x)/p(x)}} \frac{1}{q(x)} |v_k(x)|^{q(x)} \right) dx \tag{3.6}$$

and by a direct calculation we obtain that $J_k(u_k) \geq J_k^D(v_k)$. By (3.4) it follows that $J_k(u_k) \leq \inf_{v \in X_k^d} J_k^D(v) \leq J_k^D(v_k)$. Hence $J_k(u_k) = J_k^D(v_k)$ and by a direct calculation we have

$$\int_{\Omega} \frac{a_k(x)}{p(x)} |\nabla u_k(x)|^{p(x)} dx = \int_{\Omega} \left(v_k(x) \nabla u_k(x) - \frac{1}{(a_k(x))^{q(x)/p(x)}} \frac{1}{q(x)} |v_k(x)|^{q(x)} \right) dx.$$

Thus we actually have equalities in (3.6). Therefore (3.2) holds. Assertion (3.3) follows by (3.4) and since $J_k^D(v_k) = J_k(u_k)$. □

REMARK 1. From the proof of Theorem 3.1 it follows that the minimizing sequence $\{u_k^n\}_{n=1}^\infty$ has the following properties for $n \rightarrow \infty$:

$$\begin{aligned} u_k^n &\rightharpoonup u_k \text{ weakly in } W_0^{1,p(x)}(\Omega), \\ a_k(\cdot)|\nabla u_k^n(\cdot)|^{p(x)-2}\nabla u_k^n(\cdot) &\rightharpoonup a_k(\cdot)|\nabla u_k(\cdot)|^{p(x)-2}\nabla u_k(\cdot) \text{ weakly in } L^{q(x)}(\Omega), \\ \nabla u_k^n &\rightharpoonup \nabla u_k \text{ weakly in } L^{p(x)}(\Omega) \text{ and} \\ u_k^n &\rightarrow u_k \text{ a.e. in } \Omega. \end{aligned}$$

COROLLARY 3.2. Assume Assumptions 1–3 hold. For all $k = 0, 1, 2, \dots$ there exists $u_k \in X_k$ such that

$$\begin{aligned} -\operatorname{div}(a_k(x)|\nabla u_k(x)|^{p(x)-2}\nabla u_k(x)) &= F_u^k(x, u_k(x)), \quad u_k|_{\partial\Omega} = 0 \text{ and} \\ J_k(u_k) &= \inf_{u \in X_k} J_k(u). \end{aligned}$$

Moreover $-\operatorname{div}(a_k(\cdot)|\nabla u_k(\cdot)|^{p(x)-2}\nabla u_k(\cdot)) \in L^\infty(\Omega)$ and $\|\nabla u_k\|_{L^{p(x)}(\Omega)} \leq d_k/C_1C_2$, $|u_k(x)| \leq d_k$.

Now we make an additional assumption on p .

Assumption 4. The region Ω has a Lipschitz-continuous boundary and for all $x, y \in \Omega$ such that $|x - y| < 1$, we have

$$|p(x) - p(y)| < \frac{M}{\ln(1/|x - y|)}$$

for a certain constant $M > 0$.

This assumption guarantees that $C_0^\infty(\Omega)$ is dense in $W^{1,p(x)}(\Omega)$. Exactly as in [8] we prove the following result.

THEOREM 3.3. Assume Assumptions 1–4 hold and that for all $u \in X_0$ there exists a subsequence $\{k_i\}_{i=1}^\infty$ such that $\lim_{i \rightarrow \infty} F_u^{k_i}(x, u(x)) = F_u^0(x, u(x))$ weakly in $L^{q(x)}(\Omega)$. For each $k = 0, 1, 2, \dots$ there exists a solution u_k to problem (1.1). There exists a subsequence $\{u_{k_n}\}_{n=1}^\infty$ of the sequence $\{u_k\}_{k=1}^\infty$ and $\bar{u} \in W_0^{1,p(x)}$ such that

$$\begin{aligned} u_{k_n} &\rightharpoonup \bar{u} \in X, \quad \text{weakly in } W_0^{1,p(x)}(\Omega) \text{ and} \\ -\operatorname{div}(a_0(x)|\nabla \bar{u}(x)|^{p(x)-2}\nabla \bar{u}(x)) &= F_u^0(x, \bar{u}(x)), \quad \bar{u}(x)|_{\partial\Omega} = 0. \end{aligned}$$

REMARK 2. From the proof contained in [8] it follows that the sequence $\{u_k\}_{k=1}^\infty$ that approximates \bar{u} has the following properties for $k \rightarrow \infty$:

$$\begin{aligned} u_k &\rightharpoonup \bar{u} \text{ weakly in } W_0^{1,p(x)}(\Omega), \\ a_k(\cdot)|\nabla u_k(\cdot)|^{p(x)-2}\nabla u_k(\cdot) &\rightharpoonup a_0(\cdot)|\nabla \bar{u}(\cdot)|^{p(x)-2}\nabla \bar{u}(\cdot) \text{ weakly in } L^{q(x)}(\Omega), \\ \nabla u_k &\rightharpoonup \nabla \bar{u} \text{ weakly in } L^{p(x)}(\Omega) \text{ and} \\ u_k &\rightarrow \bar{u} \text{ a.e. in } \Omega. \end{aligned}$$

4. Approximation of solutions

Following [9] the authors in [2] give finite-dimensional Galerkin-type approximation in the anisotropic case with suitable modification due to the properties of Orlicz-Sobolev spaces. In the case of Equation (1.4) we obtain, following reasoning from [2], that there exists a sequence $\{v_k^{n,j}\}_{j=1}^\infty$ of Galerkin approximations such that for a minimising sequence $\{u_k^n\}_{n=1}^\infty$ of J_k over X_k we have

$$\begin{aligned} v_k^{n,j} &\rightharpoonup u_k^n \text{ weakly in } W_0^{1,p(x)}(\Omega), \\ a_k(\cdot) \left| \nabla v_k^{n,j}(\cdot) \right|^{p(x)-2} \nabla v_k^{n,j}(\cdot) &\rightharpoonup a_k(\cdot) \left| \nabla u_k^n(\cdot) \right|^{p(x)-2} \nabla u_k^n(\cdot) \text{ weakly in } L^{q(x)}(\Omega), \\ \nabla v_k^{n,j} &\rightharpoonup \nabla u_k^n \text{ weakly in } L^{p(x)}(\Omega) \quad \text{and} \\ v_k^{n,j} &\rightarrow u_k^n \text{ a.e. in } \Omega. \end{aligned}$$

THEOREM 4.1. *Assume Assumptions 1–4 hold. For all $k = 0, 1, 2, \dots$ there exists $u_k \in X_k$ such that $J_k(u_k) = \inf_{u \in X_k} J_k(u)$ and*

$$-\operatorname{div} (a_k(x) |\nabla u_k(x)|^{p(x)-2} \nabla u_k(x)) = F_u^k(x, u_k(x)), \quad u_k \in W_0^{1,p(x)}(\Omega).$$

There exists a minimizing sequence $\{u_k^n\}_{n=1}^\infty$ for a restriction of a functional J_k to the set X_k such that $u_k^n \rightharpoonup u_k$ weakly in $W_0^{1,p(x)}(\Omega)$. Moreover there exists a sequence $\{v_k^{n,j}\}_{j=1}^\infty$ of finite-dimensional Galerkin approximations such that

$$\begin{aligned} v_k^{n,j} &\rightharpoonup u_k \text{ weakly in } W_0^{1,p(x)}(\Omega), \\ a_k(\cdot) \left| \nabla v_k^{n,j}(\cdot) \right|^{p(x)-2} \nabla v_k^{n,j}(\cdot) &\rightharpoonup a_k(\cdot) \left| \nabla u_k(\cdot) \right|^{p(x)-2} \nabla u_k(\cdot) \text{ weakly in } L^{q(x)}(\Omega), \\ \nabla v_k^{n,j} &\rightharpoonup \nabla u_k \text{ weakly in } L^{p(x)}(\Omega) \quad \text{and} \\ v_k^{n,j} &\rightarrow u_k \text{ a.e. in } \Omega. \end{aligned} \tag{4.1}$$

PROOF. The existence of $u_k \in X_k$ and of a minimizing sequence $\{u_k^n\}_{n=1}^\infty$, having properties (3.5) and (1.4) follows by Theorem 3.1. By the remarks preceding the proof, for each u_k^n for $n = 1, 2, \dots$ there exists a sequence $\{v_k^{n,j}\}_{j=1}^\infty$ of Galerkin approximations such that

$$\begin{aligned} v_k^{n,j} &\rightharpoonup u_k^n \text{ weakly in } W_0^{1,p(x)}(\Omega), \\ a_k(\cdot) \left| \nabla v_k^{n,j}(\cdot) \right|^{p(x)-2} \nabla v_k^{n,j}(\cdot) &\rightharpoonup a_k(\cdot) \left| \nabla u_k^n(\cdot) \right|^{p(x)-2} \nabla u_k^n(\cdot) \text{ weakly in } L^{q(x)}(\Omega), \\ \nabla v_k^{n,j} &\rightharpoonup \nabla u_k^n \text{ weakly in } L^{p(x)}(\Omega) \quad \text{and} \\ v_k^{n,j} &\rightarrow u_k^n \text{ a.e. in } \Omega. \end{aligned}$$

Now by Remark 1 we take a diagonal sequence with the property (4.1). □

Using Remark 2, by taking the diagonal sequence we obtain the following stability and approximation theorem.

THEOREM 4.2. *Assume Assumptions 1–4 hold and that for all $u \in X_0$ there exists a subsequence $\{k_i\}_{i=1}^\infty$ such that $\lim_{i \rightarrow \infty} F_u^{k_i}(x, u(x)) = F_u^0(x, u(x))$ weakly in $L^{q(x)}(\Omega)$. For each $k = 0, 1, 2, \dots$ there exists a solution u_k to Problem (1.1). There exists a subsequence $\{u_{k_n}\}_{n=1}^\infty$ of the sequence $\{u_k\}_{k=1}^\infty$ and $\bar{u} \in W_0^{1,p(x)}$ such that*

$$u_{k_n} \rightharpoonup \bar{u} \in X, \text{ weakly in } W_0^{1,p(x)}(\Omega) \quad \text{and} \\ -\operatorname{div}(a_0(x) |\nabla \bar{u}(x)|^{p(x)-2} \nabla \bar{u}(x)) = F_u^0(x, \bar{u}(x)), \quad \bar{u}(x)|_{\partial\Omega} = 0.$$

Moreover there exists a sequence $\{v^j\}_{j=1}^\infty$ of finite-dimensional Galerkin approximations such that

$$v^j \rightharpoonup \bar{u} \text{ weakly in } W_0^{1,p(x)}(\Omega), \\ a_k(\cdot) |\nabla v^j(\cdot)|^{p(x)-2} \nabla v^j(\cdot) \rightharpoonup a_0(\cdot) |\nabla \bar{u}(\cdot)|^{p(x)-2} \nabla \bar{u}(\cdot) \text{ weakly in } L^{q(x)}(\Omega), \\ \nabla v^j \rightharpoonup \nabla \bar{u} \text{ weakly in } L^{p(x)}(\Omega) \quad \text{and} \\ v^j \rightarrow \bar{u} \text{ a.e. in } \Omega.$$

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